

# Nonlinear Optimization

Derek Li

## Contents

<b>1</b>	<b>Review</b>	<b>2</b>
1.1	One-Variable Calculus . . . . .	2
1.2	Multi-variable Calculus . . . . .	3

# 1 Review

## 1.1 One-Variable Calculus

**Theorem 1.1** (Mean Value Theorem). Let  $g \in C^1$  on  $\mathbb{R}$ . We have

$$\frac{g(x+h) - g(x)}{h} = g'(x + \theta h),$$

for some  $\theta \in (0, 1)$  and  $\frac{g(x+h)-g(x)}{h}$  is the slope of secant line between  $(x, g(x))$  and  $(x+h, g(x+h))$ . Or we can write  $g(x+h) = g(x) + hg'(x + \theta h)$ .

**Theorem 1.2** (First Order Taylor Approximation). Let  $g \in C^1$  on  $\mathbb{R}$ . We have

$$g(x+h) = g(x) + hg'(x) + o(h),$$

where  $o(h)$  is the error and we say a function  $f(h) = o(h)$  to mean

$$\lim_{h \rightarrow 0} \frac{f(h)}{h} = 0.$$

*Proof.* Want to show  $g(x+h) - g(x) - hg'(x) = o(h)$ .

We have

$$\begin{aligned} \lim_{h \rightarrow 0} \frac{g(x+h) - g(x) - hg'(x)}{h} &= \lim_{h \rightarrow 0} \frac{hg'(x + \theta h) - hg'(x)}{h} \\ &= \lim_{h \rightarrow 0} g'(x + \theta h) - g'(x) = 0. \end{aligned}$$

□

**Theorem 1.3** (Second Order Mean Value Theorem). Let  $g \in C^2$  on  $\mathbb{R}$ . We have

$$g(x+h) = g(x) + hg'(x) + \frac{h^2}{2}g''(x + \theta h),$$

for some  $\theta \in (0, 1)$ .

**Theorem 1.4** (Second Order Taylor Approximation). Let  $g \in C^2$  on  $\mathbb{R}$ . We have

$$g(x+h) = g(x) + hg'(x) + \frac{h^2}{2}g''(x) + o(h^2).$$

*Proof.* W.T.S.  $g(x+h) - g(x) - hg'(x) - \frac{h^2}{2}g''(x) = o(h^2)$ .

We have

$$\begin{aligned}\lim_{h \rightarrow 0} \frac{g(x+h) - g(x) - hg'(x) - \frac{h^2}{2}g''(x)}{h^2} &= \lim_{h \rightarrow 0} \frac{\frac{h^2}{2}g''(x+\theta h) - \frac{h^2}{2}g''(x)}{h^2} \\ &= \lim_{h \rightarrow 0} \frac{1}{2}[g''(x+\theta h) - g''(x)] = 0.\end{aligned}$$

□

## 1.2 Multi-variable Calculus

**Definition 1.1** (Gradient). Gradient of  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  at  $\mathbf{x} \in \mathbb{R}^n$ ,  $\nabla f(\mathbf{x})$ , if exists is a vector characterized by the property

$$\lim_{\mathbf{v} \rightarrow \mathbf{0}} \frac{f(\mathbf{x} + \mathbf{v}) - f(\mathbf{x}) - \nabla f(\mathbf{x}) \cdot \mathbf{v}}{\|\mathbf{v}\|} = 0,$$

and  $\nabla f(\mathbf{x}) = \left( \frac{\partial f}{\partial x_1}(\mathbf{x}), \dots, \frac{\partial f}{\partial x_n}(\mathbf{x}) \right)$ .

