

Automata Theory and Computability

- 18CS54

- 1) Theory of Computation
- 2) computability
- 3) complexity

Automata

- Finite
- Push Down
- Linear Bounded
- Turing Machine

Formal Language

Formal Languages : Some mathematical model or formula

- 1) Regular
- 2) context free
- 3) Context-Sensitive.
- 4) Recursively Enumerable.

Introduction to Finite Automata

- These are computing devices that accept/recognise regular languages and are used to model operations of many systems we find in practice.

* Σ - It is alphabet (Stands for alphabet)

It is defined as a set of finite symbols.

Eg : 1) $\Sigma = \{0, 1\}$ Binary alphabet

2) $\Sigma = \{0, 1, 2, 3, \dots, 9\}$ Set for decimal numbers

3) $\Sigma = \{a, b, c, d, \dots, z\}$ Alphabet set for English alph.

* S - Stands for String

It is defined as a finite sequence of symbols derived from alphabet (Σ).

Ex. i) Consider $\Sigma = \{0, 1\}$

Strings that can be derived are

0, 1, 01, 001, 101, 1001, 101010, ...

* ϵ - Epsilon - It is a special string

It is called the null string or empty string.

Its length is always 0. ($|\epsilon| = 0$)

* Σ^* → It can be zero or more. (Called Kleen star operator)

Jan 2018

$\Sigma^* \rightarrow$ Its the power of alphabet

$$\Sigma^* = \Sigma^0 \cup \Sigma^1 \cup \Sigma^2 \cup \Sigma^3 \cup \dots$$

Ex. i) $\Sigma = \{0, 1\}$

Σ^0 = Set of string of length 0

Σ^1 = Set of string of length 1

$$\Sigma^* = \{0, 1, 00, 11, 10, 01, 000, 001, \dots 1111; \dots\}$$

It is defined as set of strings of all possible strings length derived from Σ .

July 2019 * L - It stands for Language

Jan 2019 It is defined as the set of strings derived from

$$\Sigma^* \text{ (Sigma Star) i.e. } L \subseteq \Sigma^*$$

Ex. i) Consider $\Sigma = \{a, b\}$

→ L_1 = Set of strings whose length is odd.

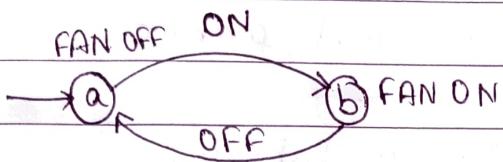
$$L_1 = \{a, b, aaa, bbb, ababa, \dots, bbbbb, \dots\}$$

→ L_2 = Set of strings begin with a and end with b

$$L_2 = \{ab, ababb, aaab, aabaabb, \dots\}$$

Symbols to draw an Automata.

- ○ → Initial State
- → Transition
- → Intermediate State
- → End / final State



Strings

↓
Functions

- Length
- Concatenation
- Replication
- Reversal

Functions :

↓
Relations

- Substrings
- Proper Substrings
- Prefix, Proper prefix
- Suffix, Proper suffix

* Length of Strings : No. of symbols in the given strings.
Ex. $|101| = 3$, $|\epsilon| = 0$

* Concatenation of String : Concatenation of two strings ($s \sqcup t$) is defined as string appending t to s .
Ex. $x = ab, y = c \Rightarrow xy = abc$

* Replication : Replication of string w is defined as

$$w^0 = \epsilon$$

$$w^{i+1} = w^i \cdot w$$

$$\text{Eg. } a^3 = aaa$$

(Repeating the occurrence of w 'i' no. of times).

* Reversal of String w - for each string w , the reverse is defined as

- i) if $|w| = 0$, then $w = w^R = \epsilon$. Eg. $(abc)^R = cba$
- ii) if $|w| \geq 1$, then $\forall a \in \Sigma (\forall u \in \Sigma^*(w = ua))$, then $w^R = au^R$

Relations

* Substrings : A string 't' is a substring of 's' iff 't' continuously occurs in strings.

* Proper Substring : A string 't' is a proper substring of 's' iff it is a substring of 's' and $t \neq s$.

Ex. = 'εaabbaε'

$\underbrace{\epsilon, a, aa, aab, aabba}$

Proper Substring

* Prefix : A string 's' is a prefix of 't' iff there exists $\exists x \in \Sigma^* (t = sx)$

* Proper Prefix : A string 's' is a P.P. of 't', iff string is prefix of t and $s \neq t$

Ex. Consider "abba"

$\underbrace{\epsilon, a, ab, abb, abba}$

Proper Prefix

* Suffix : A string 's' is a suffix of 't' iff there exists $\exists x \in \Sigma^* (t = xs)$.

* Proper Suffix : A string 's' is a P.Suffix of 's' iff string is suffix of t and $s \neq t$

Ex. Consider "abba"

bba
 $\underbrace{\epsilon, b, bb, \text{[redacted]}, abba}$

Proper Suffix

Page _____

Techniques for defining Languages

- By enumeration / defining property

Examples : (Enumeration)

Let $L = \{w \in \{a, b\}^*: \text{all strings begin with } a\}$

$$L = \{a, ab, aab, aabb, \dots\}$$

Strings not in L are :

$$\{b, ba, \epsilon, bbb, \dots\}$$

- By (defining property)

Let $L = \{w \in \{a, b\}^*: |w| \bmod 3 = 1\}$

$$L = \{a, a^4, a^7, a^{10}, \dots\}$$

Strings not in L are :

$$\{\epsilon, a^2, a^3, a^5, a^6, \dots\}$$

Functions on Languages : All set operations like Union, Intersection, Difference and Complement can be applied.

Concatenation of Languages

Ex. $L_1 = \{aa, ab\}$

$L_2 = \{xx, yy\}$

$$L_1 L_2 = \{aaxx, aayy, abxx, abyx\}$$

Set Operations on Languages

$L_1 = \{\epsilon, a^2, a^4, a^6, \dots\}$ || Even no. of a 's

$L_2 = \{a^1, a^3, a^5, \dots\}$ || Odd no. of a 's

$\rightarrow L_1 \cup L_2 = \Sigma^* \cap \{a\}^*$ || Union operation

$\rightarrow L_1 \cap L_2 = \emptyset \cap \{a\}^*$ || Intersection operation

$\rightarrow L_1 - L_2$ || Difference operation

$\rightarrow \complement(L_1 - L_2)$ || Complement operation.

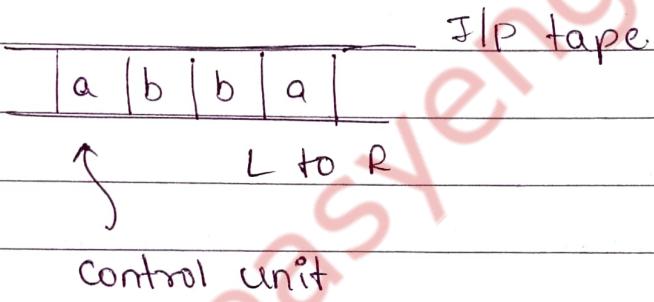
July '18 # Deterministic Finite State Machines (DFSM) / FSM)

Jan 2019

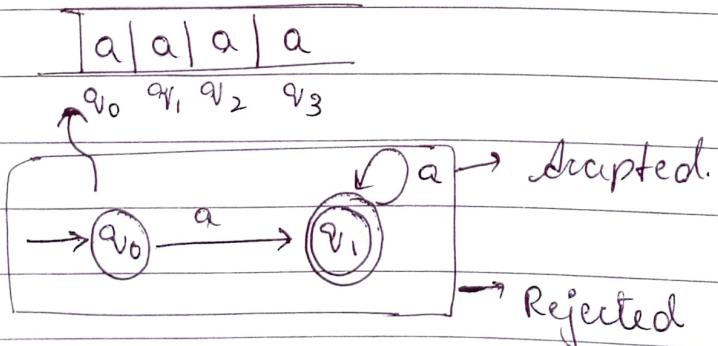
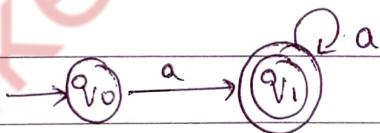
Definition : A FSM or DFSM , M is quintuple : $(Q, \Sigma, \delta, s_0, F)$

where,

- Q is finite set of states
- Σ is the input alphabet
- $s_0 \in Q$ is the initial state
- F - End / final accepting state
- δ - It is the transition function it maps from $Q \times \Sigma$ to Q



Ex. L_1 = Strings of one or more 'a's
 $L_1 = \{a, aa, aaa, aaaa, \dots\}$



Rejected

Finite State Machine has 3 Parts

i) Control Unit :

- Reading the contents of JIP tape from L to R
and cell by cell

ii) Input Tape :

- It contains many rectangular cell of each cell
is able to hold any only one symbol.

iii) Read Head :

- Control unit is reading the contents of JIP tape
from L to R and cell by cell.

The logic or the strategy to recognize the lang.
resides inside control unit.

Finally the machine gives either of the two
messages (accepted @ rejected).

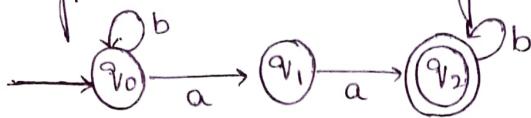
How to write transition diagram?

Steps are

- 1) Find the minimum string accepted, this decides the no. of states in the FSM, in most of the cases.
- 2) Then, take longer strings and make them accepted, while modifying the transitions
- 3) Check for the minimum strings that are not to be accepted, are really not accepted as per the transition diagram.
- 4) See that each state has transitions equal to the no. of alphabets present (Σ).
- 5) Two transition on the same alphabet do not go to different states.

Examples

- 1) From the given transition diagram of DFSA define all the tuples.



Sol.

$$Q = \{q_0, q_1, q_2\}$$

$$M = \{Q, \Sigma, q_0, F, \delta\}$$

$$\Sigma = \{a, b\}$$

$q_0 \rightarrow$ Initial State

$F \rightarrow q_2$ (Final State)

δ is shown in transition table

δ	a	b
q_0	q_1	q_0
q_1	q_2	-
q_2	-	q_2

- 2) Draw a DFSA to accept strings of 0's and 1's ending with string 011.

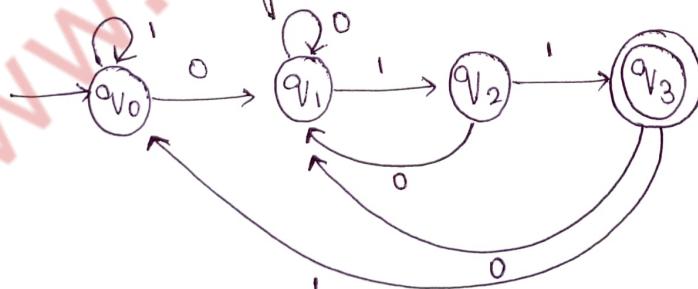
Sol. $\Sigma = \{0, 1\}$

$$(0+1)^* 011 \rightarrow \text{Regular Expression.}$$

Minimum String $\rightarrow 011$

Sample String - 0011, 1011, 10011.

As the string ends with 011.



$$Q = \{q_0, q_1, q_2, q_3\}$$

$$\Sigma = \{0, 1\}$$

$q_0 \rightarrow$ Initial State

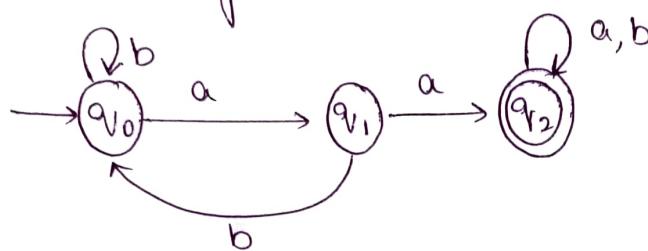
$F \rightarrow q_3$ (Final State)

3) Draw a DFA to accept string of a's and b's having sub string aa.

Sol) Regular Expression : $(a+b)^*aa(a+b)^*$

Minimum String = aa

Sample Strings : baaab, abaa, aabb



$$M = \{ Q, \Sigma, q_0, F, \delta \}$$

$$Q = \{ q_0, q_1, q_2 \}$$

$$\Sigma = \{ a, b \}$$

$q_0 \rightarrow$ Initial State

$F \rightarrow q_2 \rightarrow$ Final State

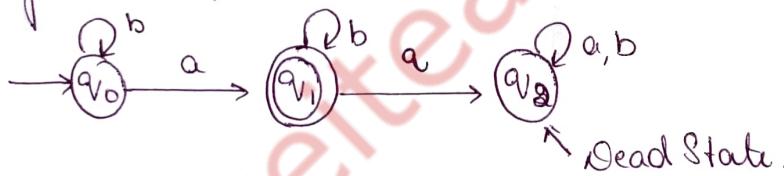
4) Obtain a DFA to accept strings of a's and b's having exactly one a.

Sol) $\Sigma = \{ a, b \}$

Minimum String : a

Sample String : a, bab, bba, abb.

Regular Expression : $b^* a b^*$



Dead State.

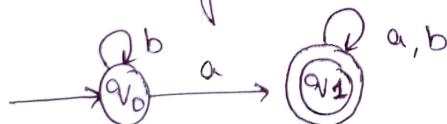
5) Obtain a DFA to accept strings of a's and b's having atleast one a.

Sol) $\Sigma = \{ a, b \}$

Regular Expression : $(a+b)^* a (a+b)^*$

Minimum String : a

Sample String : a, aa, aaa, abab.



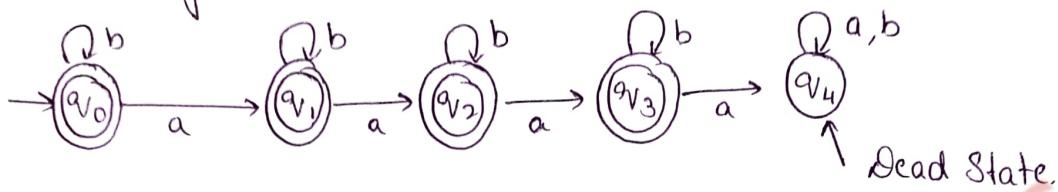
6) Obtain a DFA to accept strings a's and b's having not more than 3 a's.

Sol $\Sigma = \{a, b\}$

Not more than 3 a's can be either 0, 1, 2, or 3 a's.

