8086 Instruction Set

CLASSIFICATION OF INSTRUCTION SET OF 8086

1) DATA TRANSFER INSTRUCTIONS

E.g.:: MOV, PUSH, POP

2) ARITHMETIC INSTRUCTIONS

E.g.:: ADD, SUB, MUL

3) LOGIC INSTRUCTIONS (BIT MANIPULATION INSTRUCTIONS)

E.g.:: AND, OR, XOR

4) Shift Instructions & Rotate Instructions

E.g.:: ROL, RCL, ROR, SHL

5) PROGRAM EXECUTION AND TRANSFER INSTRUCTIONS (BRANCH INSTRUCTIONS)

E.g.:: JMP, CALL, JC

6) ITERATION CONTROL INSTRUCTIONS (LOOP INSTRUCTIONS)

E.g.:: LOOP, LOOPZ, LOOPNE

7) Processor Control Instructions (Instructions operating on Flags)

E.g.:: STC, CLC, CMC

8) External Hardware Synchronization Instructions

E.g.:: LOCK, ESC, WAIT

9) Interrupt Control Instructions

E.g.:: INT n, IRET, INTO (Interrupt on overflow)

10) STRING INSTRUCTIONS

E.g.:: MOVSB, LODSB, STOSB

Data Transfer Instructions

1) MOV Destination, Source

Moves a byte/word **from** the **source to** the **destination** specified in the instruction.

Source: Register, Memory Location, Immediate Number

Destination: Register, Memory Location

Both, source and destination cannot be memory locations.

Eg: MOV CX, 0037H ; CX ← 0037H MOV BL, [4000H] ; BL ← DS:[4000H] MOV AX, BX ; AX ← BX

MOV AX, BX; $AX \leftarrow BX$ MOV DL, [BX]; $DL \leftarrow DS:[BX]$ MOV DS, BX; $DS \leftarrow BX$

2) PUSH Source

Push the **source** (word) **into** the **stack** and decrement the stack pointer by two.

The source MUST be a WORD (16 bits).

Source: Register, Memory Location

Eg: **PUSH CX** ; *SS:*[*SP-1*] ← *CH*, *SS:*[*SP-2*] ← *CL*

; SP ← SP - 2

PUSH DS ; *SS*:[*SP*-1, *SP*-2] ← *DS*

; SP ← SP - 2

3) POP Destination

POP a **word from** the **stack** into the given destination and increment the Stack Pointer by 2. The destination MUST be a **WORD** (16 bits).

Destination: Register [EXCEPT CS], Memory Location

Eg: **POP CX** ; $CH \leftarrow SS:[SP], CL \leftarrow SS:[SP+1]$

; SP **←** SP + 2

POP DS ; $DS \leftarrow SS:[SP, SP+1]$

; SP ← SP + 2

<u>Please Note</u>: MOV, PUSH, POP are the ONLY instructions that use the Segment Registers as operands {except CS}.

4) PUSHF

Push value of **Flag Register into stack** and decrement the stack pointer by 2.

Eq: **PUSHF** ; $SS:[SP-1] \leftarrow Flag_H$, $SS:[SP-2] \leftarrow Flag_L$ $SP \leftarrow SP - 2$

5) POPF

POP a word from the stack into the Flag register.

Eg: **POPF** ; $Flag_L \leftarrow SS:[SP]$, $Flag_H \leftarrow SS:[SP+1]$, $SP \leftarrow SP + 2$

6) XCHG Destination, Source

Exchanges a byte/word between the **source and** the **destination** specified in the instruction.

Source: Register, Memory Location Destination: Register, Memory Location

Even here, both operands cannot be memory locations.

Eg: XCHG CX, BX ; $CX \leftarrow \rightarrow BX$ XCHG BL, CH ; $BL \leftarrow \rightarrow CH$

7) **XLATB / XLAT** (very important)

Move into AL, the contents of the memory location in Data Segment, whose effective address is formed by the sum of BX and AL.

Eg: **XLAT** ; $AL \leftarrow DS:[BX + AL]$; i.e. if DS = 1000H; BX = 0200H; AL = 03H ; \therefore 10000 ... DS × 16 ; + 0200 ... BX ; + 03 ... AL ; = 10203 \therefore AL \leftarrow [10203H]

Note: the difference between XLAT and XLATB

In XLATB there is no operand in the instruction.

E.g.:: XLATB

It works in an implied mode and does exactly what is shown above.

In XLAT, we can specify the name of the look up table in the instruction

E.g.:: XLAT SevenSeg

This will do the translation form the look up table called SevenSeg.

In any case, the base address of the look up table must be given by BX.

8) LAHF

Loads AH with **lower byte** of the **Flag** Register.

9) SAHF

Stores the contents of **AH into** the **lower byte** of the **Flag** Register.

10)LEA register, source

Loads Effective Address (offset address) **of** the **source into** the **given register**. Eg: **LEA BX, Total** ; $BX \leftarrow offset \ address \ of \ Total \ in \ Data \ Segment.$

11)LDS destination register, source

Loads the destination register and DS register with offset address and segment address specified by the source.

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Eg: LDS BX, Total ; BX \leftarrow \{DS:[Total], DS:[Total + 1]\}, ; DS \leftarrow \{DS:[Total + 2], DS:[Total + 3]\}
```

12)LES destination register, source

Loads the **destination register and ES** register with the **offset address and** the **segment address** indirectly specified by the **source**.

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Eg: LES BX, Total ; BX \leftarrow \{DS:[Total], DS:[Total + 1]\}, ; ES \leftarrow \{DS:[Total + 2], DS:[Total + 3]\}
```

I/O ADDRESSING MODES OF 8086 (5m - Important Question)

I/O addresses in 8086 can be either 8-bit or 16-bit

Direct Addressing Mode:

If we use **8-bit I/O address** we get a range of **00H... FFH**.

