

# Supervised Contrastive learning

# reference

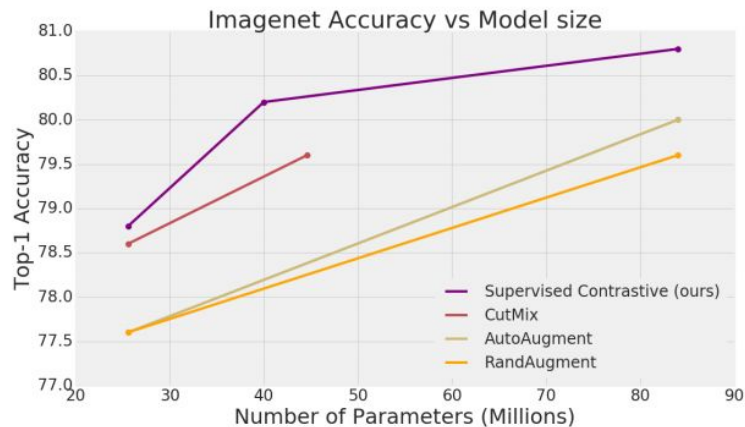
<https://amitness.com/2020/03/illustrated-simclr/>

<https://app.wandb.ai/authors/scl/reports/Improving-Image-Classifiers-with-Supervised-Contrastive-Learning--VmIldzoxMzQwNzE>

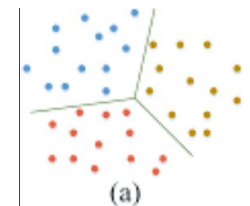
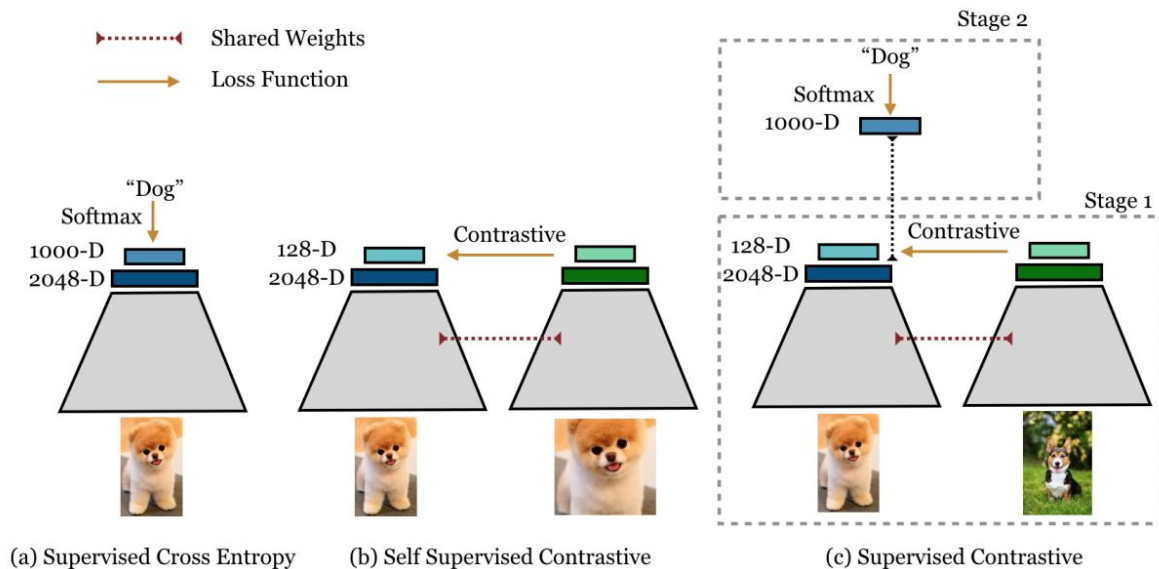
<https://www.youtube.com/watch?v=MpdbFLXOOIw>

# Supervised Contrastive learning

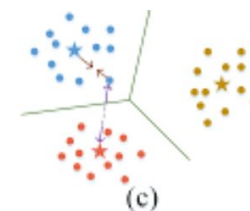
1. cross entropy 단점
  - lack of robustness to noisy labels
  - possibility of poor margin -> reduced generalization
2. proposed
  - label smoothing
  - self-distillation
  - Mixup and related data augmentation strategies
3. propose new loss for supervised training(contrastive loss)



