

BR41N.10

THE BRAIN-COMPUTER INTERFACE
DESIGNERS HACKATHON



ECoG Hand Pose Data Analysis

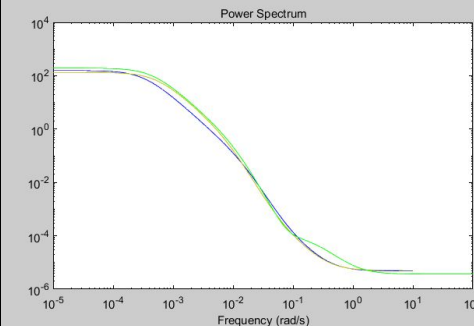
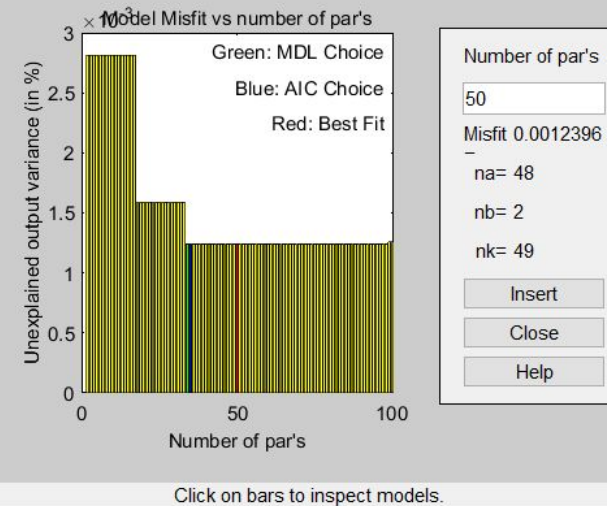
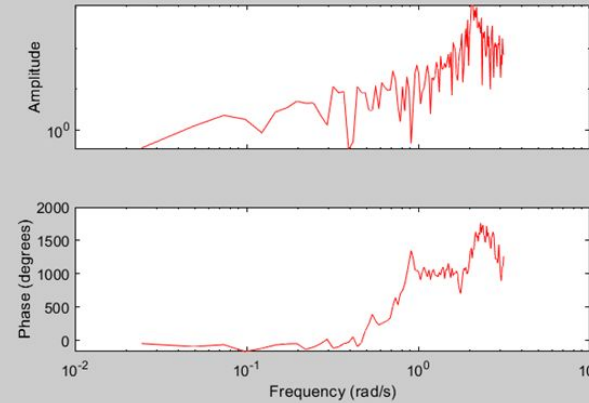
Amardeep, Bruno, Deepa, Lucas, Salina

What We Did

- Preprocessing
 - Detrending
 - Notch Filter 50Hz and Harmonics
 - High-Gama filtering (70-140 Hz Bandpass)
 - Separation on Class Epochs (from -0.2s~2s)
 - Downsampling (200Hz)
 - Hilbert Enveloping
- Various Classifications Methodologies!