This gives a total of **256 I/O ports.**

Here we use Direct addressing Mode, that is, the I/O address is specified in the instruction.

E.g.:: IN AL, 80H ; AL gets data from I/O port address 80H.

This is also called **Fixed Port Addressing**.

Indirect Addressing Mode:

If we use 16-bit I/O address we get a range of 0000H... FFFFH.

This gives a total of **65536 I/O ports.**

Here we use Indirect addressing Mode, that is, the I/O address is specified by DX register.

E.g.:: MOV DX, 2000H

IN AL, DX ; AL gets data from I/O port address 2000H given by DX.

This is also called **Variable Port Addressing**.

13)IN destination register, source port

Loads the **destination register with** the contents of the **I/O port** specified by the source.

Source: It is an I/O port address.

If the address is 8-bit it will be given in the instruction by **Direct addressing mode.**

If it is a 16 bit address it will be given by DX register using **Indirect addressing mode.**

Destination: It has to be some form of "A" register, in which we will get data from the I/O device. If we are getting 8-bit data, it will be AL or AH register.

If we are getting 16-bit data, it will be AX register.

Eg: IN AL, 80H ; AL gets 8-bit data from I/O port address 80H IN AX, 80H ; AX gets 16-bit data from I/O port address 80H IN AL, DX ; AL gets 8-bit data from I/O port address given by DX.

IN AX, DX , AL gets 8-bit data from I/O port address given by DX.

; AX gets 16-bit data from I/O port address given by DX.

14)OUT destination port, source register

Loads the destination I/O port with the contents of the source register.

Eg: **OUT 80H, AL** ; I/O port 80H gets 8-bit data from AL **OUT 80H, AX** ; I/O port 80H gets 16-bit data from AX

OUT DX, AL ; I/O port whose address is given by DX gets 8-bit data from AL OUT DX, AX ; I/O port whose address is given by DX gets 16-bit data from AX

Segment Overriding

In every instruction, a particular segment register is accessed for the base address.

Eg: MOV CL, [5000H] ; $CL \leftarrow DS$:[5000H] as Data Seg is accessed by default

However, we can also **override the segment** as follows:

Eg: MOV CL, CS:[5000H] ; Here CL \leftarrow CS:[5000H], this is **Segment Overriding**.

By default, the address 5000H would have been an offset for the data segment, BUT here we **override** it with the Code segment as shown above.

Another example:

 $\begin{array}{ll} \text{MOV BL, [BP]} & \text{$;$ BL \leftarrow SS:[BP] \dots \textbf{Normal}$} \\ \text{MOV BL, DS:[BP]} & \text{$;$ BL \leftarrow DS:[BP] \dots \textbf{Overriding}$} \end{array}$

Arithmetic Instructions

1) ADD/ADC destination, source

Adds the source to the destination and stores the result back in the destination.

Source: Register, Memory Location, Immediate Number

Destination: Register

Both, source and destination have to be of the same size.

ADC also adds the carry into the result.

Eg: ADD AL, 25H ; $AL \leftarrow AL + 25H$ ADD BL, CL ; $BL \leftarrow BL + CL$ ADD BX, CX ; $BX \leftarrow BX + CX$

ADC BX, CX ; $BX \leftarrow BX + CX + Carry Flag$

2) SUB/SBB destination, source

It is similar to ADD/ADC except that it does subtraction.

3) INC destination

Adds "1" to the specified destination.

Destination: Register, Memory Location

Note: Carry Flag is NOT affected.

Eg: INC AX ; $AX \leftarrow AX + 1$ INC BL ; $BL \leftarrow BL + 1$

INC BYTE PTR [BX] ; Increment the **byte** pointed by BX in the Data Segment

; i.e. DS:[BX] ← DS;[BX] + 1

INC WORD PTR [BX] ; Increment **word** pointed by BX in the Data Segment

; {DS:[BX], DS:[BX+1]} ← {DS:[BX], DS:[BX+1]}+1

4) DEC destination

It is similar to INC. Here also Carry Flag is NOT affected.

5) MUL source(unsigned 8/16-bit register)

If the **source** is **8-bit**, it is **multiplied with AL** and the **result** is stored in **AX** (AH-higher byte, AL-lower byte)

If the **source** is **16-bit**, it is **multiplied** with **AX** and the **result** is stored in **DX-AX** (DX-higher byte, AX-lower byte)

Source: Register, Memory Location

MUL affects AF, PF, SF and ZF. Eg:**MUL BL** ; $AX \leftarrow AL \times BL$

MUL BX ; $DX-AX \leftarrow AX \times BX$ MUL BYTE PTR [BX] ; $AX \leftarrow AL \times DS:[BX]$

6) IMUL source(signed 8/16-bit register)

Same as MUL except that the source is a SIGNED number.

7) DIV source(unsigned 8/16-bit register – divisor)

This instruction is used for **UNSIGNED** division.

Divides a WORD by a BYTE, OR a DOUBLE WORD by a WORD.

If the divisor is 8-bit then the dividend is in AX register.

After division, the quotient is in AL and the Remainder in AH.

If the divisor is 16-bit then the dividend is in DX-AX registers.

After division, the quotient is in AX and the Remainder in DX.

Source: Register, Memory Location

ALL flags are **undefined** after DIV instruction.

Eg: **DIV BL** ; AX ÷ BL :- AL ← Quotient; AH ← Remainder

DIV BX ; {DX,AX} ÷ BX :- AX ← Quotient; DX ← Remainder

Please Note: If the divisor is 0 or the result is too large to fit in AL (or AX for 16-bit divisor), them 8086 does a Type 0 interrupt (Divide Error).