Min String: ϵ

Sample String: $\epsilon, a, aa, aaa, ba, aab$

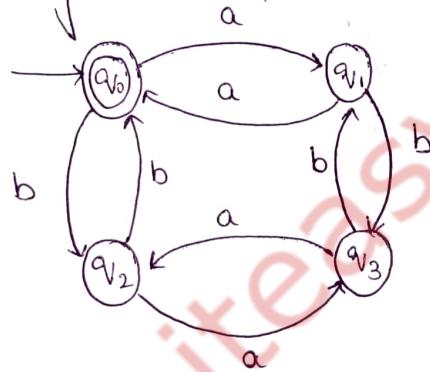


Jan 2019
7) Obtain a DFA to accept strings of a's and b's having even number of a's and b's.

Sol $\Sigma = \{a, b\}$

Min String = ϵ, aa, bb

Sample String: abab, aabb, aaaa, abababab.



- $q_1 \rightarrow$ Odd no. of a's, Even of b's
- $q_2 \rightarrow$ Even no. of a's, Odd of b's
- $q_3 \rightarrow$ Odd no. of a's, Odd no. of b's

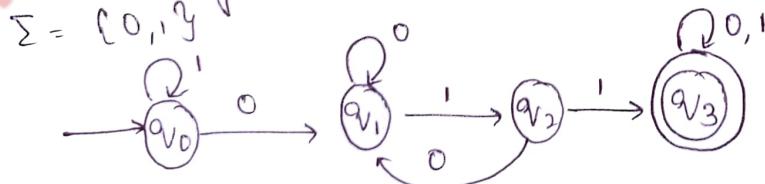
8) Construct a DFA to accept strings of 0's and 1's having (i) 011 as the substring (ii) string starting with 011

iii) $L = \{w \mid w \in (a+b)^* \text{ and } N_a(w) \bmod 3 = 0 \text{ and } N_b(w) \bmod 2 = 0\}$

Sol Jan 2019

i) Having 011 as substring

Min String: 011



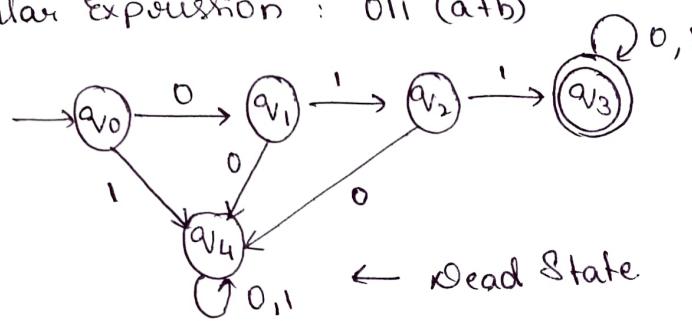
$N_a(w) \bmod 3$ means a in multiples of 3 and respectively
b in multiples of 2

ii) Starting with 011

$$\Sigma = \{0, 1\}$$

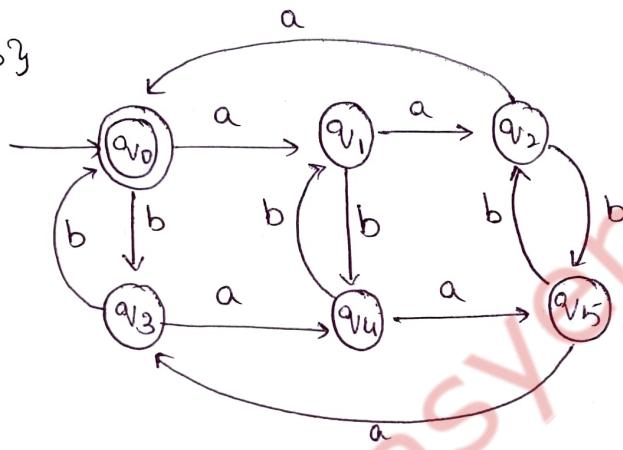
Min String: 011

Regular Expression: $011(a+b)^*$



iii) $L = \{w_1 w_2 (a+b)^*\} \text{ and } N_a(w) \bmod 3 = 0, N_b(w) \bmod 2 = 0$

$$\Sigma = \{a, b\}$$

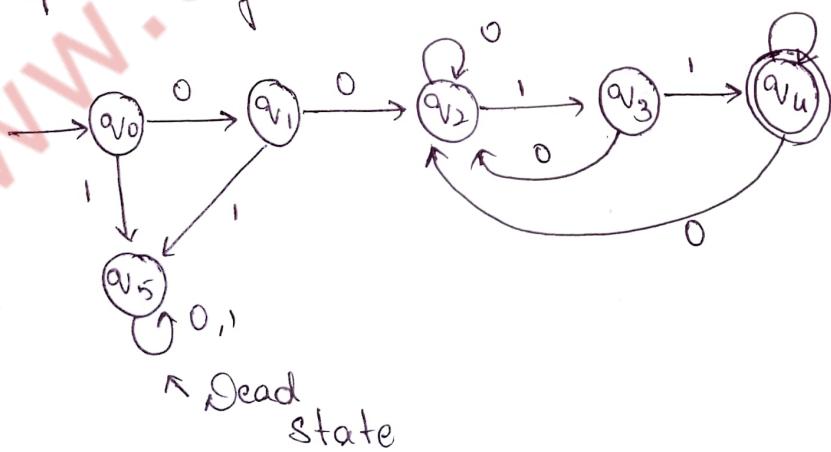


a) Obtain a DFA accepting strings of 0's and 1's starting with at least 2 0's and ending with atleast 2 1's.

Sol $\Sigma = \{0, 1\}$

Min String: 0011

Sample String: 001010011, 0010111

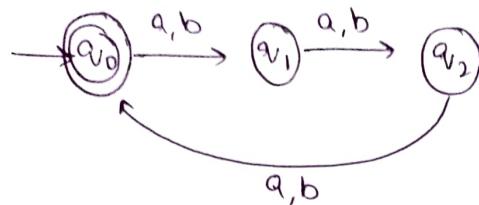


10) Obtain a DFSM to accept language

i) $L = \{w \mid w \text{ mod } 3 = 0\}$ on $\Sigma = \{a, b\}$

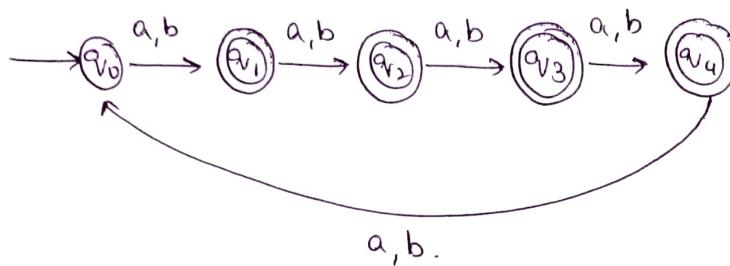
ii) $L = \{w \mid w \text{ mod } 5 = 0\}$ on $\Sigma = \{a, b\}$

Sol.



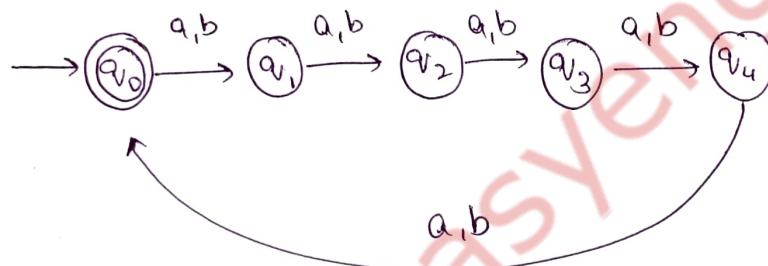
iii) $L = \{w \mid (w) \text{ mod } 5 = 0\}$ on $\Sigma = \{a, b\}$

Sol.



iv) $L = \{w \mid (w) \text{ mod } 5 = 0\}$ on $\Sigma = \{a, b\}$

Sol.



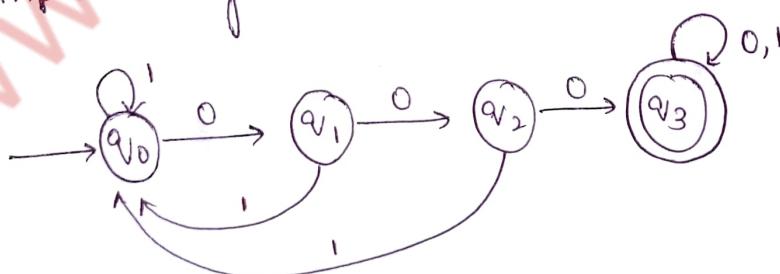
v) Draw a DFSM that accepts strings of 0's and 1's that contain 3 consecutive 0's as a substring.

Sol.

$$\Sigma = \{0, 1\}$$

$$K = \{q_0, q_1, q_2, q_3\}$$

Sample String = {000, 0001, 100011, 010001100...}

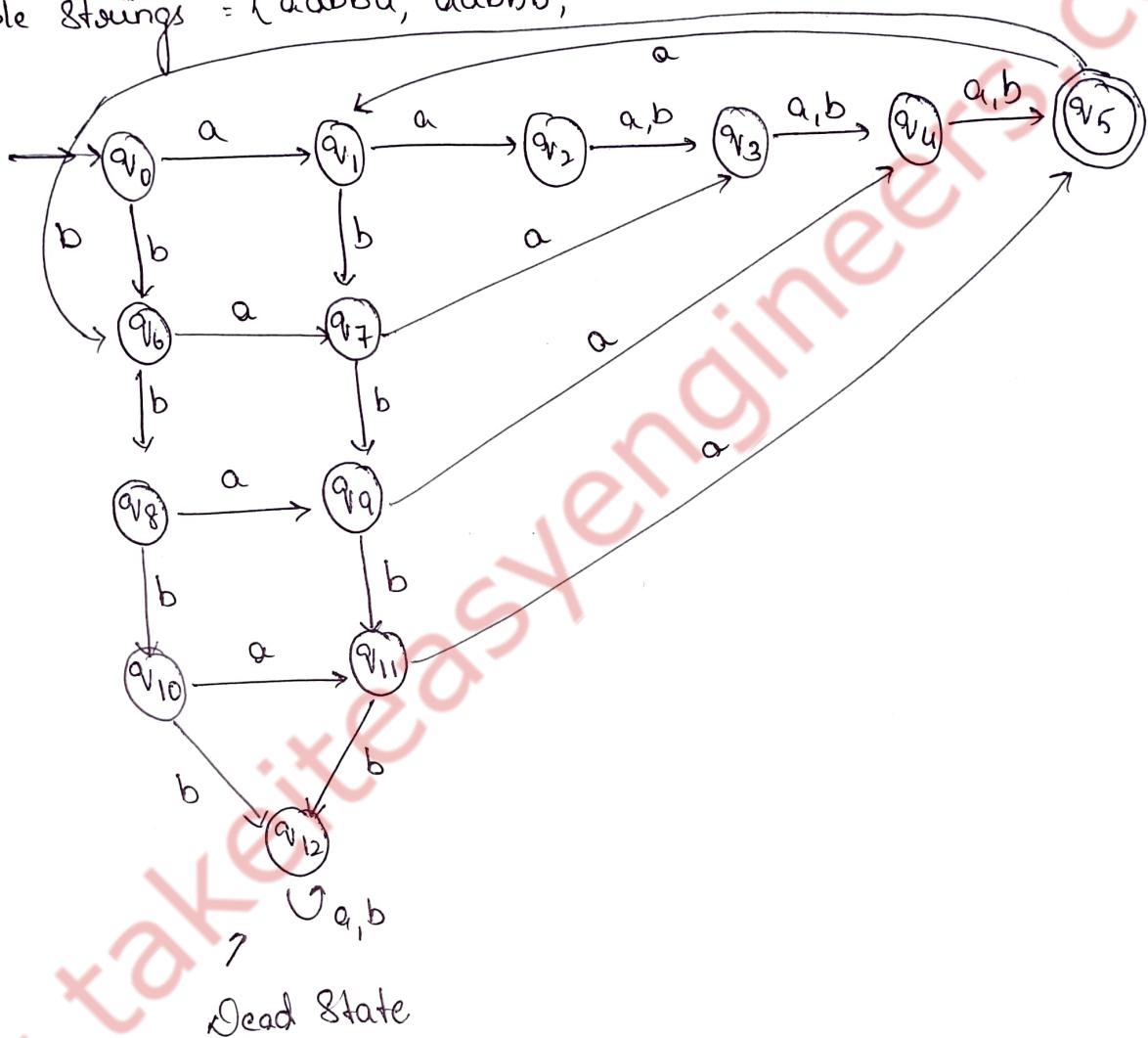


Q) Construct a DFA to accept strings of 'a's and 'b's such that each block of 5 consecutive symbols should have atleast 2 'a's

Sol $\Sigma = \{a, b\}$

Min String = aaaaa

Sample Strings = (aabba, aabbb, abaab...)

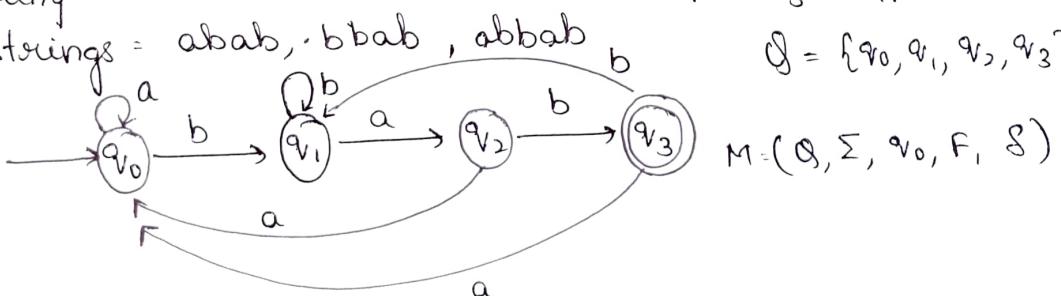


Jan 2018
Q) Draw a DFA to accept strings of 'a's and 'b's ending with bab.

Sol $\Sigma = \{a, b\}$

Min String = bab

Sample Strings = abab, bbab, abbab



$q_0 \rightarrow$ Initial State

$F \rightarrow q_3 \rightarrow$ Final State

$$Q = \{q_0, q_1, q_2, q_3\}$$

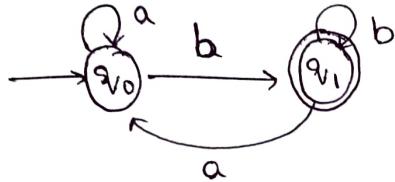
$$M = (Q, \Sigma, q_0, F, S)$$

- 14) Design a DFSM to accept strings of a's and b's where every string ends in b.

Sol: $\Sigma = \{a, b\}$

Min String: b

Sample strings: ab, abb, aabb, babb.

