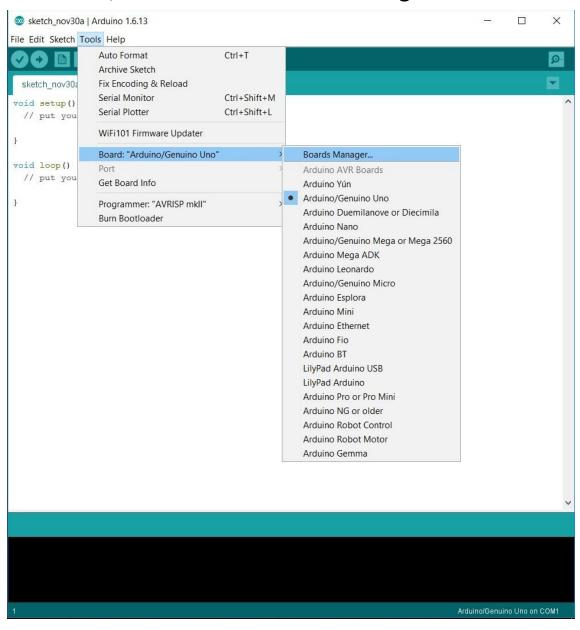


ESP32

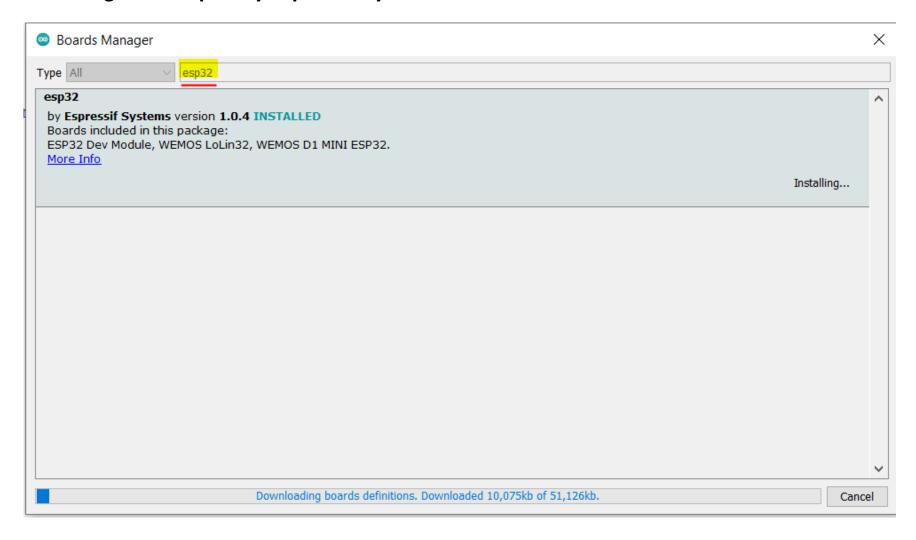
- Open the Arduino IDE.
- Go to Files and click on the Preference in the Arduino IDE.
- Copy the URL below in the Additional boards Manager.
 - https://raw.githubusercontent.com/espressif/arduino-esp32/gh-pages/package_esp32_index.json
- Click **OK** to close the preference Tab.

Preferences				
Settings Network				
Sketchbook location:				
C:\Users\z665059\OneDrive - Z	F Friedrichshafen AG\Documents\Arduino	Browse		
Editor language:	System Default v (requires restart of Arduino)			
Editor font size:	18			
Interface scale:	✓ Automatic 100 → % (requires restart of Arduino)			
Theme:	Default theme ∨ (requires restart of Arduino)			
Show verbose output during: 🗸 compilation 🗸 upload				
Compiler warnings: None V				
☑ Display line numbers	Enable Code Folding			
✓ Verify code after upload	Use external editor			
☐ Check for updates on startup				
Use accessibility features				
Additional Boards Manager URLs: .githubusercontent.com/espressif/arduino-esp32/gh-pages/package_esp32_index.json				
More preferences can be edited directly in the file				
C:\Users\z665059\AppData\Local\Arduino15\preferences.txt				
(edit only when Arduino is not running)				
	ОК	Cancel		

Go to Tools and Board, and then select Board Manager.

