#### **DEEP LEARNING PROJECT**



# ROAD EXTRACTION FROM SATELLITE IMAGES

BY

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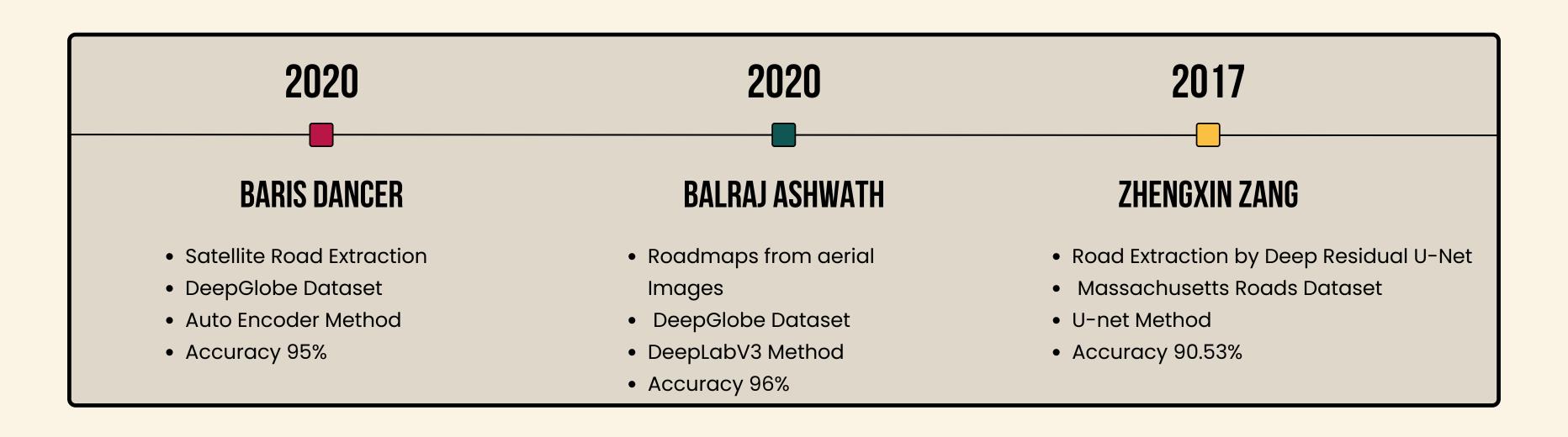
# PROBLEM STATEMENT

In traffic management, urban planning, automatic vehicle navigation, and emergency management, road information retrieval is critical. How can we extract road information from remote sensing photographs is a critical concern.

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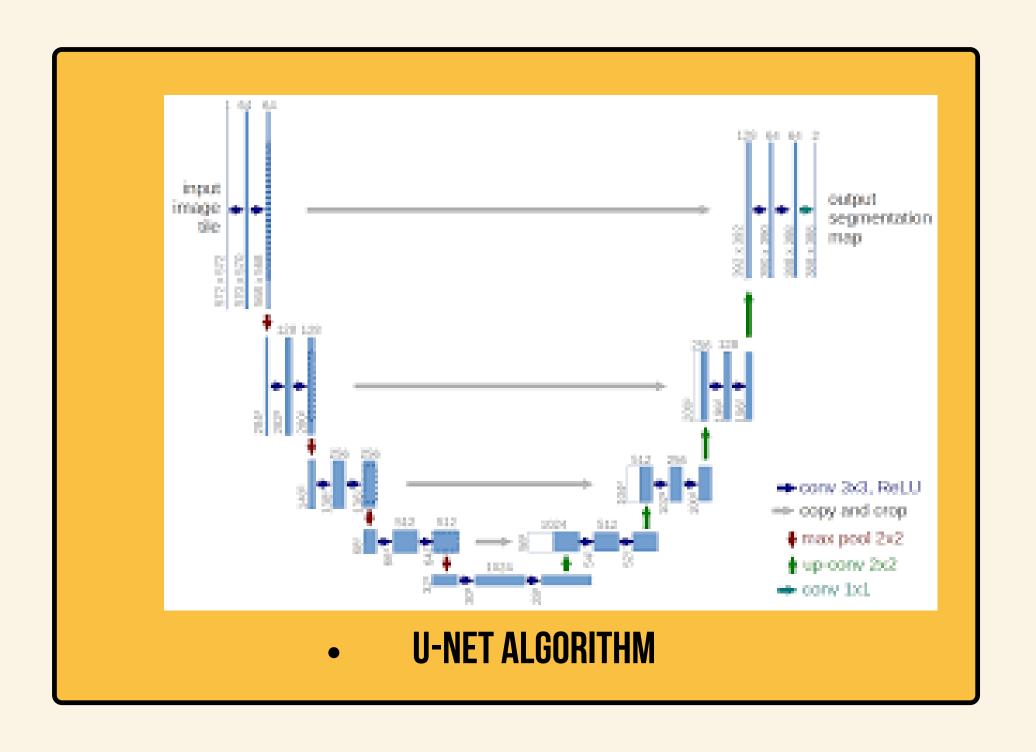
# LITERATURE SURVEY