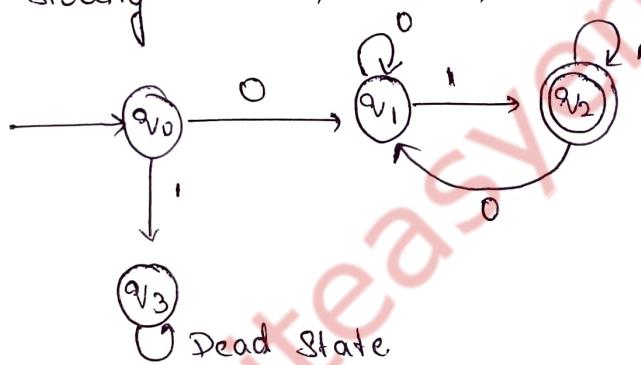


- 15) Design a DFSM to accept strings of 0's and 1's where it begins with 0 and ends with 1.

Sol: $\Sigma = \{0, 1\}$

Min String: 01

Sample String: 0011, 01001, 011001, ...



$$M = \{Q, \Sigma, q_0, F, S\}$$

$$Q = \{q_0, q_1, q_2, q_3\}$$

$$\Sigma = \{0, 1\}$$

q_0 - Initial

q_2 - Final/End state

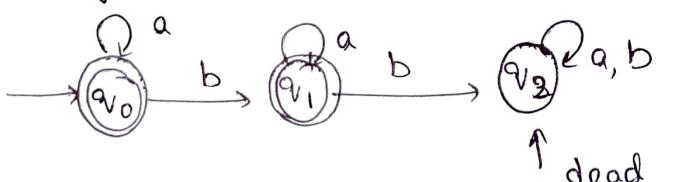
$$S = Q \times \Sigma \Rightarrow Q$$

- 16) Design a DFSM that accepts strings of a's and b's that contain not more than 1 b

Sol: $\Sigma = \{a, b\}$

Min String = ϵ, b

Sample String = ab, aab, aba



$$F = q_0, q_1 \quad (\text{Two final states})$$

Non deterministic Finite State Machines (NFSM)

Definition : A NFSM , M is a Quintuple : $(Q, \Sigma, \Delta, \delta, A)$ where,

$Q \rightarrow$ Finite set of states

$\Sigma \rightarrow$ Input alphabets

$\delta \rightarrow$ Initial state

$F \rightarrow$ subset of Q is the set of accepting states

$\delta \rightarrow$ It is the transition function it maps from $(Q \times (\Sigma \cup \{\epsilon\}))$ to Q

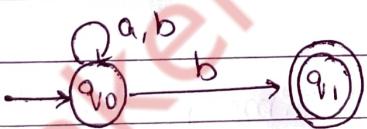
Example

- i) Write a NFSM to accept the language
 $L = \{w \in \{a, b\}^* \mid |w| \text{ ends in } b\}$.

Sol $\Sigma = \{a, b\}$ Regular Expression : $(a+b)^* b$

Min String b.

Sample String = {b, bb, bbb, aaab, ababb, ...}

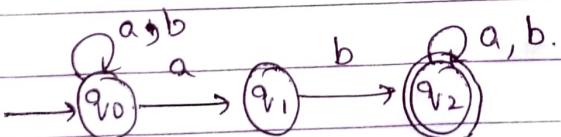


- ii) Write NFSM to recognize $L = \{w \in \{a, b\}^* \mid |w| \text{ contains } ab\}$

Sol $\Sigma = \{a, b\}$

Min String = a, b.

Regular Expression $(a+b)^* ab(a+b)^*$



Sample Strings : {aab, aabb, baab, ...}

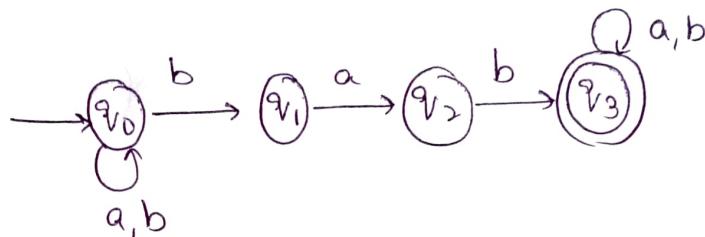
3) Design NFSM that accepts strings of a's and b's that contain substring bab.

Sol, $\Sigma = \{a, b\}$

$$Q = \{q_0, q_1, q_2, q_3\}$$

$$S = q_0 \text{ (Initial)}$$

$$F = q_3 \text{ (Final)}$$

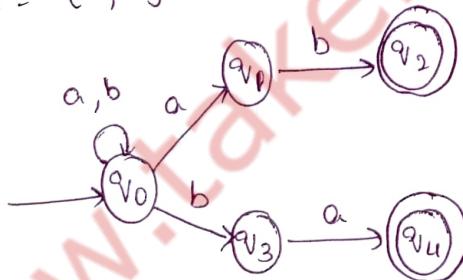


Δ	a	b
$\rightarrow q_0$	q_0	$\{q_0, q_1\}$
q_1	q_2	-
q_2	-	b
* q_3	q_3	q_3

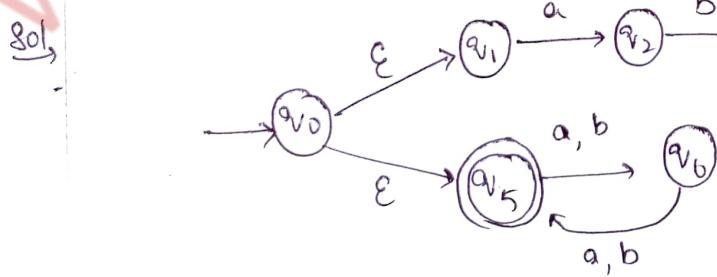
4) July 2019
Design a NFSM that accept the language
 $L = \{w \in \{a, b\}^* \mid w \text{ ends in } ab \text{ or } ba\}$

Sol, Regular expression : $(ab)^* (ab + ba)$

$$\Sigma = \{a, b\}$$



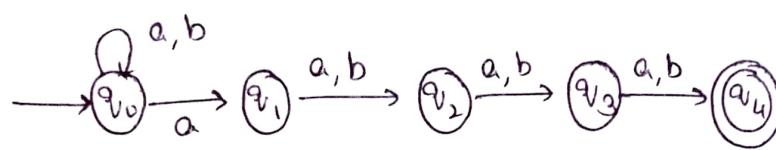
5) Design NFSM. $L = \{w \in \{a, b\}^* \mid w = aba \text{ or } |w| \text{ is even}\}$



6) Design a NFSM.

$L = \{w \in \{a,b\}^* \mid \text{Not starting the 4^{th} character from right is } a\}$.

Sol,



$$\Sigma = \{a, b\}$$

$$Q = \{q_0, q_1, q_2, q_3, q_4\}$$

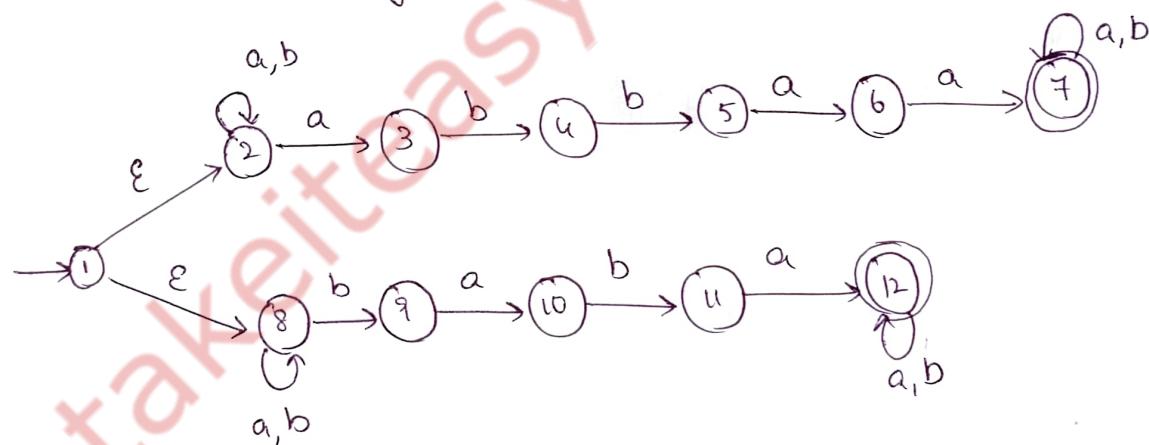
$$S = q_0 \text{ (Initial)}$$

$$F = q_4 \text{ (final / End state)}$$

Δ	a	b
q_{v_0}	$\{q_{v_0}, q_{v_1}\}$	q_{v_0}
q_{v_1}	q_{v_2}	q_{v_2}
q_{v_2}	q_{v_3}	q_{v_3}
q_{v_3}	q_{v_4}	q_{v_4}
q_{v_4}	-	-

7) Design a NFSM

$L = \{w \in \{a,b\}^* \mid \forall x, y \in \{a,b\}^*, w = (xabbay) \vee w = (xbabay)\}$



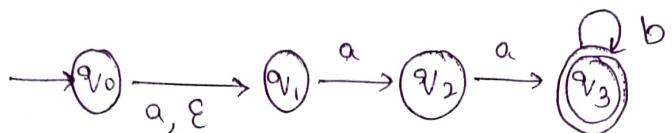
8) Write a NFSM to recognise the language.

$L = \{w \in \{a,b\}^* \mid w \text{ is made up of an optional } a \text{ followed by } a, \text{ zero or more } b's\}$

Sol

$$\Sigma = \{a, b\}$$

$$\text{Regular Expression.} = (a + \epsilon)aa(b)^*$$



Equivalence of NDFSM and DFSM.

We can say NFSM and DFSM are equivalent when the language accepted by both are same.

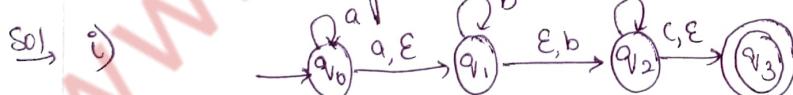
Epsilon closures of state 'q'

It is defined as a set of states that is reachable from q on Epsilon transition only.

$$\text{eps}(q) = \{p \in K : (q, \omega) \xrightarrow{*} (p, \omega)\}$$

Examples

i) Compute epsilon closures for all the states given in the transition diagrams



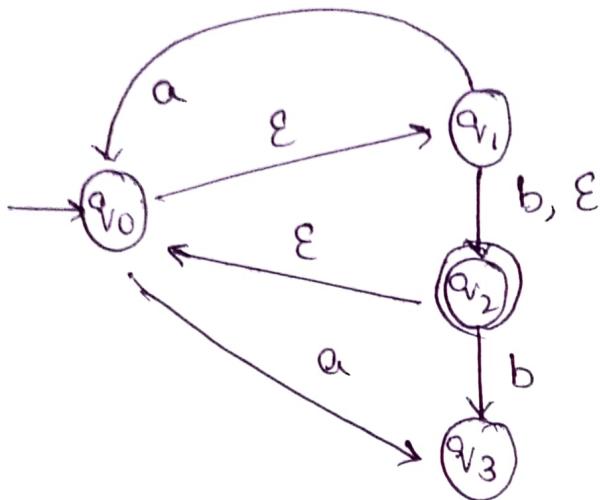
$$\text{eps}(q_0) = \{q_0, q_1, q_2, q_3\}$$

$$\text{eps}(q_1) = \{q_1, q_2, q_3\}$$

$$\text{eps}(q_2) = \{q_2, q_3\}$$

$$\text{eps}(q_3) = \{q_3\}$$

ii)



$$\text{Eps}(qv_0) = \{qv_0, qv_1, qv_2\}$$

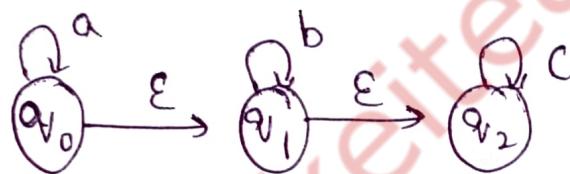
$$\text{Eps}(qv_1) = \{qv_1, qv_2, qv_0\}$$

$$\text{Eps}(qv_2) = \{qv_0, qv_1, qv_2\}$$

$$\text{Eps}(qv_3) = \{qv_3\}$$

NOTE : $\text{eps}(\text{any state}) = \{\text{that state is always included}\}$

iii)



$$\text{Eps}(qv_0) = \{qv_0, qv_1, qv_2\}$$

$$\text{Eps}(qv_1) = \{qv_1, qv_2\}$$

$$\text{Eps}(qv_2) = \{qv_2\}$$

Conversion of NDFSM to DFSM.

Let $M_N = (Q_N, \Sigma_N, S_N, q_0, A_N)$ be an NDFSM and accepts the language $L(M_N)$. There should be an equivalent DFSM $M_D = (Q_D, \Sigma_D, S_D, q_0, A_D)$ such that $L(M_D) = L(M_N)$. The procedure to convert an NDFSM to its equivalent DFSM is shown below.

Step 1

The state i.e. start state of NDFSM M_N is the start state of DFSM M_D . So add q_0 (which is the start state of NDFSM) to Q_D and find the transitions from this state. The way to obtain different transitions is shown in Step 2.

Step 2

For each state $[q_i, q_j, \dots, q_k]$ in Q_D , the transitions for each input symbol in Σ can be obtained as below

$$\begin{aligned} \Rightarrow S_D([q_i, q_j, \dots, q_k], a) &= S_N(q_i, a) \cup S_N(q_j, a) \cup \dots \cup S_N(q_k, a) \\ &= [q_m, q_n, \dots] \text{ say.} \end{aligned}$$

2) Add the state $[q_1, q_m, \dots, q_n]$ to Q_D if it's not already present in Q_D .

3) Add the transition from $[q_i, q_j, \dots, q_k]$ to $[q_1, q_m, \dots, q_n]$ on the input symbol a iff the state $[q_1, q_m, \dots, q_n]$ is added to Q_D in b4 step.

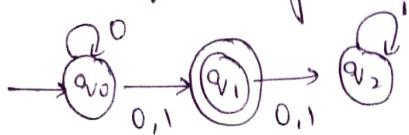
Step 3 4) The state $[q_a, q_b, \dots, q_c] \in Q_D$ is the final state, if atleast one of the state in $[q_a, q_b, \dots, q_c \in A_N]$ i.e. atleast one component in $[q_a, q_b, \dots, q_c]$ should be final state of NDFSM.

Step 4

If epsilon (ϵ) is accepted by NDFSM, then start state q_0 of DFSM is made the final state.