8) IDIV source(signed 8/16-bit register – divisor)

Same as DIV except that it is used for **SIGNED** division.

9) NEG destination

This instruction forms the **2's complement** of the destination, and stores it back in the destination.

Destination: Register, Memory Location

ALL condition flags are **updated**. Eg: **Assume** AL= 0011 0101 = 35 H then

NEG AL ; $AL \leftarrow 1100\ 1011 = CBH.\ i.e.\ AL \leftarrow 2's\ Complement\ (AL)$

10)CMP destination, source

This instruction **compares the source with the destination**.

The source and the destination must be of the same size.

Comparison is done by internally SUBTRACTING the SOURCE form DESTINATION.

The result of this subtraction is NOT stored anywhere, instead the Flag bits are affected.

Source: Register, Memory Location, Immediate Value

Destination: Register, Memory Location

ALL condition flags are updated.

Eg: **CMP BL, 55H** ; *BL compared with 55H i.e. BL – 55H.*

CMP CX, BX ; CX compared with BX i.e. CX – BX.

11)CBW [Convert signed BYTE to signed WORD]

This instruction **copies sign of** the byte in **AL into** all the bits of **AH**.

AH is then called sign extension of AL.

No Flags affected.

Eg: Assume

AX = XXXX XXXX**1**001 0001

Then **CBW** gives

AX = 1111 1111 1001 0001

12)CWD [Convert signed WORD to signed DOUBLE WORD]

This instruction copies sign of the WORD in AX into all the bits of DX.

DX is then called sign extension of AX.

No Flags affected.

Eg: Assume

 $\overline{AX} = 100000001001001$

DX = XXXX XXXX XXXX XXXX

Then **CWD** gives

AX = 1000 0000 1001 0001

DX = 1111 1111 1111 1111

Note: Both CBW and CWD are used for Signed Numbers.

Decimal Adjust Instructions

13)DAA [Decimal Adjust for Addition]

It makes the **result** in **packed BCD** form **after** BCD **addition** is performed.

It works **ONLY** on **AL** register.

All Flags are updated; OF becomes undefined after this instruction.

For AL register ONLY

If $D_3 - D_0 > 9$ OR Auxiliary Carry Flag is set => ADD 06H to AL.

If $D_7 - D_4 > 9$ OR Carry Flag is set => ADD 60H to AL.

Assume AL = 14H

CL = 28H

Then ADD AL, CL gives

AL = 3CH

Now **DAA** gives

AL = 42 (06 is added to AL as C > 9)

If you notice, $(14)_{10} + (28)_{10} = (42)_{10}$

14)DAS [Decimal Adjust for Subtraction]

It makes the result in packed BCD form after BCD subtraction is performed.

It works **ONLY** on **AL** register.

All Flags are updated; OF becomes undefined after this instruction.

For AL register ONLY

If $D_3 - D_0 > 9$ OR Auxiliary Carry Flag is set => Subtract 06H from AL.

If $D_7 - D_4 > 9$ OR Carry Flag is set => Subtract 60H from AL.

Assume AL = 86H

CL = 57H

Then SUB AL, CL gives

AL = 2FH

Now **DAS** gives

AL = 29 (06 is subtracted from AL as F > 9)

If you notice, $(86)_{10}$ - $(57)_{10}$ = $(29)_{10}$

ASCII Adjust Instructions (for the AX register ONLY)

15)AAA [ASCII Adjust for Addition]

It makes the **result** in **unpacked BCD form**.

In **ASCII** Codes, **0** ... **9** are represented as **30** ... **39**.

When we **add ASCII Codes**, we need to **mask** the **higher byte** (Eg: 3 of 39).

This can be avoided if we use AAA instruction after the addition is performed.

AAA updates the **AF** and the **CF**; But **OF, PF, SF, ZF** are **undefined** after the instruction. **Eg: Assume**

AL = 0011 0100 ... ASCII 4.

CL = 0011 1000 ... ASCII 8.

Then ADD AL, CL gives

AL = 01101100

i.e. AL = 6CH ... it is the Incorrect temporary Result

```
Now AAA gives
```

 $AL = 0000 \ 0010 \dots Unpacked BCD for 2.$

Carry = $1 \dots$ this indicates that the answer is 12.

16) AAS [ASCII Adjust for Subtraction]

It makes the **result** in **unpacked BCD form**.

In **ASCII** Codes, **0** ... **9** are represented as **30** ... **39**.

When we **subtract ASCII Codes**, we need to **mask** the **higher byte** (Eg: 3 of 39).

This can be **avoided** if we **use AAS** instruction **after the subtraction** is performed.

AAS updates the AF and the CF; But OF, PF, SF, ZF are undefined after the instruction.

Eg: Assume

AL = 0011 1001 ... ASCII 9.

CL = 0011 0101 ... ASCII 5.

Then SUB AL, CL gives

AL = 0000 0100

i.e. AL = 04H

Now **AAS** gives

 $AL = 0000 \ 0100 \dots Unpacked BCD for 4.$

Carry = 0 ... this indicates that the answer is 04.

17) AAM [BCD Adjust After Multiplication]

Before we multiply two ASCII digits, we mask their upper 4 bits.

Thus we have two unpacked BCD operands.

After the two unpacked BCD operands are multiplied, the AAM instruction converts this result into unpacked BCD form in the AX register.

AAS updates PF, SF ZF; But OF, AF, CF are undefined after the instruction.

Eg: Assume

 $AL = 0000 \ 1001 \dots \ unpacked BCD 9.$

CL = 0000 0101 ... unpacked BCD 5.

Then **MUL CL** gives

 $AX = 0000\ 0000\ 0010\ 1101 = 002DH.$

Now **AAM** gives

 $AX = 0000\ 0100\ 0000\ 0101 = 0405H.$

This is 45 in the unpacked BCD form.

