Assignment - 4

wokwi for the ultrasonic sensor

Date	01 November 2022
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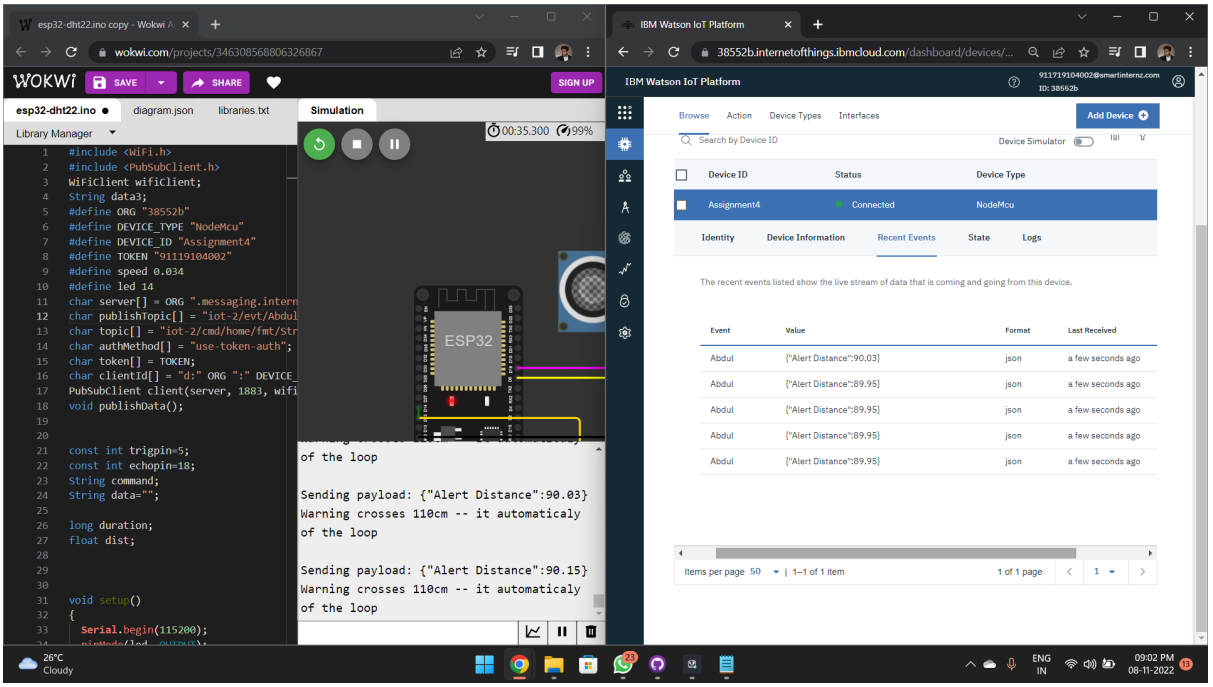
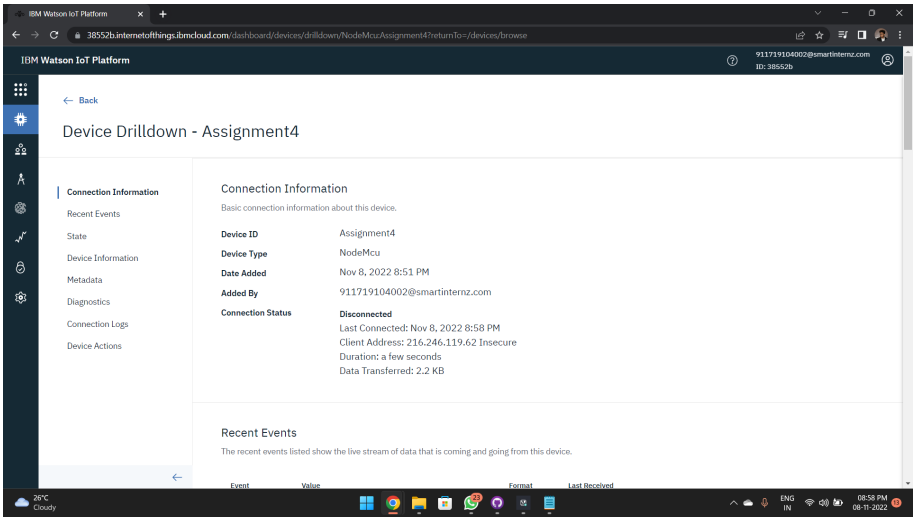
Maximum Marks	2 Marks