Jan 2019

Q) Convert the following NDFSM to DFSM



Step 1 q_0 is start of DFSM

$$\text{So, } Q_D = \{[q_0]\}$$

Step 2 Find the new states from each state in Q_D .

Consider $[q_0]$:

$$\text{when } a=0, \quad S_D([q_0], 0) = S_N([q_0, 0]) \\ = [q_0, q_1]$$

$$\text{when } a=1, \quad S_D([q_0], 1) = S_N([q_0], 1) \\ = [q_1]$$

$$\text{So, Now, } Q_D = \{[q_0], [q_0, q_1], [q_1]\}$$

Now consider $[q_0, q_1]$.

$$\text{when } a=0, \quad S_D([q_0, q_1], 0) = S_N([q_0, q_1], 0) \\ = S_N(q_0, 0) \cup S_N(q_1, 0) \\ = \{q_0, q_1\} \cup \{q_2\} \\ = [q_0, q_1, q_2]$$

$$\text{when } a=1, \quad S_D([q_0, q_1], 1) = S_N([q_0, q_1], 1) \\ = S_N(q_0, 1) \cup S_N(q_1, 1) \\ = \{q_1\} \cup \{q_2\} \\ = [q_1, q_2]$$

$$\text{So, Now, } Q_D = \{[q_0], [q_0, q_1], [q_1], [q_0, q_1, q_2], [q_1, q_2]\}$$

Consider state $[q_1]$

$$\text{when } a=0, \quad S_D([q_1], 0) = S_N([q_1], 0) \\ = [q_2]$$

$$\text{when } a=1, \quad S_D([q_1], 1) = S_N([q_1], 1) \\ = [q_2]$$

So now,

$$S_D = \{[q_0], [q_0, q_1], [q_1], [q_0, q_1, q_2], [q_1, q_2]\}$$

Consider state $[q_0, q_1, q_2]$

$$\text{when } a=0, \quad S_D([q_0, q_1, q_2], 0) = S_N([q_0, q_1, q_2], 0) \\ = S_N(q_0, 0) \cup S_N(q_1, 0) \cup S_N(q_2, 0) \\ = \{q_0\} \cup \{q_1\} \cup \{\emptyset\} \\ = [q_0, q_1, q_2]$$

$$\text{when } a=1, \quad S_D([q_0, q_1, q_2], 1) = S_N([q_0, q_1, q_2], 1) \\ = S_N(q_0, 1) \cup S_N(q_1, 1) \cup S_N(q_2, 1) \\ = \{q_1\} \cup \{q_2\} \cup \{\emptyset\} \\ = [q_1, q_2]$$

So, the states obtained are

not new states. $\therefore S_D$ remains same.

Consider state $[q_1, q_2]$

$$\text{when } a=0, \quad S_D([q_1, q_2], 0) = S_N([q_1, q_2], 0) \\ = S_N(q_1, 0) \cup S_N(q_2, 0) \\ = \{q_2\} \cup \{\emptyset\} \\ = [q_2]$$

$$\text{when } a=1, \quad S_D([q_1, q_2], 1) = S_N([q_1, q_2], 1) \\ = S_N(q_1, 1) \cup S_N(q_2, 1) \\ = \{q_2\} \cup \{q_2\} \\ = [q_2]$$

Since, the states obtained are not new,

S_D remains same.

Consider state $[q_2]$

$$\text{when } a=0, \quad S_D([q_2], 0) = S_N([q_2], 0) \\ = \{\emptyset\}$$

$$\text{when } a=1, \quad S_D([q_2], 1) = S_N([q_2], 1) \\ = [q_2]$$

Since, the states obtained are not new states,

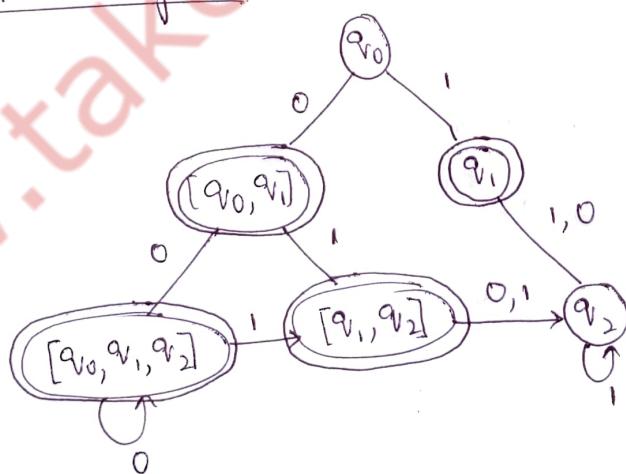
Q_D remains same.

$$Q_D = \{[q_0], [q_1, q_2], [q_2], [q_0, q_1, q_2] [q_0, q_1] [q_1]\}$$

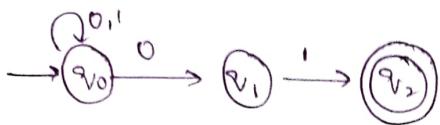
Transition Table

S	0	1
q_0	$[q_0, q_1]$	$[q_1]$
$[q_0, q_1]$	$[q_0, q_1, q_2]$	$[q_1, q_2]$
$[q_1]$	$[q_2]$	$[q_2]$
$[q_0, q_1, q_2]$	$[q_0, q_1, q_2]$	$[q_1, q_2]$
$[q_1, q_2]$	$[q_2]$	$[q_2]$
$[q_2]$	\emptyset	$[q_2]$

Transition Diagram



2) Convert NFA into DFA



Step 1

$[q_0]$ is starting state of DFA.

$$Q_D = [q_0].$$

Step 2

consider q_0 .

$$\text{when } a=0, \quad S_D([q_0], 0) = S_N([q_0], 0)$$
$$= [q_0, q_1]$$

$$\text{when } a=1, \quad S_D([q_0], 1) = S_N([q_0], 1)$$
$$= [q_0].$$

$$\text{now, } Q_D = \{[q_0], [q_0, q_1]\}$$

consider $[q_0, q_1]$

$$\text{when } a=0, \quad S_D([q_0, q_1], 0) = S_N([q_0, q_1], 0)$$
$$= S_N(q_0, 0) \cup S_N(q_1, 0)$$
$$= [q_0, q_1] \cup \{\emptyset\}$$
$$= [q_0, q_1]$$

$$\text{when } a=1, \quad S_D([q_0, q_1], 1) = S_N([q_0, q_1], 1)$$
$$= S_N(q_0, 1) \cup S_N(q_1, 1)$$
$$= \{q_0\} \cup \{q_1\}$$
$$= [q_0, q_1]$$

$$Q_D = \{[q_0], [q_0, q_1], [q_0, q_2]\}$$

Consider $[q_0, q_2]$

$$\text{when } a=0, \quad S_D([q_0, q_2], 0) = S_N([q_0, q_2], 0)$$

$$= S_N(q_0, 0) \cup S_D(q_2, 0)$$

$$= [q_0, q_1]$$

$$\text{when } a=1, \quad S_N([q_0, q_2], 1) = S_N([q_0, q_2], 1)$$

$$= S_N(q_0, 1) \cup S_N(q_2, 1)$$

$$= \{q_0\} \cup \{\emptyset\}$$

$$= \{q_0\}$$

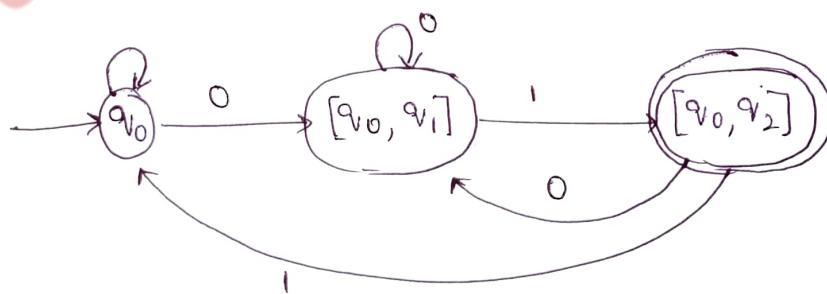
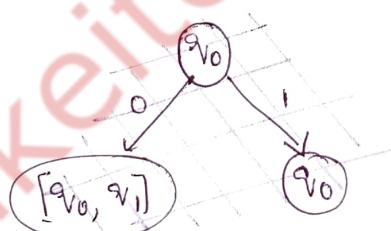
Since, obtained states are not new,

$$Q_D \text{ remains same. } \Rightarrow Q_D = \{[q_0], [q_0, q_1], [q_0, q_2]\}$$

Transition Table.

	g	0	1
\rightarrow	$[q_0]$	$[q_0, q_1]$	$[q_0]$
	$[q_0, q_1]$	$[q_0, q_1]$	$[q_0, q_2]$
*	$[q_0, q_2]$	$[q_0, q_1]$	$[q_0]$

Transition Diagram.

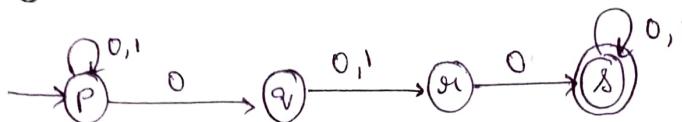


Convert NFSM to DFSM

3)

	0	1
$\rightarrow P$	$\{P, \gamma\}$	P
γ	γ	$\{\gamma\}$
δ	δ	\emptyset
*	S	δ

Sol



Step 1

$Q_D = \{P\}$ is starting state

Step 2

consider $[P]$

$$\text{when } a=0, \quad S_D[P, 0] = S_N[P, 0]$$

$$= [P, \gamma]$$

$$= [P, \gamma]$$

$$\text{when } a=1, \quad S_D[P, 1] = S_N[P, 1]$$

$$= [P].$$

Now,

$$Q_D = \{[P], [P, \gamma]\}$$

consider $[P, \gamma]$

$$\text{when } a=0, \quad S_D[(P, \gamma), 0] = S_N[(P, \gamma), 0]$$

$$= S_N(P, 0) \cup S_N(\gamma, 0)$$

$$= [P, \gamma] \cup \{\gamma\}$$

$$= [P, \gamma, \gamma]$$

$$\text{when } a=1, \quad S_D[(P, \gamma), 1] = S_N[(P, \gamma), 1]$$

$$= S_N(P, 1) \cup S_N(\gamma, 1)$$

$$= \{P\} \cup \{\gamma\}$$

$$= [P, \gamma]$$

Now,

$$Q_D = \{[P], [P, \gamma], [P, \gamma, \gamma], [P, \gamma]\}$$

Consider $[P, \gamma]$

$$\begin{aligned}\text{when } a=0, \quad S_D([P, \gamma], 0) &= S_N([P, \gamma], 0) \\ &= S_N(P, 0) \cup S_N(\gamma, 0) \\ &= \{P, \gamma\} \cup \{\gamma\} \\ &= [P, \gamma, \delta]\end{aligned}$$

when $a=1$, $S_D([P, \gamma], 1) = S_N([P, \gamma], 1)$

$$\begin{aligned}&= S_N(P, 1) \cup S_N(\gamma, 1) \\ &= \{P\} \cup \{\emptyset\} \\ &= [P]\end{aligned}$$

$$Q_D = \{[P], [P, \gamma], [P, \gamma, \gamma], [P, \gamma], [P, \gamma, \delta]\}$$

Consider $[P, \gamma, \tau]$.

$$\begin{aligned}\text{when } a=0, \quad S_D([P, \gamma, \tau], 0) &= S_N([P, \gamma, \tau], 0) \\ &= S_N(P, 0) \cup S_N(\gamma, 0) \cup S_N(\tau, 0) \\ &= \{P, \gamma\} \cup \{\gamma\} \cup \{\tau\} \\ &= [P, \gamma, \tau, \delta]\end{aligned}$$

when $a=1$, $S_D([P, \gamma, \tau], 1) = S_N([P, \gamma, \tau], 1)$

$$\begin{aligned}&= S_N(P, 1) \cup S_N(\gamma, 1) \cup S_N(\tau, 1) \\ &= \{P\} \cup \{\gamma\} \cup \{\emptyset\} \\ &= [P, \tau]\end{aligned}$$

$$Q_D = \{[P], [P, \gamma], [P, \gamma, \tau], [P, \gamma], [P, \gamma, \delta], [P, \gamma, \tau, \delta]\}$$

Consider $[P, \gamma, \tau, \delta]$

$$\begin{aligned}\text{when } a=0, \quad S_D([P, \gamma, \tau, \delta], 0) &= S_N([P, \gamma, \tau, \delta], 0) \\ &= S_N(P, 0) \cup S_N(\gamma, 0) \cup S_N(\tau, 0) \cup S_N(\delta, 0) \\ &= \{P, \gamma\} \cup \{\gamma\} \cup \{\tau\} \cup \{\delta\} \\ &= [P, \gamma, \tau, \delta]\end{aligned}$$

when $a=1$, $S_D([P, \gamma, \tau, \delta], 1) = S_N([P, \gamma, \tau, \delta], 1)$

$$\begin{aligned}&= S_N(P, 1) \cup S_N(\gamma, 1) \cup S_N(\tau, 1) \cup S_N(\delta, 1) \\ &= \{P\} \cup \{\gamma\} \cup \{\tau\} \cup \{\delta\} \\ &= [P, \tau, \delta]\end{aligned}$$

$$Q_D = \{[P], [P, \gamma], [P, \gamma, \tau], [P, \gamma], [P, \gamma, \delta], [P, \gamma, \tau, \delta], [P, \tau, \delta]\}$$

Consider $[P, Q, S]$

$$\begin{aligned}\text{when } a=0, \quad S_D[[P, Q, S], 0] &= S_N[[P, Q, S], 0] \\ &= S_N(P, 0) \cup S_N(Q, 0) \cup S_N(S, 0) \\ &= \{P, Q\} \cup \{\bar{Q}\} \cup \{\bar{S}\} \\ &= [P, Q, \bar{Q}, \bar{S}]\end{aligned}$$

$$\begin{aligned}\text{when } a=1, \quad S_D[[P, Q, S], 1] &= S_N[[P, Q, S], 1] \\ &= S_N(P, 1) \cup S_N(Q, 1) \cup S_N(S, 1) \\ &= [P, Q, S]\end{aligned}$$

Consider $[P, R, S]$

$$\begin{aligned}\text{when } a=0, \quad S_D[[P, R, S], 0] &\neq S_N[[P, R, S], 0] \\ &= S_N(P, 0) \cup S_N(R, 0) \cup S_N(S, 0) \\ &= \{P, Q\} \cup \{\bar{S}\} \cup \{\bar{S}\} \\ &= [P, Q, \bar{S}]\end{aligned}$$

$$\begin{aligned}\text{when } a=1, \quad S_D[[P, R, S], 1] &= S_N[[P, R, S], 0] \\ &= S_N(P, 0) \cup S_N(R, 0) \cup S_N(S, 0) \\ &= [P] \overset{0}{\cancel{\cup}} [\bar{S}] \\ &= [P, \bar{S}]\end{aligned}$$