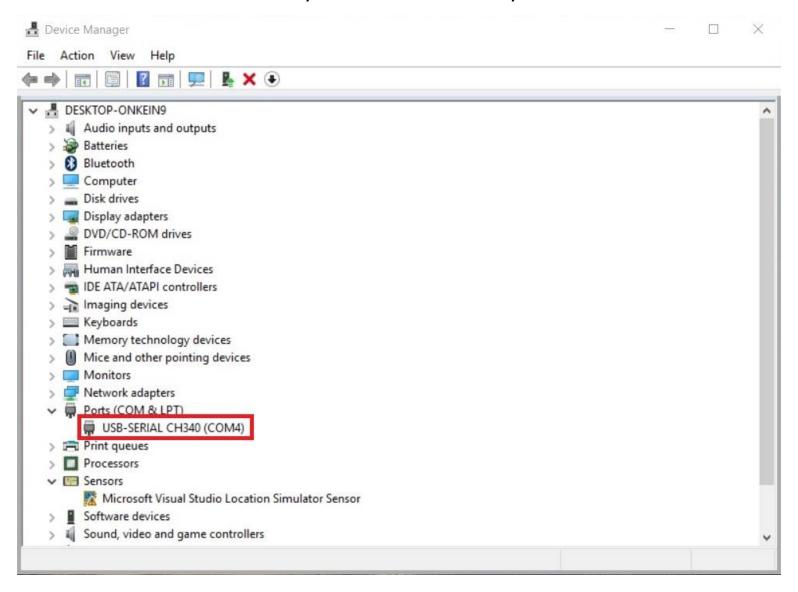


Navigate to esp32 by Espressif Systems and install the software for Arduino.



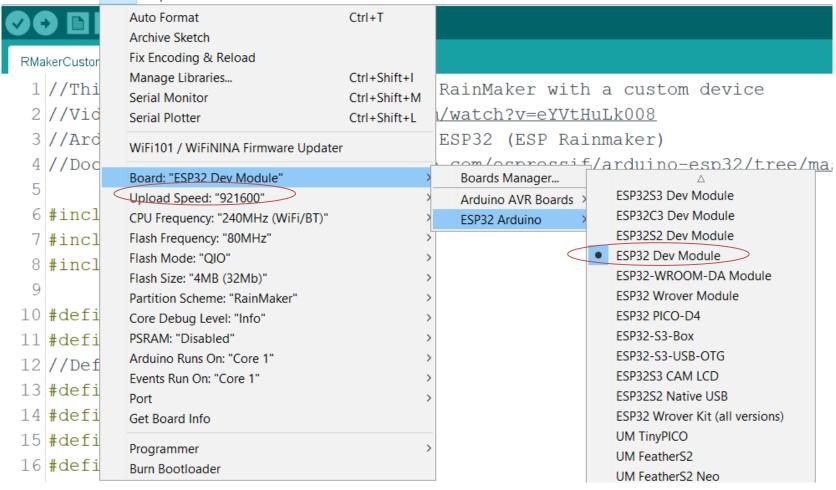
 Once all the above process has been completed we are ready to program our ESP32 with Arduino IDE.

- Connect ESP32 to PC with USB to microUSB cable.
- Windows should automatically download necessary drivers for it.



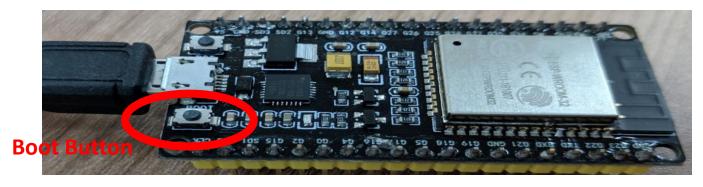
RMakerCustom | Arduino 1.8.13

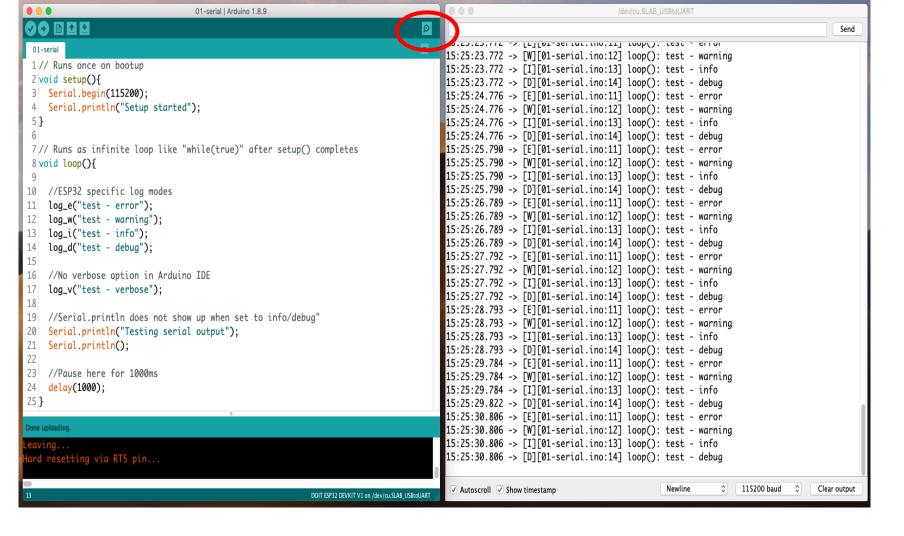
File Edit Sketch Tools Help



01-Serial

- 1. Verify Portable Arduino SDK installed correctly by Blinking OnBoard Led
- How to flash an ESP32 program?
 By Pressing BOOT Button when connecting......
- 3. Using the serial console and ESP32 log facility