# difference with self supervised contrastive learning

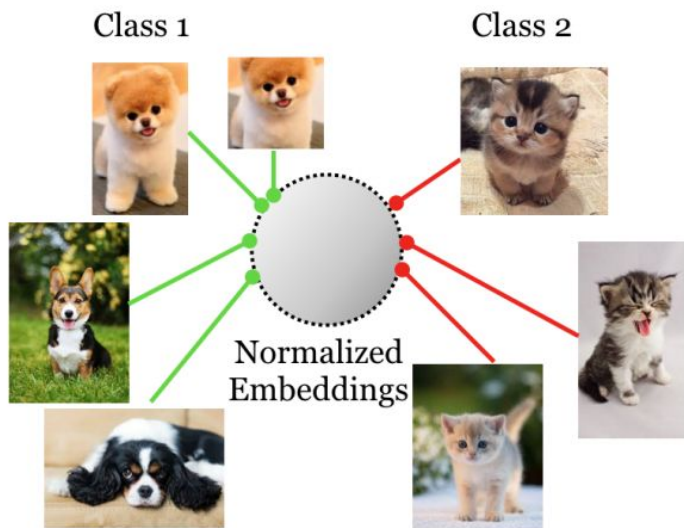


cross entropy

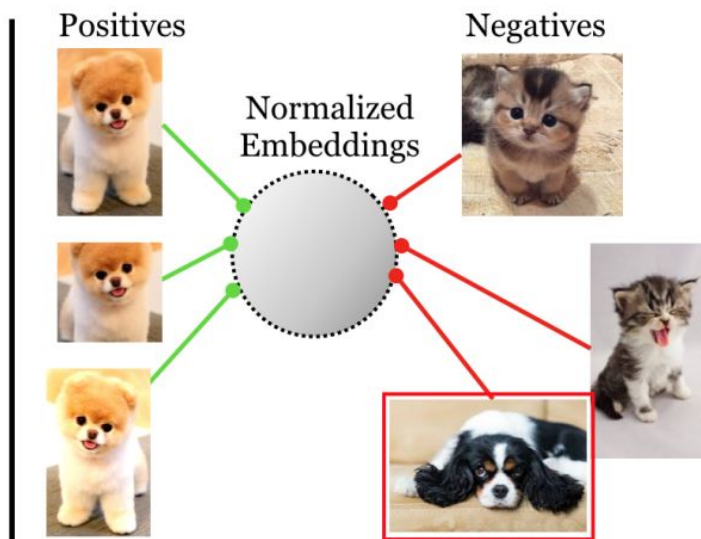


contrastive loss

# difference with self supervised contrastive learning



Supervised Contrastive



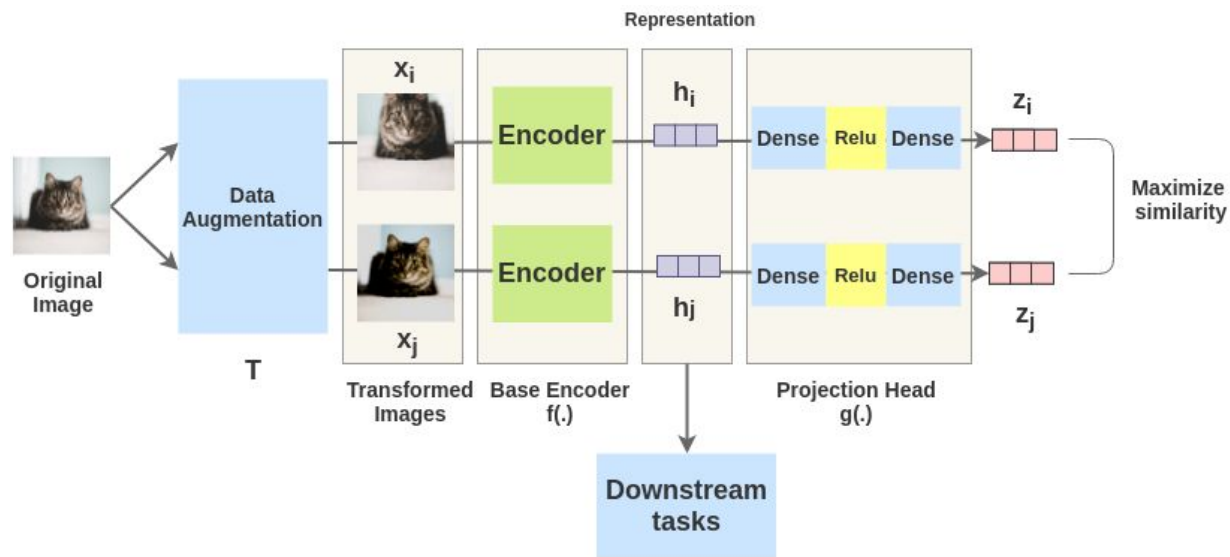
Self Supervised Contrastive

# contrastive learning framework

A data augmentation module

An encoder network

A projection network



# data augmentation module

generate two randomly augmented images

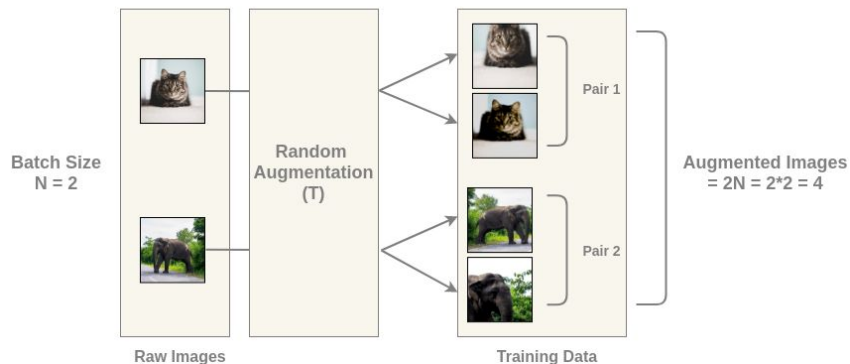
- a random crop to the image and then resizing