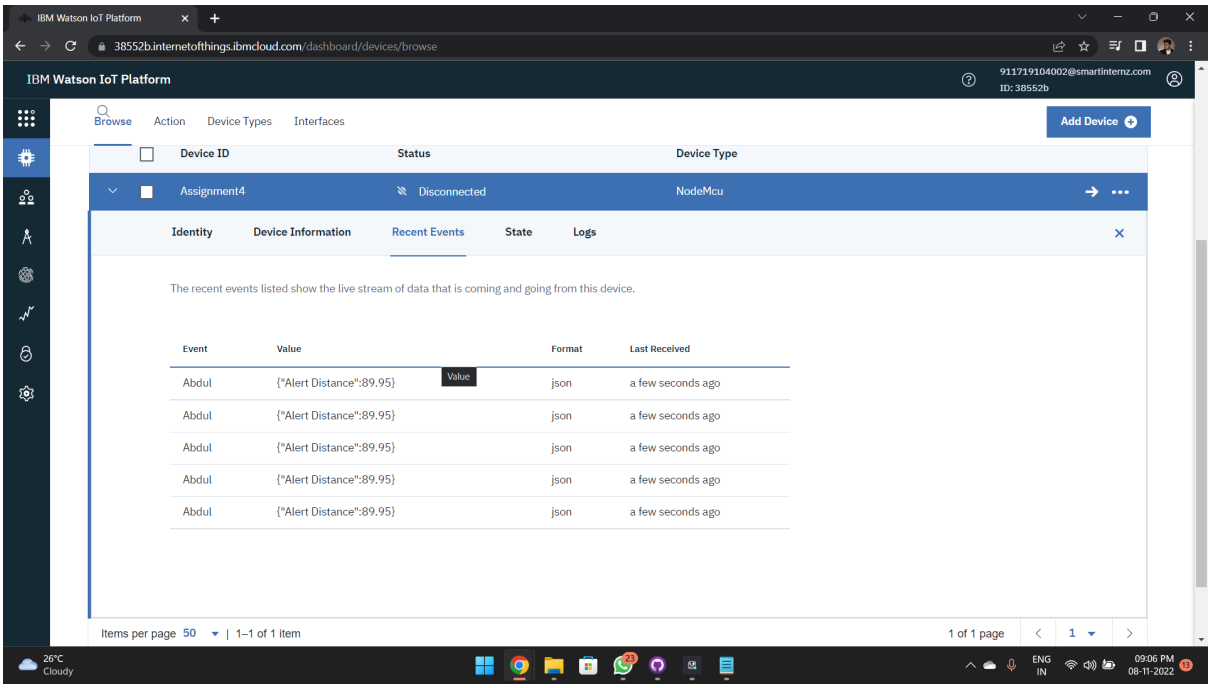
Question-3:

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events. Upload document with wokwi share link and images of IBM cloud.

Output :







Code :

```
/*

Done By Abdul Rahman S



Assignment 4


Write code and connections in wokwi for the ultrasonic sensor.

Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in

the device recent events.

Upload document with wokwi share link and images of IBM cloud


*/



#include <WiFi.h>
```

```
#include <PubSubClient.h>

WiFiClient wifiClient;

String data3;

#define ORG "38552b"

#define DEVICE_TYPE "NodeMcu"

#define DEVICE_ID "Assignment4"

#define TOKEN "91119104002"

#define speed 0.034

#define led 14

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";

char publishTopic[] = "iot-2/evt/Abdul/fmt/json";

char topic[] = "iot-2/cmd/home/fmt/String";

char authMethod[] = "use-token-auth";

char token[] = TOKEN;

char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;

PubSubClient client(server, 1883, wifiClient);

void publishData();



const int trigpin=5;

const int echopin=18;

String command;

String data="";


long duration;

float dist;




void setup()
```

```
{
  Serial.begin(115200);
  pinMode(led, OUTPUT);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
  wifiConnect();
  mqttConnect();
}

void loop() {
  bool isNearby = dist < 100;
  digitalWrite(led, isNearby);

  publishData();
  delay(500);

  if (!client.loop()) {
    mqttConnect();
  }
}

void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  }
  Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
```

```
}


void mqttConnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting MQTT client to ");
Serial.println(server);
    while (!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
    }
    initManagedDevice();
    Serial.println();
  }
}


void initManagedDevice() {
  if (client.subscribe(topic)) {
    // Serial.println(client.subscribe(topic));
    Serial.println("IBM subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}
void publishData()
{
  digitalWrite(trigpin,LOW);
  digitalWrite(trigpin,HIGH);
  delayMicroseconds(10);
  digitalWrite(trigpin,LOW);
  duration=pulseIn(echopin,HIGH);
```

```
  dist=duration*speed/2;
  if(dist<100){
    String payload = "{\"Alert Distance\":";
    payload += dist;
    payload += "}";

    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
      if(client.publish(publishTopic, (char*) payload.c_str())) {
      Serial.println("Warning crosses 110cm -- it automaticaly of the
loop");
      digitalWrite(led,HIGH);
    }

  }
    if(dist>101 && dist<111){
    String payload = "{\"Normal Distance\":";
    payload += dist;
    payload += "}";

    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);

    }

  }
```

```
  void callback(char* subscribeTopic, byte* payload, unsigned int
payloadLength){
  Serial.print("callback invoked for topic:");
  Serial.println(subscribeTopic);
  for(int i=0; i<payloadLength; i++){
    dist += (char)payload[i];
  }
  Serial.println("data:"+ data3);
  if(data3=="lighton"){
    Serial.println(data3);
    digitalWrite(led,HIGH);
  }
  data3="";
}
```