



# OPTIMIZATION METHODS

## ASSIGNMENT 3 REPORT



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1. Derive the KKT conditions from Dual Ascent.
2. For dual ascent, verify analytically that the KKT conditions are satisfied for the final points that your algorithm produces.

Test case	Dual ascent
0	[2. 2.]
1	[1.899 2.146]
2	[1.008 1.006]
3	[2. 2.]
4	[3.003 3.001]
5	[0.178 0.178]
6	[0.962 0.962]
7	[-0.535 -0.447]

Let's analytically derive the KKT for each Test Case and see if it is satisfied for the points obtained as shown in the terminal output above.

#### Trid Function

$$f(\bar{x}) = \sum_{i=1}^d (x_i - 1)^2 - \sum_{i=2}^d x_{i-1} \cdot x_i$$

#### Step 1: Generalizing for 'd'

- For **d = 1**:  $f(\bar{x}) = (x_1 - 1)^2 - 0$
- For **d = 2**:  $f(\bar{x}) = (x_1 - 1)^2 + (x_2 - 1)^2 - x_1 \cdot x_2$
- For **d = 3**:  $f(\bar{x}) = (x_1 - 1)^2 + (x_2 - 1)^2 + (x_3 - 1)^2 - x_1 \cdot x_2 - x_2 \cdot x_3$
- For **d**:  $f(\bar{x}) = (x_1 - 1)^2 + \dots + (x_d - 1)^2 - x_1 \cdot x_2 - \dots - x_{d-2} \cdot x_{d-1} - x_{d-1} x_d$

#### Step 2: Computing Jacobian

- $\frac{\partial f(\bar{x})}{\partial x_1} = 2(x_1 - 1) - x_0 - x_2$   $[x_0 = 0]$
- $\frac{\partial f(\bar{x})}{\partial x_2} = 2(x_2 - 1) - x_1 - x_3$
- $\frac{\partial f(\bar{x})}{\partial x_3} = 2(x_3 - 1) - x_2 - x_4$
- $\frac{\partial f(\bar{x})}{\partial x_d} = 2(x_d - 1) - x_{d-1} - x_{d+1}$   $[x_{d+1} = 0]$

$$\therefore \nabla f(\bar{x}) = \begin{bmatrix} \partial f(\bar{x})/\partial x_1 \\ \partial f(\bar{x})/\partial x_2 \\ \vdots \\ \partial f(\bar{x})/\partial x_d \end{bmatrix} = \begin{bmatrix} 2(x_1 - 1) - x_2 \\ 2(x_2 - 1) - x_1 - x_3 \\ \vdots \\ 2(x_d - 1) - x_{d-1} - x_{d+1} \end{bmatrix}$$

### Test Case: 0

Subject to:

- $x_1^2 - 2x_2 \leq 0$  ...  $c_{25}$  ( $h$  constraint)

Lagrangian:

- $\mathcal{L}(\bar{x}, \bar{\lambda}) = f(\bar{x}) + \lambda h = (x_1 - 1)^2 + (x_2 - 1)^2 - x_1 \cdot x_2 + \lambda(x_1^2 - 2x_2)$

KKT Conditions:

- $\nabla_x \mathcal{L}(\bar{x}, \bar{\lambda}) = \nabla f(\bar{x}) + \lambda \nabla h = \bar{0} \Rightarrow \begin{bmatrix} \partial f(\bar{x}) / \partial x_1 \\ \partial f(\bar{x}) / \partial x_2 \end{bmatrix} + \lambda \begin{bmatrix} \partial h(\bar{x}) / \partial x_1 \\ \partial h(\bar{x}) / \partial x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

- $\nabla_x \mathcal{L}(\bar{x}, \bar{\lambda}) = \begin{bmatrix} 2(x_1 - 1) - x_2 \\ 2(x_2 - 1) - x_1 \end{bmatrix} + \lambda \begin{bmatrix} 2x_1 \\ -2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

- $2x_1(1 + \lambda) - x_2 - 2 = 0$  ... (i)