18) AAD [Binary Adjust before Division]

This instruction converts the unpacked BCD digits in AH and Al into a Packed BCD in AL.

AAD updates PF, SF ZF; But **OF, AF, CF** are **undefined** after the instruction.

Eg: Assume

CL = 07H.

AH = 04.

AL = 03.

 \therefore AX = 0403H ... unpacked BCD for (43)₁₀

Then **AAD** gives

 $AX = 002BH ... i.e. (43)_{10}$

Now **DIV CL** gives (divide AX by unpacked BCD in CL)

AL = Quotient = 06 ... unpacked BCD

AH = Remainder = 01 ... unpacked BCD

LOGICAL INSTRUCTIONS [BIT MANIPULATION INSTRUCTIONS]

1) NOT destination

This instruction forms the **1's complement** of the destination, and stores it back in the destination. *Destination*: Register, Memory Location. **No Flags affected**.

Eq: **Assume** AL= 0011 0101

NOT AL ; $AL \leftarrow 1100\ 1010\ ...\ i.e.\ AL = 1's\ Complement\ (AL)$

2) AND destination, source

This instruction **logically ANDs** the source with the destination and stores the **result in the destination**. Source and destination have to be of the same size.

Source: Register, Memory Location, Immediate Value

Destination: Register, Memory Location

PF, **SF**, **ZF affected**; **CF**, **OF ← 0**; **AF** becomes **undefined**.

Eg: **AND BL, CL** ; $BL \leftarrow BL \ AND \ CL$

3) OR destination, source

This instruction **logically Ors** the source with the destination and stores the **result in the destination**. Source and destination have to be of the same size.

Source: Register, Memory Location, Immediate Value

Destination: Register, Memory Location

PF, **SF**, **ZF** affected; **CF**, **OF** ← **0**; **AF** becomes **undefined**.

Eg: **OR BL, CL** ; $BL \leftarrow BL OR CL$

4) XOR destination, source

This instruction **logically X-Ors** the source with the destination and stores the **result in the destination**. Source and destination have to be of the same size.

Source: Register, Memory Location, Immediate Value

Destination: Register, Memory Location

PF, **SF**, **ZF affected**; **CF**, **OF ← 0**; **AF** becomes **undefined**.

Eg: **XOR BL, CL** ; $BL \leftarrow BL XOR CL$

5) TEST destination, source

This instruction **logically ANDs** the source with the destination **BUT** the **RESULT** is **NOT STORED ANYWHERE**. **ONLY** the **FLAG** bits are **AFFECTED**.

Source: Register, Memory Location, Immediate Value

Destination: Register, Memory Location

PF, **SF**, **ZF affected**; **CF**, **OF ← 0**; **AF** becomes **undefined**.

Eq: **TEST BL, CL** ; BL AND CL; result not stored; Flags affected.

Note: Don't forget this instruction because it will be used later in multiprocessor systems!

SHIFT INSTRUCTIONS

 SAL/SHL destination, count LEFT-Shifts the bits of destination. MSB shifted into the CARRY. LSB gets a 0.

Bits are shifted 'count' number of times.

If count = 1, it is directly specified in the instruction.

If count > 1, it has to be given using CL Register.

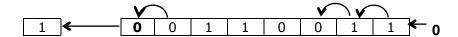
Destination: Register, Memory Location.

Eg: **SAL BL, 1** ; Left-Shift BL bits, once.

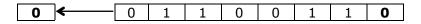
Assume:

Before Operation: BL = 0011 0011 and CF = 1

Carry Destination



After Operation: BL = 0110 0110 and CF = 0



More examples:

MOV CL, 05H ; Load number of shifts in CL register.
SAL BL, CL ; Left-Shift BL bits CL (5) number of times.

2) SHR destination, count

RIGHT-Shifts the bits of destination.

MSB gets a 0 (∴ Sign is lost). LSB shifted into the CARRY.

Bits are shifted 'count' number of times.

If count is 1, it is directly specified in the instruction.

If count > 1, it has to be given using CL register.

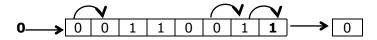
Eg: **SHR BL, 1** ; Right-Shift BL bits, once.

Assume:

Before Operation: BL = 0011 0011 and CF = 0

Destination

Carry



After Operation: BL = 00011 1001 and CF = 1

								_	
0	0	0	1	1	0	0	1	>	1

3) SAR destination, count

RIGHT-Shifts the bits of destination.

MSB placed **in MSB itself** (∴ Sign is preserved).

LSB shifted into the CARRY.

Bits are shifted 'count' number of times.

If count is 1, it is directly specified in the instruction.

If count > 1 it has to be given using CL register.

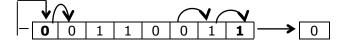
Destination: Register, Memory Location

Eg: **SAR BL, 1** ; Right-Shift BL bits, once.

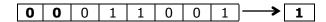
Assume:

Before Operation: BL = 0011 0011 and CF = 0





After Operation: BL = 0001 1001 and CF = 1



ROTATE INSTRUCTIONS

1) ROL destination, count

LEFT-Shifts the bits of destination.

MSB shifted into the CARRY.

MSB also goes to LSB.

Bits are shifted 'count' number of times.

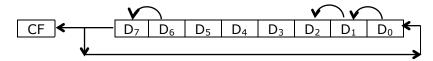
If count = 1, it is directly specified in the instruction.

If count > 1, it has to be loaded in the CL register, and CL gives the count in the instruction.

Destination: Register, Memory Location

Eg: **ROL BL, 1** ; Left-Shift BL bits once.

Carry Destination



More examples:

MOV CL, 05H ROL BL, CL ; Load number of shifts in CL register.

; Left-Shift BL bits CL (5) number of times.