- 3 different options

AutoAugment

RandAugment

SimAugment (A simple framework for contrastive learning of visual representations),  
apply random color distortion and Gaussian blurring

Preparing similar pairs in a batch

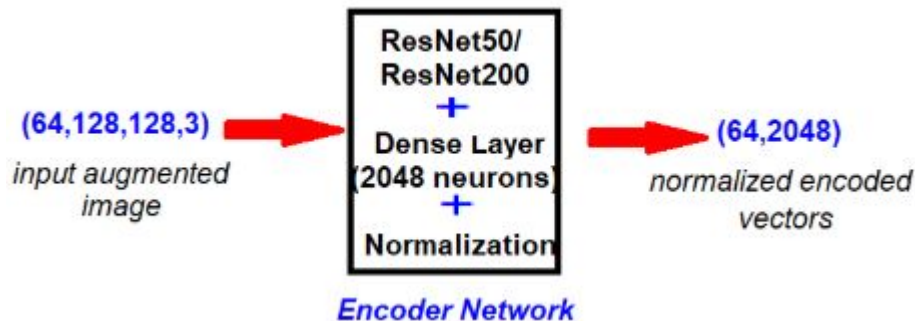


# encoder network

maps an augmented image  $\tilde{x}$  to a representation vector,  $r$

ResNet-50 and ResNet-200, dim = 2048

normalized to the unit hypersphere





# projection network

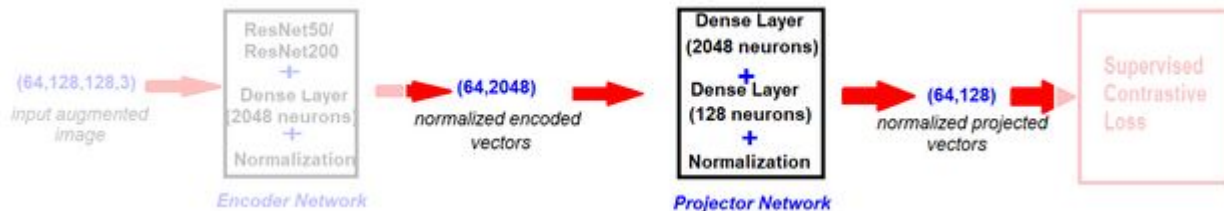
which maps the normalized representation vector  $r$  into a vector  $z$  (dim = 128)

