

Edge Computing Lab

Class: TY-AIEC

School of Computing, MIT Art Design Technology University

Academic Year: 2024-25

Experiment No. 7

Introduction

Study of Classification learning block using a NN Classifier on Edge Devices

Objective: Build a project to detect the keywords using built-in sensor on Nano BLE Sense / Mobile Phone

Tasks:

- Generate the dataset for keyword
- Configure BLE Sense / Mobile for Edge Impulse
- Building and Training a Model

Study of **Confusion matrix**

Introduction

Edge Impulse is a development platform for machine learning on edge devices, targeted at developers who want to create intelligent device solutions. The "classification block" equivalent in Edge Impulse would typically involve creating a simple machine learning model that can run on an edge device, like classifying sensor data or recognizing a basic pattern.

Materials Required

- Nano BLE Sense Board

Theory

GPIO (General Purpose Input/Output) pins on the Raspberry Pi are used for interfacing with other electronic components. BCM numbering refers to the pin numbers in the Broadcom SOC channel, which is a more consistent way to refer to the GPIO pins across different versions of the

Here's a high-level overview of steps you'd follow to create a "Hello World" project on Edge Impulse:

Steps to Configure the Edge Impulse:

1. Create an Account and New Project:
 - Sign up for an Edge Impulse account.
 - Create a new project from the dashboard.
2. Connect a Device:

- You can use a supported development board or your smartphone as a sensor device.
- Follow the instructions to connect your device to your Edge Impulse project.

3. Collect Data:

- Use the Edge Impulse mobile app or the Web interface to collect data from the onboard sensors.
- For a "Hello World" project, you could collect accelerometer data, for instance.

4. Create an Impulse:

- Go to the 'Create impulse' page.
- Add a processing block (e.g., time-series data) and a learning block (e.g., classification).
- Save the impulse, which defines the machine learning pipeline.

5. Design a Neural Network:

- Navigate to the 'NN Classifier' under the 'Learning blocks'.
- Design a simple neural network. Edge Impulse provides a default architecture that works well for most basic tasks.

6. Train the Model:

- Click on the 'Start training' button to train your machine learning model with the collected data.

7. Test the Model:

- Once the model is trained, you can test its performance with new data in the 'Model Testing' tab.

8. Deploy the Model:

- Go to the 'Deployment' tab.
- Select the deployment method that suits your edge device (e.g., Arduino library, WebAssembly, container, etc.).
- Follow the instructions to deploy the model to your device.

9. Run Inference:

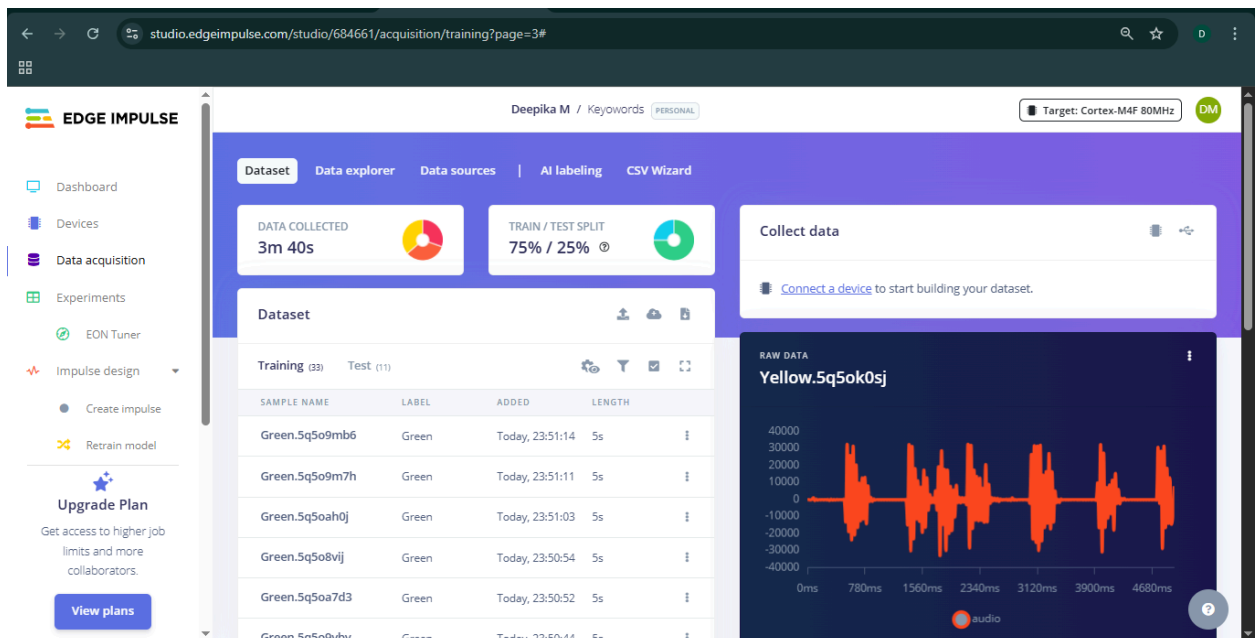
- With the model deployed, run inference on the edge device to see it classifying data in real-time.

