Part III

Deep Learning Research

In the previous parts of the book, we have shown how to solve supervised learning problems—how to learn to map one vector to another, given enough examples of the mapping.

Not all problems we might want to solve fall into this category. We may wish to generate new examples, or determine how likely some point is, or handle missing values and take advantage of a large set of unlabeled examples or examples from related tasks. A shortcoming of the current state of the art for industrial applications is that our learning algorithms require large amounts of supervised data to achieve good accuracy. In this part of the book, we discuss some of the speculative approaches to reducing the amount of labeled data necessary for existing models to work well and be applicable across a broader range of tasks. Accomplishing these goals usually requires some form of unsupervised or semi-supervised learning.

Many deep learning algorithms have been designed to tackle unsupervised learning problems, but none have truly solved the problem in the same way that deep learning has largely solved the supervised learning problem for a wide variety of tasks. In this part of the book, we describe the existing approaches to unsupervised learning and some of the popular thought about how we can make progress in this field.

A central cause of the difficulties with unsupervised learning is the high dimensionality of the random variables being modeled. This brings two distinct challenges: a statistical challenge and a computational challenge. The statistical challenge regards generalization: the number of configurations we may want to distinguish can grow exponentially with the number of dimensions of interest, and this quickly becomes much larger than the number of examples one can possibly have (or use with bounded computational resources). The computational challenge associated with high-dimensional distributions arises because many algorithms for learning or using a trained model (especially those based on estimating an explicit probability function) involve intractable computations that grow exponentially with the number of dimensions.

With probabilistic models, this computational challenge arises from the need to perform intractable inference or simply from the need to normalize the distribution.

• Intractable inference: inference is discussed mostly in chapter 19. It regards the question of guessing the probable values of some variables given other variables b, with respect to a model that captures the joint distribution over

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- a, b and c. In order to even compute such conditional probabilities one needs to sum over the values of the variablesc, as well as compute a normalization constant which sums over the values of a and c.
- Intractable normalization constants (the partition function): the partition function is discussed mostly in chapter 18. Normalizing constants of probability functions come up in inference (above) as well as in learning. Many probabilistic models involve such a normalizing constant. Unfortunately, learning such a model often requires computing the gradient of the loga-

rithm of the partition function with respect to the model parameters. That computation is generally as intractable as computing the partition function itself. Monte Carlo Markov chain (MCMC) methods (chapter 17) are often used to deal with the partition function (computing it or its gradient). Unfortunately, MCMC methods suffer when the modes of the model distribution are numerous and well-separated, especially in high-dimensional spaces (section 17.5).

One way to confront these intractable computations is to approximate them, and many approaches have been proposed as discussed in this third part of the book. Another interesting way, also discussed here, would be to avoid these intractable computations altogether by design, and methods that do not require such computations are thus very appealing. Several generative models have been proposed in recent years, with that motivation. A wide variety of contemporary approaches to generative modeling are discussed in chapter 20.

Part III is the most important for a researcher—someone who wants to understand the breadth of perspectives that have been brought to the field of deep learning, and push the field forward towards true artificial intelligence.