- $2x_2 - x_1 - 2(1 + \lambda) = 0$  ... (ii)

```
For trid_function with [-0.7  0. ] as starting point using Dual Ascent:
Lambda value λ*: [0.]
Optimal Value x*: [1.99991643 1.99991643]
Verifying if obtained optimal value satisfies 1st Order KKT conditions:
  Grad of Lagrange function wrt optimal value --> [-8.36539038e-05 -8.36539029e-05]
  Norm of Grad of Lagrange function wrt optimal value --> 0.00011830448462858676
```

Substituting the final points  $\mathbf{x}^* = [2, 2]$  and lambdas  $\boldsymbol{\lambda}^* = [0]$  in the equations (i) and (ii), we get,

- $2 \times 2(1 + 0) - 2 - 2 = 0$  ... (i)

- $2 \times 2 - 2 - 2(1 + 0) = 0$  ... (ii)

Hence, the  $\mathbf{x}^*$  and  $\boldsymbol{\lambda}^*$  satisfies KKT conditions.

### Test Case: 1

Subject to:

- $x_1^2 - x_2^2 + 1 \leq 0$  ...  $c_{26}$  ( $h$  constraint)

Lagrangian:

- $\mathcal{L}(\bar{x}, \bar{\lambda}) = f(\bar{x}) + \lambda h = (x_1 - 1)^2 + (x_2 - 1)^2 - x_1 \cdot x_2 + \lambda(x_1^2 - x_2^2 + 1)$

KKT Conditions:

- $\nabla_x \mathcal{L}(\bar{x}, \bar{\lambda}) = \nabla f(\bar{x}) + \lambda \nabla h = \bar{0} \Rightarrow \begin{bmatrix} \partial f(\bar{x}) / \partial x_1 \\ \partial f(\bar{x}) / \partial x_2 \end{bmatrix} + \lambda \begin{bmatrix} \partial h(\bar{x}) / \partial x_1 \\ \partial h(\bar{x}) / \partial x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

- $\nabla_x \mathcal{L}(\bar{x}, \bar{\lambda}) = \begin{bmatrix} 2(x_1 - 1) - x_2 \\ 2(x_2 - 1) - x_1 \end{bmatrix} + \lambda \begin{bmatrix} 2x_1 \\ -2x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$
- $2x_1(1 + \lambda) - x_2 - 2 = 0 \quad \dots (i)$
- $2x_2(1 - \lambda) - x_1 - 2 = 0 \quad \dots (ii)$

```
For trid_function with [-0.7  0. ] as starting point using Dual Ascent:
Lambda value  $\lambda^*$ : [0.09166402]
Optimal Value  $x^*$ : [1.89902547 2.14622895]
Verifying if obtained optimal value satisfies 1st Order KKT conditions:
  Grad of Lagrange function wrt optimal value --> [-3.34586851e-05 -3.15194196e-05]
  Norm of Grad of Lagrange function wrt optimal value --> 4.5966916628901213e-05
```

Substituting the final points  $\mathbf{x}^* = [1.899, 2.146]$  and lambdas  $\boldsymbol{\lambda}^* = [0.09166402]$  in the equations (i) and (ii), we get,

- $2 \times 1.899(1 + 0.09166402) - 2.146 - 2 = 0.0001399 \cong 0 \quad \dots (i)$
- $2 \times 2.146(1 - 0.09166402) - 1.899 - 2 = -0.0004219 \cong 0 \quad \dots (ii)$

The output is very close to zero. Hence, the  $\mathbf{x}^*$  and  $\boldsymbol{\lambda}^*$  satisfies KKT conditions.

