

# MechTwin – Intelligent Digital Failure Predictor

Theme: Smart Automation Solutions

- ❖ Predictive maintenance & failure intelligence
- ❖ Real-time digital twin for mechanical systems



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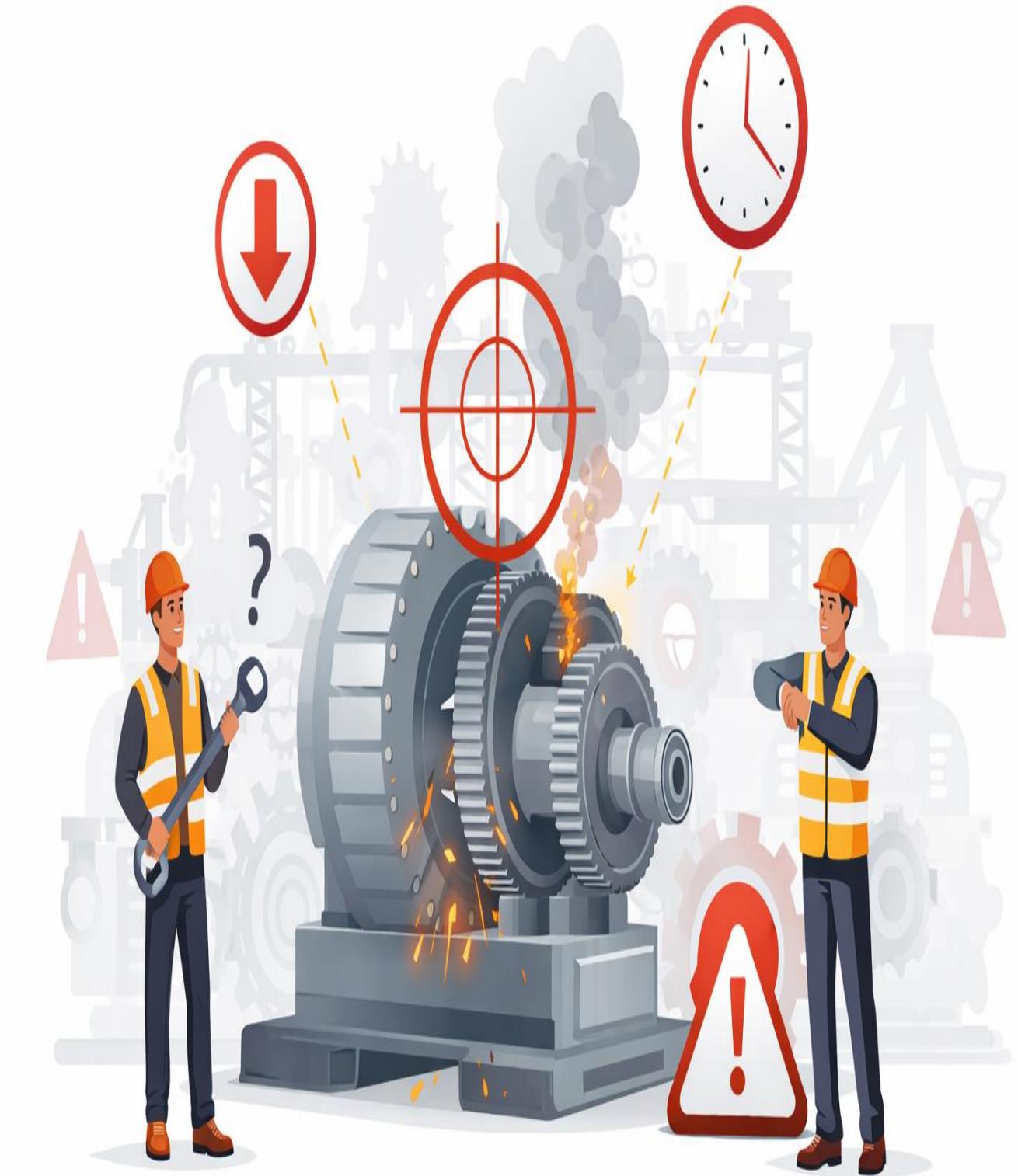
# Problem Identified

## PROBLEM DESCRIPTION

- Unexpected mechanical failures
- Reactive maintenance approaches
- No real-time visibility of system health