Consider $[P, S]$

$$\begin{aligned}\text{when } a=0, \quad S_D[[P, S], 0] &= S_N[[P, S], 0] \\ &= S_N(P, 0) \cup S_N(S, 0) \\ &= \{P, Q\} \cup \{\bar{S}\} \\ &= [Q, P, \bar{S}]\end{aligned}$$

$$\begin{aligned}\text{when } a=1, \quad S_D[[P, S], 1] &= S_N[[P, S], 1] \\ &= S_N(P, 1) \cup S_N(S, 1) \\ &= [P] \cup \{\bar{S}\} \\ &= [P, \bar{S}]\end{aligned}$$

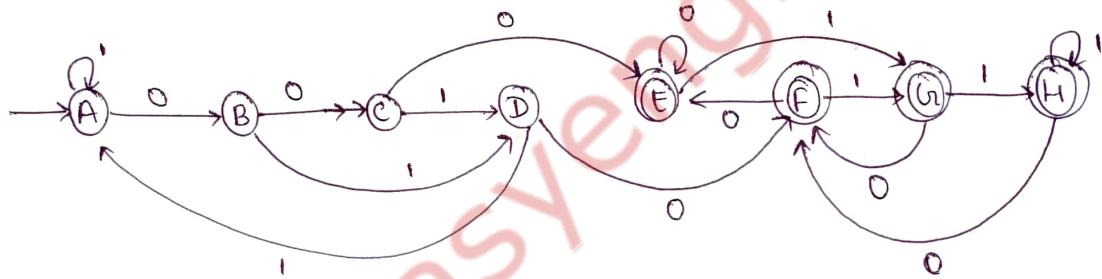
\therefore we arrive at

$$S_D = \{[P], [P, Q], [P, \bar{Q}], [P, R], [P, \bar{R}], [P, S], [P, \bar{S}], [Q, P, \bar{S}]\}.$$

Transition Table

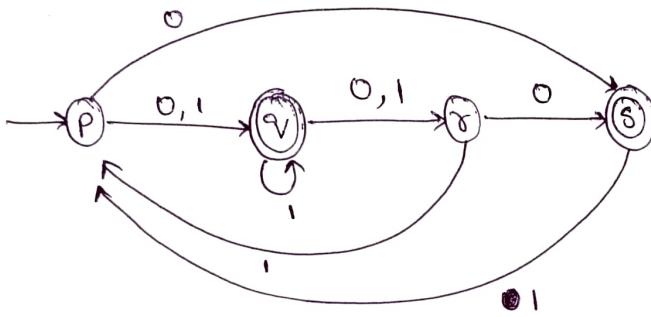
	S	O	I
$\rightarrow A = [P]$	B $[P, \varphi]$	A $[P]$	
$B = [P, \varphi]$	C $[P, \varphi, \gamma]$	D $[P, \gamma]$	
$C = [P, \varphi, \gamma]$	E $[P, \varphi, \gamma, \delta]$	D $[P, \gamma]$	
$D = [P, \delta]$	F $[P, \varphi, \delta]$	A $[P]$	
* $E = [P, \varphi, \gamma, \delta]$	G $[P, \varphi, \gamma, \delta]$	H $[P, \gamma, \delta]$	
* $F = [P, \varphi, \delta]$	G $[P, \varphi, \gamma, \delta]$	H $[P, \gamma, \delta]$	
* $G = [P, \gamma, \delta]$	F $[P, \varphi, \delta]$	H $[P, \delta]$	
* $H = [P, \delta]$	F $[P, \varphi, \delta]$	H $[P, \delta]$	

Transition Diagram



4) Convert the following NDFSM into DFMS.

S	O	I
→ P	{q ₁ , q ₂ }	q ₃
* q ₁	{q ₂ }	{q ₁ , q ₂ }
r	• S	{P}
* s	Ø	{P}



Step 1

Consider P, initial state of DFMS.

$$Q_D = \{P\}$$

Step 2

Consider P
when $a=0$, $S_D(P, 0) = S_N(P, 0)$
 $= \{q_1, q_2\}$

when $a=1$, $S_D(P, 1) = S_N(P, 1)$
 $= \{q_3\}$

NOW,

$$Q_D = \{[P], [q_1], [q_1, q_2]\}$$

Consider [q₁]
when $a=0$, $S_D(q_1, 0) = S_N(q_1, 0)$
 $= \{\gamma\}$

when $a=1$, $S_D(q_1, 1) = S_N(q_1, 1)$
 $= \{q_1, \gamma\}$

NOW,

$$Q_D = \{[P], [q_1], [q_1, q_2], [\gamma], [q_1, \gamma]\}$$

Consider $[q, s]$

when $a=0$, $S_D([q, s], 0) = S_N([q, s], 0)$
= $S_N\{(q, 0) \cup (s, 0)\}$
= $[r]$

when $a=1$, $S_D([q, s], 1) = S_N([q, s], 1)$
= $S_N\{(q, 1) \cup (s, 1)\}$
= $[q, r, p]$

$$\Omega_D = \{[p], [q], [q, s], [r], [q, r], [q, r, p]\}$$

Consider $[r]$

when $a=0$, $S_D(r, 0) = S_N(r, 0)$
= $[s]$

when $a=1$, $S_D(r, 1) = S_N(r, 1)$
= $[p]$

Consider $[q, r]$

when $a=0$, $S_D([q, r], 0) = S_N([q, r], 0)$
= $S_N\{(q, 0) \cup (r, 0)\}$
= $[r, s]$

when $a=1$, $S_D([q, r], 1) = S_N([q, r], 1)$
= $S_N\{(q, 1) \cup (r, 1)\}$
= $[q, r, p]$

$$\Omega_D = \{[p], [q], [q, s], [r], [q, r], [q, r, p], [s], [r, s], [q, r, s]\}$$

Consider $[q, r, p]$

when $a=0$, $S_D([q, r, p], 0) = S_N([q, r, p], 0)$
= $S_N(q, 0) \cup S_N(r, 0) \cup S_N(p, 0)$
= $[r, s, q]$

when $a=1$, $S_D([q, r, p], 1) = S_N([q, r, p], 1)$
= $S_N\{(q, 1) \cup (r, 1) \cup (p, 1)\}$
= $[q, r, p]$

$$\Omega_D = \{[p], [q], [q, s], [r], [q, r], [q, r, p], [s], [r, s], [q, r, s]\}$$

Consider $[s]$

$$\text{when } a=0, S_D([s], 0) = S_N([s], 0)$$
$$= \{\emptyset\}$$

$$\text{when } a=1, S_D([s], 1) = S_N([s], 1)$$
$$= [P]$$

Consider $[v, r, s]$

$$\text{when } a=0, S_D([v, r, s], 0) = S_N([v, r, s], 0)$$
$$= S_N\{(v, 0) \cup (r, 0) \cup (s, 0)\}$$
$$= [r, s] \quad \text{∅}$$

$$\text{when } a=1, S_D([v, r, s], 1) = S_N([v, r, s], 1)$$
$$= S_N\{(v, 1) \cup (r, 1) \cup (s, 1)\}$$
$$= [v, r, P] = [P, v, r]$$

Consider $[r, s]$

$$\text{when } a=0, S_D([r, s], 0) = S_N([r, s], 0)$$
$$= S_N(r, 0) \cup S_N(s, 0)$$
$$= \{s, \emptyset\}$$
$$= [s]$$

$$\text{when } a=1, S_D([r, s], 1) = S_N([r, s], 1)$$
$$= S_N\{[r, 1] \cup [s, 1]\}$$
$$= \{P\} \cup \{P\}$$
$$= [P]$$

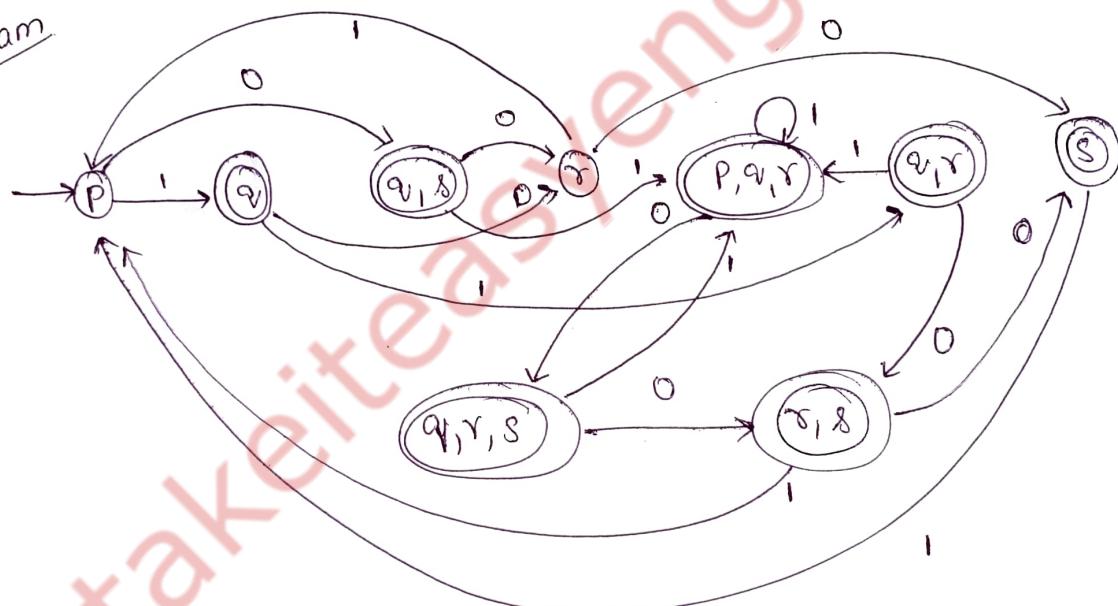
Therefore, we have

$$Q_D = [P, J, [v], [v, r], [v, s], [r], [r, s], [s], [v, r, s], [v, r, P]]$$

Transition Table

	δ	0	1
\rightarrow	[P]	[q ₁ , s]	[q ₁]
*	[q ₁]	[q ₁]	[q ₁ , s]
*	[q ₁ , s]	[r]	[P, q ₁ , r]
*	[r]	[s]	[P]
*	[P, q ₁ , r]	[q ₁ , r, s]	[P, q ₁ , r]
*	[q ₁ , r]	[r, s]	[q ₁ , r, P]
*	[s]	\emptyset	[P]
*	[q ₁ , r, s]	[r, s]	[P, q ₁ , r]
*	[r, s]	[s]	[P]

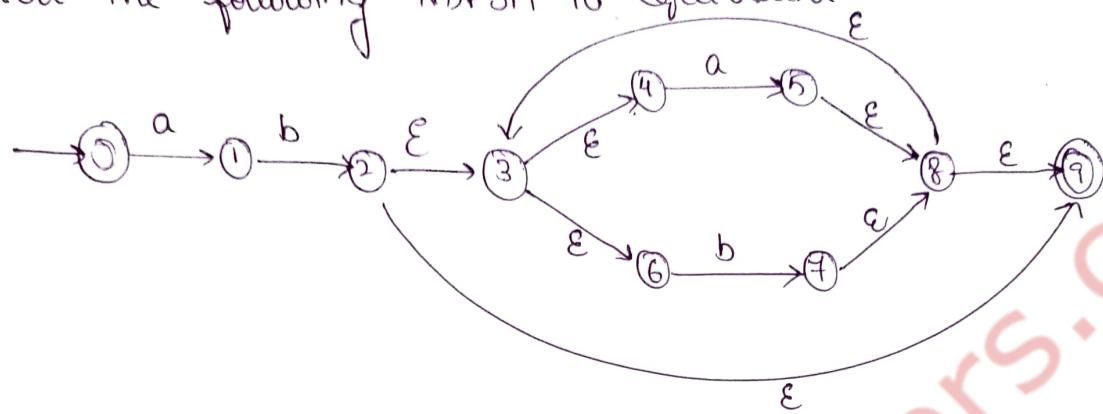
Transition
Diagram



Jan 2018

ϵ - NDFSM to DFSM.

- 1) Convert the following NDFSM to equivalent DFSM



Sol, Starting State: ϵ closure $[0] = [0]$.

$$Q_D = [0]$$

Consider $Q_D = [0]$, initial state.