- Magnifying glass opens serial console
- Show Timestamps
- Newline
- 115200 baud

02-Blinky

- 1. Do NOT Connect an LED, use OnBoard LED at pin no 2
- 2. Blink from the LED
- 3. #define PIN_LED 2

Blinky Video kept in 02-Blinky Folder



Basics of Wi-Fi

- Devices that connect to Wi-Fi network are called stations.
- Connection to Wi-Fi is provided by an access point, that acts as a hub for one or more stations.
- Each access point is recognized by a SSID (Service Set IDentifier).
- Clients can access services provided by servers in order to send, receive and process data.
- Server provide functionality to other programs or devices, called clients.
- We need to use ESP8266WiFi library to make Wi-Fi applications on NodeMCU.

WiFi library for ESP8266

WiFi.begin(ssid, password, channel, bssid, connect)
 Meaning of parameters is as follows:

ssid - a character string containing the SSID of Access Point we would like to connect to, may have up to 32 characters

password to the access point, a character string that should be minimum 8 characters long and not longer than 64 characters

channel of AP, if we like to operate using specific channel (optional)

bssid - mac address of AP (optional)

connect - a boolean parameter that if set to false, will instruct module just to save the other parameters without actually establishing connection to the access point

WiFi.localIP()

Station Mode

WiFi.status()

Function returns one of the following connection statuses:

WL_CONNECTED after successful connection is established
WL_NO_SSID_AVAILin case configured SSID cannot be reached
WL_CONNECT_FAILED if password is incorrect
WL_IDLE_STATUS when Wi-Fi is in process of changing between statuses
WL_DISCONNECTED if module is not configured in station mode

WiFi.isConnected()

Soft Access Point Mode

- WiFi.softAP(ssid, password, channel, hidden)
- The first parameter of this function is required, remaining three are optional.
- Meaning of parameters

channel - optional parameter to set Wi-Fi channel, from 1 -13. Default channel is 1. **hidden** - optional parameter, if set to true will hide SSID

- Function will return true or false depending on result of setting the soft-AP
- WiFi.softAPgetStationNum()
- The maximum number of stations that may be connected to ESP8266 soft-AP is five.

Scanning

- WiFi.scanNetworks()
- WiFi.scanNetworks(async, show hidden)
- Both function parameters are of boolean type.

asysnc - if set to true then scanning will start in background and function will exit without waiting for result. To check for result use separate function.

show_hidden - set it to true to include in scan result networks with hidden SSID.

WiFi.scanComplete()

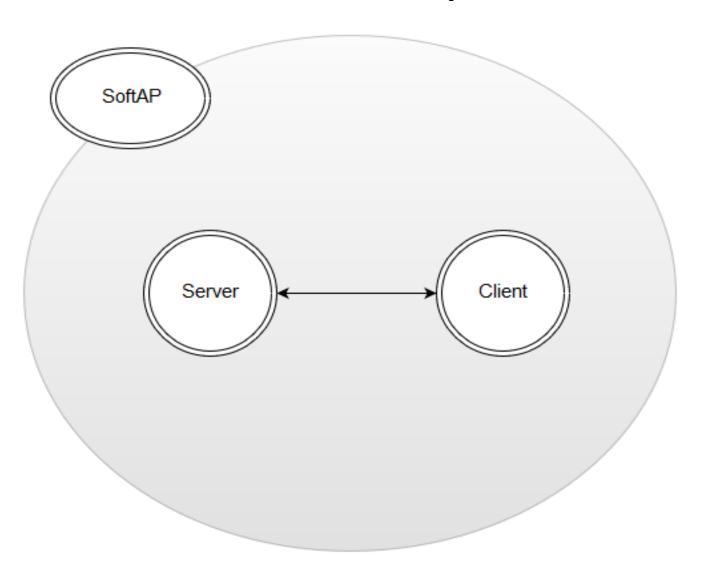
Client Mode

- Create a client object using
- WiFiClient client;
- Declare server address using
- IPAddress server(74,125,115,105);
- client.connect(server, 80)
- client.stop()
- client.available()
- Returns the number of bytes available for reading
- client.write(data)
- Write data to the server the client is connected to
- client.read()
- Read the next byte received from the server the client is connected to (after the last call to read()).