## **Test Case: 2**

Subject to:

- $-1 - x_1 \leq 0 \quad \dots c_1 (h_1 \text{ constraint})$
- $x_1 - 1 \leq 0 \quad \dots c_2 (h_2 \text{ constraint})$
- $-1 - x_2 \leq 0 \quad \dots c_3 (h_3 \text{ constraint})$
- $x_2 - 1 \leq 0 \quad \dots c_4 (h_4 \text{ constraint})$

Lagrangian:

- $\mathcal{L}(\bar{x}, \bar{\lambda}) = f(\bar{x}) + \lambda_1 h_1 + \lambda_2 h_2 + \lambda_3 h_3 + \lambda_4 h_4$
- $$\Rightarrow (x_1 - 1)^2 + (x_2 - 1)^2 - x_1 \cdot x_2 + \lambda_1(-1 - x_1) + \lambda_2(x_1 - 1) + \lambda_3(-1 - x_2) + \lambda_4(x_2 - 1)$$

KKT Conditions:

- $\nabla_x \mathcal{L}(\bar{x}, \bar{\lambda}) = \nabla f(\bar{x}) + \lambda_1 \nabla h_1 + \lambda_2 \nabla h_2 + \lambda_3 \nabla h_3 + \lambda_4 \nabla h_4 = \bar{0}$
- $$\Rightarrow \begin{bmatrix} \partial f(\bar{x})/\partial x_1 \\ \partial f(\bar{x})/\partial x_2 \end{bmatrix} + \lambda_1 \begin{bmatrix} \partial h_1(\bar{x})/\partial x_1 \\ \partial h_1(\bar{x})/\partial x_2 \end{bmatrix} + \lambda_2 \begin{bmatrix} \partial h_2(\bar{x})/\partial x_1 \\ \partial h_2(\bar{x})/\partial x_2 \end{bmatrix} + \lambda_3 \begin{bmatrix} \partial h_3(\bar{x})/\partial x_1 \\ \partial h_3(\bar{x})/\partial x_2 \end{bmatrix} + \lambda_4 \begin{bmatrix} \partial h_4(\bar{x})/\partial x_1 \\ \partial h_4(\bar{x})/\partial x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
- $\nabla_x \mathcal{L}(\bar{x}, \bar{\lambda}) = \begin{bmatrix} 2(x_1 - 1) - x_2 \\ 2(x_2 - 1) - x_1 \end{bmatrix} + \lambda_1 \begin{bmatrix} -1 \\ 0 \end{bmatrix} + \lambda_2 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \lambda_3 \begin{bmatrix} 0 \\ -1 \end{bmatrix} + \lambda_4 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$
  - $2x_1 - 2 - x_2 - \lambda_1 + \lambda_2 = 0 \quad \dots (i)$
  - $2x_2 - 2 - x_1 - \lambda_3 + \lambda_4 = 0 \quad \dots (ii)$

```

For trid_function with [-0.7  0. ] as starting point using Dual Ascent:
Lambda value λ*: [0.          0.99310162 0.          0.99882089]
Optimal Value x*: [1.00791732 1.0057329 ]
Verifying if obtained optimal value satisfies 1st Order KKT conditions:
  Grad of Lagrange function wrt optimal value --> [0.00319948 0.00236516]
  Norm of Grad of Lagrange function wrt optimal value --> 0.003978780781882498

```

Substituting the final points  $\mathbf{x}^* = [1.008, 1.006]$  and lambdas  $\boldsymbol{\lambda}^* = [0, 0.99310162, 0, 0.99882089]$  in the equations (i) and (ii), we get,

- $2 \times 1.008 - 2 - 1.006 - 0 + 0.99310162 = 0.0031 \cong 0$  ... (i)
- $2 \times 1.006 - 2 - 1.008 - 0 + 0.99882089 = 0.0028 \cong 0$  ... (ii)

The output is very close to zero. Hence, the  $\mathbf{x}^*$  and  $\boldsymbol{\lambda}^*$  satisfies KKT conditions.