## Background:

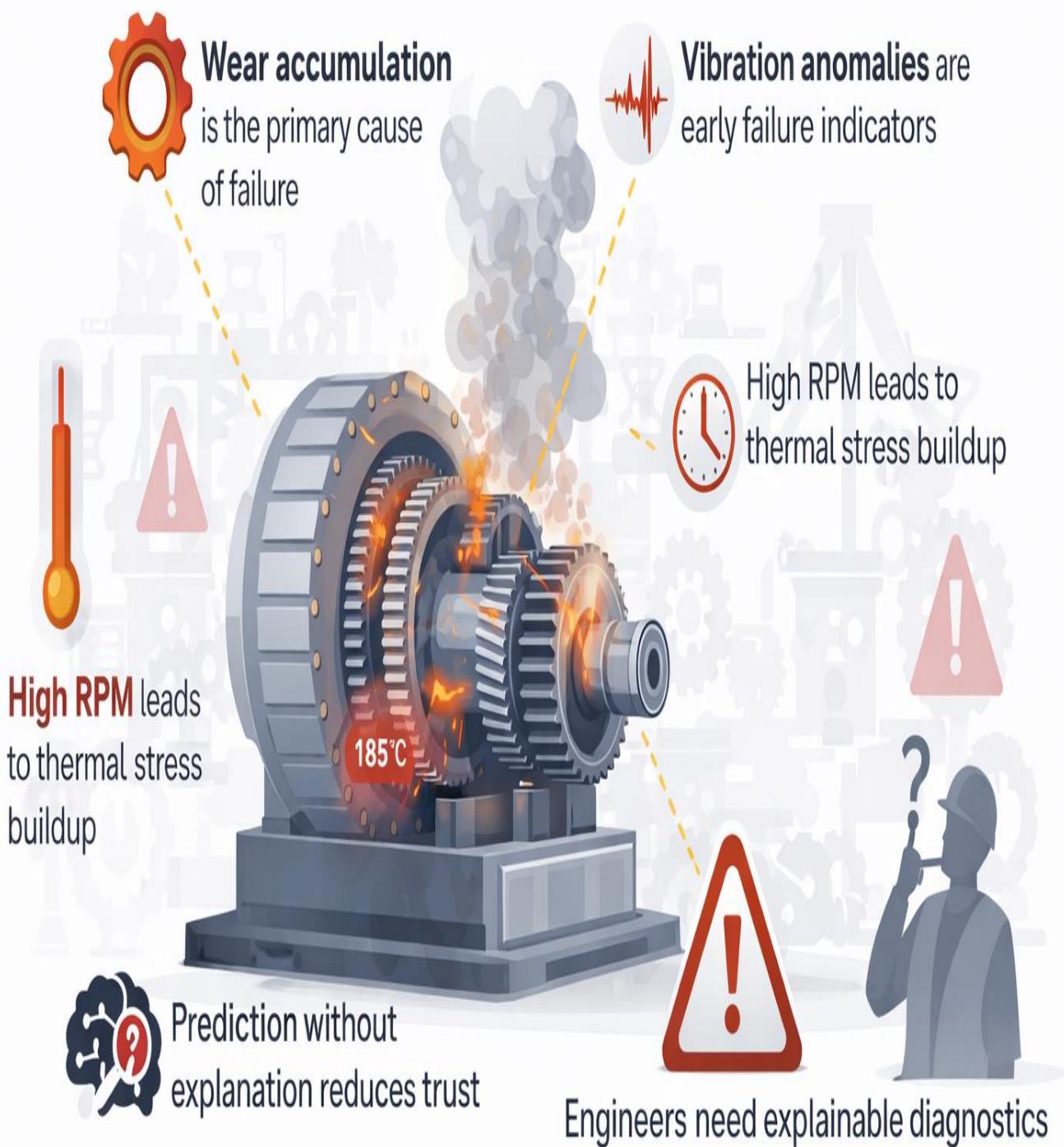
- Existing systems only monitor raw parameters
- Failures are detected only after breakdown
- Engineers lack explanation for failure causes



# Research findings

- Wear accumulation is the primary cause of failure
- Vibration anomalies are early failure indicators
- High RPM leads to thermal stress buildup
- Prediction without explanation reduces trust
- Engineers need explainable diagnostics

