Assignment - 4

Assignment Date	21 October 2022
Student Name	ABISHEK A S
Student Roll Number	813819205004
Maximum Marks	2 Marks

Question-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "Alert" to ibm cloud and display in device recent events.

Solution:

```
// Pins
const int TRIG_PIN = 7;
const int ECHO PIN = 8;
// Anything over 400 cm (23200 us pulse) is "out of range"
const unsigned int MAX DIST = 23200;
void setup() {
 // The Trigger pin will tell the sensor to range find
 pinMode(TRIG PIN, OUTPUT);
 digitalWrite(TRIG PIN, LOW);
 //Set Echo pin as input to measure the duration of
 //pulses coming back from the distance sensor
 pinMode(ECHO PIN, INPUT);
 // We'll use the serial monitor to view the sensor output
 Serial.begin(9600);
void loop() {
 unsigned long t1;
 unsigned long t2;
 unsigned long pulse width;
 float cm;
 float inches;
 // Hold the trigger pin high for at least 10 us
```

```
digitalWrite(TRIG PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG PIN, LOW);
// Wait for pulse on echo pin
while (digitalRead(ECHO PIN) == 0);
// Measure how long the echo pin was held high (pulse width)
// Note: the micros() counter will overflow after ~70 min
t1 = micros();
while (digitalRead(ECHO PIN) == 1);
t2 = micros();
pulse width = t2 - t1;
// Calculate distance in centimeters and inches. The constants
// are found in the datasheet, and calculated from the assumed speed
//of sound in air at sea level (\sim340 m/s).
cm = pulse width / 58.0;
inches = pulse width / 148.0;
// Print out results
if (pulse width > MAX DIST) {
 Serial.println("Out of range");
} else {
 Serial.println("*******************************);
 Serial.print("The Measured Distance in cm : ");
 Serial.println(cm);
 if(cm<100){
  // while(true){
  Serial.println("Alert!!");
  // }
// Wait at least 1000ms before next measurement
delay(1000);
```

Output:

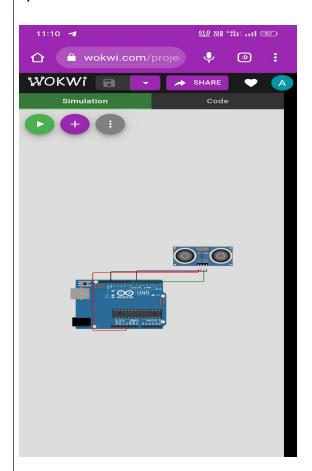
1)If the distance is less than 100 cms, it alerts.

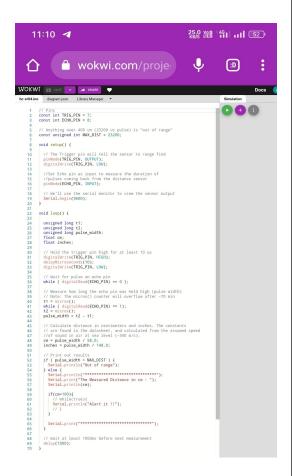
```
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           // Pins
const int TRIG_PIN = 7;
                                                                                                     5
           const int ECHO_PIN = 8;
           // Anything over 400 cm (23200 us pulse) is "out of range" const unsigned int MAX_DIST = 23200;
           void setup() {
            // The Trigger pin will tell the sensor to range find
pinMode(TRIG_PIN, OUTPUT);
digitalWrite(TRIG_PIN, LOW);
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            //Set Echo pin as input to measure the duration of
//pulses coming back from the distance sensor
pinMode(ECHO_PIN, INPUT);
             // We'll use the serial monitor to view the sensor output
             Serial.begin(9600);
                                                                                                                                 NAME OF STATES
     21
           void loop() {
             unsigned long t1;
             unsigned long t2;
unsigned long pulse_width;
float cm;
float inches;
                                                                                                   The Measured Distance in cm : 84.14
                                                                                                   **********
                                                                                                                                                                                     // Hold the trigger pin high for at least 10 us
```

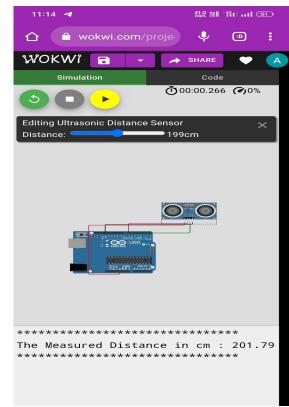
2)If the distance is more than 100 cms, it won't alert.

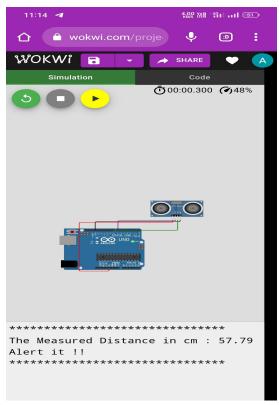
```
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 hc-sr04.ino
         // Pins
                                                                                                                                                     Ō00:00.599 (%62%
         const int TRIG_PIN = 7;
        const int ECHO_PIN = 8;
         // Anything over 400 cm (23200 us pulse) is "out of range"
        const unsigned int MAX_DIST = 23200;
         void setup() {
          // The Trigger pin will tell the sensor to range find
pinMode(TRIG_PIN, OUTPUT);
    10
    11
          digitalWrite(TRIG_PIN, LOW);
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    13
    14
          //Set Echo pin as input to measure the duration of
    15
          //pulses coming back from the distance sensor
    16
          pinMode(ECHO_PIN, INPUT);
    17
    18
          // We'll use the serial monitor to view the sensor output
    19
          Serial.begin(9600);
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    20
    21
    22
         void loop() {
    23
          unsigned long t1;
                                                                                    **********
           unsigned long t2;
                                                                                    The Measured Distance in cm : 227.10
          unsigned long pulse_width;
    27
           float cm;
                                                                                                                                    Activate Windows
          float inches;
                                                                                                                                    Go to Settings to activate Windows
                                                                                                                                                           <u>⊬</u> II ©
         // Hold the trigger pin high for at least 10 us
```

3) Simulation and code execution









Project Link:							
https://	wokwi.co	m/project	cs/3461364	1 <u>29340918</u>	<u>356</u>		