


getRotationVectorValue



```
graph LR; A[getRotationVectorValue] --> B[SensorErrorCheck]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is gray with a black border and contains the text 'getRotationVectorValue'. A dark blue arrow points from the right side of this box to the left side of the right box. The right box is white with a black border and contains the text 'SensorErrorCheck'.

SensorErrorCheck