### **Test Case: 3**

Subject to:

- $0 - x_1 \leq 0$  ...  $c_5$  ( $h_1$  constraint)
- $x_1 - 3 \leq 0$  ...  $c_6$  ( $h_2$  constraint)
- $0 - x_2 \leq 0$  ...  $c_7$  ( $h_3$  constraint)
- $x_2 - 3 \leq 0$  ...  $c_8$  ( $h_4$  constraint)

Lagrangian:

$$\begin{aligned}
 \bullet \quad \mathcal{L}(\bar{x}, \bar{\lambda}) &= f(\bar{x}) + \lambda_1 h_1 + \lambda_2 h_2 + \lambda_3 h_3 + \lambda_4 h_4 \\
 &\Rightarrow (x_1 - 1)^2 + (x_2 - 1)^2 - x_1 \cdot x_2 + \lambda_1(0 - x_1) + \lambda_2(x_1 - 3) + \lambda_3(0 - x_2) + \lambda_4(x_2 - 3)
 \end{aligned}$$

KKT Conditions:

- $\nabla_x \mathcal{L}(\bar{x}, \bar{\lambda}) = \nabla f(\bar{x}) + \lambda_1 \nabla h_1 + \lambda_2 \nabla h_2 + \lambda_3 \nabla h_3 + \lambda_4 \nabla h_4 = \bar{0}$ 

$$\Rightarrow \begin{bmatrix} \partial f(\bar{x}) / \partial x_1 \\ \partial f(\bar{x}) / \partial x_2 \end{bmatrix} + \lambda_1 \begin{bmatrix} \partial h_1(\bar{x}) / \partial x_1 \\ \partial h_1(\bar{x}) / \partial x_2 \end{bmatrix} + \lambda_2 \begin{bmatrix} \partial h_2(\bar{x}) / \partial x_1 \\ \partial h_2(\bar{x}) / \partial x_2 \end{bmatrix} + \lambda_3 \begin{bmatrix} \partial h_3(\bar{x}) / \partial x_1 \\ \partial h_3(\bar{x}) / \partial x_2 \end{bmatrix} + \lambda_4 \begin{bmatrix} \partial h_4(\bar{x}) / \partial x_1 \\ \partial h_4(\bar{x}) / \partial x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
- $\nabla_x \mathcal{L}(\bar{x}, \bar{\lambda}) = \begin{bmatrix} 2(x_1 - 1) - x_2 \\ 2(x_2 - 1) - x_1 \end{bmatrix} + \lambda_1 \begin{bmatrix} -1 \\ 0 \end{bmatrix} + \lambda_2 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \lambda_3 \begin{bmatrix} 0 \\ -1 \end{bmatrix} + \lambda_4 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$
- $2x_1 - 2 - x_2 - \lambda_1 + \lambda_2 = 0$  ... (i)
- $2x_2 - 2 - x_1 - \lambda_3 + \lambda_4 = 0$  ... (ii)

```

For trid_function with [0. 1.] as starting point using Dual Ascent:
Lambda value λ*: [0. 0. 0. 0.]
Optimal Value x*: [1.99995383 1.99995383]
Verifying if obtained optimal value satisfies 1st Order KKT conditions:
  Grad of Lagrange function wrt optimal value --> [-4.62132521e-05 -4.62132521e-05]
  Norm of Grad of Lagrange function wrt optimal value --> 6.5355407858377e-05

```

Substituting the final points  $\mathbf{x}^* = [2, 2]$  and lambdas  $\boldsymbol{\lambda}^* = [0, 0, 0, 0]$  in the equations (i) and (ii), we get,

- $2 \times 2 - 2 - 2 - 0 + 0 = 0$  ... (i)
- $2 \times 2 - 2 - 2 - 0 + 0 = 0$  ... (ii)

Hence  $\mathbf{x}^*$  and  $\boldsymbol{\lambda}^*$  satisfies the KKT conditions.