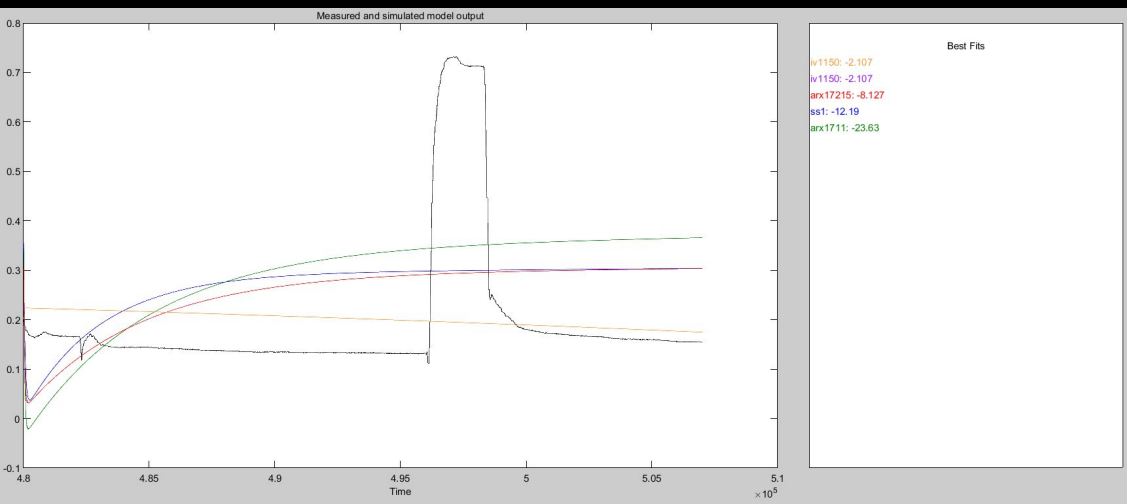
What We Did

- ARMAX, ARMA, FIR, Box Jenkins and SSM
- Time series modelling and forecasting experiments using system identification toolbox.
- Polynomial model tests and validation using error analysis and noise reduction.



TIME SERIES MODELLING- MATLAB

- Data for hand pose is cleaned and modelled against state space models and polynomial models.
- ARMAX, ARX, FIR and Box Jenkins algorithms were applied on the dataset after removing means and trends.
- System identification toolbox allows for addition of order selection and parameter experiments.



Status: Estimated using N4SID with prediction focus

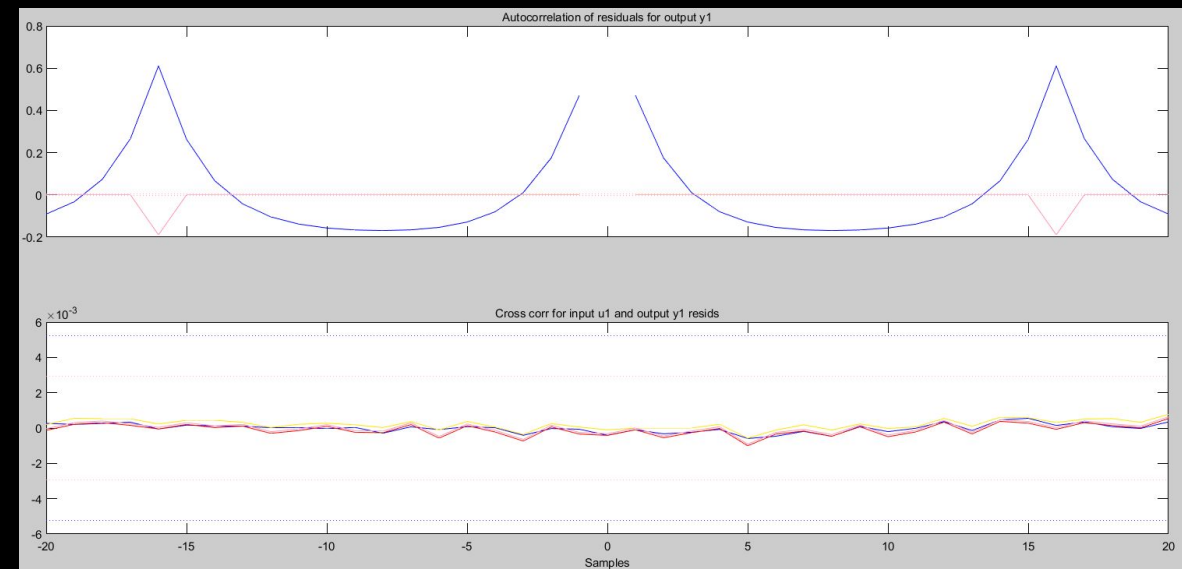
Fit to estimation data: **100%**, FPE: 2.24356e-21

Termination condition: Maximum number of iterations reached.