## Research Findings



# Product specifications

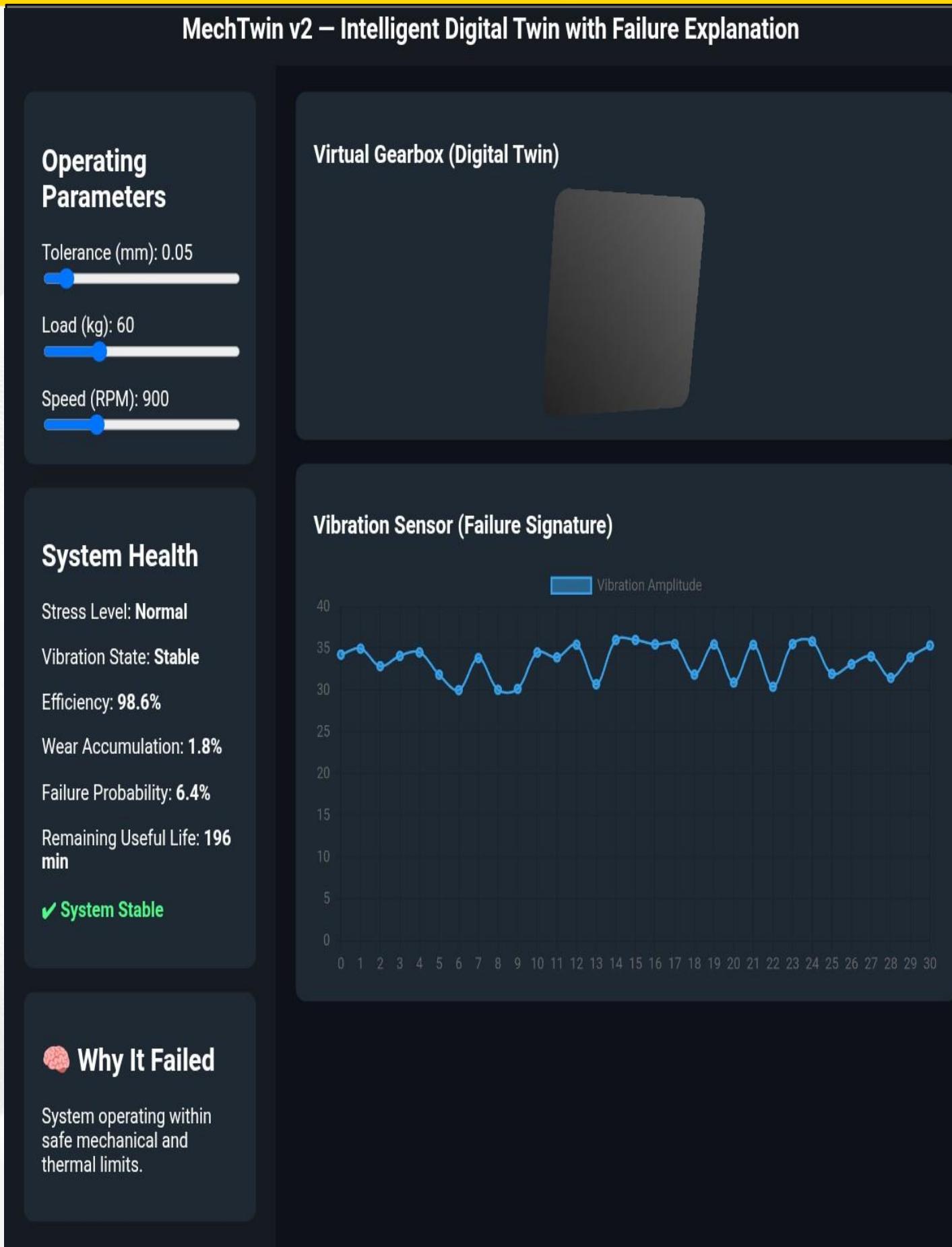
## Components required

- **Technical** : Digital Twin Simulation Engine, Wear & vibration modeling, Failure prediction logic, Real-time visualization dashboard.
- **Human factors** : Decision support using RUL, failure probability, and health status
- **Constraints** : Real-time computation limitations, Simulation accuracy vs visual clarity trade-off



