

addRotationVectorCallback



```
graph LR; A[addRotationVectorCallback] --> B[SensorErrorCheck]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'addRotationVectorCallback'. The right box is white and contains the text 'SensorErrorCheck'. A dark blue arrow points from the right side of the gray box to the left side of the white box.

SensorErrorCheck