Number of iterations: 20, Number of function evaluations: 96

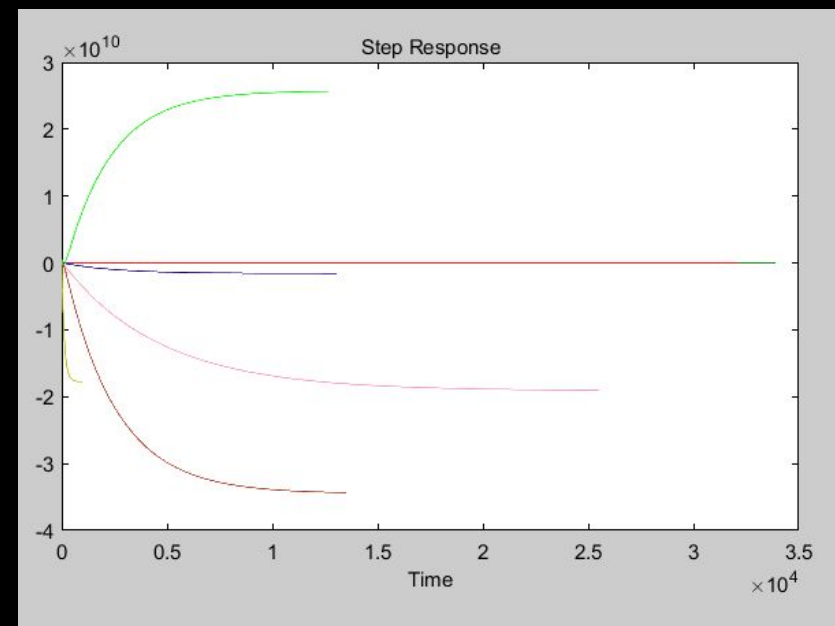
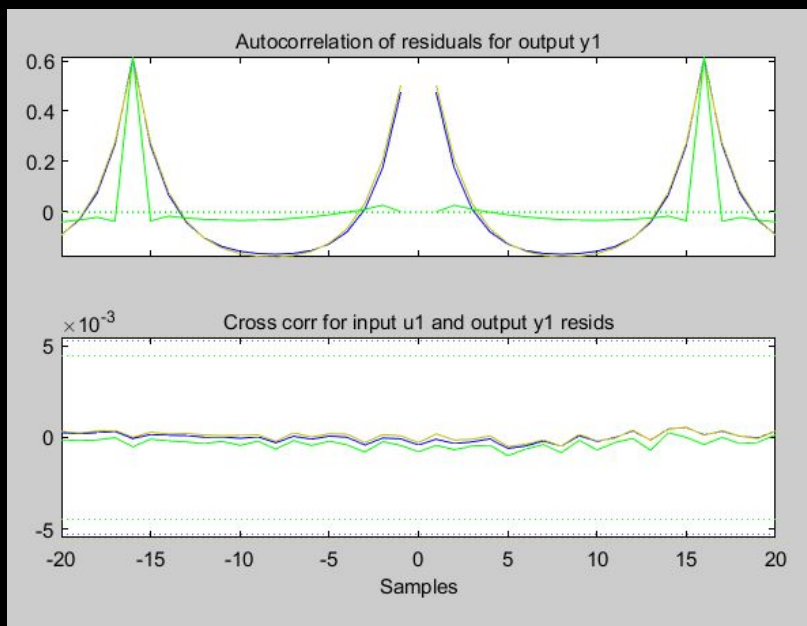
Status: Estimated using PEM with prediction focus

Fit to estimation data: **99.19%**, FPE: 2.96609e-06



Status: Estimated using N4SID with prediction focus

Fit to estimation data: **98.83%**, FPE: 6.56351e-06



Discrete-time ARX model: $A(z)y(t) = B(z)u(t) + e(t)$

$$A(z) = 1 - z^{-1} - 2.68e-08 z^{-2} - 2.037e-08 z^{-3} + 4.979e-08 z^{-4} - 3.265e-08 z^{-5} \\ - 1.266e-08 z^{-6} + 2.085e-08 z^{-7} - 2.936e-08 z^{-8} + 4.379e-08 z^{-9} - 3.041e-08 z^{-10} \\ + 9.161e-09 z^{-11} - 6.709e-09 z^{-12} + 5.334e-09 z^{-13} - 7.097e-09 z^{-14} \\ + 1.079e-09 z^{-15} - 0.6541 z^{-16} + 0.6541 z^{-17}$$

