

# Surveys, Sampling and Observational Data

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# 1 Review

## 1.1 Basic Definition

**Definition 1.1.** *Random experiment* is the process of observing the outcome of a chance event.

**Definition 1.2.** *Elementary outcomes* are all possible results of the random experiment.

**Definition 1.3.** *Sample space* ( $\Omega$ ) is the set of all the elementary outcomes.

**Definition 1.4.** *Random variable*  $Y$  is a real-valued function defined over a sample space.

**Definition 1.5.** *Sample survey* is a partial investigation of the finite population using samples.

The purpose of the sample survey is to obtain information about the population.

**Definition 1.6.** *Population* is a set of elements defined according to the aims and objects of the survey.

**Definition 1.7.** *Variable* is the function defined on population elements, characteristic of population elements. Variable can be quantitative (numerical) or qualitative (categorical).

**Definition 1.8.** *Distribution* or *frequency distribution* is the proportion of elements with value in an interval  $[a, b]$ ,  $\forall a, b$ .

**Definition 1.9.** *Sampling* is the selection of part of the population.

**Definition 1.10.** *Sampling method* is a scientific and objective procedure of selecting units from a population. It provides a sample that is expected to be representative of the population as a whole, and procedures for estimation of the population parameters.

## 1.2 Basic Notations

- Population:  $E = \{e_1, e_2, \dots, e_N\}$  with population size  $N$ , where  $e_i$ 's are elements.
- Variable:  $y, x, z, t, \dots$ .
- Range:  $\{y(e), e \in E\}$ .
- Probability: In discrete case,

$$P(y_i) = \frac{|\{e, y(e) = y_i\}|}{N} = \frac{N_i}{N}.$$

In continuous case,

$$P(a, b) = P(a < y < b) = \int_a^b f(y)dy,$$

where  $f(y)$  is the density function s.t.

$$f(y) \geq 0, \forall y \text{ and } \int_{-\infty}^{\infty} f(y)dy = 1.$$

## 1.3 Population Parameters

### 1.3.1 Population Mean ( $\mu_y$ )

- Using distribution:

$$\mu_y = \sum_{i=1}^k y_i P(y_i) = \frac{1}{N} \sum_{i=1}^k N_i y_i.$$

- Using population values:

$$\mu_y = \frac{1}{N} \sum_{i=1}^N y(e_i) = \frac{1}{N} \sum_{i=1}^N y_i.$$

### 1.3.2 Population Variance ( $\sigma_y^2$ )

- Using distribution:

$$\sigma_y^2 = \sum_{i=1}^k (y_i - \mu_y)^2 P(y_i) = \frac{1}{N} \sum_{i=1}^k N_i (y_i - \mu_y)^2.$$

- Using population values:

$$\sigma_y^2 = \frac{1}{N} \sum_{i=1}^N (y_i - \mu_y)^2 = \frac{1}{N} \sum_{i=1}^N y_i^2 - \mu_y^2.$$

- Population standard deviation is  $\sigma_y = \sqrt{\sigma_y^2}$ .

### 1.3.3 Population Total ( $\tau_y$ )

$$\tau_y = \sum_{i=1}^N y(e_i) = \sum_{i=1}^N y_i = \sum_{i=1}^N N_i y_i = N \mu_y.$$

### 1.3.4 Population Proportion

Define

$$y(e) = \begin{cases} 0, & e \text{ does not have the property} \\ 1, & e \text{ has the property} \end{cases},$$

then

$$p = \frac{1}{N} \sum_{i=1}^N y(e_i) = \frac{M}{N} = \mu,$$

where  $M$  is the number of elements with the property.

### 1.3.5 Population Ratio

Ratio of two variables' means or totals:

$$R_{y/x} = \frac{\mu_y}{\mu_x} = \frac{N \mu_y}{N \mu_x} = \frac{\tau_y}{\tau_x}.$$

## 1.4 Basic Rules from Probability

In probability, the covariance of  $X$  and  $Y$  is

$$\text{Cov}(X, Y) = \mathbb{E}[(X - \mathbb{E}[X])(Y - \mathbb{E}[Y])] = \mathbb{E}[XY] - \mathbb{E}[X]\mathbb{E}[Y].$$

In statistics, the covariance of  $x$  and  $y$  is

$$\begin{aligned}\text{Cov}(x, y) &= \frac{1}{N} \sum_{i=1}^N (x_i - \mu_x)(y_i - \mu_y) = \frac{1}{N} \sum_{i=1}^N x_i y_i - \mu_x \mu_y \\ &= \frac{1}{N} \sum_{i,j} N_{ij} (x_i - \mu_x)(y_j - \mu_y) = \frac{1}{N} \sum_{i,j} N_{ij} x_i y_j - \mu_x \mu_y.\end{aligned}$$

In probability, the correlation of  $X$  and  $Y$  is

$$\rho_{X,Y} = \rho_{Y,X} = \frac{\text{Cov}(X, Y)}{\sqrt{\text{Var}[X]\text{Var}[Y]}}.$$

In statistics, the correlation of  $x$  and  $y$  is

$$\rho_{x,y} = \rho_{y,x} = \frac{\text{Cov}(x, y)}{\sigma_x \sigma_y}.$$

## 1.5 Sample

**Definition 1.11.** *Sample* is a subset of the population.

**Definition 1.12.** *Random sample* is a sequence of random variables (independent or dependent)

$$Y_1 = y_1, \dots, Y_n = y_n,$$

where  $Y_i$  is the random variable and  $y_i$  is the obtained value.

**Definition 1.13.** *Sample function* is also called statistic, such sample mean (average), sample variance, etc.

**Definition 1.14.** *Sampling distribution* is the distribution of the sample function. This distribution depends on the population distribution of  $y$  and function  $f$ .