Server Mode

- WiFiServer server(80);
- Creates a server that listens for incoming connections on the specified port.
- server.begin()
- server.available()
- Returns a Client object, if no Client has data available for reading, this object will return false.
- server.write(data)
- Write data to all the clients connected to a server (one byte at a time).
- To read data from client use available to get client object and use client.read() to read data.

Basic Example



Writing your first program (sketch)

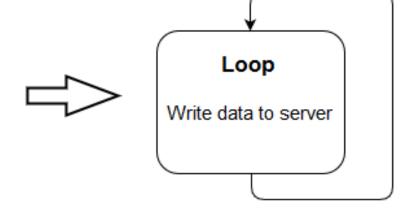
- The code always has at least 2 functions
 - setup()
 - loop()
- The setup() function is called when a sketch starts. Use it to initialize variables, pin modes, start using libraries, etc.
- The setup function will only run once, after each power up or reset.
- After creating a setup() function, which initializes and sets the initial values, the loop() function does precisely what its name suggests, and loops consecutively.
- Its very similar to C/C++.

Client

Setup

Initialize Serial port; Connect to WiFi network; Check if successfully connected; Disable Nagle Algorithm; Connect to server;

Serial.begin(baud);
Serial.println();
WiFi.begin(ssid, password);
WiFi.status();
client.setNoDelay(true);
client.connect(server,port);

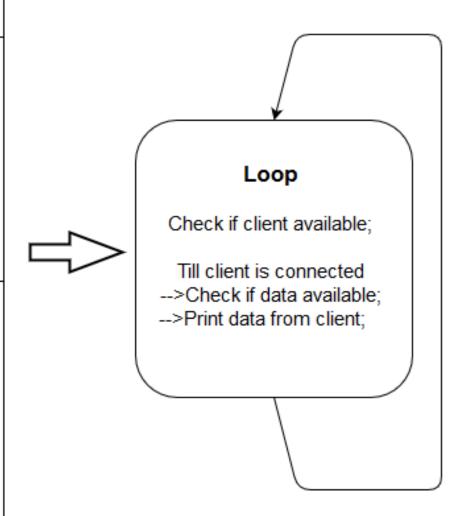


Server

Setup

Initialize Serial port; Connect to WiFi network; Check if successfully connected; Start server; Get IP Address

> Serial.begin(baud); Serial.println(); WiFi.begin(ssid, password); WiFi.status(); server.begin(); WiFi.locallP();



PART2

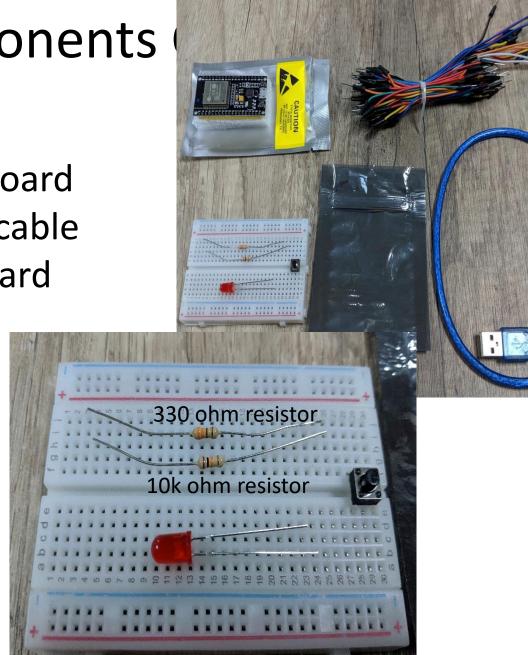
ESP32

SDK installation

- https://github.com/yeokm1/iot-esp32-mcu-workshop
- Install Serial Virtual Com Port drivers for your operating system if needed
 - https://www.silabs.com/products/development-tools/software/usb-touart-bridge-vcp-drivers
- Install Arduino IDE:
 - https://www.arduino.cc/en/main/software
- Install ESP32 SDK addon to Arduino IDE
 - Add the following path to Additional Boards URL configuration
 - https://dl.espressif.com/dl/package_esp32_index.json

Components

- ESP32 breakout board
- 50cm micro-USB cable
- Half-size breadboard
- Bunch of wires
- In ESD bag
 - Red LED
 - Push button
 - 330 ohm resistor
 - 10k ohm resistor



31

Agenda

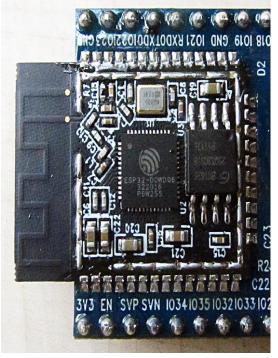
- Basics of Wifi
 - 1. Setup ESP32 as a Station
 - 2. Setup ESP32 as a AP
- Basics of electronics
 - 1. Serial Setting up of software SDK and testing
 - 2. Blink Connecting and blinking LED
 - 3. Button Connecting button and try to detect press
 - 4. Debounce Concept of input debouncing
- The "Internet" portion of IoT
 - 5. Post Posting Request to a server on button press
 - Get Repeatedly polling the server for on or off instruction

