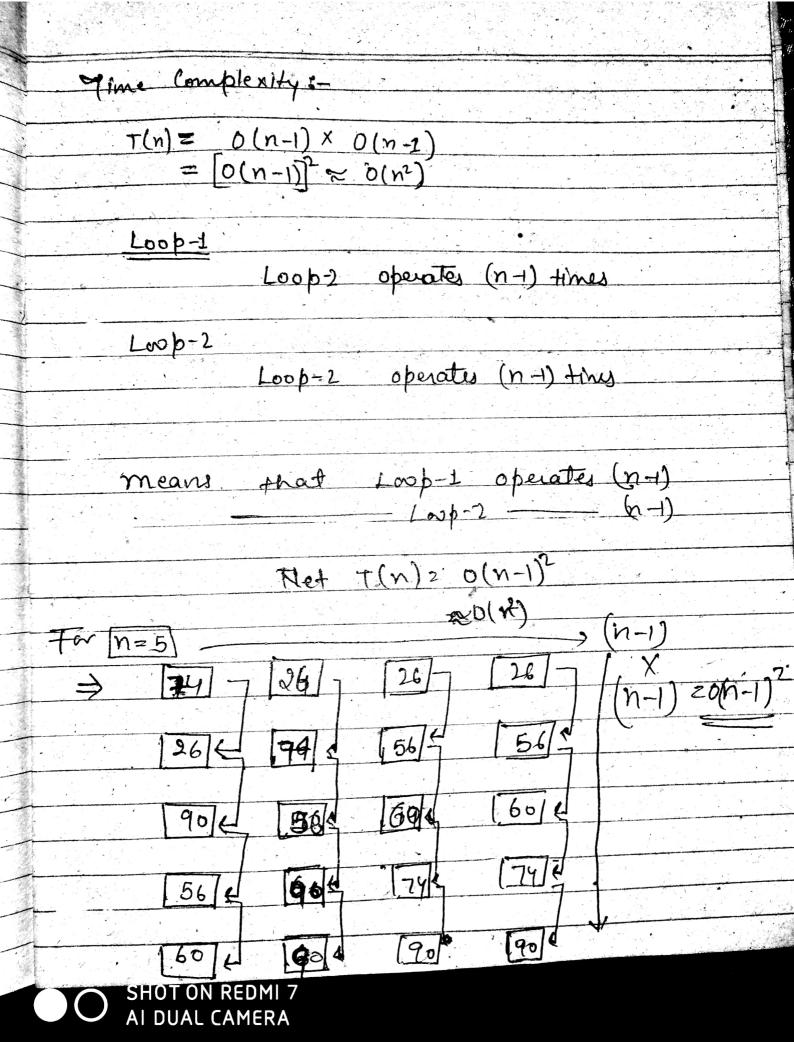
dey 1 Analysis of time complexity of any list in insection sobrt. case sort schould be in ascending order as we know Algorithm Insolution. Borton for (int X=1; X<n; X++) temp = am [x] for lint y= x-1; 47=0; 4= if (temp < arr[4]) temp[4+1] = tomp[4]; temp[]= temp; else break; consider List is \$7,9,11,13,16} Loop-1-) temp = 17 Loop249, (9<7) else break

AI DUAL CAMERA

		Ras been	
means	at x=1	Loop-2 Tcalled 1	time
means Similiarly			
, 6			
(ii) for X=2			
	temb=11		
100 p2	YZIV	770 + rue	
	of (415 am	[1] Han break	
	False		
means	at x=2 again-	100p2 has boe	nd called
om ce.	again -		
So we	can say	- [In Ascende	y order
	Loop-1	-Loop-2	10
Val 1	x=1	Y20	1
YOU	x22	V22	1
	X=3	722	3
	×24	· × 23	1
		924	1
	X25		
		y=n-2	1
	$\sqrt{x_{z}}$	- A A A A A A A A A A A A A A A A A A A	n-
SHOUT ONLD	enmia to	tol for peall	
AL DANALISM	MEDA		of the same of the

Time complexity = o(n+) &o(n) lus)2 Mage post: * Bubble sort: Algorithmsfor lint a=0; asm-ja++) for list b=0; b(nha++) f ef (a[b] >a[b++]) temp= a[b]; a[b] = a[bfi]; a[b+1] = tempi DUAL CAMERA



Space Complexity 6-0(1) = Constant flerge sort Algorithm:void menge sont (int 1, intr, inta) if (\$ < 8) int m = (1+8); mengesort (1, m, a); mergesort (m+2, 91, a); merge (l, m, r, a); void merge (int 1, int m, int r int * b) int n12 m-1+1; int m2 = r-m; # array[n1]; so tres initial Data # array2[n2]; solvier final pout of Date than buill store in arrayty array 2 to st by sorting with o(n)

SHOT ON REDMI 7
AL DUAL CAMERA

consider a element AITIO E Level 3 0131A 14,7,A M. (274) => 0,1,A 2,3,A 4,5,A 6,7,A n (1 *8) > 0,0,A | (2,2,A | 4,4,A | 1,1,A | 3,3,A Namber of Levelo(n) = log_2(n) = log_2(0)=3 Time Complexity (T(n)) > n logn Merge sort. space Complexity = O(n) * Inscution surt Algo nithms-For Lint a=1. ja(n j. a++) for (int b2a-1; b>20; b+4) SHOT ON REL AI DUAL CAME

if (array [b] > array [b+1]) tempozamay [b] array[b] = trendy[b+1]) array [b+1]z temp; break; # the complexity at worst case = 0(n2)

best case = 0(n) # Space Complexity = O(1) * Quick Bot 8-# Provot declaration important from its original array. it is used to by part array into two way which are in which first 8 subarray contains all makes tens than piret of AI DUAL CAMERA

other soub array will content all values
of greater than prot partition (& ma, array) 120; m2n-1 m) int start=l int end 2 m i bivot = a[l] while (stant (end) while (a:[stout] <= pivot) fol (stare stort++; while (a [end > pivot) & & (end>=) if (start < end) soaping (array Estert), arrelas swaping (away [l.], away [end] return end;

AI DUAL CAMERA