On input symbol 'a' and 'b'

$$\text{when } \cancel{a} : S_D[[0], a] = \epsilon\text{-closure}(S_N[0, a]) \\ = \epsilon\text{-closure}(1) \\ = [1]$$

$$\text{when } \cancel{b} ; S_D[[0], b] = \epsilon\text{-closure}(S_N[0, b]) \\ = \epsilon\text{-closure}(\emptyset) \\ = \emptyset$$

Now,

$$Q_D = \{[0], [1]\}$$

Consider $[1]$

On input symbols 'a' and 'b'

$$\text{when } a : S_D[[1], a] = \epsilon\text{-closure}(S_N(1, a)) \\ = \epsilon\text{-closure}(\emptyset) \\ = \emptyset$$

$$\text{when } b : S_D[[1], b] = \epsilon\text{-closure}(S_N(1, b)) \\ = \epsilon\text{-closure}(2) \\ = [2, 3, 4, 6, 9]$$

Now,

$$Q_D = \{[0], [1], [2, 3, 4, 6, 9]\}$$

Consider $[2, 3, 4, 6, 9]$

On inputs "a" and 'b'

when a : $S_D([2, 3, 4, 6, 9], a) = \text{E-Closure}[S_N([2, 3, 4, 6, 9], a)]$

$$= \text{E-Closure}[S_N\{2; a\} \cup \{3, a\} \cup \{4, a\} \cup \{6, a\} \cup \{9, a\}^y]$$
$$= \text{E-Closure}[\emptyset \cup \emptyset \cup \{5\} \cup \emptyset]$$
$$= \text{E-Closure}[5]$$
$$= [3, 4, 5, 6, 8, 9]$$

when b : $S_D([2, 3, 4, 6, 9], b) = \text{E-Closure}[S_N([2, 3, 4, 6, 9], b)]$

$$= \text{E-Closure}[S_N\{2, b\} \cup \{3, b\} \cup \{4, b\} \cup \{6, b\} \cup \{9, b\}^y]$$
$$= \text{E-Closure}[7]$$
$$= [7, 8, 9, 3, 4, 6] = [3, 4, 6, 7, 8, 9]$$

$$Q_D = \{[0], [1], [2, 3, 4, 6, 9], [3, 4, 5, 6, 8, 9], [3, 4, 6, 7, 8, 9]\}$$

Consider $[3, 4, 5, 6, 8, 9]$

when b : $S_D([3, 4, 5, 6, 8, 9], b) = \text{E-Closure}[S_N([3, 4, 5, 6, 8, 9], b)]$

$$= \text{E-Closure}[S_N\{3, b\} \cup \{4, b\} \cup \{5, b\} \cup \{6, b\} \cup \{8, b\} \cup \{9, b\}^y]$$
$$= \text{E-Closure}[7]$$
$$= [3, 4, 6, 7, 8, 9]$$

when a : $S_D([3, 4, 5, 6, 8, 9], a) = \text{E-Closure}[S_N([3, 4, 5, 6, 8, 9], a)]$

$$= \text{E-Closure}[S_N\{3, a\} \cup \{4, a\} \cup \{5, a\} \cup \{6, a\} \cup \{8, a\} \cup \{9, a\}^y]$$
$$= \text{E-Closure}[5]$$
$$= [3, 4, 5, 6, 8, 9]$$

Consider $\{3, 4, 6, 7, 8, 9\}$

On a:

$$\begin{aligned}
 S_D[\{3, 4, 6, 7, 8, 9\}, a] &= \text{E-Closure}[S_N[\{3, 4, 6, 7, 8, 9\}, a]] \\
 &= \text{E-Closure}[S_N\{(3, a) \cup (4, a) \cup (6, a) \cup \\
 &\quad (7, a) \cup (8, a) \cup (9, a)\}] \\
 &= \text{E-Closure}[5] \\
 &= \{3, 4, 5, 6, 8, 9\}
 \end{aligned}$$

On b:

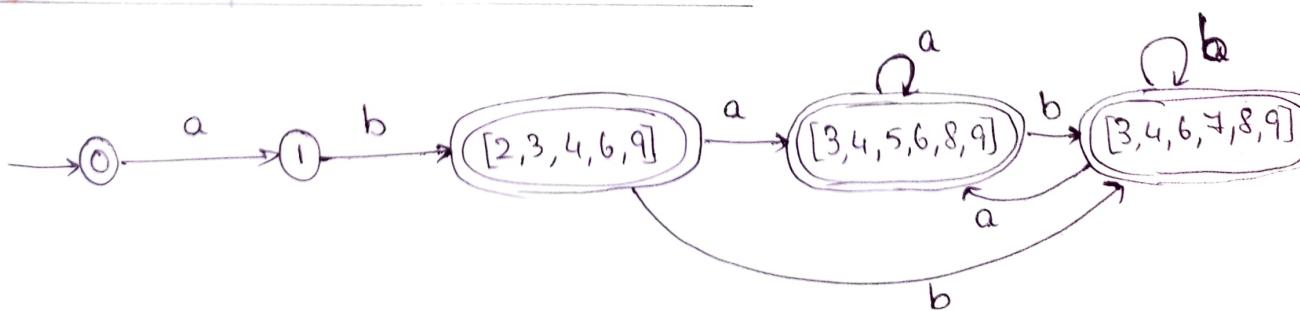
$$\begin{aligned}
 S_D[\{3, 4, 6, 7, 8, 9\}, b] &= \text{E-Closure}[S_N[\{3, 4, 6, 7, 8, 9\}, b]] \\
 &= \text{E-Closure}[S_N\{(3, b) \cup (4, b) \cup (6, b) \cup (7, b) \\
 &\quad \cup (8, b) \cup (9, b)\}] \\
 &= \text{E-Closure}[7] \\
 &= \{3, 4, 6, 7, 8, 9\}
 \end{aligned}$$

Now, we have.

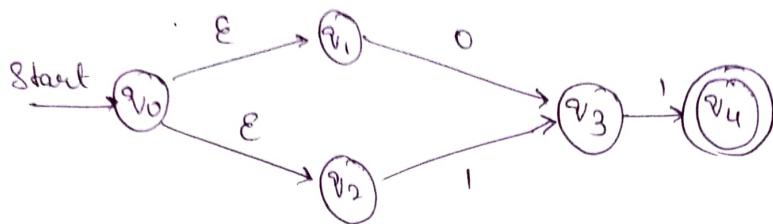
$$Q_D = \{[0], [1], [2, 3, 4, 6, 9], [3, 4, 5, 6, 8, 9], [3, 4, 6, 7, 8, 9]\}$$

Table

	S	a	b
\rightarrow	[0]	[1]	-
	[1]	-	[2, 3, 4, 6, 9]
*	[2, 3, 4, 6, 9]	[3, 4, 5, 6, 8, 9]	[3, 4, 6, 7, 8, 9]
*	[3, 4, 5, 6, 8, 9]	[3, 4, 5, 6, 8, 9]	[3, 4, 6, 7, 8, 9]
*	[3, 4, 6, 7, 8, 9]	[3, 4, 6, 8, 9]	[3, 4, 6, 7, 8, 9]



2) Convert the \in NDFSM into equivalent DFSM.



Sol → Let us obtain ϵ closures of each other.

$$\epsilon\text{-closure } [v_0] = [v_0, v_1, v_2] \quad \dots \quad ①$$

$$\epsilon\text{-closure } [v_1] = [v_1]$$

$$\epsilon\text{-closure } [v_2] = [v_2]$$

$$\epsilon\text{-closure } [v_3] = [v_3]$$

$$\epsilon\text{-closure } [v_4] = [v_4]$$

Consider $[v_0, v_1, v_2]$: $S_D = [v_0, v_1, v_2]$

On input symbol '0' and '1'

when 0, $S_D([v_0, v_1, v_2], 0) = \epsilon\text{-closure } [S_N([v_0, v_1, v_2], 0)]$
 $= \epsilon\text{-closure } [S_N \{ (v_0, 0) \cup (v_1, 0) \cup (v_2, 0) \}]$
 $= \epsilon\text{-closure } [\emptyset \cup v_3 \cup \emptyset]$
 $= \epsilon\text{-closure } [v_3] = [v_3]$

when 1, $S_D([v_0, v_1, v_2], 1) = \epsilon\text{-closure } [S_N([v_0, v_1, v_2], 1)]$
 $= \epsilon\text{-closure } [S_N \{ (v_0, 1) \cup (v_1, 1) \cup (v_2, 1) \}]$
 $= \epsilon\text{-closure } [\emptyset \cup \emptyset \cup v_3]$
 $= [v_3]$

$$S_D = \{[v_0, v_1, v_2], [v_3]\}.$$

consider $[v_3]$

when input symbol is 0 : $S_D([v_3], 0) = \epsilon\text{-closure } [S_D([v_3], 0)]$
 $= \epsilon\text{-closure } (\emptyset)$
 $= \emptyset$

When input symbol is 1

$$\begin{aligned} S_D([q_3], 1) &= \text{\textit{\varepsilon}}\text{-Closure}(S_N([q_3], 1)) \\ &= \text{\textit{\varepsilon}}\text{-Closure}(q_4) \\ &= [q_4] \end{aligned}$$

$$S_D = \{[q_0, q_1, q_2], [q_3], [q_4]\}.$$

Consider $[q_4]$

When input symbol is 0 : $S_D([q_4], 0) = \text{\textit{\varepsilon}}\text{-Closure}([S_D(q_4), 0])$

$$\begin{aligned} &= \text{\textit{\varepsilon}}\text{-Closure}(\emptyset) \\ &= \emptyset. \end{aligned}$$

When input symbol is 1 : $S_D([q_4], 1) = \text{\textit{\varepsilon}}\text{-Closure}[S_D(q_4), 1]$

$$\begin{aligned} &= \text{\textit{\varepsilon}}\text{-Closure}(\emptyset) \\ &= \emptyset. \end{aligned}$$

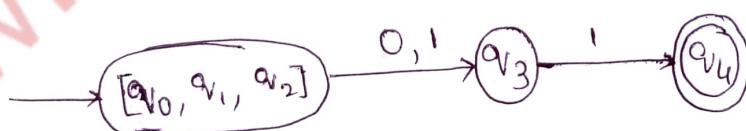
We have,

$$S_D = \{[q_0, q_1, q_2], [q_3], [q_4]\}$$

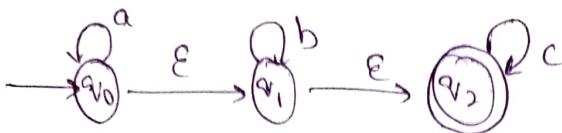
Transition Table.

δ	0	1
$\rightarrow [q_0, q_1, q_2]$	q_3	q_3
$[q_3]$	-	q_4
* $[q_4]$	-	-

Transition Diagram of Obtained DFSA.



3) Convert ϵ -NFSM into equivalent DFSM.



\Rightarrow

$$\epsilon\text{-Closure } (q_0) = [q_0, q_1, q_2]$$

$$\epsilon\text{-Closure } (q_1) = [q_1, q_2]$$

$$\epsilon\text{-Closure } (q_2) = [q_2]$$

Starting with $\epsilon\text{-Closure } (q_0) = [q_0, q_1, q_2]$

$$Q_D = [q_0, q_1, q_2]$$

Consider $[q_0, q_1, q_2]$

On input signal a

$$\begin{aligned} S_D[[q_0, q_1, q_2], a] &= \epsilon\text{-Closure } (S_N([q_0, q_1, q_2], a)) \\ &= \epsilon\text{-Closure } (S_N \{ (q_0, a) \cup (q_1, a) \cup (q_2, a) \}) \\ &= \epsilon\text{-Closure } (q_0 \cup \emptyset \cup \emptyset) \\ &= \epsilon\text{-Closure } (q_0) = [q_0, q_1, q_2] \end{aligned}$$

On input signal b

$$\begin{aligned} S_D[[q_0, q_1, q_2], b] &= \epsilon\text{-Closure } (S_N([q_0, q_1, q_2], b)) \\ &= \epsilon\text{-Closure } (S_N \{ (q_0, b) \cup (q_1, b) \cup (q_2, b) \}) \\ &= \epsilon\text{-Closure } (\emptyset \cup q_1 \cup \emptyset) \\ &= \epsilon\text{-Closure } (q_1) = [q_1] = [q_1, q_2] \end{aligned}$$

On input signal c

$$\begin{aligned} S_D[[q_0, q_1, q_2], c] &= \epsilon\text{-Closure } (S_N([q_0, q_1, q_2], c)) \\ &= \epsilon\text{-Closure } (S_N \{ (q_0, c) \cup (q_1, c) \cup (q_2, c) \}) \\ &= \epsilon\text{-Closure } (\emptyset \cup \emptyset \cup q_2) \\ &= \epsilon\text{-Closure } (q_2) = [q_2] \end{aligned}$$

Now,

$$Q_D = \{ [q_0, q_1, q_2], [q_1, q_2], [q_2] \}$$

Now Consider $[q_1, q_2]$

when on input a

$$\begin{aligned} S_D[[q_1, q_2], a] &= \epsilon\text{-closure}((S_N(q_1, q_2), a)) \\ &= \epsilon\text{-closure}(S_N\{(q_1, a) \cup (q_2, a)\}) \\ &= \epsilon\text{-closure}(\emptyset \cup \emptyset) = [\emptyset] \end{aligned}$$

when on input b

$$\begin{aligned} S_D[[q_1, q_2], b] &= \epsilon\text{-closure}((S_N(q_1, q_2), b)) \\ &= \epsilon\text{-closure}(S_N\{(q_1, b) \cup (q_2, b)\}) \\ &= \epsilon\text{-closure}(q_1 \cup q_2) \\ &= \epsilon\text{-closure}(q_1) = [q_1, q_2] \end{aligned}$$

when on input c

$$\begin{aligned} S_D[(q_1, q_2), c] &= \epsilon\text{-closure}(S_N(q_1, q_2), c)) \\ &= \epsilon\text{-closure}(S_N\{(q_1, c) \cup (q_2, c)\}) \\ &= \epsilon\text{-closure}(\emptyset \cup q_2) \\ &= [q_2] \end{aligned}$$

Since no new states are obtained Q_D remains same.

Consider state $[q_2]$

On input symbol a

$$\begin{aligned} S_D[[q_2], a] &= \epsilon\text{-closure}(S_N[q_2], a)) \\ &= \epsilon\text{-closure}(\emptyset) \\ &= \boxed{\emptyset} [\emptyset] \end{aligned}$$

on b.

$$\begin{aligned} S_D[[q_2], b] &= \epsilon\text{-closure}(S_N[q_2], b)) \\ &= \epsilon\text{-closure}(\emptyset) \\ &= \emptyset \end{aligned}$$

on input symbol c.

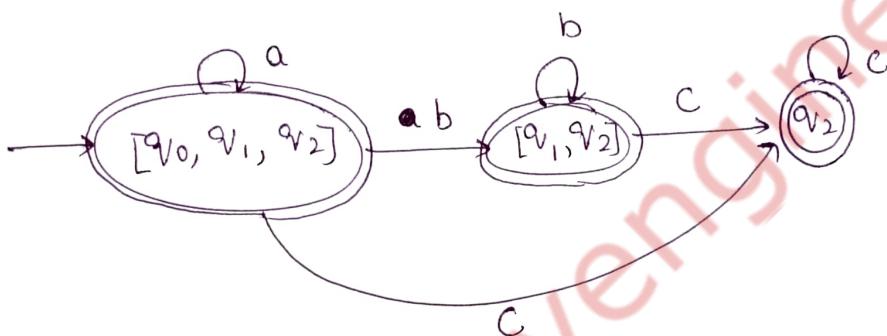
$$\begin{aligned} S_D[[q_2], c] &= \epsilon\text{-closure}(S_N(q_2, c)) \\ &= \epsilon\text{-closure}(q_2) \\ &= [q_2] \end{aligned}$$

$$Q_D = \{[q_0, q_1, q_2], [q_1, q_2], [q_2]\}$$

Transition Table

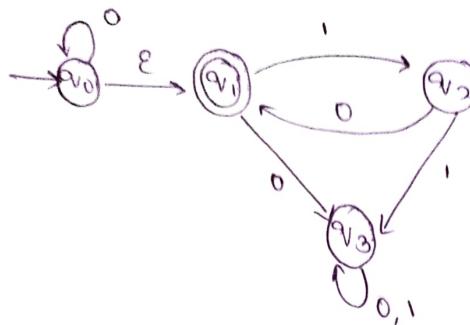
S	a	b	c
$[q_0, q_1, q_2]$	$[q_0, q_1, q_2]$	$[q_1, q_2]$	$[q_2]$
$[q_1, q_2]$	-	$[q_1, q_2]$	$[q_2]$
$[q_2]$	-	-	$[q_2]$

Transition DFA diagram



Jan 2020

4) Convert ϵ -NFSM to DFSM.