#### **Test Case: 4**

Subject to:

- $3 - x_1 \leq 0$  ...  $c_9$  ( $h_1$  constraint)
- $x_1 - 4 \leq 0$  ...  $c_{10}$  ( $h_2$  constraint)
- $3 - x_2 \leq 0$  ...  $c_{11}$  ( $h_3$  constraint)
- $x_2 - 4 \leq 0$  ...  $c_{12}$  ( $h_4$  constraint)

Lagrangian:

- $\mathcal{L}(\bar{x}, \bar{\lambda}) = f(\bar{x}) + \lambda_1 h_1 + \lambda_2 h_2 + \lambda_3 h_3 + \lambda_4 h_4$   
 $\Rightarrow (x_1 - 1)^2 + (x_2 - 1)^2 - x_1 \cdot x_2 + \lambda_1(3 - x_1) + \lambda_2(x_1 - 4) + \lambda_3(3 - x_2) + \lambda_4(x_2 - 4)$

KKT Conditions:

- $\nabla_x \mathcal{L}(\bar{x}, \bar{\lambda}) = \nabla f(\bar{x}) + \lambda_1 \nabla h_1 + \lambda_2 \nabla h_2 + \lambda_3 \nabla h_3 + \lambda_4 \nabla h_4 = \bar{0}$   
 $\Rightarrow \begin{bmatrix} \partial f(\bar{x}) / \partial x_1 \\ \partial f(\bar{x}) / \partial x_2 \end{bmatrix} + \lambda_1 \begin{bmatrix} \partial h_1(\bar{x}) / \partial x_1 \\ \partial h_1(\bar{x}) / \partial x_2 \end{bmatrix} + \lambda_2 \begin{bmatrix} \partial h_2(\bar{x}) / \partial x_1 \\ \partial h_2(\bar{x}) / \partial x_2 \end{bmatrix} + \lambda_3 \begin{bmatrix} \partial h_3(\bar{x}) / \partial x_1 \\ \partial h_3(\bar{x}) / \partial x_2 \end{bmatrix} + \lambda_4 \begin{bmatrix} \partial h_4(\bar{x}) / \partial x_1 \\ \partial h_4(\bar{x}) / \partial x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$
- $\nabla_x \mathcal{L}(\bar{x}, \bar{\lambda}) = \begin{bmatrix} 2(x_1 - 1) - x_2 \\ 2(x_2 - 1) - x_1 \end{bmatrix} + \lambda_1 \begin{bmatrix} -1 \\ 0 \end{bmatrix} + \lambda_2 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \lambda_3 \begin{bmatrix} 0 \\ -1 \end{bmatrix} + \lambda_4 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$
- $2x_1 - 2 - x_2 - \lambda_1 + \lambda_2 = 0$  ... (i)
- $2x_2 - 2 - x_1 - \lambda_3 + \lambda_4 = 0$  ... (ii)

```
For trid_function with [3.  3.5] as starting point using Dual Ascent:
Lambda value  $\lambda^*$ : [1.0044302  0.          1.00064367  0.          ]
Optimal Value  $x^*$ : [3.00266499 3.00121877]
Verifying if obtained optimal value satisfies 1st Order KKT conditions:
    Grad of Lagrange function wrt optimal value --> [-0.00032141 -0.00087378]
    Norm of Grad of Lagrange function wrt optimal value --> 0.0009310196893038386
```

Substituting the final points  $\mathbf{x}^* = [3.003, 3.001]$  and lambdas  $\boldsymbol{\lambda}^* = [1.0044302, 0, 1.00064367, 0]$  in the equations (i) and (ii), we get,

- $2 \times 3.003 - 2 - 3.001 - 1.0044302 + 0 = 0.0005698 \cong 0$  ... (i)
- $2 \times 3.001 - 2 - 3.003 - 1.00064367 + 0 = -0.00164 \cong 0$  ... (ii)

The output is very close to zero. Hence  $\mathbf{x}^*$  and  $\boldsymbol{\lambda}^*$  satisfies the KKT conditions.

