

Air Canvas Drawing using OpenCV

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Abstract

This project presents a real-time virtual drawing application using computer vision techniques. The system allows users to draw in the air by moving a colored object, which is tracked through the webcam feed using OpenCV. The drawn path is simultaneously visualized on a digital canvas.

Objective

The primary objective is to demonstrate human-computer interaction through hand gesture tracking and real-time image processing. It serves as a basic prototype for interactive AR applications and gesture-controlled interfaces.

Technologies Used

- **Programming Language:** Python
- **Libraries:** OpenCV, NumPy, Collections (Deque)
- **Computer Vision Concepts:** HSV Color Detection, Morphological Filtering, Contour Tracking

System Architecture

The system captures live webcam frames, processes each frame to isolate the colored marker, identifies its contour, and tracks its movement by appending positions to a deque. A blank canvas is overlaid with lines that follow the marker path, simulating air drawing.

Implementation

- **Marker Detection:** Converts frames to HSV color space for robust color filtering under varying lighting.
- **Masking and Morphological Ops:** Noise is reduced using erosion and dilation.
- **Drawing Engine:** Maintains separate deques for each color. Draws lines between consecutive points.
- **Interface:** Interactive buttons for switching colors and clearing canvas.

Key Features

1. Real-time tracking and drawing experience.
2. Multiple color support with dynamic switching.
3. Adjustable HSV thresholds using trackbars.
4. Simple, intuitive GUI layout.

Conclusion

The Air Canvas project integrates computer vision with intuitive design to create a seamless drawing experience without physical contact. It is highly extendable to gesture recognition, virtual whiteboards, or interactive learning environments.

Appendix: Full Source Code

```
import numpy as np
import cv2
from collections import deque

\#default called trackbar function
def setValues(x):
    print("")

\# Creating the trackbars needed for adjusting the marker colour
cv2.namedWindow("Color_detectors")
cv2.createTrackbar("Upper_Hue", "Color_detectors", 153, 180,setValues)
cv2.createTrackbar("Upper_Saturation", "Color_detectors", 255, 255,setValues)
cv2.createTrackbar("Upper_Value", "Color_detectors", 255, 255,setValues)
cv2.createTrackbar("Lower_Hue", "Color_detectors", 64, 180,setValues)
cv2.createTrackbar("Lower_Saturation", "Color_detectors", 72, 255,setValues)
cv2.createTrackbar("Lower_Value", "Color_detectors", 49, 255,setValues)

\# Giving different arrays to handle colour points of different colour
bpoints = [deque(maxlen=1024)]
gpoints = [deque(maxlen=1024)]
rpoints = [deque(maxlen=1024)]
ypoints = [deque(maxlen=1024)]

\# These indexes will be used to mark the points in particular arrays of specific colour
blue\_index = 0
green\_index = 0
red\_index = 0
yellow\_index = 0

\#The kernel to be used for dilation purpose
kernel = np.ones((5,5),np.uint8)

colors = [(255, 0, 0), (0, 255, 0), (0, 0, 255), (0, 255, 255)]
colorIndex = 0
```

```
\# Canvas setup
paintWindow = np.zeros((471, 636, 3), dtype=np.uint8) + 255
button\_centers = [(90, 33), (207, 33), (322, 33), (437, 33), (552, 33)]
button\_radius = 30
paintWindow = cv2.circle(paintWindow, button\_centers[0], button\_radius, (0, 0, 0), 2)
paintWindow = cv2.circle(paintWindow, button\_centers[1], button\_radius, colors[0], -1)
paintWindow = cv2.circle(paintWindow, button\_centers[2], button\_radius, colors[1], -1)
paintWindow = cv2.circle(paintWindow, button\_centers[3], button\_radius, colors[2], -1)
paintWindow = cv2.circle(paintWindow, button\_centers[4], button\_radius, colors[3], -1)
cv2.putText(paintWindow, "CLEAR", (65, 38), cv2.FONT\_HERSHEY\_SIMPLEX, 0.5, (0, 0, 0),
, 2)
cv2.putText(paintWindow, "GREEN", (300, 38), cv2.FONT\_HERSHEY\_SIMPLEX, 0.5, (255, 255,
), 2)
cv2.putText(paintWindow, "RED", (415, 38), cv2.FONT\_HERSHEY\_SIMPLEX, 0.5, (255, 255, 2
2)
cv2.putText(paintWindow, "YELLOW", (505, 38), cv2.FONT\_HERSHEY\_SIMPLEX, 0.5, (150, 150
0), 2)

\# Webcam and drawing logic continues...
```