10. Monitor:

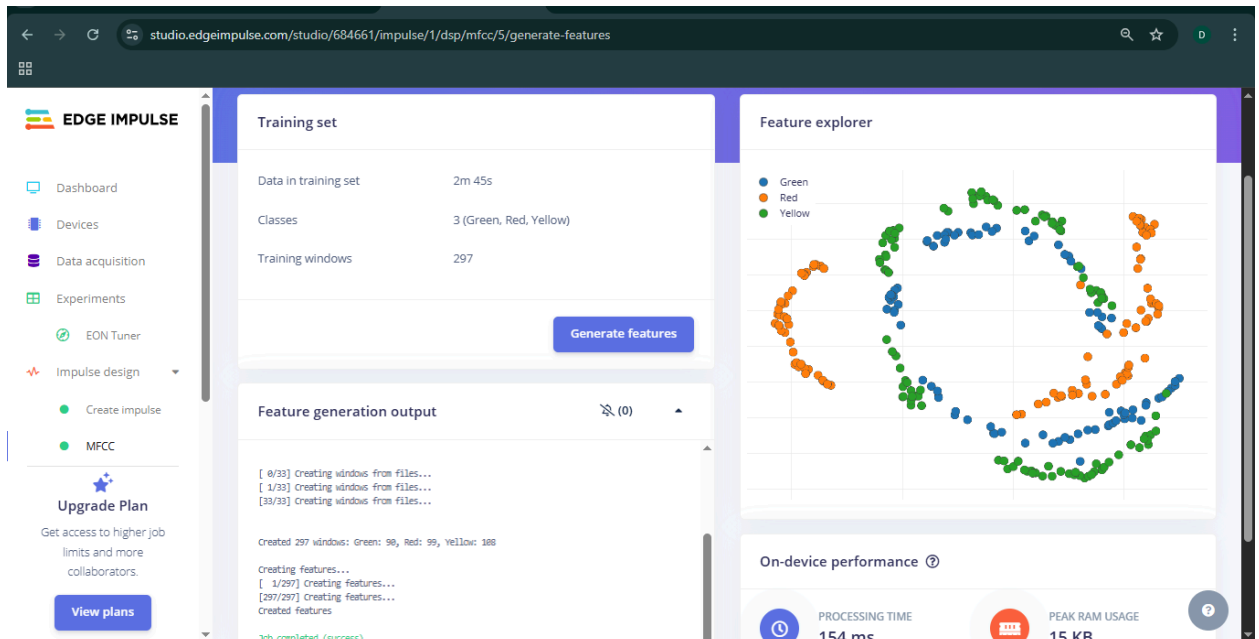
- You can monitor the performance of your device through the Edge Impulse studio.

Results:

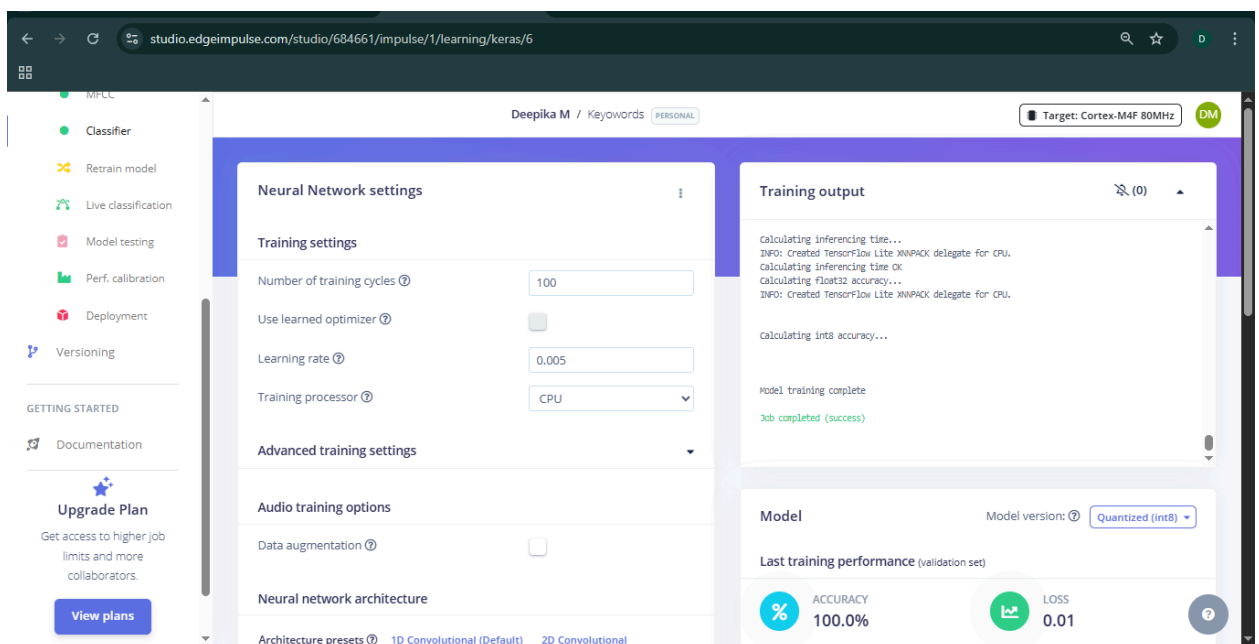
1) Dataset Image



2) Feature extraction - Image



3) Accuracy / Loss - Confusion Matrix – image



studio.edgeimpulse.com/studio/684661/impulse/1/learning/keras/6

- MFLC
- Classifier
- Retrain model
- Live classification
- Model testing
- Perf. calibration
- Deployment
- Versioning

GETTING STARTED

Documentation

Upgrade Plan
Get access to higher job limits and more collaborators.

[View plans](#)

Audio training options

Data augmentation ☐

Neural network architecture

Architecture presets ☒ 1D Convolutional (Default) ☐ 2D Convolutional

Input layer (650 features)

Reshape layer (13 columns)

1D conv / pool layer (8 filters, 3 kernel size, 1 layer)

Dropout (rate 0.25)

1D conv / pool layer (16 filters, 3 kernel size, 1 layer)

Dropout (rate 0.25)

Flatten layer

Add an extra layer

Model Model version:

Last training performance (validation set)

ACCURACY **100.0%** LOSS **0.01**

Confusion matrix (validation set)

	GREEN	RED	YELLOW
GREEN	100%	0%	0%
RED	0%	100%	0%
YELLOW	0%	0%	100%
F1 SCORE	1.00	1.00	1.00

Metrics (validation set)

METRIC	VALUE
Area under ROC Curve	1.00
Weighted average Precision	1.00
Weighted average Recall	1.00
Weighted average F1 score	1.00

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- MFLC
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GETTING STARTED

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Dropout (rate 0.25)

Flatten layer

Add an extra layer

Output layer (3 classes)

[Save & train](#)