multi-layer perceptron with hidden layer of size 2048

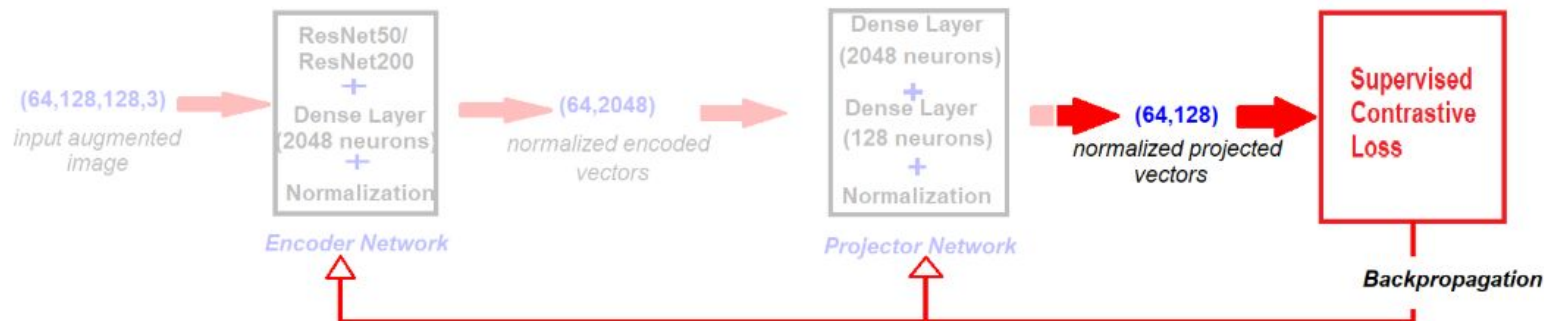
normalize this vector to lie on the unit hypersphere

(inner product to measure distances in the projection space)

The projection network is only used for training the supervised contrastive loss



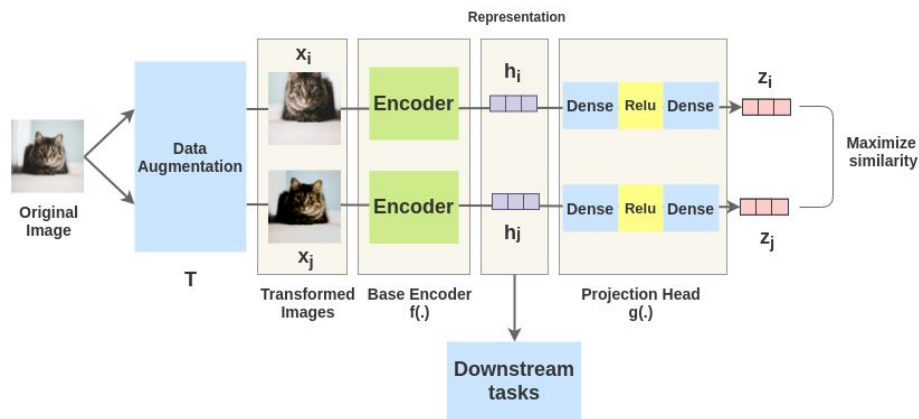
# Supervised Contrastive Loss



$$\mathcal{L}^{sup} = \sum_{i=1}^{2N} \mathcal{L}_i^{sup}$$

$$\mathcal{L}_i^{sup} = \frac{-1}{2N_{\tilde{\mathbf{y}}_i} - 1} \sum_{j=1}^{2N} \mathbb{1}_{i \neq j} \cdot \mathbb{1}_{\tilde{\mathbf{y}}_i = \tilde{\mathbf{y}}_j} \cdot \log \frac{\exp(\mathbf{z}_i \cdot \mathbf{z}_j / \tau)}{\sum_{k=1}^{2N} \mathbb{1}_{i \neq k} \cdot \exp(\mathbf{z}_i \cdot \mathbf{z}_k / \tau)}$$

# vs Supervised Contrastive Loss



$$\mathcal{L}^{self} = \sum_{i=1}^{2N} \mathcal{L}_i^{self}$$

$$\mathcal{L}_i^{self} = -\log \frac{\exp(z_i \cdot z_{j(i)}/\tau)}{\sum_{k=1}^{2N} \mathbb{1}_{i \neq k} \cdot \exp(z_i \cdot z_k/\tau)}$$

