

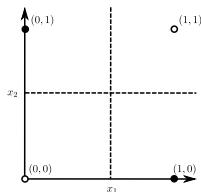
1. Feedforward neural networks

1.2. Structure and optimization criteria

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Introduction

- The perceptron unit presented before is linear.
- Nonlinear problems, as the classic XOR problem, cannot be solved with a perceptron.

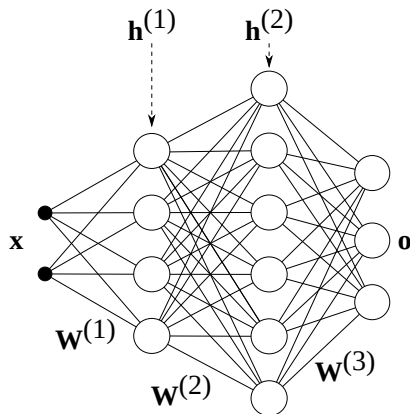


- The data labels are a XOR function of its coordinates: black dots are labelled with $+1$, white dots are labelled with 0 .

- A linear function cannot classify the data. It is possible to construct a nonlinear function with several perceptrons in two layers.

Structure of a neural network

- $L + 1$ layers, layer $j = 0$ is the input \mathbf{x}
- $L - 1$ *hidden* layers with D_j nodes with outputs $\mathbf{h}^{(j)}$.
- The last layer implements the output \mathbf{o} .
- Layers interconnected by linear weights $\mathbf{W}^{(j)}$.



Structure of a neural network

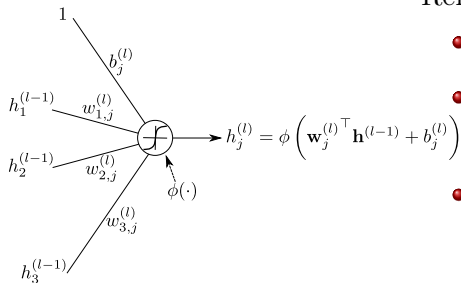
- The layers are interconnected by edges. Each edge contains a weight $w_{i,j}^{(l)}$ that connects the output of node i of layer $l - 1$ to the input of node j in layer l . Also, each node has a bias input $b_j^{(l)}$.
- Each node contains an affine transformation of the output of the previous layer as

$$z_j^{(l)} = \sum_{i=1}^{D_{l-1}} w_{i,j}^{(l)} h_i^{(l-1)} + b_j^{(l)} = \mathbf{w}_j^{(l)\top} \mathbf{h}^{(l-1)} + b_j^{(l)} \quad (1)$$

- The output j of layer l , $h_j^{(l)}$ is

$$h_j^{(l)} = \phi \left(z_j^{(l)} \right) = \phi \left(\mathbf{w}_j^{(l)\top} \mathbf{h}^{(l-1)} + b_j^{(l)} \right) \quad (2)$$

A neuron



Remarks:

- $b_j^{(l)}$ implements the bias.
- In some notations, $b_j^{(l)} = w_{0,j}^{(l)}$ and $h_0^{(l-1)} = 1$.
- Element $w_{i,j}^{(l)}$ of vector $\mathbf{w}_j^{(l)}$ represents the connection of node i of layer $l-1$ with node j of layer l .

- The nonlinear activation for a hidden layer is not usually a sigmoidal, as we will see further.

Notation conventions

The following general notation conventions are taken in this course:

- Lowercase, normal letters as b, w represent scalars, i.e. $b \in \mathbb{R}$.
- Uppercase normal letters as D, N represent constants.
- Lowercase bold letters as \mathbf{b}, \mathbf{w} are column vectors.
- Uppercase bold letters as \mathbf{W} are arrays. In this module, they are all 2D matrices, i.e, for example, $\mathbf{W} \in \mathbb{R}^{D_1 \times D_2}$ is a matrix of D_1 rows and D_2 columns. In general, an array may have more than 2 dimensions.

Notation conventions

The following conventions particular to the structure of neural networks are taken:

- Superindex (l) between parenthesis refer to output layers. $\mathbf{W}^{(l)}$ refers to a matrix of weights that connects layer $l - 1$ to layer l .
- Subindex i in vector $\mathbf{w}_i^{(l)}$ mean that this vector is the i -th column of matrix $\mathbf{W}^{(l)}$. $\mathbf{w}_i^{(l)}$ is then a *column vector*.
- $\mathbf{b}^{(l)}$ is a *column vector* containing all the biases of layer l .
- Subindexes i, j in scalar $w_{i,j}^{(l)}$ mean, equivalently, that:
 - $w_{i,j}^{(l)}$ is the connection between node i of layer $l - 1$ and node j of layer l .
 - $w_{i,j}^{(l)}$ is i -th element of vector $\mathbf{w}_j^{(l)}$
 - $w_{i,j}^{(l)}$ is element i, j of matrix $\mathbf{W}^{(l)}$.