# Final solution and innovation

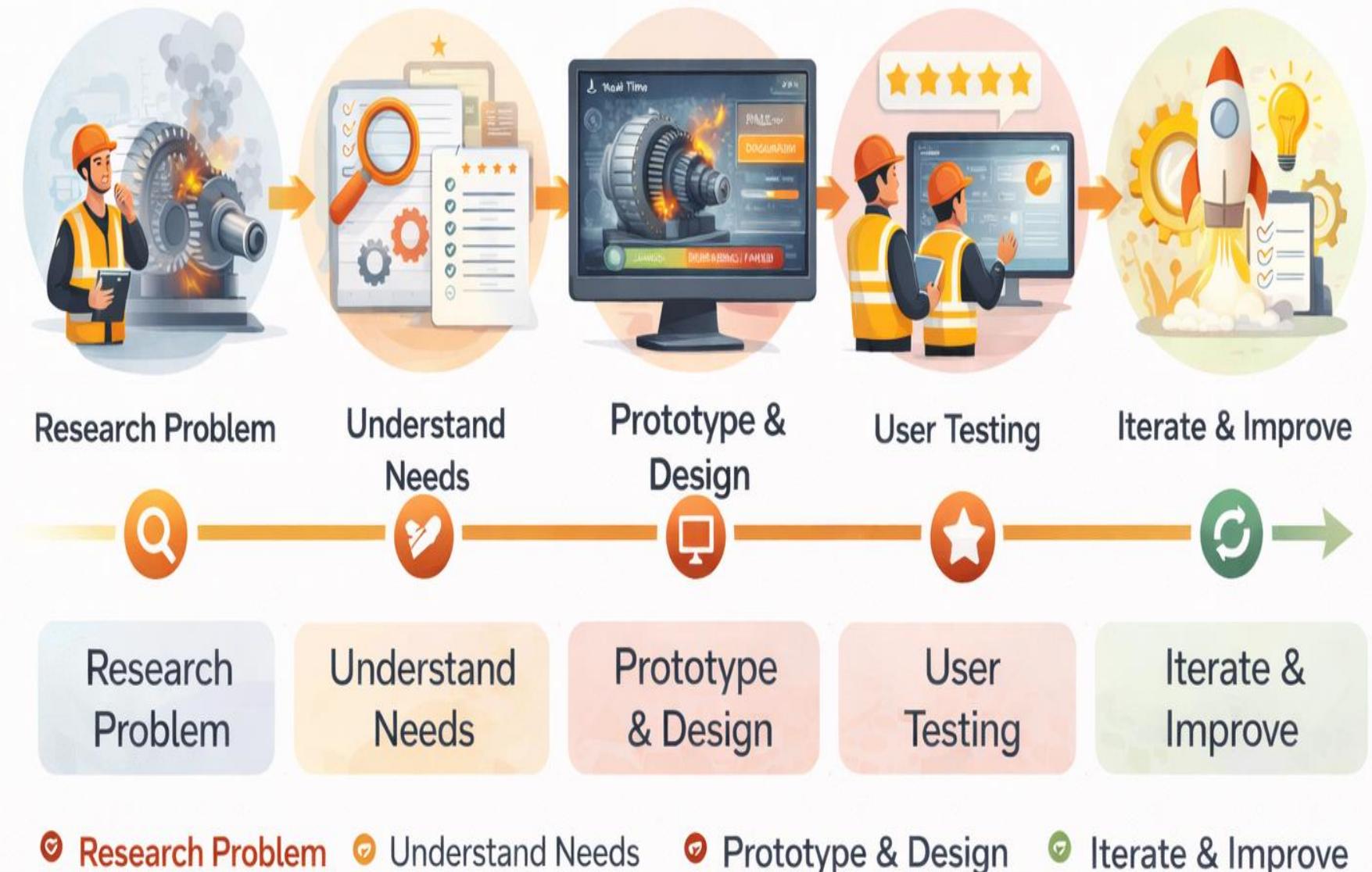
- Address the Problem:** Our solution uses an intelligent digital twin to continuously monitor mechanical health, predict failures early, and prevent unexpected system breakdowns.
- WHY IT'S INNOVATIVE:** It combines failure prediction with real-time root cause explanation, transforming complex mechanical data into human-readable intelligence.
- BENEFITS:** It reduces downtime and maintenance costs while enabling safer, more reliable, and sustainable operation of mechanical systems.



## Design Process

# Design process

- ❑ **Research:** Uncovered critical mechanical inefficiencies and system blind spots.
- ❑ **Reframed Brief:** Shifted focus to immersive, predictive, and operator-centric simulation.
- ❑ **Ideation:** Conceptualized interactive dashboards, real-time alerts, and dynamic controls.
- ❑ **Mock-up Testing:** Validated 3D gearbox logic and user interactions for precision and realism.
- ❑ **Final Development:** Delivered a fully integrated, real-time Mech Twin with predictive analytics and immersive visualization.



# SIMULATION PROCESS

## **Input Operating Parameters**

RPM, load, and tolerance are defined to replicate real gearbox conditions.

## **Virtual Gearbox Creation**

A digital twin of the gearbox is modeled with interconnected gears and gear ratios.

## **Dynamic Motion Simulation**

Gear rotation is driven by RPM while load and tolerance influence contact behavior.

## **Real-Time System Interaction**

Continuous updates simulate vibration, wear, heat, and efficiency loss.

## **Vibration & Stress Analysis**

The system monitors vibration patterns and stress intensity under varying speeds.

