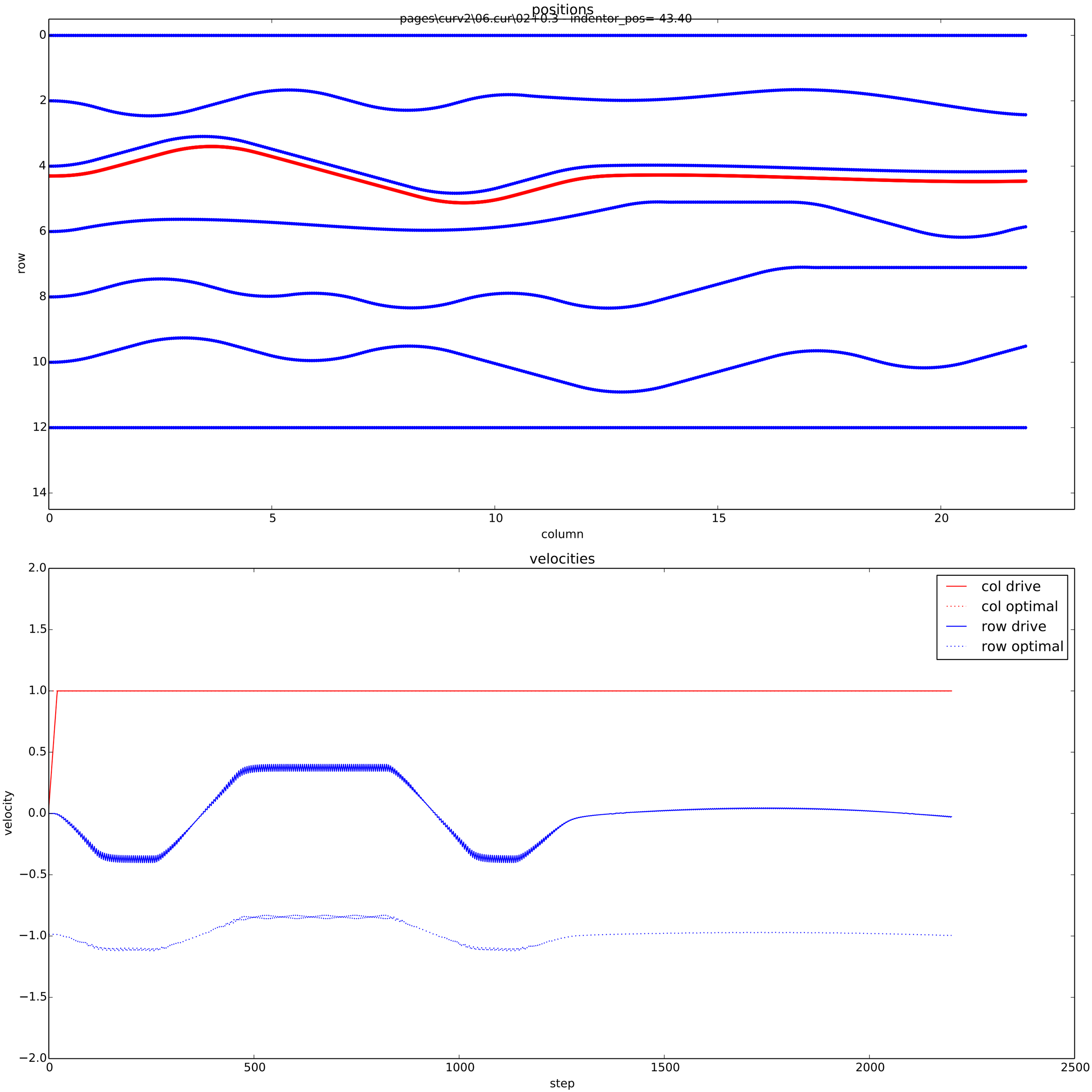
positions
pages\curv2\06.cur\02+0.3 indentor_pos= 43.40
row
column
0
2
4
6
8
10
12
14
0
5
10
15
20
velocities
velocity
step
2.0
1.5
1.0
0.5
0.0
−0.5
−1.0
−1.5
−2.0
0
500
1000
1500
2000
2500
col drive
col optimal
row drive
row optimal