Area under ROC Curve 1.00

Weighted average Precision 1.00

Weighted average Recall 1.00

Weighted average F1 score 1.00

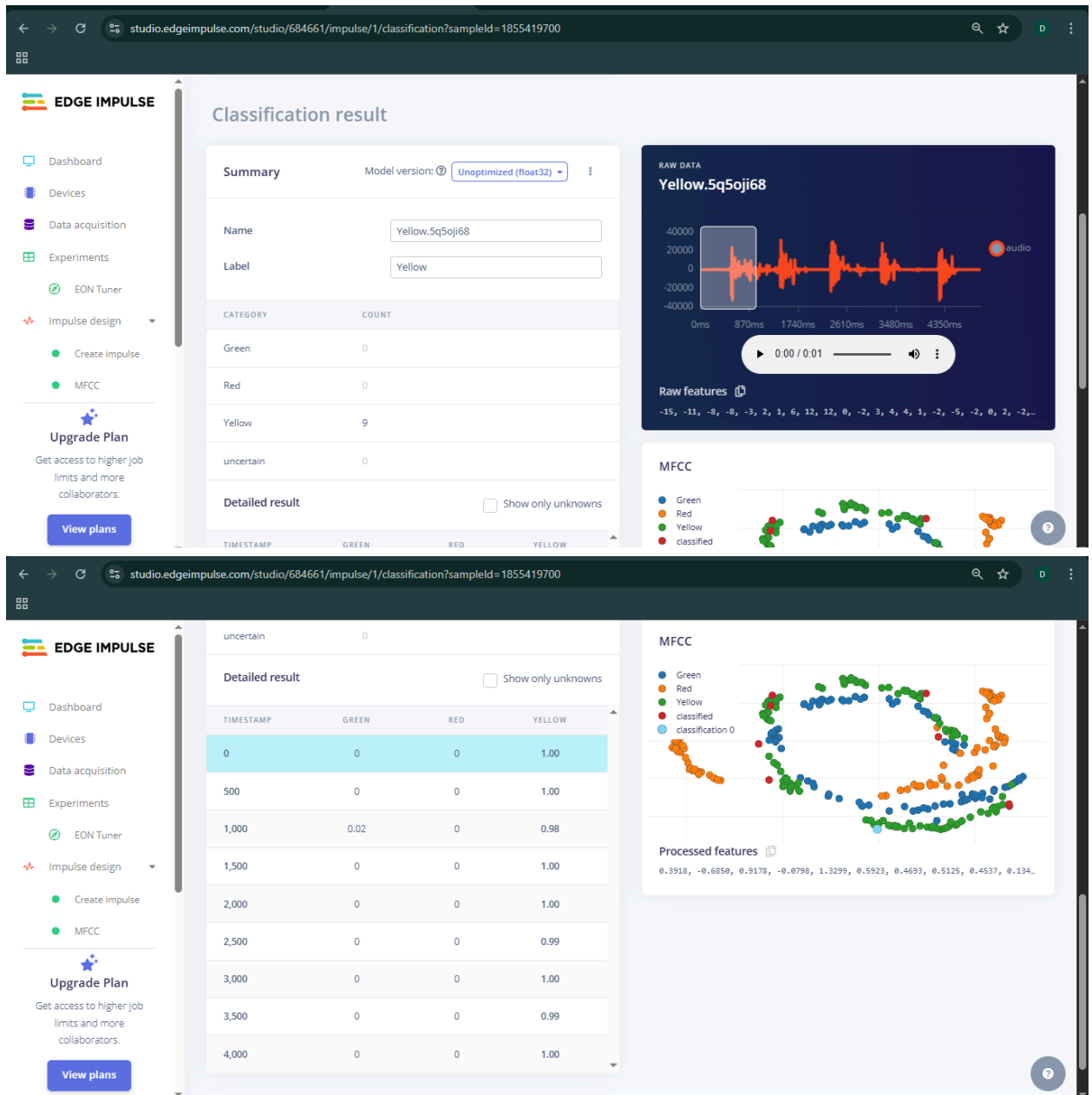
Data explorer (full training set)

Green - correct
Red - correct
Yellow - correct

On-device performance

Calculating... this could take a few minutes
[Show logs](#)

4) Validation Result – Image



5) Copy the code of Arduino Sketch

```

/* Edge Impulse ingestion SDK

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*

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*

```

```

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and

* limitations under the License.

*

*/

// If your target is limited in memory remove this macro to save 10K
RAM

#define EIDSP_QUANTIZE_FILTERBANK    0

/*

** NOTE: If you run into TFLite arena allocation issue.

**

** This may be due to may dynamic memory fragmentation.

** Try defining "-DEI_CLASSIFIER_ALLOCATION_STATIC" in
boards.local.txt (create

** if it doesn't exist) and copy this file to

**
`<ARDUINO_CORE_INSTALL_PATH>/arduino/hardware/<mbed_core>/<core_vers
ion>/`.

**

** See

**
(https://support.arduino.cc/hc/en-us/articles/360012076960-Where-are-the-installed-cores-located-)

** to find where Arduino installs cores on your machine.

**

```

```

    ** If the problem persists then there's not enough memory for this
    model and application.

    */

/* Includes
----- */

#include <PDM.h>

#include <Keywords_inferencing.h>

/** Audio buffers, pointers and selectors */
typedef struct {

    int16_t *buffer;

    uint8_t buf_ready;

    uint32_t buf_count;

    uint32_t n_samples;

} inference_t;

static inference_t inference;

static signed short sampleBuffer[2048];

static bool debug_nn = false; // Set this to true to see e.g.
features generated from the raw signal

/**
 * @brief      Arduino setup function
 */

void setup()

{

    // put your setup code here, to run once:

    Serial.begin(115200);

```



```

    // comment out the below line to cancel the wait for USB
connection (needed for native USB)

    while (!Serial);

    Serial.println("Edge Impulse Inferencing Demo");

    // summary of inferencing settings (from model_metadata.h)

    ei_printf("Inferencing settings:\n");

    ei_printf("\tInterval: %.2f ms.\n",
(float)EI_CLASSIFIER_INTERVAL_MS);

    ei_printf("\tFrame size: %d\n",
EI_CLASSIFIER_DSP_INPUT_FRAME_SIZE);

    ei_printf("\tSample length: %d ms.\n",
EI_CLASSIFIER_RAW_SAMPLE_COUNT / 16);

    ei_printf("\tNo. of classes: %d\n",
sizeof(ei_classifier_inferencing_categories) /
sizeof(ei_classifier_inferencing_categories[0]));

    if (microphone_inference_start(EI_CLASSIFIER_RAW_SAMPLE_COUNT)
== false) {

        ei_printf("ERR: Could not allocate audio buffer (size %d),
this could be due to the window length of your model\r\n",
EI_CLASSIFIER_RAW_SAMPLE_COUNT);

        return;

    }

}

/**

 * @brief      Arduino main function. Runs the inferencing loop.

 */

void loop()

{

    ei_printf("Starting inferencing in 2 seconds...\n");