Activations for hidden nodes

- The first activation for hidden nodes to be used was the sigmoid

$$\sigma(z) = \frac{1}{1 + e^{-z}}$$

- Modern neural networks use the so-called rectified linear unit (ReLU)

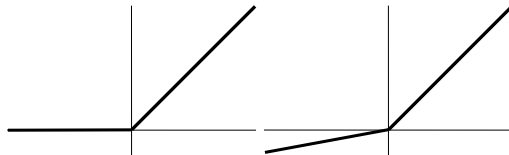
$$\phi(z) = \max(0, z) \quad (3)$$

- ReLU is enough to provide the NN with nonlinear properties.
- A nonzero gradient extension of the ReLU is

$$\phi(z_i) = \max\{0, z_i\} + \alpha_i \min\{0, z_i\} \quad (4)$$

Rectified Linear Units

- Three versions of this activation are extremely useful.
 - *Absolute value* $\phi(z_i, \alpha_i) = \max\{0, z_i\} - \min\{0, z_i\} = |z_i|$
 - *Leaky ReLU*, for small values of α_i
 - *Parametric ReLU* or PReLU, when α_i is learnable using gradient descent.



Left: Rectified Linear Unit (ReLU). Right: Leaky ReLU.

- Maxout units divide \mathbf{z} in groups of k elements, outputs the maximum

$$\phi(z)_i = \max_{j \in G^i}(z_j) \quad (5)$$

- Maxout units can generalize any of the above activations.

Training criterion: Maximum Likelihood

- Assume a dataset $\{\mathbf{x}_i, \mathbf{y}_i\}$, $1 \leq i \leq N$. If training outputs \mathbf{y}_i are independent given their corresponding inputs \mathbf{x}_i , the joint likelihood is equal to the product of likelihoods, this is

$$p(\mathbf{Y}|\mathbf{X}) = \prod_i p(\mathbf{y}_i|\mathbf{x}_i) \quad (6)$$

- Applying logarithms and dividing by the number of training data N

$$J_{ML}(\boldsymbol{\theta}) = -\frac{1}{N} \log p(\mathbf{Y}|\mathbf{X}) = -\frac{1}{N} \sum_i \log p(\mathbf{y}_i|\mathbf{x}_i) \approx -\mathbb{E}_{\mathbf{x}, \mathbf{y}} \log p(\mathbf{y}|\mathbf{x}) \quad (7)$$

where θ represents the set of parameters $w_{j,k}^{(l)}$, $b_k^{(l)}$ to optimize.

- This is the cross entropy between the real and predicted probabilities (as we will see later).

- In order to minimize overfitting, many approaches use a regularization factor in the cost function that minimizes the square norm of the parameters, such as

$$J(\boldsymbol{\theta}) = J_{ML}(\boldsymbol{\theta}) + \lambda \sum_l \|\mathbf{W}^{(l)}\|_F^2 \quad (8)$$

where $\|\cdot\|_F^2$ is the squared Frobenius norm operator.

$$\|\mathbf{W}^{(l)}\|_F^2 = \sum_{j,k} w_{j,k}^2 \quad (9)$$

- Other forms of regularization as dropout, early stopping or data augmentation will also be discussed.

Posterior distributions

- Depending on the posterior distribution that we choose, the interpretation and the uses will be different. We will primarily use
 - Gaussian posterior for regression

$$p(\mathbf{y}|\mathbf{x}) = \frac{1}{(2\pi)^{D/2}|\mathbf{\Sigma}|^{1/2}} e^{(-\frac{1}{2}(\mathbf{y}-\mathbf{z})^\top \mathbf{\Sigma}^{-1}(\mathbf{y}-\mathbf{z}))} \quad (10)$$

- Sigmoid activation for binary classification

$$p(y = 1|\mathbf{x}) = \frac{1}{1 + e^{-yz}} \quad (11)$$

- Softmax activations for multiclass classification

$$p(y = k|\mathbf{x}) = \frac{e^{z_k}}{\sum_{j=1}^K e^{z_j}}$$

Gaussian posterior for regression

- Interpreted as a regression model with linear output.
- The estimation error components are considered independent

$$p(\mathbf{y}|\mathbf{x}) = \frac{1}{(2\pi\sigma^2)^{D/2}} \exp\left(-\frac{1}{2\sigma^2}\|\mathbf{y} - \mathbf{z}\|^2\right) \quad (12)$$

- The cost function in Eq. (7) for this model is

$$\begin{aligned} J_{ML}(\boldsymbol{\theta}) &= -\mathbb{E}_{\mathbf{x},\mathbf{y}} \log p(\mathbf{y}|\mathbf{x}) = \mathbb{E}_{\mathbf{x},\mathbf{y}} \left(\frac{1}{2\sigma^2} \|\mathbf{y} - \mathbf{z}\|^2 + \frac{D}{2} 2\pi\sigma^2 \right) \\ &= \mathbb{E}_{\mathbf{x},\mathbf{y}} (\|\mathbf{y} - \mathbf{z}\|^2) + \text{constant} \approx \frac{1}{N} \sum_{i=1}^N \|\mathbf{y}_i - \mathbf{W}^{(L)\top} \mathbf{h}^{(L-1)}\|^2 \end{aligned}$$

The output \mathbf{z} and the regressors \mathbf{y} are assumed to be vectors (multitask regression).