ESP32 chip vs ESP32 module vs ESP32

hreakout





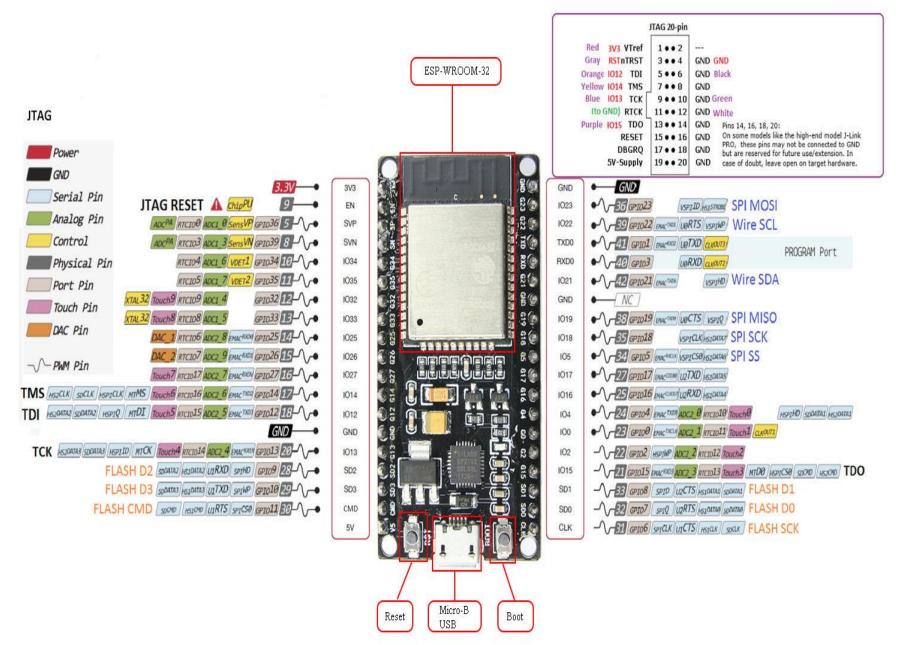




ESP32 Specs



Specs	Value	
CPU	Xtensa dual/single-core 32-bit LX6 microcontroller, operating at 160/240 MHz	
RAM	520 KiB	
Flash memory	4 - 16 MiB	
Network Connectivity	Wifi 802.11n 2.4Ghz + BT 4.2	
Peripheral Interfaces	3x UART, 2x SPI, 2x I2C, ADC, SD touch sensors, etc	



Why not single-board computers like





Specs	Arduino-compatible ESP32	Raspberry Pi 4 B
CPU type	Microcontroller	Microprocessor
Speed	Dual Core 160/240Mhz	Quad core 1.5 Ghz
RAM	520KB	1 - 4 GB
GPU/Display	None	VideoCore VI GPU, 4K
Disk	4 MiB	Depends on microSD card
Other connectivity	Wifi 802.11n 2.4Ghz + BT 4.2	USB, Ethernet, HDMI, audio, Wifi 2.4/5Ghz 802.11ac, BT 5.0
Operating System	None	Linux (usually Raspbian)
Real Time Operation	Better	Poorer
Typical Power	0.8W	8W