```

```
delay(2000);

ei_printf("Recording...\n");

bool m = microphone_inference_record();

if (!m) {
    ei_printf("ERR: Failed to record audio...\n");
    return;
}

ei_printf("Recording done\n");

signal_t signal;
signal.total_length = EI_CLASSIFIER_RAW_SAMPLE_COUNT;
signal.get_data = &microphone_audio_signal_get_data;
ei_impulse_result_t result = { 0 };

EI_IMPULSE_ERROR r = run_classifier(&signal, &result, debug_nn);
if (r != EI_IMPULSE_OK) {
    ei_printf("ERR: Failed to run classifier (%d)\n", r);
    return;
}

// print the predictions
ei_printf("Predictions ");

ei_printf("(DSP: %d ms., Classification: %d ms., Anomaly: %d ms.) ",
```

```

        result.timing.dsp, result.timing.classification,
result.timing.anomaly);

    ei_printf(": \n");

    for (size_t ix = 0; ix < EI_CLASSIFIER_LABEL_COUNT; ix++) {

        ei_printf("    %s: %.5f\n", result.classification[ix].label,
result.classification[ix].value);

    }

#if EI_CLASSIFIER_HAS_ANOMALY == 1

    ei_printf("    anomaly score: %.3f\n", result.anomaly);

#endif

}

/**
 * @brief      PDM buffer full callback
 *
 *      Get data and call audio thread callback
 */
static void pdm_data_ready_inference_callback(void)
{

    int bytesAvailable = PDM.available();

    // read into the sample buffer

    int bytesRead = PDM.read((char *)&sampleBuffer[0],
bytesAvailable);

    if (inference.buf_ready == 0) {

        for(int i = 0; i < bytesRead>>1; i++) {

            inference.buffer[inference.buf_count++] =
sampleBuffer[i];

            if(inference.buf_count >= inference.n_samples) {

```

```

        inference.buf_count = 0;

        inference.buf_ready = 1;

        break;
    }

}

}

}

}

/**
 * @brief      Init inferencing struct and setup/start PDM
 *
 * @param[in]  n_samples  The n samples
 *
 * @return     { description_of_the_return_value }
 */
static bool microphone_inference_start(uint32_t n_samples)
{
    inference.buffer = (int16_t *)malloc(n_samples *
sizeof(int16_t));

    if(inference.buffer == NULL) {
        return false;
    }

    inference.buf_count = 0;

    inference.n_samples = n_samples;

    inference.buf_ready = 0;

    // configure the data receive callback

```

```

PDM.onReceive(&pdm_data_ready_inference_callback);

PDM.setBufferSize(4096);

// initialize PDM with:
// - one channel (mono mode)
// - a 16 kHz sample rate
if (!PDM.begin(1, EI_CLASSIFIER_FREQUENCY)) {
    ei_printf("Failed to start PDM!");
    microphone_inference_end();

    return false;
}

// set the gain, defaults to 20
PDM.setGain(127);

return true;
}

/**
 * @brief      Wait on new data
 *
 * @return     True when finished
 */
static bool microphone_inference_record(void)
{
    inference.buf_ready = 0;

```

```

inference.buf_count = 0;

while(inference.buf_ready == 0) {

    delay(10);

}

return true;
}

/**
 * Get raw audio signal data
 */
static int microphone_audio_signal_get_data(size_t offset, size_t
length, float *out_ptr)
{

    numpy::int16_to_float(&inference.buffer[offset], out_ptr,
length);

    return 0;
}

/**
 * @brief      Stop PDM and release buffers
 */
static void microphone_inference_end(void)
{

    PDM.end();

    free(inference.buffer);
}

```

```
#if !defined(EI_CLASSIFIER_SENSOR) || EI_CLASSIFIER_SENSOR !=  
EI_CLASSIFIER_SENSOR_MICROPHONE  
  
#error "Invalid model for current sensor."  
  
#endif
```

6) Screen shot of Arduino Terminal - Result

(I don't have a screenshot of the terminal. I'm extremely sorry)