2) ROR destination, count

RIGHT-Shifts the bits of destination.

LSB shifted into the CARRY.

LSB also goes to MSB.

Bits are shifted 'count' number of times.

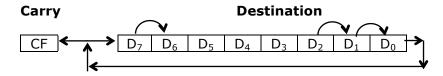
If count = 1, it is directly specified in the instruction.

If count > 1, it has to be loaded in the CL register, and CL gives the count in the instruction.

Eg:

ROR BL, 1

; Right-Shift BL bits once.



3) RCL destination, count

LEFT-Shifts the bits of destination.

MSB shifted **into** the Carry Flag **(CF)**.

CF goes to LSB.

Bits are shifted 'count' number of times.

If count = 1, it is directly specified in the instruction.

If count > 1, it has to be loaded in the CL register, and CL is specified as the count in the instruction.

Destination: Register, Memory Location

Eg: **RCL BL, 1** ; Left-Shift BL bits once.

4) RCR destination, count

RIGHT-Shifts the bits of destination.

LSB shifted into the CF.

CF goes to MSB.

Bits are shifted 'count' number of times.

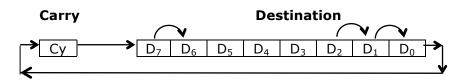
If count = 1, it is directly specified in the instruction.

If count > 1, it has to be loaded in the CL register, and CL is specified as the count in the instruction.

Destination: Register, Memory Location

Eg:

RCR BL, 1 ; Right-Shift BL bits once.



More examples:

MOV CL, 05H RCR BL, CL

; Load number of shifts in CL register. ; Right-Shift BL bits CL (5) number of times.

PROGRAM EXECUTION AND TRANSFER INSTRUCTIONS

These instructions cause a branch in the program sequence.

There are 2 main types of branching:

- i. Near branch
- ii. Far Branch

i. Near Branch

This is an **Intra-Segment Branch** i.e. the branch is to a new location within the current segment only.

Thus, only the value of IP needs to be changed.

If the Near Branch is in the range of -128 to 127, then it is called as a Short Branch.

ii. Far Branch

This is an **Inter-Segment Branch** i.e. the branch is to a new location in a different segment. Thus, the values of **CS and IP need to be changed**.

JMP (Unconditional Jump)

INTRA-Segment (NEAR) JUMP

The Jump address is specified in two ways:

1) INTRA-Segment Direct Jump

The new Branch location is specified directly in the instruction

The new address is calculated by **adding** the 8 or 16-bit **displacement** to the IP.

The CS does not change.

A +ve displacement means that the Jump is ahead (forward) in the program.

A -ve displacement means that the Jump is behind (backward) in the program.

It is also called as *Relative Jump*.

```
Eg: JMP Prev ; IP \leftarrow offset \ address \ of "Prev".

JMP Next ; IP \leftarrow offset \ address \ of "Next".
```

2) INTRA-Segment Indirect Jump

The New Branch address is specified indirectly through a **register** or a **memory location**.

The value in the IP is **replaced** with the new value.

The CS does not change.

```
Eg: JMP WORD PTR [BX] ; IP \leftarrow \{DS:[BX], DS:[BX+1]\}
```

INTER-Segment (FAR) JUMP

The Jump address is specified in two ways:

3) INTER-Segment Direct Jump

The new Branch location is **specified directly** in the instruction

Both **CS and IP get new values**, as this is an inter-segment jump.

Eg: Assume NextSeg is a label pointing to an instruction in a different segment.

JMP NextSeg ; CS and IP get the value from the label NextSeg.

4) INTER-Segment Indirect Jump

The new Branch location is specified indirectly through a register or a memory location.

```
Both CS and IP get new values, as this is an inter-segment jump. Eq:JMP DWORD PTR [BX] ; IP \leftarrow \{DS:[BX], DS:[BX+1]\},
```

; CS ← {DS:[BX+2], DS:[BX+3]}

JCondition (Conditional Jump)

This is a conditional branch instruction.

If condition is TRUE, then it is similar to an INTRA-Segment Direct Jump.

If condition is FALSE, then branch does not take place and the next sequential instruction is executed. The destination must be in the range of -128 to 127 from the address of the instruction (i.e. **ONLY SHORT Jump**).

Ea: JNC Next

; Jump to Next If Carry Flag is not set (CF = 0).

The various conditional jump instructions are as follows:

Mnemonic	Description	Jump Condition			
Common Operations					
JC	Carry	CF = 1			
JNC	Not Carry	CF = 0			
JE/JZ	Equal or Zero	ZF = 1			
JNE/JNZ	Not Equal or Not Zero	ZF = 0			
JP/JPE	Parity or Parity Even	PF = 1			
JNP/JPO	Not Parity or Parity Odd	PF = 0			
Signed Operations					
JO	Overflow	OF = 1			
JNO	Not Overflow	OF = 0			
JS	Sign	SF = 1			
JNS	Not Sign	SF = 0			
JL/JNGE	Less	(SF Ex-Or OF) = 1			
JGE/JNL	Greater or Equal	(SF Ex-Or OF) = 0			
JLE/JNG	Less or Equal	((SF Ex-Or OF) + ZF) = 1			
JG/JNLE	Greater	((SF Ex-Or OF) + ZF) = 0			
Unsigned Operations					
JB/JNAE	Below	CF = 1			
JAE/JNB	Above or Equal	CF = 0			
JBE/JNA	Below or Equal	(CF Ex-Or ZF) = 1			
JA/JNBE	Above	(CF Ex-Or ZF) = 0			

CALL (Unconditional CALL)

CALL is an instruction that transfers the program control to a sub-routine, with the intention of coming back to the main program.

Thus, in CALL 8086 saves the address of the next instruction into the stack before branching to the sub-routine.