Arduino SDK

Easy to use cross-platform IDE for microcontroller programming

Support for mar

C/C++ language

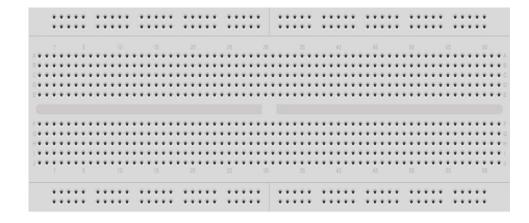
Numerous librar

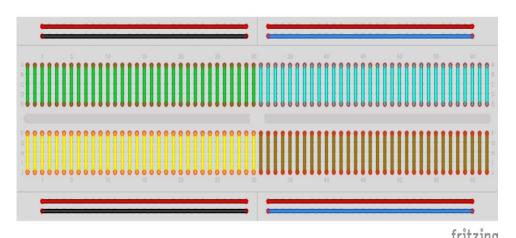


```
/dev/cu.SLAB_USBtoUART
 1 // Runs once on bootup
                                                                                      10:44:54.708 -> rst:0x10 (RTCWDT_RTC_RESET),boot:0x13 (SPI_FAST_FLASH_BOOT)
 2 void setup(){
                                                                                      10:44:54.708 -> configsip: 0, SPIWP:0xee
 3 Serial.begin(115200);
                                                                                      10:44:54.708 -> clk_drv:0x00,q_drv:0x00,d_drv:0x00,cs0_drv:0x00,hd_drv:0x00,wp_drv:0x00
   Serial.println("Setup started"):
                                                                                       10:44:54.708 -> mode:DIO, clock div:2
                                                                                       10:44:54.708 -> load:0x3fff0018.len:4
    //ESP32 specific log modes
                                                                                      10:44:54.708 -> load:0x3fff001c.len:1100
    log_e("test - error");
                                                                                      10:44:54.708 -> load:0x40078000,len:9232
   log_w("test - warning");
                                                                                       10:44:54.708 -> load:0x40080400,len:6412
   log_i("test - info");
                                                                                       10:44:54.708 -> entry 0x400806a8
   log_d("test - debug");
                                                                                       10:44:54.857 -> Setup started
                                                                                       10:44:54.857 -> [E][01-serial.ino:7] setup(): test - error
    //No verbose option in Arduino IDE
                                                                                      10:44:54.857 -> [W][01-serial.ino:8] setup(): test - warning
   log_v("test - verbose");
                                                                                      10:44:54.857 -> [I][01-serial.ino:9] setup(): test - info
                                                                                      10:44:54.857 -> [D][01-serial.ino:10] setup(): test - debug
                                                                                       10:44:55.821 -> Testing serial output
16 // Runs as infinite loop like "while(true)" after setup() completes
                                                                                      10:44:56.847 -> Testing serial output
17 void loop(){
                                                                                      10:44:57.833 -> Testing serial output
   Serial.println("Testing serial output");
                                                                                       10:44:58.832 -> Testing serial output
                                                                                       10:44:59.832 -> Testing serial output
   //Pause here for 1000ms
                                                                                       10:45:00.850 -> Testing serial output
   delay(1000);
                                                                                      10:45:01.846 -> Testing serial output
                                                                                      10:45:02.832 -> Testing serial output
                                                                                      10:45:03.851 -> Testing serial output
                                                                                       10:45:04.832 -> Testing serial output
                                                                                       10:45:05.850 -> Testing serial output
                                                                                       10:45:06.820 -> Testing serial output
                                                                                       10:45:07.822 -> Testing serial output
                                                                                       10:45:08.838 -> Testing serial output
                                                                                       10:45:09.830 -> Testing serial output
                                                                                       10:45:10.846 -> Testing serial output
                                                                                       10:45:11.850 -> Testing serial output
                                                                                       10:45:12.822 -> Testing serial output
                                                                                       10:45:13.851 -> Testing serial output
                                                                                       10:45:14.840 -> Testing serial output
                                                                                       10:45:15.836 -> Testing serial output
                                                                                       10:45:16.824 -> Testing serial output
                                                                                       10:45:17.843 -> Testing serial output
                                                                                       10:45:18.834 -> Testing serial output
                                                                                        A.4E.10 072 . Tacking camial autou
                                                                                                                                                                         115200 baud
                                                                                                                                                   Newline
                                                                                                                                                                                                Clear output
                                                                                           Autoscroll  Show timestamp
                                              DOIT ESP32 DEVKIT V1 on /dev/cu.SLAB_USBtoUAR3
```

Half/Full Breadboard

- Base Prototyping component
- Continuous lines indicate those holes are



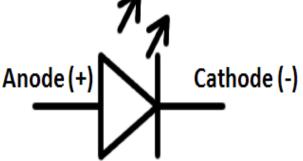


- Horizontal usually for power
- Convention: Red for +,
 Black/Blue for -
- Vertical for your



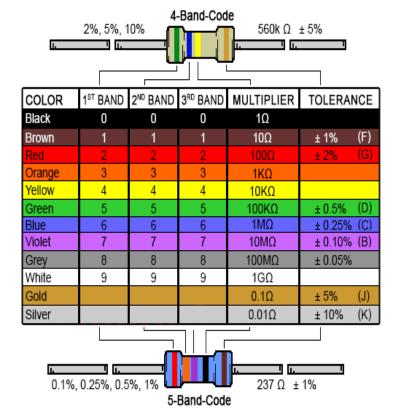
- "A light-emitting diode (LED) is
 a semiconductor light source that emits light
 when current flows through it."