Continuous-time identified state-space model:

$$\frac{dx}{dt} = A x(t) + B u(t) + K e(t)$$

$$y(t) = C x(t) + D u(t) + e(t)$$

A =

	x1	x2
x1	-1.526e-05	-0.002405

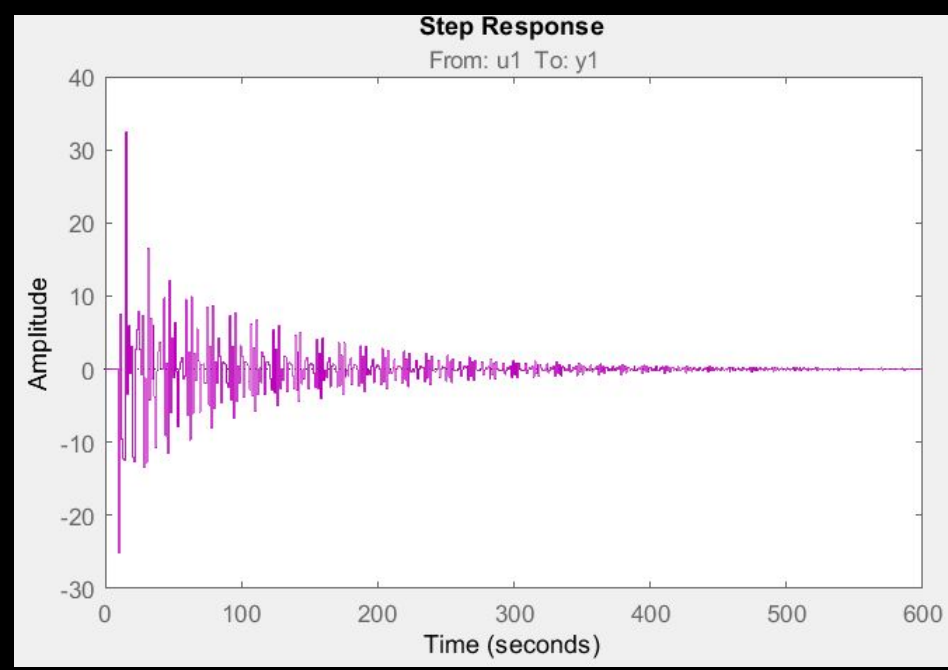


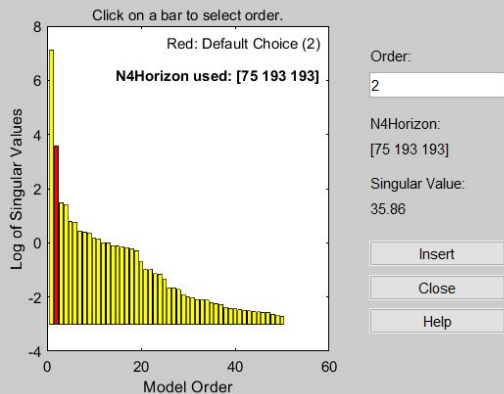
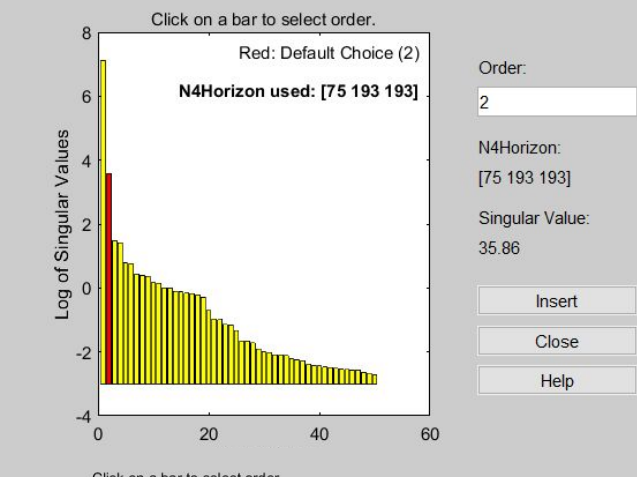
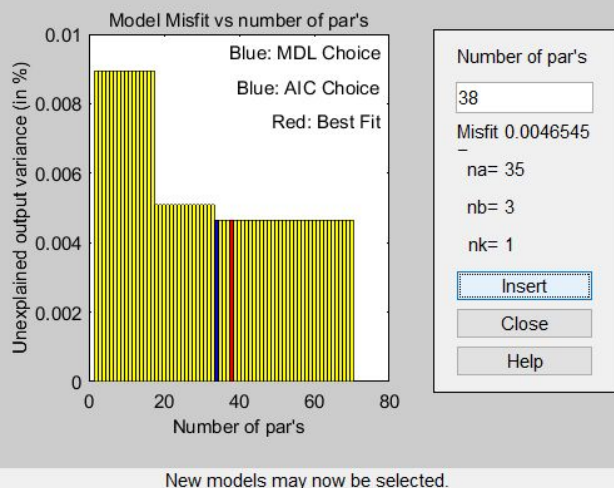
Discrete-time ARIMAX model: $A(z)y(t) = B(z)u(t) + [C(z)/(1-z^{-1})]e(t)$