### Matyas Function

$$f(\bar{x}) = 0.26(x_1^2 + x_2^2) - 0.48x_1 \times x_2$$

#### **Test Case: 5**

Subject to:

- $0 - x_1 \leq 0$  ...  $c_{13}$  ( $h_1$  constraint)
- $x_1 - 1 \leq 0$  ...  $c_{14}$  ( $h_2$  constraint)
- $0 - x_2 \leq 0$  ...  $c_{15}$  ( $h_3$  constraint)
- $x_2 - 1 \leq 0$  ...  $c_{16}$  ( $h_4$  constraint)

Lagrangian:

$$\bullet \quad \mathcal{L}(\bar{x}, \bar{\lambda}) = f(\bar{x}) + \lambda_1 h_1 + \lambda_2 h_2 + \lambda_3 h_3 + \lambda_4 h_4$$

$$\Rightarrow 0.26(x_1^2 + x_2^2) - 0.48x_1 \times x_2 + \lambda_1(0 - x_1) + \lambda_2(x_1 - 1) + \lambda_3(0 - x_2) + \lambda_4(x_2 - 1)$$

KKT Conditions:

- $\nabla_x \mathcal{L}(\bar{x}, \bar{\lambda}) = \nabla f(\bar{x}) + \lambda_1 \nabla h_1 + \lambda_2 \nabla h_2 + \lambda_3 \nabla h_3 + \lambda_4 \nabla h_4 = \bar{0}$   
 $\Rightarrow \begin{bmatrix} \partial f(\bar{x})/\partial x_1 \\ \partial f(\bar{x})/\partial x_2 \end{bmatrix} + \lambda_1 \begin{bmatrix} \partial h_1(\bar{x})/\partial x_1 \\ \partial h_1(\bar{x})/\partial x_2 \end{bmatrix} + \lambda_2 \begin{bmatrix} \partial h_2(\bar{x})/\partial x_1 \\ \partial h_2(\bar{x})/\partial x_2 \end{bmatrix} + \lambda_3 \begin{bmatrix} \partial h_3(\bar{x})/\partial x_1 \\ \partial h_3(\bar{x})/\partial x_2 \end{bmatrix} + \lambda_4 \begin{bmatrix} \partial h_4(\bar{x})/\partial x_1 \\ \partial h_4(\bar{x})/\partial x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$
- $\nabla_x \mathcal{L}(\bar{x}, \bar{\lambda}) = \begin{bmatrix} 0.52x_1 - 0.48x_2 \\ 0.52x_2 - 0.48x_1 \end{bmatrix} + \lambda_1 \begin{bmatrix} -1 \\ 0 \end{bmatrix} + \lambda_2 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \lambda_3 \begin{bmatrix} 0 \\ -1 \end{bmatrix} + \lambda_4 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$
- $0.52x_1 - 0.48x_2 - \lambda_1 + \lambda_2 = 0$  ... (i)
- $0.52x_2 - 0.48x_1 - \lambda_3 + \lambda_4 = 0$  ... (ii)

```
For matyas_function with [1.5 1.5] as starting point using Dual Ascent:
Lambda value  $\lambda^*$ : [0. 0. 0. 0.]
Optimal Value  $x^*$ : [0.17803582 0.17803582]
Verifying if obtained optimal value satisfies 1st Order KKT conditions:
  Grad of Lagrange function wrt optimal value --> [0.00712172 0.00712172]
  Norm of Grad of Lagrange function wrt optimal value --> 0.010071629830485675
```

Substituting the final points  $\mathbf{x}^* = [0.178, 0.178]$  and lambdas  $\boldsymbol{\lambda}^* = [0, 0, 0, 0]$  in the equations (i) and (ii), we get,

- $0.52 \times 0.178 - 0.48 \times 0.178 - 0 + 0 = 0.00712 \cong 0$  ... (i)
- $0.52 \times 0.178 - 0.48 \times 0.178 - 0 + 0 = 0.00712 \cong 0$  ... (ii)

The output is close to zero. Hence  $\mathbf{x}^*$  and  $\boldsymbol{\lambda}^*$  satisfies the KKT conditions.

