

getProximityValue



```
graph LR; A[getProximityValue] --> B[SensorErrorCheck]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is gray with a black border and contains the text 'getProximityValue'. The right box is white with a black border and contains the text 'SensorErrorCheck'. A blue arrow points from the right side of the gray box to the left side of the white box.

SensorErrorCheck