$$A(z) = 1 + 2.079 z^{-1} + 2.415 z^{-2} + 2.679 z^{-3} + 2.371 z^{-4} + 2.066 z^{-5} + 2.395 z^{-6} \\ + 2.19 z^{-7} + 1.526 z^{-8} + 0.7685 z^{-9} + 0.08559 z^{-10}$$

$$B(z) = -25.16 z^{-10} - 19.58 z^{-11} - 9.849 z^{-12} - 26.77 z^{-13} - 19.3 z^{-14} + 17.53 z^{-15} \\ + 16.46 z^{-16} + 24.31 z^{-17} + 32.99 z^{-18} + 9.372 z^{-19}$$

$$C(z) = 1 + 2.169 z^{-1} + 2.587 z^{-2} + 2.927 z^{-3} + 2.595 z^{-4} + 2.165 z^{-5} + 2.602 z^{-6} \\ + 2.575 z^{-7} + 1.989 z^{-8} + 1.323 z^{-9} + 0.4207 z^{-10}$$





Status: Estimated using N4SID with prediction focus
Fit to estimation data: 98.91%, FPE: 5.0093e-06

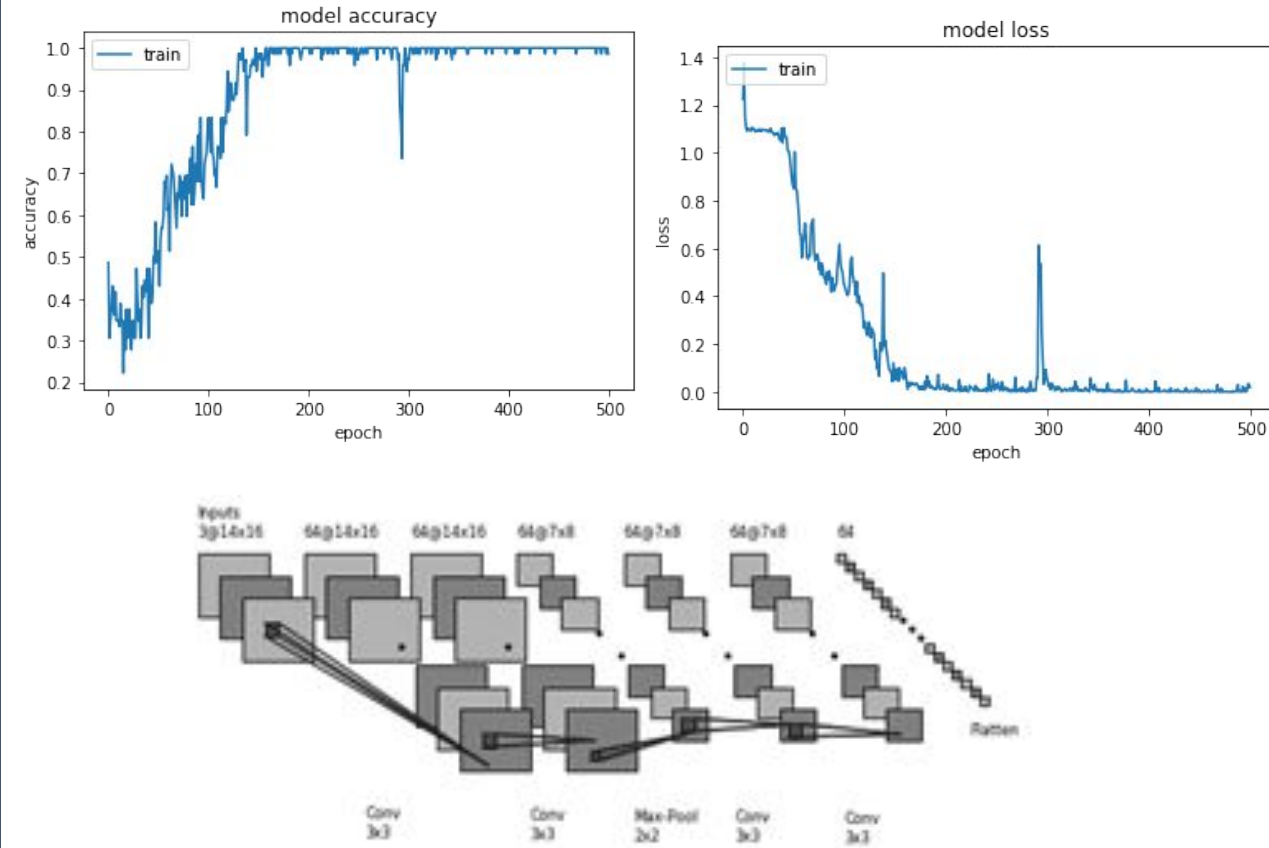
Improvement (%)	Iteration	Cost	step	optimality	Expected	Achieved	Norm of Bisections	First-order
0	4.69629e-06	-	3.62e+07	20.8	-	-		
1	4.17459e-06	3.14	1.42e+07	20.8	11.1	2		
2	4.14543e-06	0.591	1.2e+07	11.7	0.699	3		
3	4.11706e-06	0.417	1.04e+07	11.4	0.684	3		
4	3.96814e-06	0.632	7.53e+06	11	3.62	2		