- Anode +: Longer leg
- Cathode -: Shorter Leg



Resistor

- Resists the flow of current
- Resistor Colour bands
- 4-band 330 ohm
 - Orange, Orange, Brown, Gold
 - 3, 3, x10, 5% tolerance
- 4-band 10K ohm
 - 1, 0, x1000, 5% tole
 - Blown, Black, Orang



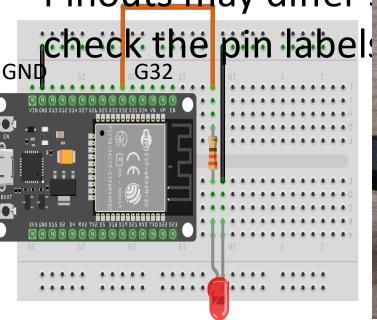


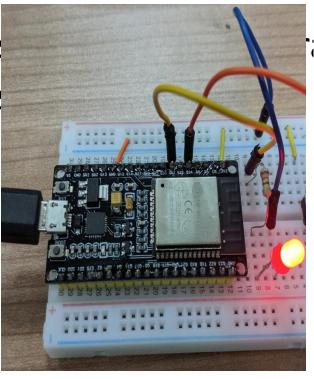
Connecting the LED setup

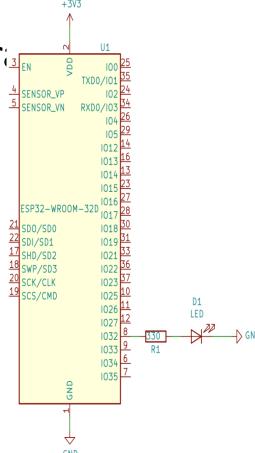
Unplug USB cable before working on electronics

 Breadboard + ESP32 board (G32, GND) + 330 ohm resistor + LED + wires

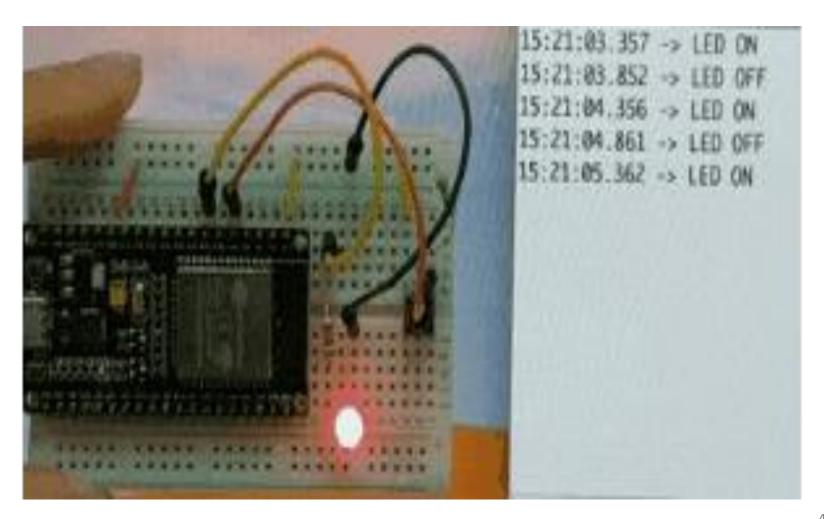
Pinouts may differ







Program the board with 02-blinky.ino



03-button button setup

• 10k ohm resistor + button + wires -> G34

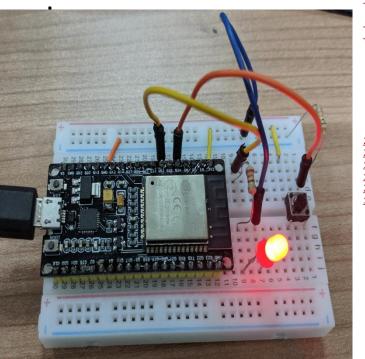
Actual breakout 3V3 pin position differs from

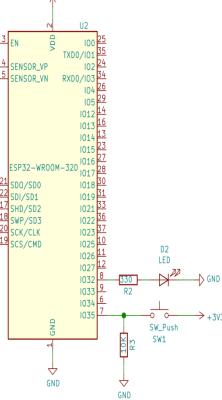
picture

• "Pull down" resistor

GND G32 G34

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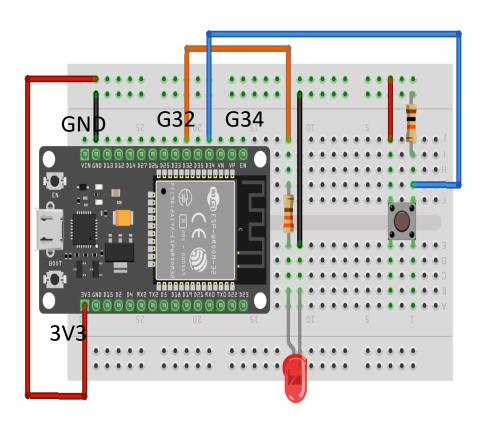