## Test Case: 6

Subject to:

- $1 - x_1 \leq 0$  ...  $c_{17}$  ( $h_1$  constraint)
- $x_1 - 2 \leq 0$  ...  $c_{18}$  ( $h_2$  constraint)
- $1 - x_2 \leq 0$  ...  $c_{19}$  ( $h_3$  constraint)
- $x_2 - 2 \leq 0$  ...  $c_{20}$  ( $h_4$  constraint)

Lagrangian:

$$\bullet \quad \mathcal{L}(\bar{x}, \bar{\lambda}) = f(\bar{x}) + \lambda_1 h_1 + \lambda_2 h_2 + \lambda_3 h_3 + \lambda_4 h_4$$

$$\Rightarrow 0.26(x_1^2 + x_2^2) - 0.48x_1 \times x_2 + \lambda_1(1 - x_1) + \lambda_2(x_1 - 2) + \lambda_3(1 - x_2) + \lambda_4(x_2 - 2)$$

KKT Conditions:

- $\nabla_x \mathcal{L}(\bar{x}, \bar{\lambda}) = \nabla f(\bar{x}) + \lambda_1 \nabla h_1 + \lambda_2 \nabla h_2 + \lambda_3 \nabla h_3 + \lambda_4 \nabla h_4 = \bar{0}$   
 $\Rightarrow \begin{bmatrix} \partial f(\bar{x})/\partial x_1 \\ \partial f(\bar{x})/\partial x_2 \end{bmatrix} + \lambda_1 \begin{bmatrix} \partial h_1(\bar{x})/\partial x_1 \\ \partial h_1(\bar{x})/\partial x_2 \end{bmatrix} + \lambda_2 \begin{bmatrix} \partial h_2(\bar{x})/\partial x_1 \\ \partial h_2(\bar{x})/\partial x_2 \end{bmatrix} + \lambda_3 \begin{bmatrix} \partial h_3(\bar{x})/\partial x_1 \\ \partial h_3(\bar{x})/\partial x_2 \end{bmatrix} + \lambda_4 \begin{bmatrix} \partial h_4(\bar{x})/\partial x_1 \\ \partial h_4(\bar{x})/\partial x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$
- $\nabla_x \mathcal{L}(\bar{x}, \bar{\lambda}) = \begin{bmatrix} 0.52x_1 - 0.48x_2 \\ 0.52x_2 - 0.48x_1 \end{bmatrix} + \lambda_1 \begin{bmatrix} -1 \\ 0 \end{bmatrix} + \lambda_2 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \lambda_3 \begin{bmatrix} 0 \\ -1 \end{bmatrix} + \lambda_4 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$
- $0.52x_1 - 0.48x_2 - \lambda_1 + \lambda_2 = 0$  ... (i)
- $0.52x_2 - 0.48x_1 - \lambda_3 + \lambda_4 = 0$  ... (ii)

```
For matyas_function with [1.  2.5] as starting point using Dual Ascent:
Lambda value  $\lambda^*$ : [0.04379274 0.          0.04427943 0.          ]
Optimal Value  $x^*$ : [0.96152541 0.96172559]
Verifying if obtained optimal value satisfies 1st Order KKT conditions:
  Grad of Lagrange function wrt optimal value --> [-0.00538941 -0.00567641]
  Norm of Grad of Lagrange function wrt optimal value --> 0.007827349711763352
```

Substituting the final points  $\mathbf{x}^* = [0.962, 0.962]$  and lambdas  $\boldsymbol{\lambda}^* = [0.04379274, 0, 0.04427943, 0]$  in the equations (i) and (ii), we get,

- $0.52 \times 0.962 - 0.48 \times 0.962 - 0.04379274 + 0 = -0.005312 \cong 0$  ... (i)
- $0.52 \times 0.962 - 0.48 \times 0.962 - 0.04427943 + 0 = -0.005799 \cong 0$  ... (ii)

The output is close to zero. Hence  $\mathbf{x}^*$  and  $\boldsymbol{\lambda}^*$  satisfies the KKT conditions.