\Rightarrow Starting state: ϵ -closure (v_0) = $[v_0, v_1]$

$$Q_D = [v_0, v_1]$$

Consider $[v_0, v_1]$

when input is 0

$$\begin{aligned}
 S_D([v_0, v_1], 0) &= \epsilon\text{-closure}(S_N([v_0, v_1], 0)) \\
 &= \epsilon\text{-closure}(S_N([v_0, 0] \cup [v_1, 0])) \\
 &= \epsilon\text{-closure}(v_0 \cup v_3) \\
 &= [v_0, v_1, v_3]
 \end{aligned}$$

when input is 1

$$\begin{aligned}
 S_D([v_0, v_1], 1) &= \epsilon\text{-closure}(S_N([v_0, v_1], 1)) \\
 &= \epsilon\text{-closure}(S_N([v_0, 1] \cup [v_1, 1])) \\
 &= \epsilon\text{-closure}(\emptyset \cup v_2) \\
 &= [v_2]
 \end{aligned}$$

Consider $[v_2]$

$$\begin{aligned}
 \text{when input is 0, } S_D(v_2, 0) &= \epsilon\text{-closure}(S_N(v_2, 0)) \\
 &= \epsilon\text{-closure}(v_1) \\
 &\rightarrow [v_1]
 \end{aligned}$$

$$\begin{aligned}
 \text{when input is 1, } S_D(v_2, 1) &= \epsilon\text{-closure}(S_N(v_2, 1)) \\
 &= \epsilon\text{-closure}(v_3) \\
 &= [v_3]
 \end{aligned}$$

Consider $[v_1]$

$$\begin{aligned}
 \text{when input is 0, } S_D(v_1, 0) &= \epsilon\text{-closure}(S_N(v_1, 0)) \\
 &= \epsilon\text{-closure}(v_3) \\
 &= [v_3]
 \end{aligned}$$

$$\begin{aligned}
 \text{when input is 1, } S_D(v_1, 1) &= \epsilon\text{-closure}(S_N(v_1, 1)) \\
 &= \epsilon\text{-closure}(v_2) \\
 &\rightarrow [v_2]
 \end{aligned}$$

Consider v_3

when input is 0: $S_D(v_3, 0) = \epsilon\text{-closure}(S_N(v_3, 0))$
= $\epsilon\text{-closure}(v_3)$
= $[v_3]$

when input is 1: $S_D(v_3, 1) = \epsilon\text{-closure}(S_N(v_3, 1))$
= $\epsilon\text{-closure}(v_3)$
= $[v_3]$

Consider $[v_0, v_1, v_3]$

when input is 0

$$\begin{aligned} S_D([v_0, v_1, v_3], 0) &= \epsilon\text{-closure}(S_D((v_0, v_1, v_3), 0)) \\ &= \epsilon\text{-closure}(S_D\{(v_0, 0) \cup (v_1, 0) \cup (v_3, 0)\}) \\ &= \epsilon\text{-closure}(v_0 \cup v_3 \cup v_3) \\ &= \epsilon\text{-closure}(v_0 \cup v_3) = \epsilon\text{-closure}(v_0, v_3) \\ &= [v_0, v_1, v_3] \end{aligned}$$

when input is 1

$$\begin{aligned} S_D([v_0, v_1, v_3], 1) &= \epsilon\text{-closure}[S_D((v_0, v_1, v_3), 1)] \\ &= \epsilon\text{-closure}(S_D\{(v_0, 1) \cup (v_1, 1) \cup (v_3, 1)\}) \\ &= \epsilon\text{-closure}(\emptyset \cup v_2 \cup v_3) \\ &= [v_2, v_3] \end{aligned}$$

Consider $[v_2, v_3]$

when input is 0

$$\begin{aligned} S_D([v_2, v_3], 0) &= \epsilon\text{-closure}[S_D((v_2, v_3), 0)] \\ &= \epsilon\text{-closure}[S_D\{(v_2, 0) \cup (v_3, 0)\}] \\ &= \epsilon\text{-closure}(v_1 \cup v_3) \\ &= [v_1, v_3] \end{aligned}$$

when input is 1

$$\begin{aligned} S_D\{(v_2, v_3), 1\} &= \epsilon\text{-closure}(S_D((v_2, v_3), 1)) \\ &= \epsilon\text{-closure}(S_D\{(v_2, 1) \cup (v_3, 1)\}) \\ &= \epsilon\text{-closure}(v_3 \cup v_3) \\ &= [v_3] \end{aligned}$$

Consider $[v_1, v_3]$

when input 0

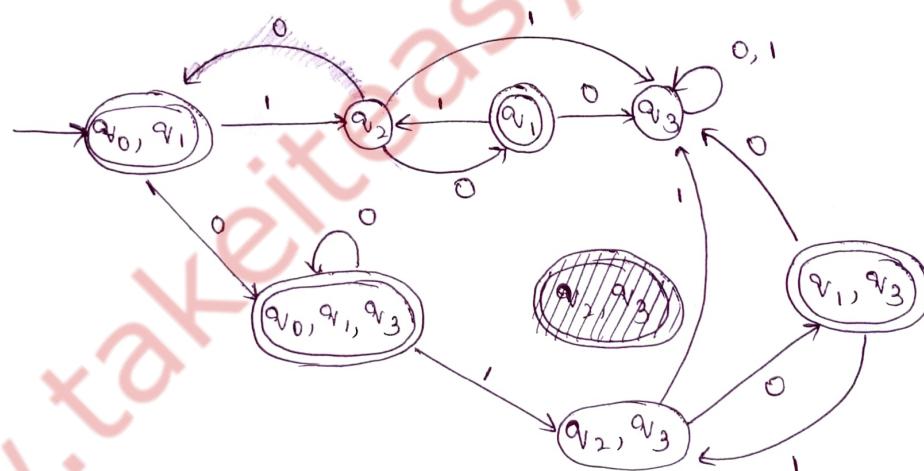
$$\begin{aligned} S_D([v_1, v_3], 0) &= \epsilon\text{-closure}(S_D((v_1, v_3), 0)) \\ &= \epsilon\text{-closure}(S_D\{(v_1, 0) \cup (v_3, 0)\}) \\ &= \epsilon\text{-closure}(v_2 \cup v_3) \\ &= [v_2, v_3] \end{aligned}$$

when on

$$\begin{aligned}
 S_D[(q_1, q_3), 1] &= \text{E-closure}(S_D(q_1, q_3), 1) \\
 &= \text{E-closure}(S_D\{q_1, 1\} \cup \{q_3, 1\}) \\
 &= \text{E-closure}(q_2 \cup q_3) \\
 &= [q_2, q_3].
 \end{aligned}$$

$$S_D = \{[q_0, q_1], [q_0, q_1, q_3], [q_2], [q_1], [q_3], [q_2, q_3], [q_1, q_3]\}$$

S	0	1
$[q_0, q_1]$	$[q_0, q_1, q_3]$	$[q_2]$
$[q_2]$	$[q_1]$	$[q_3]$
$[q_1]$	$[q_3]$	$[q_2]$
$[q_0, q_1, q_3]$	$[q_0, q_1, q_3]$	$[q_2, q_3]$
$[q_3]$	$[q_3]$	$[q_3]$
$[q_2, q_3]$	$[q_1, q_3]$	$[q_3]$
$[q_1, q_3]$	$[q_3]$	$[q_2, q_3]$



DFA Minimization using Myhill - Nerode Theorem

Input - DFA

Output - Minimized DFA

Step 1: Draw a table for all pairs of states (q_i, q_j) not necessarily connected directly [all are unmarked initially].

Step 2: Consider every state pair (q_i, q_j) in DFA where $q_i \in F$ and $q_j \notin F$ vice versa and mark them. [Here F is final states]

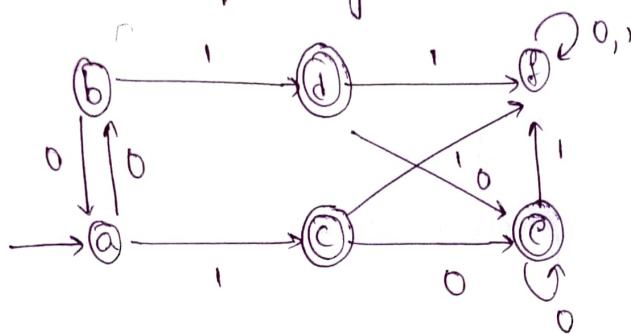
Step 3: Repeat this step until we cannot mark anymore states -

If there is an unmarked pair (q_i, q_j) mark it if the pair $\{s(q_i A), s(q_j A)\}$ is marked for some input alphabet A.

Step 4: Combine all the unmarked (q_i, q_j) and make them a single state in reduced DFA.

Examples

i) Minimize the following DFA



Step 1: We write a table for all pair states. and mark the state pairs.

b					
c	✓	✓			
d	✓	✓			
e	✓	✓			
f	✓	✓	✓	✓	✓
a		b	c	d	e

Step 2
Now, we will try to mark the state pairs with red colour checked mark. If input 1 to state (a, f) it will go to (c, f). (c, f) is already marked hence we will make pair (a, f).

S	0	1
(a, b)	(b, a)	(c, d)
(a, f)	(b, f)	(c, f)
(c, d)	(e, e)	(f, f)
(c, e)	(e, e)	(f, f)
(b, f)	(a, f)	(d, f)
(d, e)	(e, e)	(f, f)

Now, After step 2, we have got state combinations $\{a,b\}$, $\{c,d\}$, $\{c,e\}$, $\{d,e\}$ that are unmarked.

We can recombine $\{(c,d), (c,e), (d,e)\}$ into (c,d,e)

Hence we got two combined states as (a,b) and (c,d,e) .

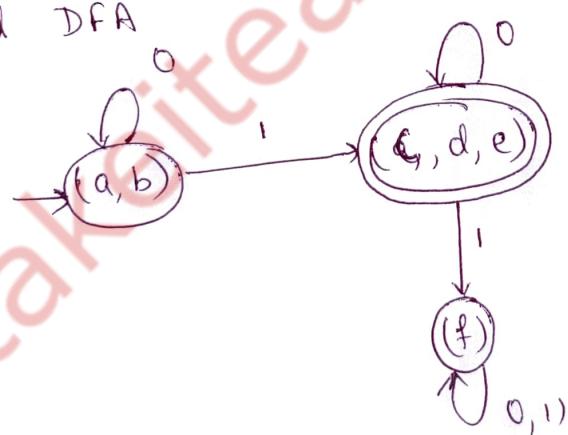
So, the final minimized DFA will contain three states

$\{\$\}$, $\{a,b\}$, $\{c,d,e\}$

Transition Table

S	0	1
$\{a,b\}$	$\{a,b\}$	$\{c,d,e\}$
$\{c,d,e\}$	$\{c,d,e\}$	$\{\$\}$
$\{\$\}$	$\{\$\}$	$\{\$\}$

Minimized DFA



Q) Minimize the following DFSM.

Sol,

δ	0	1
A	B	F
B	G	C
C	A	C
D	C	G
E	H	F
F	C	G
G	G	E
H	G	C

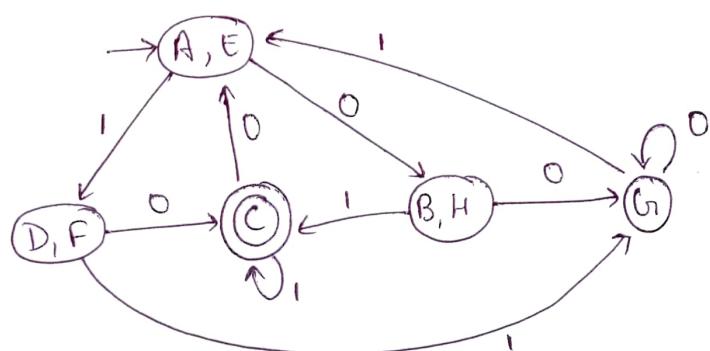
Step 1

B	✓						
C	✓	✓					
D	✓	✓	✓	✓			
E		✓	✓	✓			
F	✓	✓	✓		✓		
G	✓	✓	✓	✓	✓	✓	
H	✓		✓	✓	✓	✓	✓
	A	B	C	D	E	F	G.

→ (A, E), (B, H), (D, F) are the indistinguishable states
 and C and G are distinguishable states
 [i.e. Completely filled states].

Minimized DFSM.

[Check Next Page Transition Table]



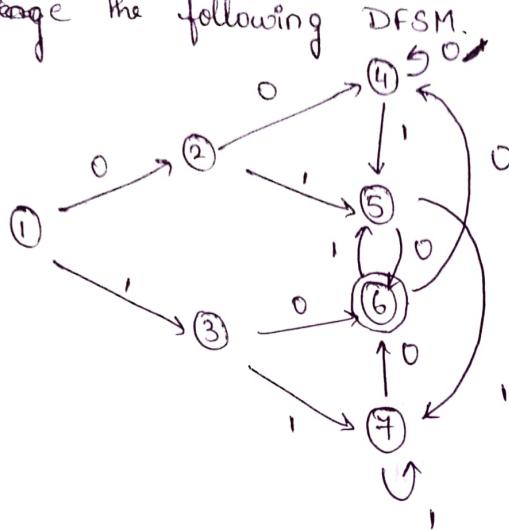
Step 2

	(P, Q)	(R, S)	(T, S)
S	O	I	
✓ (A, B)	(B, G)	(F, C)	
✓ (A, D)	(B, C)	(F, G)	
✓ (A, E)	(B, H)	(F, F)	
✓ (A, F)	(B, C)	(F, G)	
✓ (A, G)	(B, G)	(F, E)	
✓ (A, H)	(B, G)	(F, C)	
✓ (B, D)	(G, C)	(C, G)	
✓ (B, E)	(G, H)	(C, F)	
✓ (B, F)	(G, G)	(C, G)	
✓ (B, G)	(G, G)	(E, E)	
✓ (B, H)	(G, G)	(C, C)	
✓ (D, E)	(C, H)	(G, F)	
✓ (D, F)	(C, C)	(G, G)	
✓ (D, G)	(C, G)	(G, E)	
✓ (D, H)	(C, G)	(G, C)	
✓ (E, F)	(H, C)	(F, G)	
✓ (E, G)	(H, G)	(F, E)	
✓ (E, H)	(H, G)	(F, C)	
✓ (F, G)	(C, G)	(G, E)	
✓ (F, H)	(C, G)	(G, C)	
✓ (G, H)	(G, G)	(E, C)	

Transition Table. of Minimized DFSM.