The instantaneous rate of change of  $f$  at  $\mathbf{x}$  in direction  $\mathbf{v}$  (suppose w.l.o.g.  $\|\mathbf{v}\| = 1$ ) is

$$\begin{aligned}\left. \frac{d}{dt} \right|_{t=0} f(\mathbf{x} + t\mathbf{v}) &= \nabla f(\mathbf{x} + t\mathbf{v}) \cdot \mathbf{v} \Big|_{t=0} \\ &= \nabla f(\mathbf{x}) \cdot \mathbf{v} \\ &= |\nabla f(\mathbf{x})| |\mathbf{v}| \cos \theta \\ &= |\nabla f(\mathbf{x})| \cos \theta,\end{aligned}$$

where  $\theta$  is the angle between  $\nabla f(\mathbf{x})$  and  $\mathbf{v}$ . Obviously, the instantaneous rate maximizes when  $\theta = 0$ . Therefore, when it is not equal to zero,  $\nabla f(\mathbf{x})$  points in the direction of steepest ascent.

**Theorem 1.5** (Mean Value Theorem in  $\mathbb{R}^n$ ). Let  $f \in C^1$  on  $\mathbb{R}^n$ , then for any  $\mathbf{x}, \mathbf{v} \in \mathbb{R}^n$ , we have

$$f(\mathbf{x} + \mathbf{v}) = f(\mathbf{x}) + \nabla f(\mathbf{x} + \theta \mathbf{v}) \cdot \mathbf{v},$$

for some  $\theta \in (0, 1)$ .

*Proof.* Consider  $g(t) = f(\mathbf{x} + t\mathbf{v})$ , where  $t \in \mathbb{R}$  and  $g \in C^1$  on  $\mathbb{R}$ .

By Mean Value Theorem in  $\mathbb{R}$ , we have

$$\begin{aligned} g(0 + 1) &= g(0) + 1 \cdot g'(0 + \theta \cdot 1) \\ &= g(0) + g'(\theta) \\ &= f(\mathbf{x}) + \nabla f(\mathbf{x} + \theta\mathbf{v}) \cdot \mathbf{v} \\ &= g(1) = f(\mathbf{x} + \mathbf{v}), \end{aligned}$$

for some  $\theta \in (0, 1)$ . □

*Note.*

$$g'(t) = \frac{d}{dt}f(\mathbf{x} + t\mathbf{v}) = \nabla f(\mathbf{x} + t\mathbf{v}) \cdot \mathbf{v}.$$

**Theorem 1.6** (First Order Taylor Approximation in  $\mathbb{R}^n$ ). Let  $f \in C^1$  on  $\mathbb{R}^n$ . We have

$$f(\mathbf{x} + \mathbf{v}) = f(\mathbf{x}) + \nabla f(\mathbf{x}) \cdot \mathbf{v} + o(\|\mathbf{v}\|).$$

*Proof.* We have

$$\begin{aligned} \lim_{\|\mathbf{v}\| \rightarrow 0} \frac{f(\mathbf{x} + \mathbf{v}) - f(\mathbf{x}) - \nabla f(\mathbf{x}) \cdot \mathbf{v}}{\|\mathbf{v}\|} &= \lim_{\|\mathbf{v}\| \rightarrow 0} \frac{\nabla f(\mathbf{x} + \theta\mathbf{v}) \cdot \mathbf{v} - \nabla f(\mathbf{x}) \cdot \mathbf{v}}{\|\mathbf{v}\|} \\ &= \lim_{\|\mathbf{v}\| \rightarrow 0} [\nabla f(\mathbf{x} + \theta\mathbf{v}) - \nabla f(\mathbf{x})] \cdot \frac{\mathbf{v}}{\|\mathbf{v}\|} = 0. \end{aligned}$$

□

**Theorem 1.7** (Second Order Mean Value Theorem in  $\mathbb{R}^n$ ). Let  $f \in C^2$  on  $\mathbb{R}^n$ . We have

$$f(\mathbf{x} + \mathbf{v}) = f(\mathbf{x}) + \nabla f(\mathbf{x}) \cdot \mathbf{v} + \frac{1}{2} \mathbf{v}^T \nabla^2 f(\mathbf{x} + \theta\mathbf{v}) \cdot \mathbf{v},$$

for some  $\theta \in (0, 1)$ .

*Note 1.* Hessian matrix

$$\nabla^2 f(\mathbf{x}) = \left( \frac{\partial^2 f}{\partial x_i \partial x_j}(\mathbf{x}) \right)_{1 \leq i, j \leq n}$$

is a symmetric matrix because of Clairaut's Theorem.