5	3.79486e-06	0.757	1.08e+07	7.81	4.37	1		
6	3.73595e-06	0.533	1.87e+07	3.1	1.55	0		
7	3.71418e-06	0.347	2.78e+07	1.35	0.583	0		
8	3.70704e-06	0.331	8.38e+06	0.948	0.192	0		
9	3.69764e-06	0.17	1.58e+07	0.785	0.254	1		
10	3.68309e-06	0.235	9.66e+06	0.511	0.393	0		
11	3.68238e-06	0.105	7.38e+06	0.194	0.0193	2		
12	3.67828e-06	0.0767	1.7e+06	0.138	0.111	0		
13	3.67764e-06	0.0999	1.59e+06	0.0323	0.0176	0		
14	3.67747e-06	0.0558	1.16e+06	0.0195	0.0046	1		
15	3.67732e-06	0.00148	1.83e+05	0.0086	0.00412	0		

Termination condition: Near (local) minimum, (norm(g) < tol).
Number of iterations: 15, Number of function evaluations: 46

Status: Estimated using SSEST with prediction focus
Fit to estimation data: 99.07%, FPE: 3.67745e- 7

What We Did

- 2D-Convolutional Neural Network
 - Using the EEG Signal as a (pseudo)image matrix (61,110,3)
 - Inspired on VGGNet model With only 3x3 convolutions and 2x2 Maxpoolings
 - 10-Fold CV shows an average accuracy of 79%