At the end of the subroutine, control transfers back to the main program using the return address from the stack.

There are two types of CALL: Near CALL and Far CALL.

INTRA-Segment (NEAR) CALL

The **new subroutine** called must be **in the same segment** (hence intra-segment).

The CALL **address** can be **specified directly** in the instruction **OR indirectly** through Registers or Memory Locations.

The following sequence is executed for a NEAR CALL:

- i. 8086 will **PUSH Current IP** into the Stack.
- ii. Decrement SP by 2.
- iii. New value loaded into IP.

```
iv. Control transferred to a subroutine within the same segment.
```

```
Eq: CALL subAdd
                                ; {SS:[SP-1], SS:[SP-2]} ← IP, SP ← SP - 2,
                                ; IP ← New Offset Address of subAdd.
```

INTER-Segment (FAR) CALL

The new subroutine called is in another segment (hence inter-segment). Here CS and IP both get new values.

The CALL address can be specified directly OR through Registers or Memory Locations.

The following sequence is executed for a Far CALL:

- **PUSH CS** into the Stack.
- **Decrement SP** by 2. ii.
- iii. **PUSH IP** into the Stack.
- iv. **Decrement SP** by 2.
- v. **Load CS** with new segment address.
- vi. Load IP with new offset address.
- vii. **Control transferred** to a subroutine in the new segment.

```
Eg: CALL subAdd
                         ; {SS:[SP-1], SS:[SP-2]} ← CS, SP ← SP - 2,
                         ; {SS:[SP-1], SS:[SP-2]} ← CS, SP ← SP - 2,
                         ; CS ← New Segment Address of subAdd,
                         : IP ← New Offset Address of subAdd.
```

There is NO PROVISION for Conditional CALL.

RET --- Return instruction

RET instruction causes the control to return to the main program from the subroutine.

Intrasegment-RET

```
Eg: RET
                          ; IP \leftarrow SS:[SP], SS:[SP+1]
                          ; SP \leftarrow SP + 2
                          ; IP \leftarrow SS:[SP], SS:[SP+1]
     RET n
                          ; SP \leftarrow SP + 2 + n
```

Intersegment-RET

```
; IP \leftarrow SS:[SP], SS:[SP+1]
Eg: RET
                         ; CS ← SS:[SP+2], SS:[SP+3]
                        ; SP \leftarrow SP + 4
                        ; IP \leftarrow SS:[SP], SS:[SP+1]
    RET n
                         ; CS \leftarrow SS:[SP+2], SS:[SP+3]
                        ; SP \leftarrow SP + 4 + n
```

Please Note: The programmer writes the intra-seg and Inter-seg RET instructions in the same way. It is the assembler, which distinguishes between the two and puts the right opcode.

Differentiate between

	JMP Instruction	CALL INSTRUCTION	
1	JMP instruction is used to jump to a new location in the program and continue	Call instruction is used to invoke a subroutine, execute it and then return to the main program.	
2	A jump simply puts the branch address into IP.	A call first stores the return address into the stack and then loads the branch address into IP.	
3	In 8086 Jumps can be either unconditional or conditional.	In 8086, Calls are only unconditional .	
4	Does not use the stack	Uses the stack	
5	Does not need a RET instruction.	Needs a RET instruction to return back to main program.	

Differentiate between

	PROCEDURE (FUNCTION)	Macro	
1	A procedure (Subroutine/ Function) is a set of instruction needed repeatedly by the program. It is stored as a subroutine and invoked from several places by the main program.	A Macro is similar to a procedure but is not invoked by the main program. Instead, the Macro code is pasted into the main program wherever the macro name is written in the main program.	
2	A subroutine is invoked by a CALL instruction and control returns by a RET instruction.	A Macro is simply accessed by writing its name . The entire macro code is pasted at the location by the assembler.	
3	Reduces the size of the program	Increases the size of the program	
4	Executes slower as time is wasted to push and pop the return address in the stack.	Executes faster as return address is not needed to be stored into the stack, hence push and pop is not needed.	
5	Depends on the stack	Does not depend on the stack	

Type 1) Iteration Control Instructions

These instructions cause a series of instructions to be executed repeatedly.

The **number of iterations** is loaded **in CX** register.

CX is decremented by 1, after every iteration. Iterations occur until CX = 0.

The **maximum difference between** the **address** of the instruction and the address of the Jump **can be** 127.

; Do CX ← CX - 1.

1) LOOP Label

```
Jump to specified label if CX not equal to 0; and decrement CX.
```

Eg: MOV CX, 40H BACK: MOV AL, BL

ADD AL, BL

. OV BL AL

MOV BL, AL LOOP BACK

; Go to BACK if CX not equal to 0.

2) LOOPE/LOOPZ Label (Loop on Equal / Loop on Zero)

Same as above except that looping occurs ONLY if Zero Flag is set (i.e. ZF = 1)

Eg: **MOV CX, 40H**

BACK: MOV AL, BL

ADD AL, BL

MOV BL, AL

LOOPZ BACK

; Do CX ← CX - 1.

; Go to BACK if CX not equal to 0 and ZF = 1.

3) LOOPNE/LOOPNZ Label (Loop on NOT Equal / Loop on NO Zero)

Same as above except that looping occurs ONLY if Zero Flag is reset (i.e. ZF = 0)

Eg: MOV CX, 40H
BACK: MOV AL, BL

ADD AL, BL

MOV BL, AL

LOODZ BACI

LOOPZ BACK ; Do $CX \leftarrow CX - 1$.

; Go to BACK if CX not equal to 0 and ZF = 0.

Type 2) Processor Control / Machine Control Instructions

(these are instructions that directly operate on Flag Reg)

In the exam first explain the following instructions: PUSHF, POPF, LAHF and SAHF

For Carry Flag

1) STC

This instruction **sets** the **Carry Flag**. No Other Flags are affected.