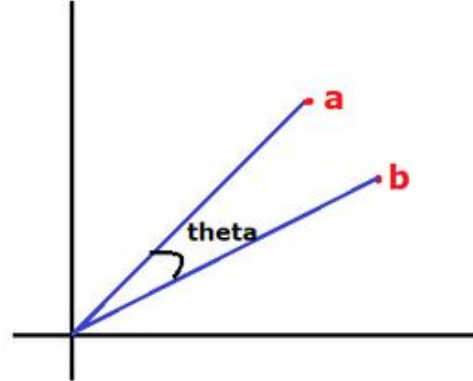
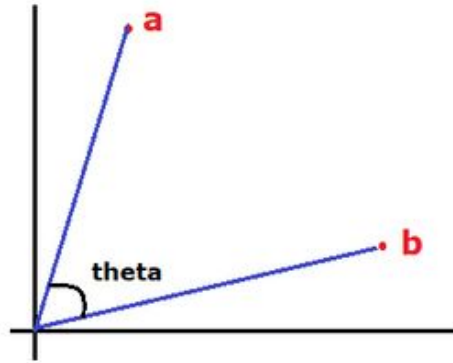
$$\mathcal{L}^{sup} = \sum_{i=1}^{2N} \mathcal{L}_i^{sup}$$

$$\mathcal{L}_i^{sup} = \frac{-1}{2N_{\tilde{y}_i} - 1} \sum_{j=1}^{2N} \mathbb{1}_{i \neq j} \cdot \mathbb{1}_{\tilde{y}_i = \tilde{y}_j} \cdot \log \frac{\exp(z_i \cdot z_j/\tau)}{\sum_{k=1}^{2N} \mathbb{1}_{i \neq k} \cdot \exp(z_i \cdot z_k/\tau)}$$

# similarity

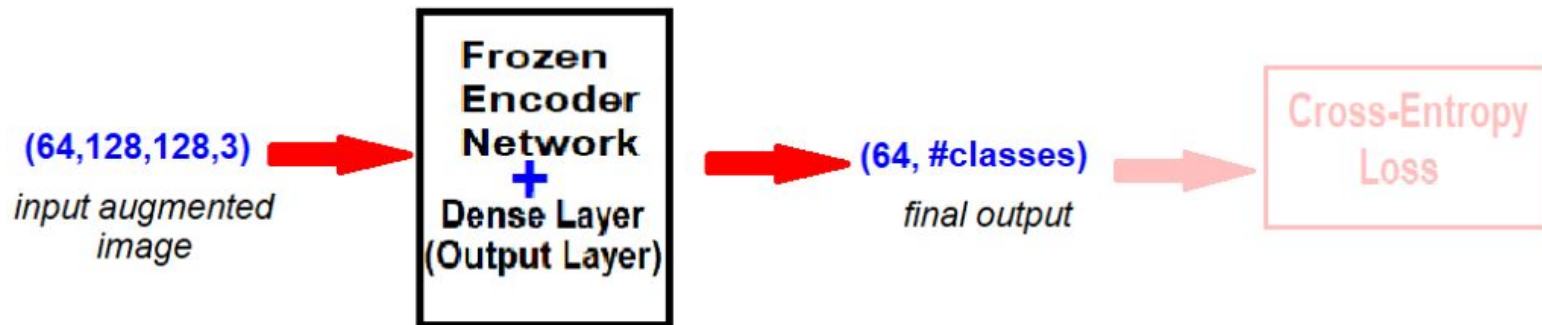
dot product between normalized vector, z

$$\bar{a} \bullet \bar{b} = |\bar{a}| |\bar{b}| \cos \theta$$



# Downstream Task

Not projection but representation



# Supervised Contrastive Loss Gradient Properties

$$\mathcal{L}^{sup} = \sum_{i=1}^{2N} \mathcal{L}_i^{sup}$$

$$\mathcal{L}_i^{sup} = \frac{-1}{2N\tilde{\mathbf{y}}_i - 1} \sum_{j=1}^{2N} \mathbb{1}_{i \neq j} \cdot \mathbb{1}_{\tilde{\mathbf{y}}_i = \tilde{\mathbf{y}}_j} \cdot \log \frac{\exp(\mathbf{z}_i \cdot \mathbf{z}_j / \tau)}{\sum_{k=1}^{2N} \mathbb{1}_{i \neq k} \cdot \exp(\mathbf{z}_i \cdot \mathbf{z}_k / \tau)}$$

