

## **Planning of course:**

- Dimensional reduction: singular value decomposition, principal component analysis, model reduction
- Regression, optimization, model selection
- Neural networks
- Physics informed neural networks, model discovery
- Projects

Model discovery

<https://www.youtube.com/watch?v=NxAn0ogIMVw>

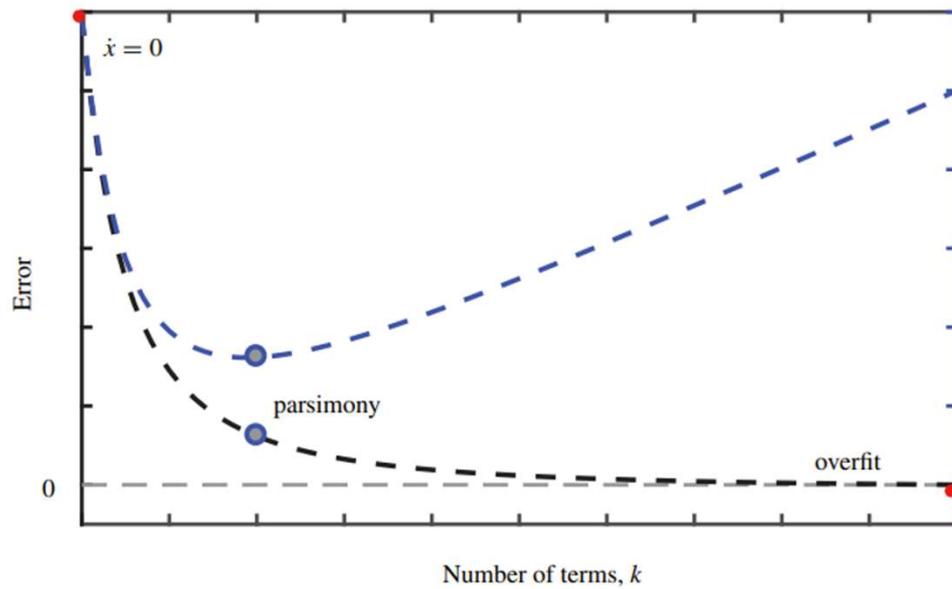
### 7.3 Sparse Identification of Nonlinear Dynamics (SINDy)

A parsimonious (as simple as possible) model defined by the sparse regression

$$\dot{\xi}_k = \underset{\xi'_k}{\operatorname{argmin}} \| \dot{\mathbf{X}}_k - \Theta(\mathbf{X}) \xi'_k \|_2 + \lambda \| \xi'_k \|_1.$$

$m \times 1 \quad m \times \dim(\Theta) \quad \dim(\Theta) \times 1$

where  $k=1, \dots, \dim(x)$  (each column in  $X$ )