Sigmoid posterior for binary classification

- We assume an unnormalized log-likelihood as

$$\log \tilde{p}(y|\mathbf{x}) = yz \longrightarrow \tilde{p}(y|\mathbf{x}) = e^{yz} \quad (13)$$

which must be normalized as

$$p(y|\mathbf{x}) = \frac{e^{yz}}{\sum_{y'=0}^1 e^{yz}} = \frac{e^{yz}}{1 + e^z} \quad (14)$$

- Therefore

$$\begin{aligned} p(y = 0|\mathbf{x}) &= \frac{1}{1 + e^z} \\ p(y = 1|\mathbf{x}) &= \frac{e^z}{1 + e^z} \end{aligned} \quad (15)$$

Sigmoid posterior for binary classification

- Since the sigmoid function is $\sigma(a) = \frac{1}{1+e^{-a}}$, then

$$p(y|\mathbf{x}) = \frac{1}{1 + e^{-(2y-1)z}} = \begin{cases} \frac{1}{1+e^z}, & y = 0 \\ \frac{1}{1+e^{-z}} = \frac{e^z}{1+e^z}, & y = 1 \end{cases} \quad (16)$$

- Finally

$$p(y|\mathbf{x}) = \sigma \left((2y - 1) \mathbf{w}^{(L)\top} \mathbf{h}^{(L-1)} \right) \quad (17)$$

- According to Eq. (7), the cost function is

$$J_{ML}(\boldsymbol{\theta}) = \mathbb{E} [\log \sigma((2y - 1)z)] = -\mathbb{E} \left[\log \left(1 + e^{(1-2y)z} \right) \right] \quad (18)$$

Softmax posterior for multiclass classification

- Here the neural network has a vectorized output

$$\mathbf{z} = \mathbf{W}^{(L)\top} \mathbf{h}^{(L-1)} \quad (19)$$

- Then, we model each element z_k in \mathbf{z} as

$$\begin{aligned} z_k &= \log \tilde{p}(y = k | \mathbf{x}) \\ \tilde{p}(y = k | \mathbf{x}) &= e^{z_k} \end{aligned} \quad (20)$$

and then we normalize *softmax* function,

$$p(y = k | \mathbf{x}) = \text{softmax}(z_k) = \frac{e^{z_k}}{\sum_{j=1}^K e^{z_j}} \quad (21)$$

Softmax posterior for multiclass classification

- The log-likelihood function can be interpreted as a cross-entropy between the actual probability of the label and the estimated one:

$$H(q, p) = -\mathbb{E}[q \log p] \quad (22)$$

For the binary case, the equivalence is straightforward (exercise).

- For the multiclass case:
 - 1 We first change the multiclass label $y_i = k$, $1 \leq k \leq K$ by a vector $\mathbf{y}_i = [y_i^{(1)}, \dots, y_i^{(K)}]$ where $y_i^{(k)} = 1$ and the rest are zero.
 - 2 We denote the real probability that $y_i = k$ as

$$q(y_i^{(k)} = 1) = q_i(k) = \begin{cases} 1, & y_i = k \\ 0, & y_i \neq k \end{cases} \quad (23)$$

Softmax posterior for multiclass classification

- The cross-entropy loss for sample i can be written as

$$\ell_i = - \sum_{k=1}^K q_y(k) \log p(y_i = k | \mathbf{x}) \quad (24)$$

- Note that $q_i(k) = y_i^{(k)}$. By changing $p(y_i = k | \mathbf{x})$ by Eq. (21)

$$l_i = - \sum_{k=1}^K y_i^{(k)} \log \frac{e^{z_{i,k}}}{\sum_{j=1}^K e^{z_{i,j}}} = - \sum_{k=1}^K y_i^{(k)} z_{i,k} + \sum_{k=1}^K y_i^{(k)} \log \sum_{j=1}^K e^{z_{i,j}} \quad (25)$$

- Since only one of the elements of vector \mathbf{y}_i is 1

$$l_i = - \sum_{k=1}^K y_i^{(k)} z_{i,k} + \log \sum_{j=1}^K e^{z_{i,j}} \quad (26)$$

where $z_{i,k}$ is the k -th output for input sample \mathbf{x}_i .