	S	O	I
→ (A, E)	(B, H)	(D, F)	
(B, H)	[G]	[C]	
(D, F)	[C]	[G]	
* [C]	(A, E)	[C]	
[G]	(G)	(A, E)	

3) Minimize the following DFA.



Sol:

2						
3	✓	✓				
4			✓			
5	✓	✓				
6	✓	✓	✓	✓	✓	
7	✓	✓		✓		✓
	1	2	3	4	5	6

Pairs marked with black(✓) are those of which exactly one element is in F (final state)

The pairs marked in(✓) are those marked on second pass. E.g. (2,5) is one of those since $(2,5) \xrightarrow{0} (4,6)$ and pair (4,6) is already marked on pass 1 (✓)

Step 2

δ	0	1
(1,2)	(2,4)	(3,5)
(1,3)	(2,6)	(3,7)
(1,4)	(2,4)	(3,4)
(1,5)	(2,6)	(3,7)
(1,7)	(2,6)	(3,7)
(2,3)	(4,6)	(5,7)
(2,4)	(4,4)	(5,4)
(2,5)	(4,6)	(5,7)

δ	0	1
(2,7)	(4,6)	(5,7)
(3,4)	(6,4)	(7,4)
(3,5)	(6,6)	(7,7)
(3,7)	(6,6)	(7,7)
(4,5)	(4,6)	(5,7)
(4,7)	(4,6)	(5,7)
(5,7)	(6,6)	(7,7)

$(1,2)$ $(1,4)$ $(2,4)$ $(3,5)$ $(3,7)$ $(5,7)$ are the indistinguishable states . and $\{6\}$ is the distinguishable state

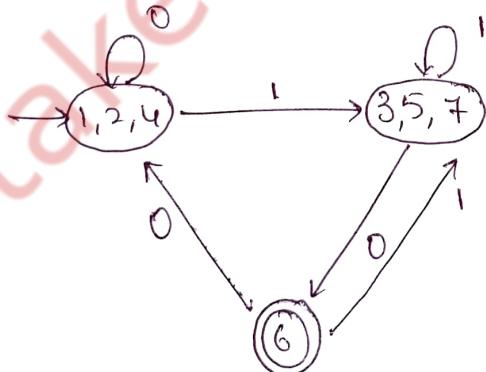
We can combin

$$\begin{aligned} \text{i)} (1,2) (1,4) (2,4) &= \{1,2,4\} \\ \text{ii)} (3,5) (3,7) (5,7) &= \{3,5,7\} \end{aligned} \quad \left. \begin{array}{l} \text{Indistinguishable Pairs} \\ \text{ } \end{array} \right\}$$

Transition Table of Minimized DFSM

δ	0	1
$\rightarrow \{1,2,4\}$	$\{1,2,4\}$	$\{3,5,7\}$
$\{3,5,7\}$	$\{6\}$	$\{3,5,7\}$
$\star \{6\}$	$\{1,2,4\}$	$\{3,5,7\}$

Transition Diagram of Minimized DFSM.



4) *[Jan 2018]* Minimize the following DFA.

S	O	I
A	B	A
B	A	C
C	D	B
D	D	A
E	D	F
F	G	E
G	F	G
H	G	D

Sol.

B	✓						
C	✓	✓					
D	✓	✓	✓	✓			
E	✓	✓			✓		
F	✓		✓	✓	✓		
G		✓	✓	✓	✓	✓	
H	✓	✓	✓	✓	✓	✓	✓
	A	B	C	D	E	F	G.

(A, G), (B, F), (C, E) are indistinguishable pairs

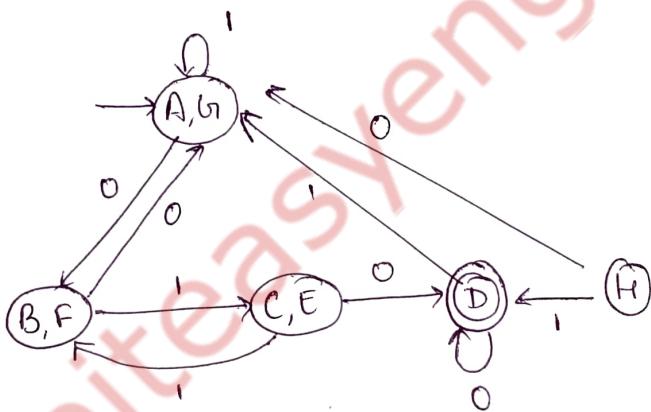
(D) and (H) are the distinguishable states.

	$S_{(P, Q)}$	$O_{(r, s)}$	$I_{(r, s)}$
✓	(A, B)	(B, A)	(A, C)
✓	(A, C)	(B, D)	(A, B)
✓	(A, E)	(B, D)	(A, F)
✓	(A, F)	(B, G)	(A, E)
	(A, G)	(B, F)	(A, G)
✓	(A, H)	(B, G)	(A, D)
✓	(B, C)	(A, D)	(C, B)
✓	(B, E)	(A, D)	(C, F)
	(B, F)	(A, G)	(C, E)
✓	(B, G)	(A, F)	(C, G)
✓	(B, H)	(A, G)	(C, D)
	(C, E)	(D, D)	(B, F)
✓	(C, F)	(D, G)	(B, E)
✓	(C, G)	(D, F)	(B, G)
✓	(C, H)	(D, G)	(B, D)
✓	(E, F)	(D, G)	(F, E)
✓	(E, G)	(D, F)	(F, G)
✓	(E, H)	(D, G)	(F, D)
✓	(F, G)	(G, F)	(E, G)
✓	(F, H)	(G, G)	(E, D)
✓	(G, H)	(F, G)	(G, D)

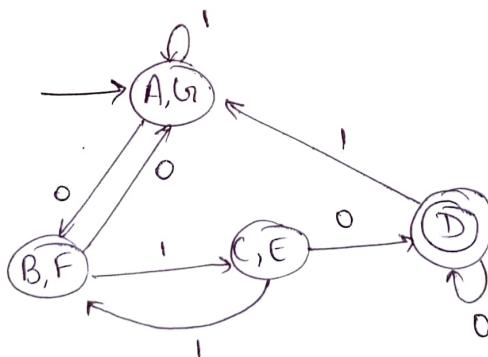
Transition Table

δ	0	1
(A, G)	(B, F)	(A, G)
(B, F)	(A, G)	(C, E)
(C, E)	(D)	(B, F)
H	(A, G)	(D)
D	D	(A, G)

Minimized DFSM Transition Diagram.



Now, since H is not reachable state to starting state (A, G)
H is removed.



Transducer: A device that converts variations in a physical quantity, such as pressure or brightness, into an electrical signal or vice versa.

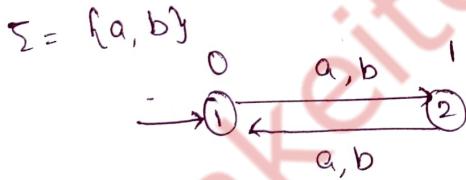
Moore Machine : A Moore Machine, M is a seven tuple: $(K, \Sigma, O, S, D, s_0, A)$ where

- K is finite set of states
- Σ is input alphabet
- O is the output alphabet
- $s_0 \in K$ is the start state
- A subset of K is the set of accepting states (not limp)
- D is the display or output function from $K \times (\Sigma)^*$
- δ is the transition function it maps from $K \times \Sigma$ to K

Example

In moore machine each state is associated with a output.

Suppose we want Moore machine to output '0' when the length of input string is even, otherwise output '1'.



Transition Table

Transition Function.	Input = a	Input = b	Output
1	2	2	0
2	1	1	1

Mealy Machine (Transducer)

A mealy machine, M is a six tuple
 $(K, \Sigma, O, S, \delta, A)$ where

$K \rightarrow$ finite set of states

$\Sigma \rightarrow$ Input alphabet

$O \rightarrow$ Output Alphabet

$s \in K$ is start state

A subset of K is the set of accepting states

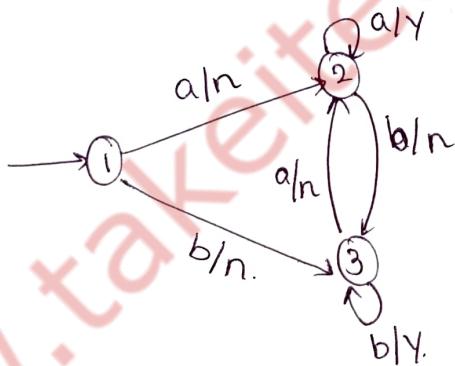
δ is the transition function it maps from $(K \times \Sigma)$ to $(K \times O^*)$

NOTE: Output is associated with each input.

Example

$$L = \{w \in \{a, b\}^* \mid w \text{ ends in } aa \text{ or } bb\}$$

Requirements are when input ends aa it should have Y and when ends bb should have n. output.



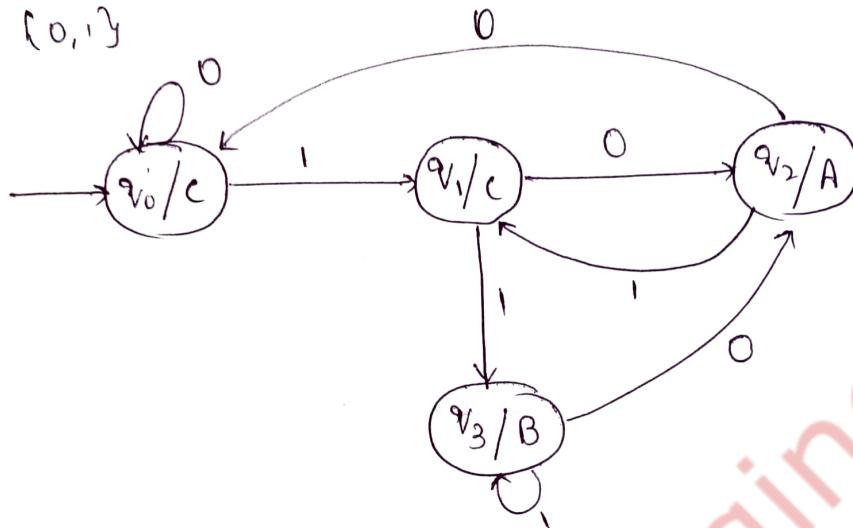
Transition Table

Trans function	a	0/P	b	0/P
1	2	n	3	n
2	2	Y	3	n
3	2	n	3	Y

Examples (Moore Machine)

- 1) Construct a Moore Machine that prints 'A' 'B' and 'C' depending on input that ends with '10', '11' @ other respectively

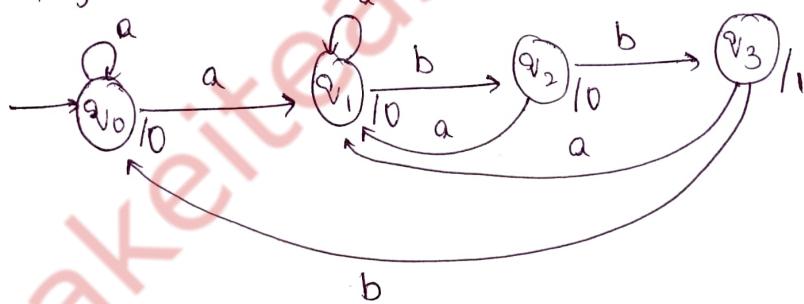
Sol: $\Sigma = \{0, 1\}$



A, B, C are the outputs

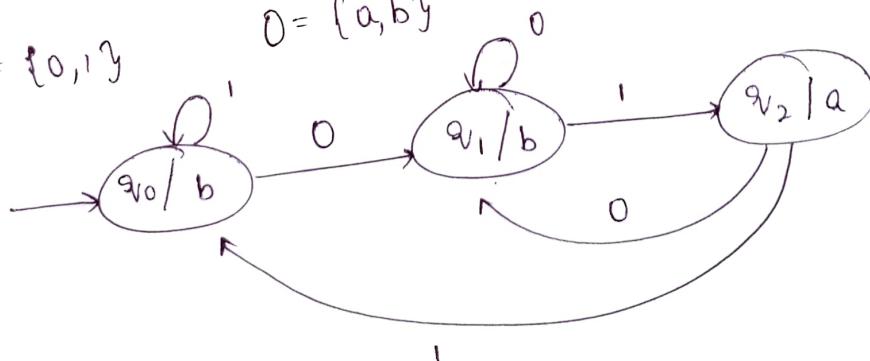
- 2) Draw a moore machine that counts the occurrence of sequence 'abb' in any input string over $\{a, b\}$

Sol: $\Sigma = \{a, b\}$ $O = \{0, 1\}$ 0 and 1 are the outputs.



- 3) Construct a Moore Machine that prints 'a' whenever '01' sequence is encountered in input binary string.

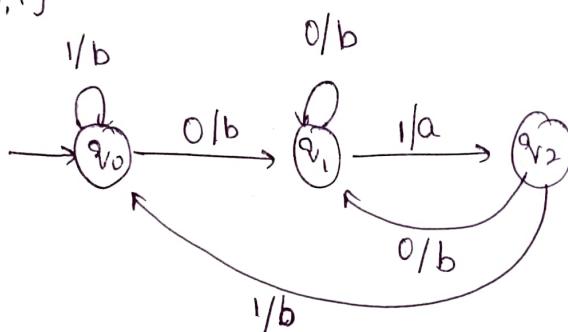
An $\Sigma = \{0, 1\}$



Example (MEALY Machine)

- 1) Design a mealy machine that prints 'a' whenever the sequence '01' is encountered in binary input string.

Sol. $\Sigma = \{0, 1\}$

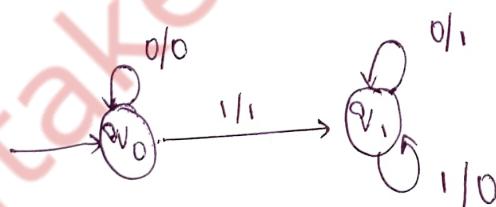


- 2) Design a mealy machine that takes input and produces 2's complement of that number as output. Assume the string is read from LSB to MSB and carry is discarded.

Sol. 2's Complement = 1's complement + 1

Ex

$$\begin{array}{r}
 10100 \\
 \rightarrow 01011 \\
 + \quad 1 \\
 \hline
 001100
 \end{array}
 \quad
 \begin{array}{r}
 11100 \\
 \rightarrow 00011 \\
 + \quad 1 \\
 \hline
 00100
 \end{array}$$



- 3) Construct a mealy machine that produces 1's complement of any binary input string.

Input String : 00101

Output String : 11010