2) CLC

This instruction **clears** the **Carry Flag**. No Other Flags are affected.

3) CMC

This instruction complements the Carry Flag. No Other Flags are affected.

For Direction Flag

4) STD

This instruction **sets** the **Direction Flag**. No Other Flags are affected.

5) CLD

This instruction **clears** the **Direction Flag**. No Other Flags are affected.

For Interrupt Enable Flag

6) STI

This instruction **sets** the **Interrupt Enable Flag**. No Other Flags are affected.

7) CLI

This instruction clears the Interrupt Enable Flag. No Other Flags are affected.

Note: There is no direct way to alter TF. It can be altered through program as follows:

To set TF:

```
PUSHF ; push contents of Flag register into the stack
POP BX ; pop contents of flag reg from the stack-top into BX

OR BH, O1H ; set the bit corresponding to TF, in the BH register
PUSH BX ; push the modified BX register into the stack
POPF ; pop the modified contents into flag register.
```

To reset TF:

```
PUSHF ; push contents of Flag register into the stack
POP BX ; pop contents of flag reg from the stack-top into BX

AND BH, FEH ; reset the bit corresponding to TF, in the BH register
PUSH BX ; push the modified BX register into the stack
POPF ; pop the modified contents into flag register.
```

Type 3) External Hardware Synchronization Instructions

1) ESC

This is an 8086 instruction-prefix used to indicate that the current instruction is for the 8087 NDP.

We write a homogeneous program for the two processors 8086 and 8087.

Instructions are fetched by 8086 into its queue.

8087 duplicates the instruction queue of 8086 and monitors this queue.

When an instruction with **ESC prefix** (binary code 11011) is **encountered**, **8087** is activated, and hence it executes the instruction.

8086 treats the instruction as NOP.

ESC has to be written before each 8087 instruction.

2) WAIT

This instruction is used to synchronize 8086 with the 8087 Co-Processor via the $\overline{\text{TEST}}$ input pin of 8086. Whenever 8087 is busy it puts a "1" on its BUSY o/p line connected to the $\overline{\text{TEST}}$ i/p of the μP .

The WAIT instruction makes the μP check the $\overline{\text{TEST}}$ pin.

If the μP checks the **TEST** pin and finds a "1" on it, 8086 understands that 8087 is busy and so it enters wait state. Here it does no processing.

It can come out of this idle state in 2 ways:

i. TEST input is made low

i.e. 8087 is no longer busy.

This takes 8086 completely out of the IDLE state.

ii. Valid Interrupt on INTR or NMI

In this case 8086 **exits wait state**, **executes the ISR** for the interrupt, and then **re-enters the WAIT state**. (*This is because the address of the WAIT instruction is what was pushed into the stack before executing the ISR*.)

Thus if **we write a WAIT instruction before every 8087 instruction**, we can ensure that 8087 is ready for executing its own instruction whenever it arrives.

WAIT can also be written before an 8086 instruction that requires the result of a previous 8087 operation.

3) LOCK

This is an 8086 instruction prefix.

It prevents any external bus master from taking control of the system bus during execution of the instruction, which has a LOCK prefix.

It causes 8086 to activate the **LOCK** signal so that no other bus master takes control of the system bus.

4) NOP

There is **no operation performed** while executing this instruction.

8086 requires 3 T-States for this instruction.

It is mainly used to insert time delays, and can also be used while debugging.

5) HLT

This instruction causes 8086 to **stop fetching any more instructions**.

8086 enters Halt state.

8086 can **come out** of this halt state only if there is a **valid hardware interrupt** (NMI or INTR) or **by reset**.

Type 4) Interrupt Control Instructions

1) INT Type

This instruction causes an interrupt of the given type. The **'Type'** can be a number between **0** ... **255**. The following action takes place:

- i. **PUSH Flag** Register onto the Stack. SP decremented by 2.
- ii. **IF** and **TF** are **cleared**. No other flags are affected.
- iii. **PUSH CS** onto the Stack. SP decremented by 2.
- iv. **PUSH IP** onto the Stack. SP decremented by 2. .. In all **SP decremented by 6**.
- v. **New value of IP** taken from location **type** × **4**.

```
Eg: INT 1; IP \leftarrow {[00004] and [00005]} (as 1 \times 4 = 00004H)
```

vi. New value of CS taken from location (type \times 4) + 2.

Eg: INT 1 ; CS ← {[00006] and [00007]}

Execution of ISR begins from the address formed by new values of CS and IP.

2) INTO (Interrupt on Overflow)

This instruction causes an interrupt of type 4, ONLY if Overflow Flag (OF) is set.

The above sequence is followed and the control is transferred to the location pointed by 00010H.

Eq: **INTO** ; If OF = 1 then execute INT 4.

Please Note: - This is INTO (O for Overflow) and NOT INT 0 (i.e. Type 0 ==> Zero Divide Interrupt).

3) IRET (Return from ISR)

This instruction causes the 8086 to return to the main program from an ISR.

The following action takes place:

i. **POP IP** from the Stack.

SP incremented by 2.

ii. **POP CS** from the Stack.

SP incremented by 2.

iii. **POP Flag Register** from the Stack.

SP incremented by 2.

∴ In all **SP incremented by 6**.

Execution of the **Main Program** continues from the address formed values of CS and IP restored from the stack.

Please Note:- The original value of TF and IF are restored from the Stack. Also note that to come back from an ISR, the programmer must use the IRET instruction and not the normal RET instruction as the RET instruction will not POP back the Flag.

Type 5) String Instructions of 8086 (Very Important × 10m)

A **String** is a **series of bytes** stored sequentially in the memory. String Instructions operate on such "Strings".