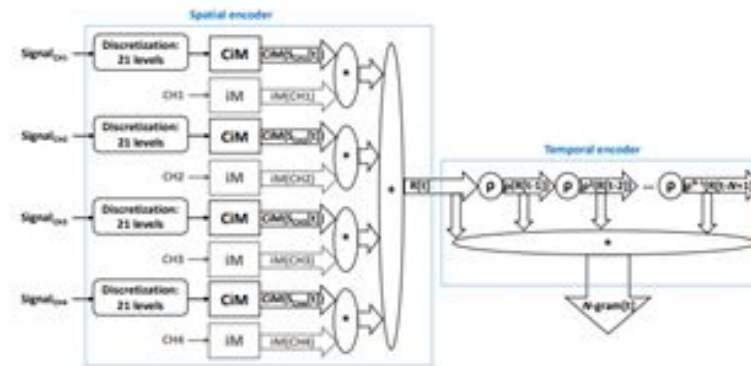
Training accuracy and loss of and early test model and architecture of the model

What We Did

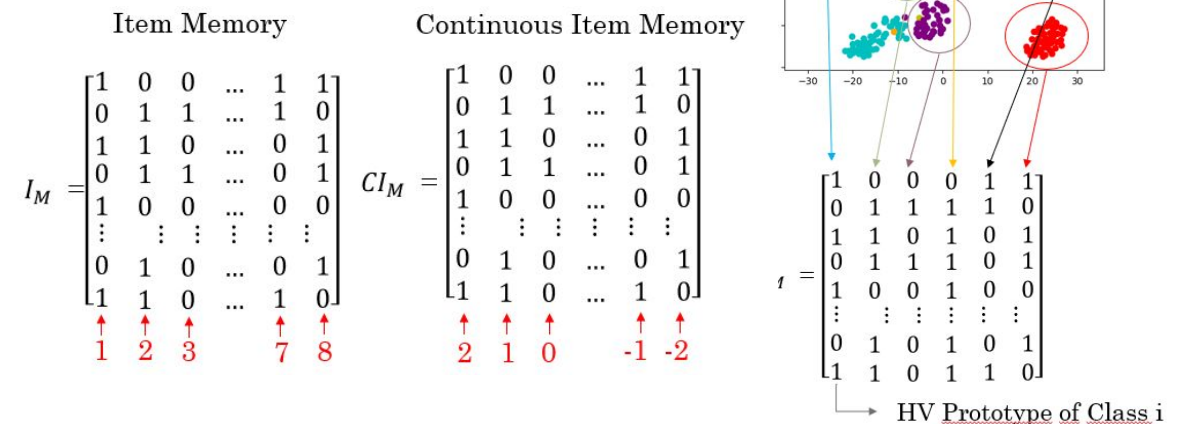
- Hyperdimensional Computing
 - Initially proposed by Kanerva, for NPL processing. Some studies on biosignals
 - Brain inspired using high dimension (<10.000) (pseudo)random i.i.d binary vectors.
 - 10-Fold CV shows and average accuracy of 65%

A. Rahimi et al. "Hyperdimensional biosignal processing: A case study for EMG-based hand gesture recognition," in 2016

P. Kanerva, "Hyperdimensional computing: An introduction to computing in distributed representation with high-dimensional random vectors,"