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### METHODOLOGY

U-Net is a semantic segmentation architecture. It has two paths: one that contracts and one that expands. The convolutional network's contracting route follows the standard architecture. It comprises two 3x3 convolutions (unpadded convolutions) that are applied repeatedly, each followed by a rectified linear unit (ReLU) and a 2x2 max pooling operation with stride 2 for downsampling.



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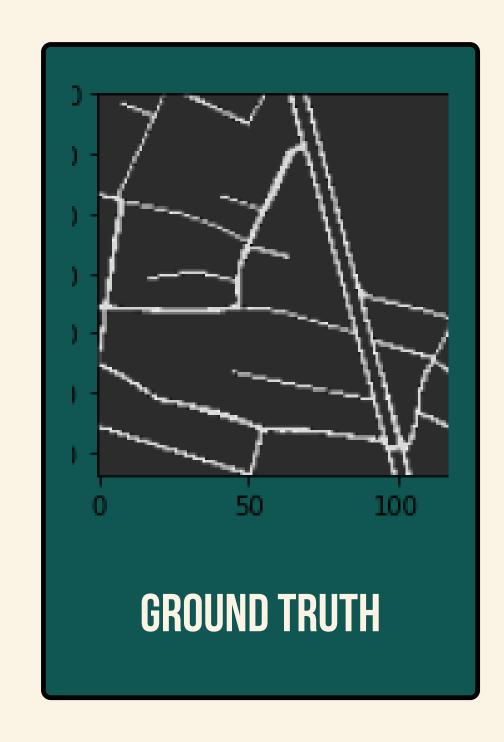
### RESULTS

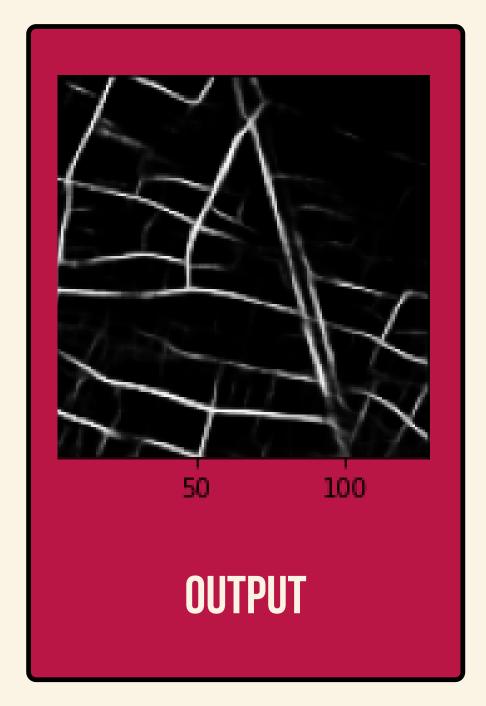
The values we achieved are as follows:

Accuracy: 61%

• IoU: 0.41

• Binary Accuracy: 93%





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