# Nonlinear Optimization

# Derek Li

# Contents

1	Review			
	1.1	One-Variable Calculus		
		1.1.1	Mean Value Theorem	
		1.1.2	First Order Taylor Approximation	
		1.1.3	Second Order MVT	
		1.1.4	Second Order Taylor Approximation	
	1.2	Multi-	variable Calculus	
		1.2.1	Gradient	
		1.2.2	Mean Value Theorem in $\mathbb{R}^n$	
		1.2.3	First Order Taylor Approximation in $\mathbb{R}^n$	
		1.2.4	Second Order MVT in $\mathbb{R}^n$	
		1.2.5	Second Order Taylor Approximation in $\mathbb{R}^n$	
		1.2.6	Geometric Meaning of Gradient	

# 1 Review

### 1.1 One-Variable Calculus

#### 1.1.1 Mean Value Theorem

Let  $g \in C^1$  on  $\mathbb{R}$ . We have

$$\frac{g(x+h) - g(x)}{h} = g'(x+\theta h),$$

for some  $\theta \in (0,1)$  and  $\frac{g(x+h)-g(x)}{h}$  is the slope of secant line between (x,g(x)) and (x+h,g(x+h)). Or we can write  $g(x+h)=g(x)+hg'(x+\theta h)$ .

### 1.1.2 First Order Taylor Approximation

Let  $g \in C^1$  on  $\mathbb{R}$ . We have

$$g(x+h) = g(x) + hg'(x) + o(h),$$

where o(h) is the error and we say a function f(h) = o(h) to mean

$$\lim_{h \to 0} \frac{f(h)}{h} = 0.$$

Proof. Want to show g(x+h) - g(x) - hg'(x) = o(h).

We have

$$\lim_{h \to 0} \frac{g(x+h) - g(x) - hg'(x)}{h} = \lim_{h \to 0} \frac{hg'(x+\theta h) - hg'(x)}{h}$$
$$= \lim_{h \to 0} g'(x+\theta h) - g'(x) = 0.$$

#### 1.1.3 Second Order MVT

Let  $g \in C^2$  on  $\mathbb{R}$ . We have

$$g(x+h) = g(x) + hg'(x) + \frac{h^2}{2}g''(x+\theta h),$$

for some  $\theta \in (0, 1)$ .

#### 1.1.4 Second Order Taylor Approximation

Let  $g \in C^2$  on  $\mathbb{R}$ . We have

$$g(x+h) = g(x) + hg'(x) + \frac{h^2}{2}g''(x) + o(h^2).$$

Proof. W.T.S. 
$$g(x+h) - g(x) - hg'(x) - \frac{h^2}{2}g''(x) = o(h^2)$$
.

We have

$$\lim_{h \to 0} \frac{g(x+h) - g(x) - hg'(x) - \frac{h^2}{2}g''(x)}{h^2} = \lim_{h \to 0} \frac{\frac{h^2}{2}g''(x+\theta h) - \frac{h^2}{2}g''(x)}{h^2}$$
$$= \lim_{h \to 0} \frac{1}{2} [g''(x+\theta h) - g''(x)] = 0.$$

# 1.2 Multi-variable Calculus

#### 1.2.1 Gradient

Gradient of  $f: \mathbb{R}^n \to \mathbb{R}$  at  $\mathbf{x} \in \mathbb{R}^n$ ,  $\nabla f(\mathbf{x})$ , if exists is a vector characterized by the property

$$\lim_{\mathbf{v}\to\mathbf{0}} \frac{f(\mathbf{x}+\mathbf{v}) - f(\mathbf{x}) - \nabla f(\mathbf{x}) \cdot \mathbf{v}}{\|\mathbf{v}\|} = 0,$$

and 
$$\nabla f(\mathbf{x}) = \left(\frac{\partial f}{\partial x_1}(\mathbf{x}), \cdots, \frac{\partial f}{\partial x_n}(\mathbf{x})\right)$$
.

#### 1.2.2 Mean Value Theorem in $\mathbb{R}^n$

Let  $f \in C^1$  on  $\mathbb{R}^n$ , then for any  $\mathbf{x}, \mathbf{v} \in \mathbb{R}^n$ , we have

$$f(\mathbf{x} + \mathbf{v}) = f(\mathbf{x}) + \nabla f(\mathbf{x} + \theta \mathbf{v}) \cdot \mathbf{v},$$

for some  $\theta \in (0,1)$ .

*Proof.* Consider  $g(t) = f(\mathbf{x} + t\mathbf{v})$ , where  $t \in \mathbb{R}$  and  $g \in C^1$  on  $\mathbb{R}$ .

By Mean Value Theorem in  $\mathbb{R}$ , we have

$$g(0+1) = g(0) + 1 \cdot g'(0+\theta \cdot 1)$$

$$= g(0) + g'(\theta)$$

$$= f(\mathbf{x}) + \nabla f(\mathbf{x} + \theta \mathbf{v}) \cdot \mathbf{v}$$

$$= g(1) = f(\mathbf{x} + \mathbf{v}),$$

for some  $\theta \in (0, 1)$ .