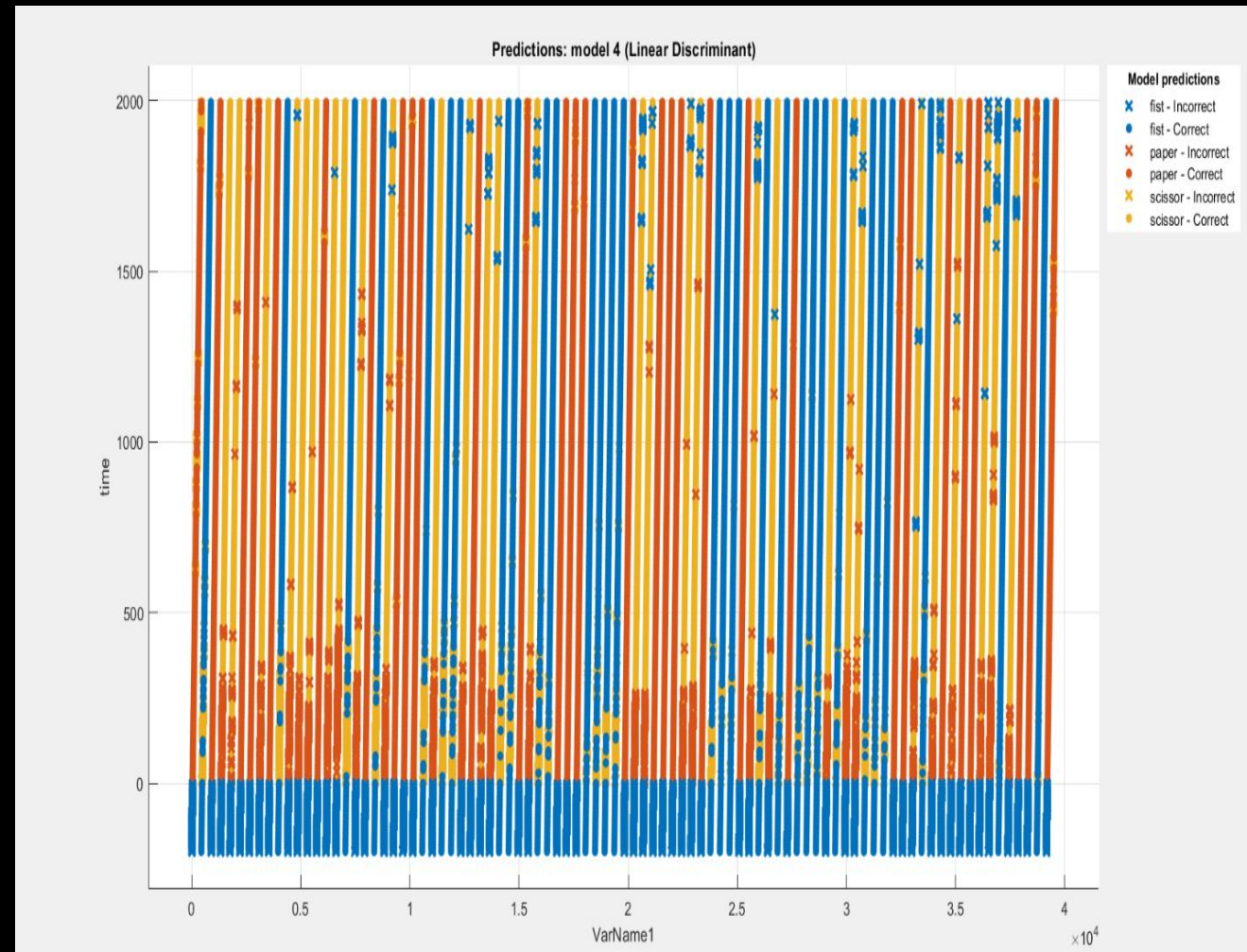
Pipeline of the spatial and temporal encoding process (adapted from reference)



Representations of the Memories used in the classification algorithm

Principal Component and Linear Discriminant Analysis

- First Band pass filter is applied
- then 10 cross validation partitioning the data set into folds and estimating accuracy on each fold.
- Principal Component Analysis (PCA) is first applied to the data set .
- The goal of PCA is to reduce the dimensionality of the data while retaining as much as possible of the variation present in the dataset.
- PCA weights are computing based only on training data .
- LDA is then applied to find the most discriminative directions.
- 10-Fold CV shows and average accuracy of 86.1%



LDA

- Methodology

$$\mathbf{y} = \mathbf{U}^T \mathbf{x}$$

projection matrix

- LDA computes a transformation that maximizes the between-class scatter while minimizing the within-class scatter:

$$\max \frac{|\mathbf{U}^T \mathbf{S}_b \mathbf{U}|}{|\mathbf{U}^T \mathbf{S}_w \mathbf{U}|} = \max \frac{|\tilde{\mathbf{S}}_b|}{|\tilde{\mathbf{S}}_w|}$$

products of eigenvalues !

$\tilde{\mathbf{S}}_b, \tilde{\mathbf{S}}_w$: scatter matrices of the projected data \mathbf{y}

What We Would Do

- Better Preprocessing!
 - More Frequencies
 - Channel selection
- More emphasis on length of the classification window
- Rigorous comparison between models



Thank You !