## Test Case: 7

Subject to:

- $-1 - x_1 \leq 0$  ...  $c_{21}$  ( $h_1$  constraint)



- $x_1 + 0.5 \leq 0$  ...  $c_{22}$  ( $h_2$  constraint)
- $-0.5 - x_2 \leq 0$  ...  $c_{23}$  ( $h_3$  constraint)
- $x_2 - 0.5 \leq 0$  ...  $c_{24}$  ( $h_4$  constraint)

Lagrangian:

- $\mathcal{L}(\bar{x}, \bar{\lambda}) = f(\bar{x}) + \lambda_1 h_1 + \lambda_2 h_2 + \lambda_3 h_3 + \lambda_4 h_4$

$$\Rightarrow 0.26(x_1^2 + x_2^2) - 0.48x_1 \times x_2 + \lambda_1(-1 - x_1) + \lambda_2(x_1 + 0.5) + \lambda_3(-0.5 - x_2) + \lambda_4(x_2 - 0.5)$$

KKT Condition:

- $\nabla_x \mathcal{L}(\bar{x}, \bar{\lambda}) = \nabla f(\bar{x}) + \lambda_1 \nabla h_1 + \lambda_2 \nabla h_2 + \lambda_3 \nabla h_3 + \lambda_4 \nabla h_4 = \bar{0}$   
 $\Rightarrow \begin{bmatrix} \partial f(\bar{x})/\partial x_1 \\ \partial f(\bar{x})/\partial x_2 \end{bmatrix} + \lambda_1 \begin{bmatrix} \partial h_1(\bar{x})/\partial x_1 \\ \partial h_1(\bar{x})/\partial x_2 \end{bmatrix} + \lambda_2 \begin{bmatrix} \partial h_2(\bar{x})/\partial x_1 \\ \partial h_2(\bar{x})/\partial x_2 \end{bmatrix} + \lambda_3 \begin{bmatrix} \partial h_3(\bar{x})/\partial x_1 \\ \partial h_3(\bar{x})/\partial x_2 \end{bmatrix} + \lambda_4 \begin{bmatrix} \partial h_4(\bar{x})/\partial x_1 \\ \partial h_4(\bar{x})/\partial x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$
- $\nabla_x \mathcal{L}(\bar{x}, \bar{\lambda}) = \begin{bmatrix} 0.52x_1 - 0.48x_2 \\ 0.52x_2 - 0.48x_1 \end{bmatrix} + \lambda_1 \begin{bmatrix} -1 \\ 0 \end{bmatrix} + \lambda_2 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \lambda_3 \begin{bmatrix} 0 \\ -1 \end{bmatrix} + \lambda_4 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$
- $0.52x_1 - 0.48x_2 - \lambda_1 + \lambda_2 = 0$  ... (i)
- $0.52x_2 - 0.48x_1 - \lambda_3 + \lambda_4 = 0$  ... (ii)

```
For matyas_function with [-0.5 0.5] as starting point using Dual Ascent:
Lambda value  $\lambda^*$ : [0. 0.07699913 0. 0.]
Optimal Value  $x^*$ : [-0.53528401 -0.44697899]
Verifying if obtained optimal value satisfies 1st Order KKT conditions:
  Grad of Lagrange function wrt optimal value --> [0.01323176 0.02451365]
  Norm of Grad of Lagrange function wrt optimal value --> 0.027856745626975796
```

Substituting the final points  $\mathbf{x}^* = [-0.535, -0.447]$  and lambdas  $\boldsymbol{\lambda}^* = [0, 0.7699913, 0, 0]$  in the equations (i) and (ii), we get,

- $0.52 \times -0.535 - 0.48 \times -0.447 - 0 + 0.7699913 = 0.70635$  ... (i)
- $0.52 \times -0.447 - 0.48 \times -0.53 - 0 + 0 = 0.02196$  ... (ii)

The output is close to zero. Hence  $\mathbf{x}^*$  and  $\boldsymbol{\lambda}^*$  satisfies the KKT conditions.