Note:

$$g'(t) = \frac{\mathrm{d}}{\mathrm{d}t} f(\mathbf{x} + t\mathbf{v}) = \nabla f(\mathbf{x} + t\mathbf{v}) \cdot \mathbf{v}.$$

# 1.2.3 First Order Taylor Approximation in $\mathbb{R}^n$

Let  $f \in C^1$  on  $\mathbb{R}^n$ . We have

$$f(\mathbf{x} + \mathbf{v}) = f(\mathbf{x}) + \nabla f(\mathbf{x}) \cdot \mathbf{v} + o(\|\mathbf{v}\|).$$

*Proof.* We have

$$\lim_{\|\mathbf{v}\| \to 0} \frac{f(\mathbf{x} + \mathbf{v}) - f(\mathbf{x}) - \nabla f(\mathbf{x}) \cdot \mathbf{v}}{\|\mathbf{v}\|} = \lim_{\|\mathbf{v}\| \to 0} \frac{\nabla f(\mathbf{x} + \theta \mathbf{v}) \cdot \mathbf{v} - \nabla f(\mathbf{x}) \cdot \mathbf{v}}{\|\mathbf{v}\|}$$

$$= \lim_{\|\mathbf{v}\| \to 0} \left[ \nabla f(\mathbf{x} + \theta \mathbf{v}) - \nabla f(\mathbf{v}) \right] \cdot \frac{\mathbf{v}}{\|\mathbf{v}\|} = 0.$$

#### 1.2.4 Second Order MVT in $\mathbb{R}^n$

Let  $f \in C^2$  on  $\mathbb{R}^n$ . We have

$$f(\mathbf{x} + \mathbf{v}) = f(\mathbf{x}) + \nabla f(\mathbf{x}) \cdot \mathbf{v} + \frac{1}{2} \mathbf{v}^T \nabla^2 f(\mathbf{x} + \theta \mathbf{v}) \cdot \mathbf{v},$$

for some  $\theta \in (0, 1)$ .

Note 1: Hessian matrix

$$\nabla^2 f(\mathbf{x}) = \left(\frac{\partial^2 f}{\partial x_i \partial x_j}(\mathbf{x})\right)_{1 \le i, j \le n}$$

is a symmetric matrix because of Clairaut's Theorem.

Note 2:

$$\mathbf{v}^T \nabla^2 f(\mathbf{x}) \cdot \mathbf{v} = \sum_{1 \le i, j \le n} \frac{\partial^2 f}{\partial x_i \partial x_j} (\mathbf{x}) v_i v_j.$$

#### 1.2.5 Second Order Taylor Approximation in $\mathbb{R}^n$

Let  $f \in C^2$  on  $\mathbb{R}^n$ . We have

$$f(\mathbf{x} + \mathbf{v}) = f(\mathbf{x}) + \nabla f(\mathbf{x}) \cdot \mathbf{v} + \frac{1}{2} \mathbf{v}^T \nabla^2 f(\mathbf{x}) \cdot \mathbf{v} + o(\|\mathbf{v}\|^2).$$

*Proof.* We have

$$\lim_{\|\mathbf{v}\| \to 0} \frac{f(\mathbf{x} + \mathbf{v}) - f(\mathbf{x}) - \nabla f(\mathbf{x}) \cdot \mathbf{v} - \frac{1}{2}\mathbf{v}^T \nabla^2 f(\mathbf{x}) \cdot \mathbf{v}}{\|\mathbf{v}\|^2}$$

$$= \lim_{\|\mathbf{v}\| \to 0} \frac{\frac{1}{2}\mathbf{v}^T \nabla^2 f(\mathbf{x} + \theta \mathbf{v}) \cdot \mathbf{v} - \frac{1}{2}\mathbf{v}^T \nabla^2 f(\mathbf{x}) \cdot \mathbf{v}}{\|\mathbf{v}\|^2}$$

$$= \lim_{\|\mathbf{v}\| \to 0} \frac{1}{2} \left(\frac{\mathbf{v}}{\|\mathbf{v}\|}\right)^T \cdot \left[\nabla^2 f(\mathbf{x} + \theta \mathbf{v}) - \nabla^2 f(\mathbf{x})\right] \cdot \frac{\mathbf{v}}{\|\mathbf{v}\|}$$

$$= 0.$$

#### 1.2.6 Geometric Meaning of Gradient

The instantaneous rate of change of f at  $\mathbf{x}$  in direction  $\mathbf{v}$  (suppose w.l.o.g.  $\|\mathbf{v}\| = 1$ ) is

$$\frac{\mathrm{d}}{\mathrm{d}t}\Big|_{t=0} f(\mathbf{x} + t\mathbf{v}) = \nabla f(\mathbf{x} + t\mathbf{v}) \cdot \mathbf{v}\Big|_{t=0}$$

$$= \nabla f(\mathbf{x}) \cdot \mathbf{v}$$

$$= |\nabla f(\mathbf{x})| |\mathbf{v}| \cos \theta$$

$$= |\nabla f(\mathbf{x})| \cos \theta,$$

where  $\theta$  is the angle between  $\nabla f(\mathbf{x})$  and  $\mathbf{v}$ . Obviously, the instantaneous rate maximizes when  $\theta = 0$ . Therefore, when it is not equal to zero,  $\nabla f(\mathbf{x})$  points in the direction of steepest ascent.