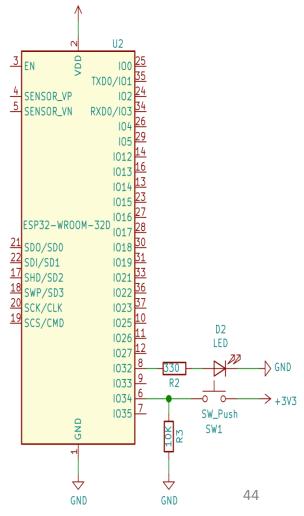


Pull down resistor for button

Resistor "pulls" IO34 to ground when button is released

Guarantees that IO34 pin goes to 0



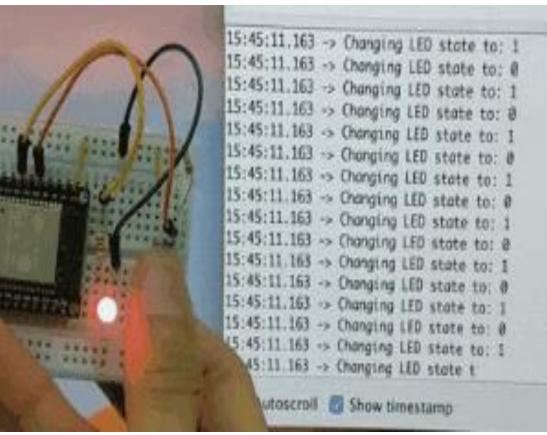


Program the board with 03-button.ino

We want to toggle LED on each button press

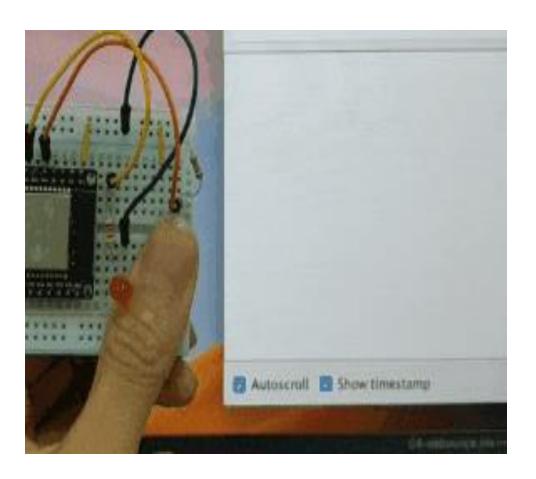
Observe looping speed of button press detection is too fast to

be useful



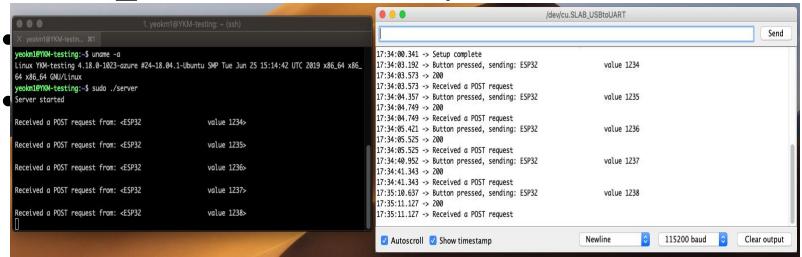
04-debounce

Process one input within an interval



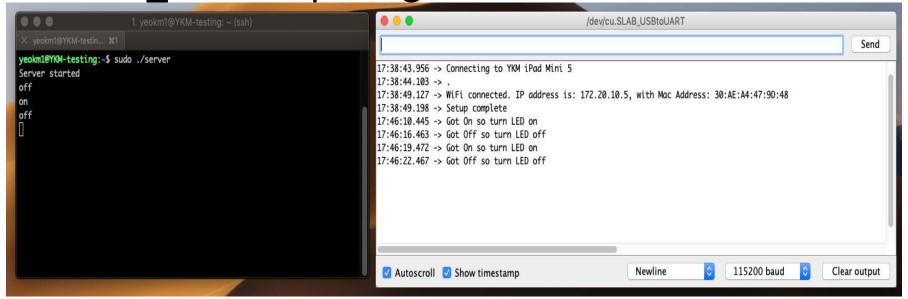
05-wifi-post

- Making a POST request to the server via a button press
- Able to receive a POST request using a Go program
- WIFI_SSID: iot-workshop



06-wifi-get

- 1. Making a Get Request to a server to get instruction
- 2. Serve a GET request using a Go program
- WIFI_SSID: iot-workshop
- WIFI PASS: esp32isgreat



Useful websites

- http://frightanic.com/iot/comparison-of-esp8266-nodemcu-development-boards/
- https://www.gitbook.com/book/krzychb/esp8266wifi-library/details
- https://github.com/esp8266/Arduino/blob/master/doc/reference.md
- http://www.esp8266.com/wiki/doku.php
- https://github.com/esp8266/Arduino/blob/master/doc/libraries.md
- http://esp8266.github.io/Arduino/versions/2.0.0/doc/libraries.html

Thank You