$$\frac{\partial \mathcal{L}_i^{sup}}{\partial \mathbf{w}_i} = \left. \frac{\partial \mathcal{L}_i^{sup}}{\partial \mathbf{w}_i} \right|_{\text{pos}} + \left. \frac{\partial \mathcal{L}_i^{sup}}{\partial \mathbf{w}_i} \right|_{\text{neg}}$$

$$\left. \frac{\partial \mathcal{L}_i^{sup}}{\partial \mathbf{w}_i} \right|_{\text{pos}} \propto \sum_{j=1}^{2N} \mathbb{1}_{i \neq j} \cdot \mathbb{1}_{\tilde{\mathbf{y}}_i = \tilde{\mathbf{y}}_j} \cdot ((\mathbf{z}_i \cdot \mathbf{z}_j) \cdot \mathbf{z}_i - \mathbf{z}_j) \cdot (1 - P_{ij})$$

$$\left. \frac{\partial \mathcal{L}_i^{sup}}{\partial \mathbf{w}_i} \right|_{\text{neg}} \propto \sum_{j=1}^{2N} \mathbb{1}_{i \neq j} \cdot \mathbb{1}_{\tilde{\mathbf{y}}_i = \tilde{\mathbf{y}}_j} \cdot \sum_{k=1}^{2N} \mathbb{1}_{k \notin \{i, j\}} \cdot (\mathbf{z}_k - (\mathbf{z}_i \cdot \mathbf{z}_k) \cdot \mathbf{z}_i) \cdot P_{ik}$$

# Supervised Contrastive Loss Gradient Properties

the supervised contrastive loss to focus more on hard positives and negative

$$\|((\mathbf{z}_i \cdot \mathbf{z}_j) \cdot \mathbf{z}_i - \mathbf{z}_j)\| \cdot (1 - P_{ij}) = \sqrt{1 - (\mathbf{z}_i \cdot \mathbf{z}_j)^2} \cdot (1 - P_{ij}) \approx 0$$

$$\|((\mathbf{z}_i \cdot \mathbf{z}_j) \cdot \mathbf{z}_i - \mathbf{z}_j)\| \cdot (1 - P_{ij}) = \sqrt{1 - (\mathbf{z}_i \cdot \mathbf{z}_j)^2} \cdot (1 - P_{ij}) > 0$$

where

$$P_{i\ell} = \frac{\exp(\mathbf{z}_i \cdot \mathbf{z}_\ell / \tau)}{\sum_{k=1}^{2N} \mathbb{1}_{i \neq k} \cdot \exp(\mathbf{z}_k \cdot \mathbf{z}_\ell / \tau)} \quad , \quad i, \ell \in \{1 \dots 2N\} \quad , \quad i \neq \ell$$

# Connections to Triplet Loss

Contrastive learning is closely related to the triplet loss

$$\begin{aligned}\mathcal{L}_{con} &= -\log \frac{\exp(z_a \cdot z_p / \tau)}{\exp(z_a \cdot z_p / \tau) + \exp(z_a \cdot z_n / \tau)} \\ &= \log(1 + \exp((z_a \cdot z_n - z_a \cdot z_p) / \tau)) \\ &\approx \exp((z_a \cdot z_n - z_a \cdot z_p) / \tau) \quad (\text{Taylor expansion of log}) \\ &\approx 1 + \frac{1}{\tau} \cdot (z_a \cdot z_n - z_a \cdot z_p) \\ &= 1 - \frac{1}{2\tau} \cdot (\|z_a - z_n\|^2 - \|z_a - z_p\|^2) \\ &\propto \|z_a - z_p\|^2 - \|z_a - z_n\|^2 + 2\tau\end{aligned}$$

$$d(X, Y)^2 = \langle X - Y, X - Y \rangle = \langle X, X \rangle + \langle Y, Y \rangle - 2\langle X, Y \rangle = 2(1 - \langle X, Y \rangle)$$