**Code 7.4** [Python] Sequentially thresholded least-squares.

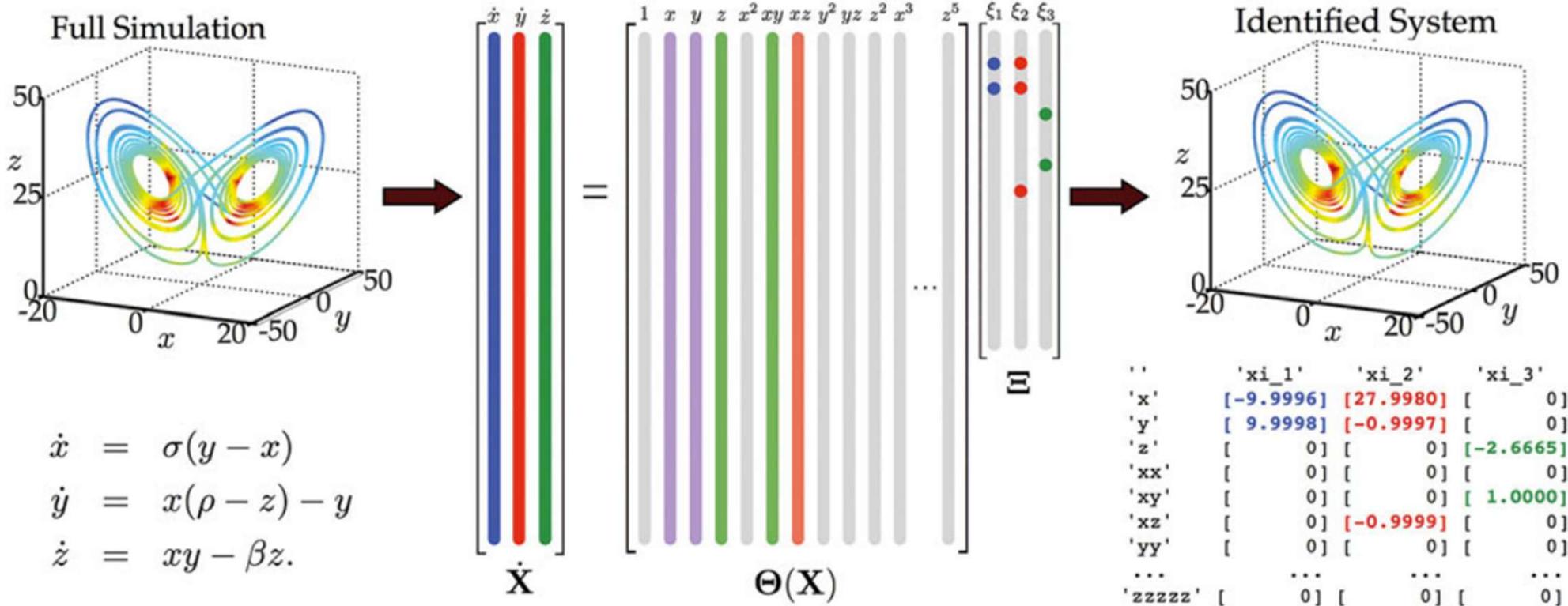
```
def sparsifyDynamics(Theta,dXdt,lamb,n):
    # Initial guess: Least-squares
    Xi = np.linalg.lstsq(Theta,dXdt,rcond=None) [0]

    for k in range(10):
        smallinds = np.abs(Xi) < lamb # Find small coeffs.
        Xi[smallinds] = 0           # and threshold
        for ind in range(n):      # n is state dimension
            biginds = smallinds[:,ind] == 0
            # Regress onto remaining terms to find sparse Xi
            Xi[biginds,ind] = np.linalg.lstsq(Theta[:,biginds],dXdt[:,ind],rcond=None) [0]

    return Xi
```

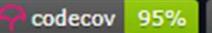
The sparse vectors  $\xi_k$  may be synthesized into a dynamical system:

$$\dot{x}_k = \Theta(\mathbf{x})\xi_k.$$



**Figure 7.5** Schematic of the sparse identification of nonlinear dynamics (SINDy) algorithm [132].

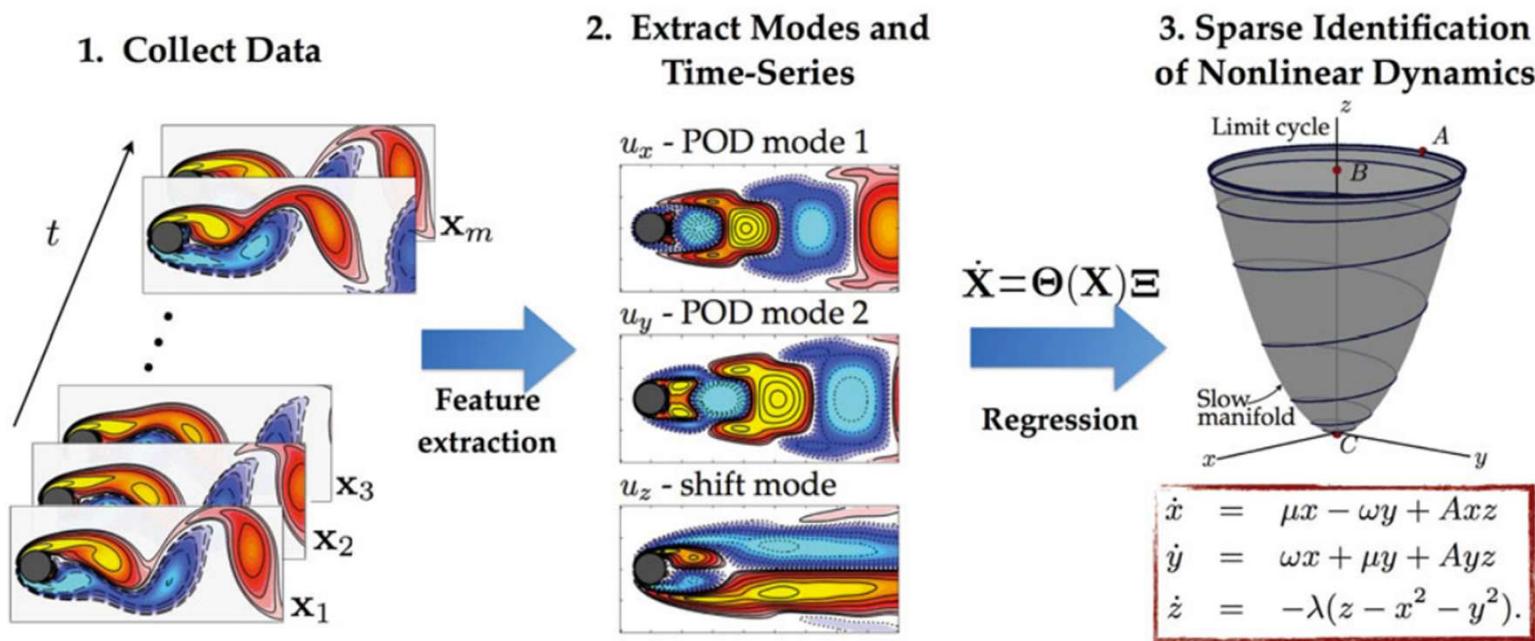
# PySINDy

 CI passing  docs passing  pypi package 1.7.5  codecov 95%  JOSS 10.21105/joss.02104  JOSS 10.21105/joss.03994  
DOI [10.5281/zenodo.7808834](https://doi.org/10.5281/zenodo.7808834)

**PySINDy** is a sparse regression package with several implementations for the Sparse Identification of Nonlinear Dynamical systems (SINDy) method introduced in Brunton et al. (2016a), including the unified optimization approach of Champion et al. (2019), SINDy with control from Brunton et al. (2016b), Trapping SINDy from Kaptanoglu et al. (2021), SINDy-PI from Kaheman et al. (2020), PDE-FIND from Rudy et al. (2017), and so on. A comprehensive literature review is given in de Silva et al. (2020) and Kaptanoglu, de Silva et al. (2021).

