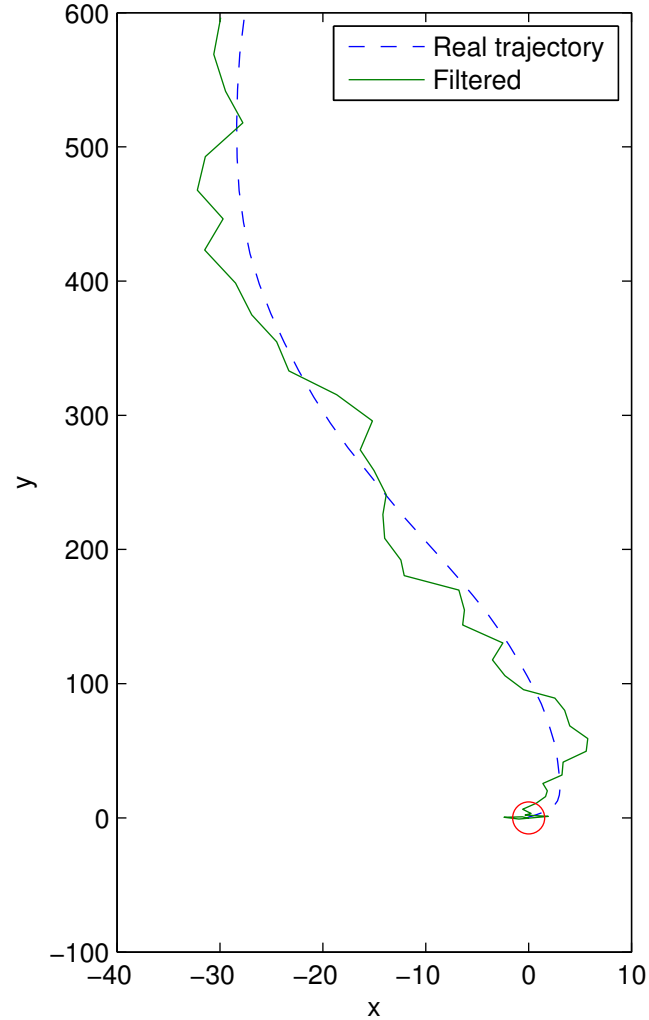


Position estimation with Kalman filter.



Velocity estimation with Kalman filter.