# Training detail

700 epochs during the pretraining stage. (350 epochs only dropped the top-1 accuracy by a small amount)

training step is about 50% slower than cross-entropy

batch sizes of up to 8192

a temperature of  $\tau = 0.07$

# ImageNet Classification Accuracy

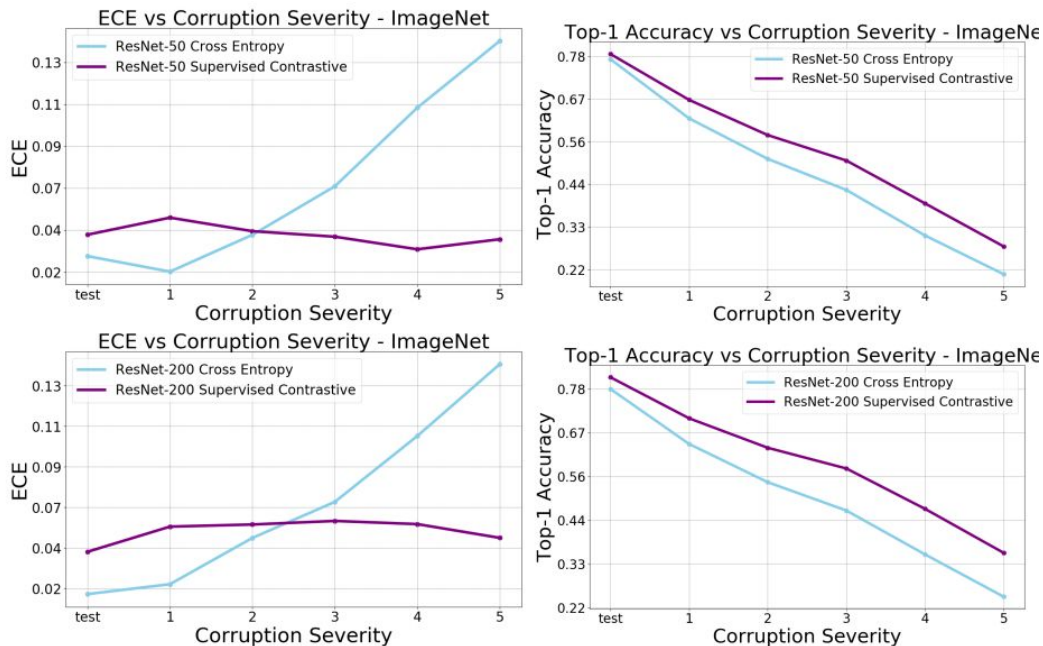
Loss	Architecture	Top-1	Top-5
Cross Entropy (baselines)	AlexNet [27]	56.5	84.6
	VGG-19+BN [42]	74.5	92.0
	ResNet-18 [20]	72.1	90.6
	MixUp ResNet-50 [56]	77.4	93.6
	CutMix ResNet-50 [55]	78.6	94.1
	Fast AA ResNet-50 [9]	77.6	95.3
	Fast AA ResNet-200 [9]	80.6	95.3
Cross Entropy (our implementation)	ResNet-50	77.0	92.9
	ResNet-200	78.0	93.3
Supervised Contrastive	ResNet-50	<b>78.8</b>	<b>93.9</b>
	ResNet-200	<b>80.8</b>	<b>95.6</b>

# Robustness to Image Corruptions and Calibration

Training with Supervised Contrastive Loss makes models more robust to corruptions in images

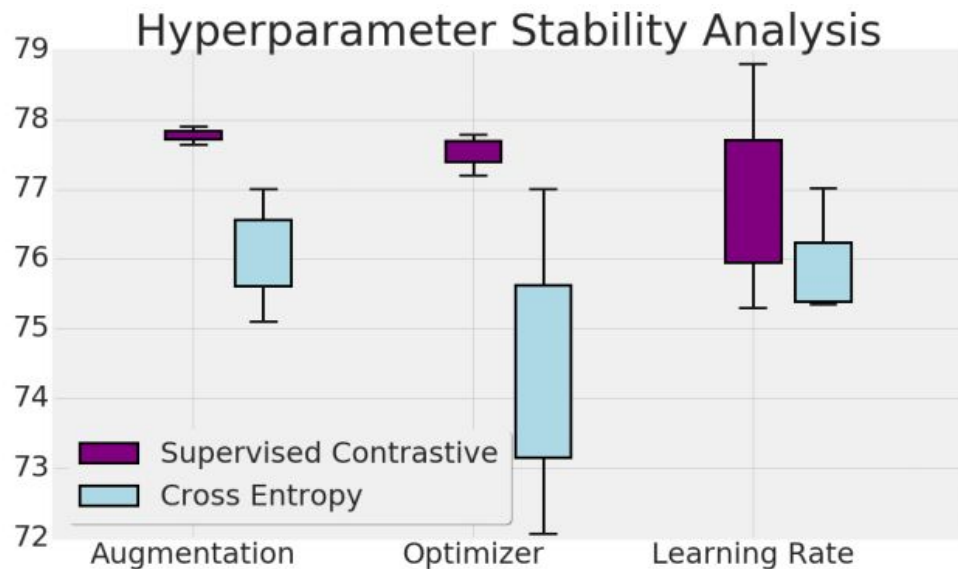
Loss	Architecture	rel. mCE	mCE
Cross Entropy (baselines)	AlexNet [27]	100.0	100.0
	VGG-19+BN [42]	122.9	81.6
	ResNet-18 [20]	103.9	84.7
Cross Entropy (our implementation)	ResNet-50	103.7	68.4
	ResNet-200	96.6	69.4
Supervised Contrastive	ResNet-50	<b>87.5</b>	<b>64.4</b>
	ResNet-200	<b>77.1</b>	<b>57.2</b>