*Note 2.*

$$\mathbf{v}^T \nabla^2 f(\mathbf{x}) \cdot \mathbf{v} = \sum_{1 \leq i, j \leq n} \frac{\partial^2 f}{\partial x_i \partial x_j}(\mathbf{x}) v_i v_j.$$

**Theorem 1.8** (Second Order Taylor Approximation in  $\mathbb{R}^n$ ). Let  $f \in C^2$  on  $\mathbb{R}^n$ . We have

$$f(\mathbf{x} + \mathbf{v}) = f(\mathbf{x}) + \nabla f(\mathbf{x}) \cdot \mathbf{v} + \frac{1}{2} \mathbf{v}^T \nabla^2 f(\mathbf{x}) \cdot \mathbf{v} + o(\|\mathbf{v}\|^2).$$

*Proof.* We have

$$\begin{aligned} & \lim_{\|\mathbf{v}\| \rightarrow 0} \frac{f(\mathbf{x} + \mathbf{v}) - f(\mathbf{x}) - \nabla f(\mathbf{x}) \cdot \mathbf{v} - \frac{1}{2} \mathbf{v}^T \nabla^2 f(\mathbf{x}) \cdot \mathbf{v}}{\|\mathbf{v}\|^2} \\ &= \lim_{\|\mathbf{v}\| \rightarrow 0} \frac{\frac{1}{2} \mathbf{v}^T \nabla^2 f(\mathbf{x} + \theta \mathbf{v}) \cdot \mathbf{v} - \frac{1}{2} \mathbf{v}^T \nabla^2 f(\mathbf{x}) \cdot \mathbf{v}}{\|\mathbf{v}\|^2} \\ &= \lim_{\|\mathbf{v}\| \rightarrow 0} \frac{1}{2} \left( \frac{\mathbf{v}}{\|\mathbf{v}\|} \right)^T \cdot [\nabla^2 f(\mathbf{x} + \theta \mathbf{v}) - \nabla^2 f(\mathbf{x})] \cdot \frac{\mathbf{v}}{\|\mathbf{v}\|} \\ &= 0. \end{aligned}$$

□

**Theorem 1.9** (Implicit Function Theorem). Let  $f : \mathbb{R}^{n+1} \rightarrow \mathbb{R}$  be a  $C^1$  function. Fix  $(\mathbf{a}, b) \in \mathbb{R}^n \times \mathbb{R}$  s.t.  $f(\mathbf{a}, b) = 0$  and  $\nabla f(\mathbf{a}, b) \neq 0$ . We have  $\{(\mathbf{x}, y) \in \mathbb{R}^n \times \mathbb{R} | f(\mathbf{x}, y) = 0\}$  is locally the graph of a function.

**Definition 1.2** (Level Set).  $\{\mathbf{x} \in \mathbb{R}^n | f(\mathbf{x}) = c\}$  is called  $c$ -level set of  $f$ .

**Theorem 1.10.** Gradient  $\nabla f(\mathbf{x}_0) \perp$  level curve through  $\mathbf{x}_0$ .

**Definition 1.3** (Convex Set).  $\Omega \subseteq \mathbb{R}^n$  is a convex set if for all  $\mathbf{x}_1, \mathbf{x}_2 \in \Omega$ , we have line segment between  $\mathbf{x}_1, \mathbf{x}_2 : s\mathbf{x}_1 + (1-s)\mathbf{x}_2 \in \Omega, s \in [0, 1]$ .

**Definition 1.4** (Convex Function). A function  $f : \Omega \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$  is convex if

$$f(s\mathbf{x}_1 + (1-s)\mathbf{x}_2) \leq sf(\mathbf{x}_1) + (1-s)f(\mathbf{x}_2),$$

for all  $\mathbf{x}_1, \mathbf{x}_2 \in \Omega$  and all  $s \in [0, 1]$ , where  $\Omega$  is a convex set.

**Definition 1.5** (Concave Function). A function  $f$  concave if  $-f$  is convex.

*Note.* The linear function is both convex and concave.