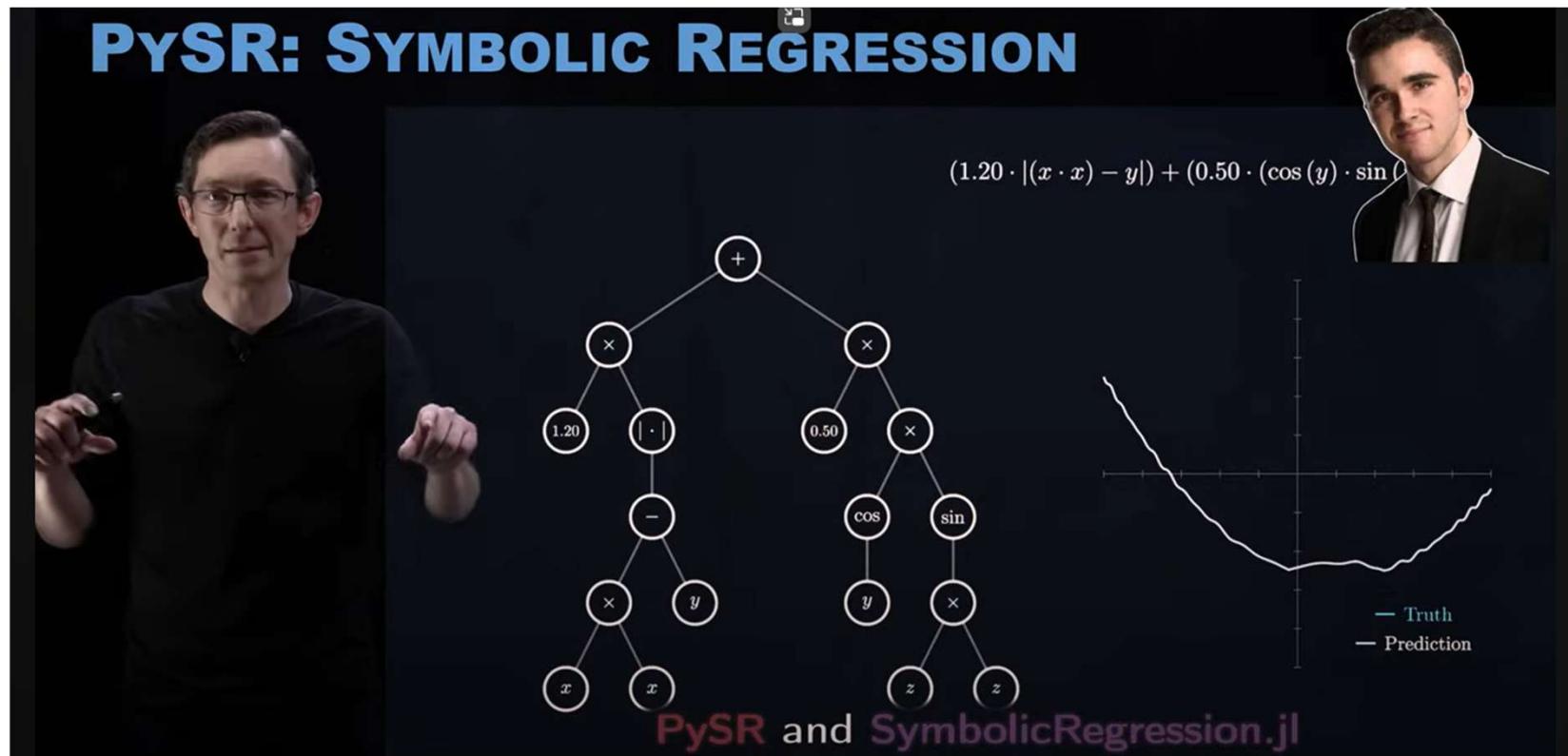
<https://github.com/dynamicslab/pysindy>

The SINDy algorithm has recently been applied to identify high-dimensional dynamical systems, such as fluid flows, based on POD coefficients [132, 454, 455]. Figure 7.6



**Figure 7.6** Schematic overview of nonlinear model identification from high-dimensional data using the sparse identification of nonlinear dynamics (SINDy) [132]. This procedure is modular, so that different techniques can be used for the feature extraction and regression steps. In this example of flow past a cylinder, SINDy discovers the model of Noack et al. [523]. Modified from Brunton et al. [132].

Symbolic regression <https://github.com/MilesCranmer/PySR>



# PySR: SYMBOLIC REGRESSION

## Code structure

SymbolicRegression.jl is organized roughly as follows. Rounded rectangles indicate objects, and rectangles indicate functions.

