


getRotationVectorValue



```
graph LR; A[getRotationVectorValue] --> B[SensorErrorCheck]
```

A flow diagram consisting of two rectangular boxes connected by a horizontal arrow. The first box on the left is gray and contains the text 'getRotationVectorValue'. A dark blue arrow points from the right side of this box to the left side of a second box on the right. The second box is white and contains the text 'SensorErrorCheck'. Both boxes have a black border.

SensorErrorCheck