## ELL715 : Assignment 2

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#### 1 Answer 1

 $({\rm Code~in~q1.m})$ 

(a) Complement and log operations

Original image



Negative image



Log image



(b) Gamma Correction:

Original Image



gamma=0.4



gamma=2.5



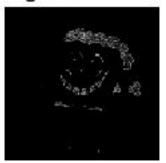
gamma=10



gamma=25



gamma=100



(c) Bit-plane Slicing

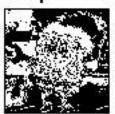
Image



Bit plane 3



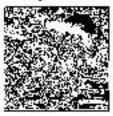
Bit plane 6



Bit plane 1



Bit plane 4



Bit plane 7



Bit plane 2



Bit plane 5



Bit plane 8



(d) Modified images and their histograms:

Original Image



Image brightened by 0.5

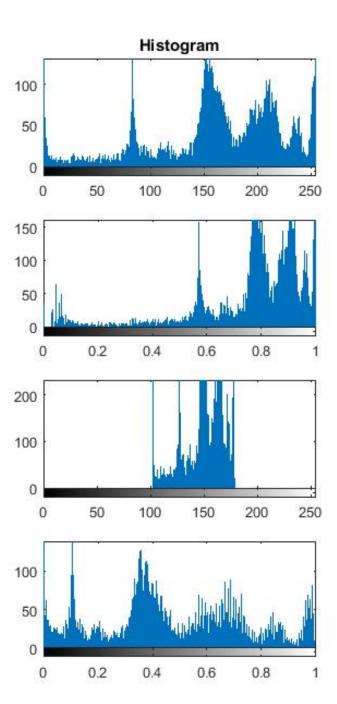


Contrast reduced from 0-1 to 0.4-0.7



Image darkened by 0.5





(e) Histogram Equalisation

# Original Image



Histogram

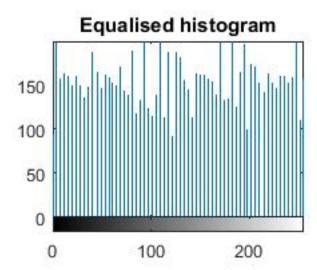
100

50

0 100 200

Histogram Equalised Image





(f) Highlighting

Original Image



Highlighted Image between 120-200



### 2 Answer 2

(Code in q2.m)

Original Image





(a) Laplacian filter (a) With diagonal terms





(b) Robert's operator (c) Sobel's operator (d) High boost filter



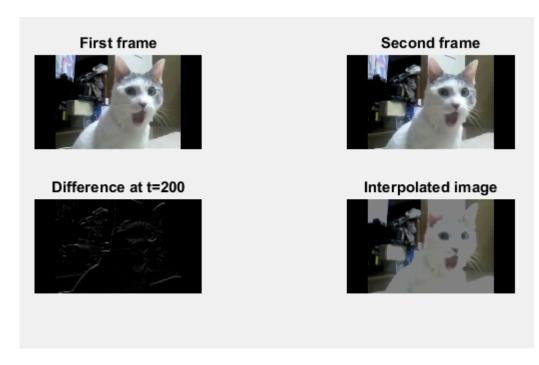


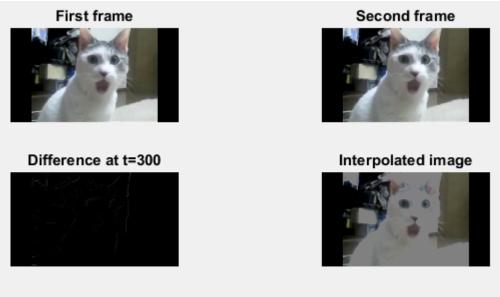
Edge estimation

#### Answer 3 3

(Code in q3.m)

First frame Second frame Interpolated image Difference at t=100





Changes in video frames over time

#### 4 Answer 4

(Code in q4.m)

The algorithm for object detection in the paper can be summarised as follows:

- (i) Prepare color images
- (ii) Image RGB adjustment
- (iii) Detect the color of each pixel and determine whether required color or not
- (iv) Delete the unrelated region by replacing the color with all black color
- (v) Change image to grayscale
- (vi) Perform median filter to eliminate the small pixel and smoothen the image
- (vii) Change to binary image and go through another object elimination that eliminates binary objects which is lesser than 200 pixels in a group of objects
- (viii) Apply CHT to find the circular patterns within an image

For the purpose of the assignment, the above algorithm was applied to detect a tennis ball in various images of a tennis match. The conditions used for detecting the colors was:

•  $Blue \leq Red \leq Green$ , or

•  $R \in (110, 255), G \in (170, 255), B \in (20, 130)$ 

The results are as follows:

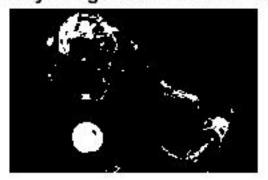
Original image



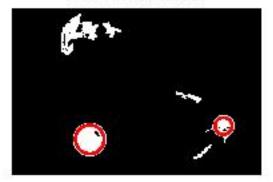
Color detection



binary image with median filter



**Ball detection** 



Original image



Color detection



binary image with median filter



**Ball detection** 



Original image



Color detection



binary image with median filter



**Ball detection** 



Thus, good accuracy levels were observed to detect the ball in various images.