# Robustness to Image Corruptions and Calibration



# Hyperparameter Stability

maybe due to the smoother geometry of the hypersphere compared to labels which are the endpoints of the n-dimensional simplex (as cross-entropy requires)

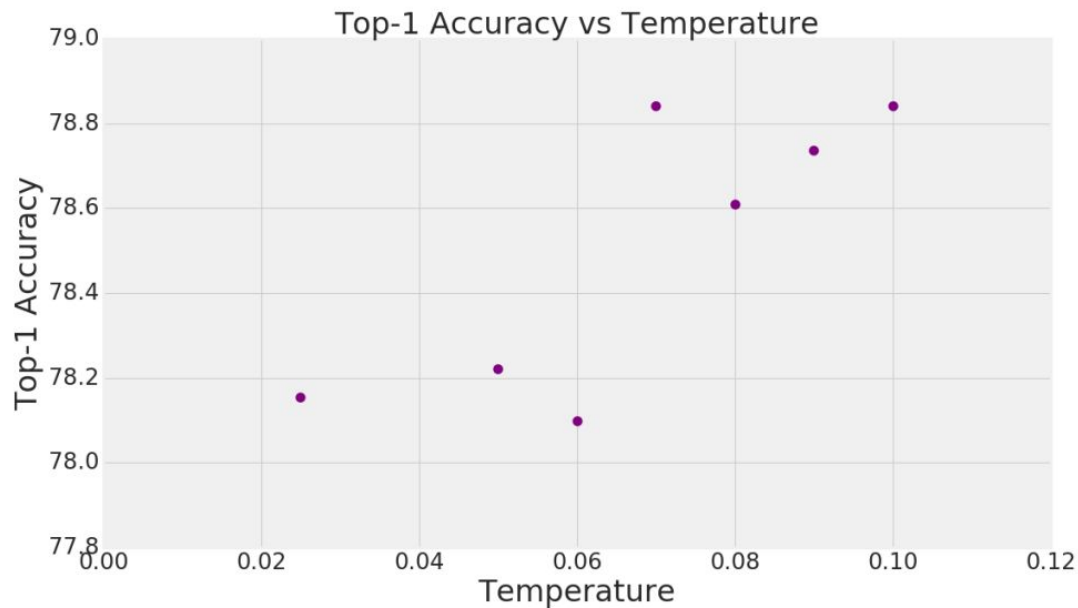


# Effect of Number of Positives

Number of positives	1 [6]	2	3	5
Top-1 Accuracy	69.3	78.1	78.2	78.8

# Effect of Temperature in Loss Function

temperature is important



# Introduction - Meta Learning

## Learning to Learn

적은 수의 **sample**만으로 학습할 수 있을까?

크게 3가지 방식으로 분류

- **metric** 기반의 **representation**을 학습하는 방식
- **model**기반의 **external/internal memory**를 통한 **recurrent network**를 학습하는 방식
- **optimization** 기반의 **fast learning**을 위한 **model**의 **hyperparameter**를 최적화하는 방식



# few shot learning/Meta learning

Not class but example specific -> overfit -> much data

Is it possible to learn with few data like person



# few shot learning/Meta learning

## Multi task learning

배경(잔디)가 개의 특징이 아님을 확인 가능

매번 다른 **task**를 학습함으로 인해 **specific feature**들에 대한 학습은 서로 상쇄되고 **class**에 대한 **general feature**들이 학습이 되게 된다.