## **Progressive Wear Accumulation**

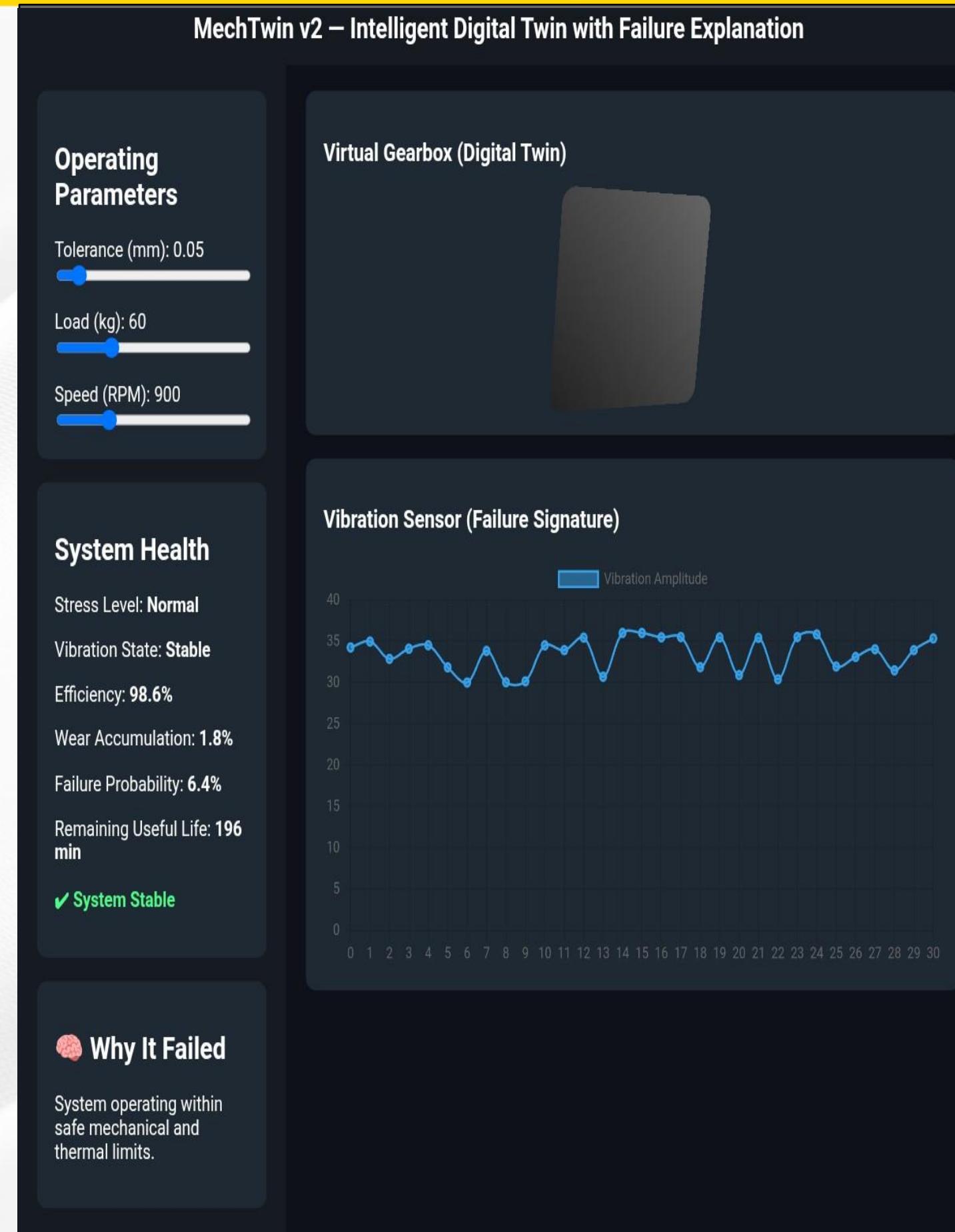
Mechanical wear increases over time based on operating severity.

## **Failure Threshold Detection**

Critical limits trigger unsafe conditions and failure prediction.

## **Predictive Output & Visualization**

System health, efficiency, and failure risk are displayed in real time.



# SUPPLEMENT LINK

<https://github.com/Deepak131205/MechTwin---Intelligent-Digital-Failure-Predictor.git>



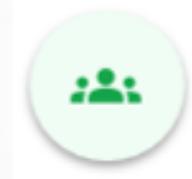
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# Thank you!



## Acknowledgements

Industry Experts

Supporting organizations



## References

Industry reports

Market analysis data



## Credits

Team member

Project Coordinator



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