The Source String is at a location pointed by SI in the Data Segment.

The Destination String is at a location pointed by DI in the Extra Segment.

The Count for String operations is always given by CX.

Since CX is a 16-bit register we can transfer max 64 KB using a string instruction.

SI and/or DI are **incremented/decremented** after each operation depending upon the direction flag "**DF**" in the flag register.

If **DF = 0**, it is **auto increment**. This is done by **CLD instruction**.

If DF = 1, it is auto decrement. This is done by STD instruction.

1)MOVS: MOVSB/MOVSW (Move String)

It is used to transfer a word/byte from data segment to extra segment.

The offset of the source in data segment is in SI.

The offset of the destination in extra segment is in DI.

SI and DI are incremented / decremented depending upon the direction flag.

Eg: MOVSB ; $ES:[DI] \leftarrow DS:[SI]$... byte transfer

; $SI \leftarrow SI \pm 1 \dots$ depending upon DF ; $DI \leftarrow DI \pm 1 \dots$ depending upon DF

MOVSW ; $\{ES:[DI], ES:[DI + 1]\} \leftarrow \{DS:[SI], DS:[SI + 1]\}$

; $SI \leftarrow SI \pm 2$; $DI \leftarrow DI \pm 2$

2)LODS: LODSB/LODSW (Load String)

It is used to Load AL (or AX) register with a byte (or word) from data segment.

The offset of the source in data segment is in SI.

SI is incremented / decremented depending upon the direction flag (DF).

Eg: LODSB ; $AL \leftarrow DS:[SI]$... byte transfer

; $SI \leftarrow SI \pm 1 \dots$ depending upon DF

LODSW ; $AL \leftarrow DS:[SI]; AH \leftarrow DS:[SI + 1]$

; $SI \leftarrow SI \pm 2$

3)STOS: STOSB/STOSW (Store String)

It is used to **Store AL** (or AX) **into** a byte (or word) in the **extra segment**.

The offset of the source in extra segment is in DI.

DI is incremented / decremented depending upon the direction flag (DF).

Eg: **STOSB** ; ES:[DI] ← AL ... byte transfer

; DI ← DI ± 1 ... depending upon DF

STOSW ; ES:[DI] ← AL; ES:[DI+1] ← AH ... word transfer

; DI \leftarrow DI \pm 2 ... depending upon DF

4) CMPS: CPMSB/CMPSW (Compare String)

It is used to **compare** a **byte** (or word) **in** the **data segment with** a **byte** (or word) **in** the **extra segment**.

The offset of the byte (or word) in data segment is in SI. The offset of the byte (or word) in extra segment is in DI.

SI and DI are incremented / decremented depending upon the direction flag.

Comparison is done by subtracting the byte (or word) from extra segment from the byte (or word) from Data segment.

The Flag bits are affected, but the result is not stored anywhere.

```
Eg : CMPSB ; Compare DS:[SI] with ES:[DI] ... byte operation ; SI \leftarrow SI \pm 1 ... depending upon DF
```

; $DI \leftarrow DI \pm 1 \dots depending upon DF$

CMPSW ; Compare {DS:[SI], DS:[SI+1]}

; with $\{ES:[DI], ES:[DI+1]\}$; $SI \leftarrow SI \pm 2 \dots$ depending upon DF

; DI \leftarrow DI $\pm 2 \dots$ depending upon DF

5)SCAS: SCASB/SCASW (Scan String)

It is used to **compare** the contents of **AL** (or AX) **with** a **byte** (or word) **in** the **extra segment**. The offset of the byte (or word) in extra segment is in DI.

DI is incremented / decremented depending upon the direction flag (DF). Comparison is done by subtracting a byte (or word) from extra segment from AL (or AX). The Flag bits are affected, but the result is not stored anywhere.

```
Eg: SCASB ; Compare AL with ES:[DI] ... byte operation
```

; DI ← DI ± 1 ... depending upon DF

```
SCASW ; Compare {AX} with {ES:[DI], ES:[DI+1]}
```

; $DI \leftarrow DI \pm 1 \dots$ depending upon DF

REP (Repeat prefix used for string instructions)

This is an **instruction prefix**, which can be used in string instructions.

It can be used with string instructions only.

It causes the instruction to be repeated CX number of times.

After each execution, the SI and DI registers are incremented/decremented based on the DF (Direction Flag) in the Flag register and CX is decremented.

i.e. **DF = 1; SI, DI decrements.**

Thus, it is important that before we use the REP instruction prefix the following steps must be carried out:

CX must be initialized to the Count value. If **auto decrementing** is required, **DF** must be **set using STD** instruction **else cleared** using **CLD** instruction.

EG: MOV CX, 0023H

CLD

REP MOVSB

The above section of a program will cause the following string operation

ES:[DI] ← DS:[SI], SI ← SI + 1, DI ← DI + 1, CX ← CX - 1

to be executed 23H times (as CX = 23H) in auto incrementing mode (as DF is cleared).

6) REPZ/REPE (Repeat on Zero/Equal)

It is a conditional repeat instruction prefix. It behaves the same as a REP instruction **provided** the Zero Flag is set (i.e. ZF = 1). It is used with CMPS instruction.

7) REPNZ/REPNE (Repeat on No Zero/Not Equal)

It is a conditional repeat instruction prefix. It behaves the same as a REP instruction **provided** the Zero Flag is reset (i.e. ZF = 0). It is used with SCAS instruction.

Please Note: 8086 instruction set has only 3 instruction prefixes:

- **1) ESC** (to identify 8087 instructions)
- **2) LOCK** (to lock the system bus during an instruction)
- **3) REP** (to repeatedly execute string instructions)

For a question on instruction prefixes (asked repeatedly), explain the above in detail.