CS1.404 (Spring 2024) Optimization Methods

Deadline: 11.55 PM, May 6th, 2024

Instructions

- 1. Attempting all questions is mandatory.
- 2. You are expected to solve all the questions using python programming language.
- 3. Use of any in-built libraries to solve the problem directly is not allowed.
- 4. Submission Format: Check assignment description or announcement post for more details.
- 5. Plagiarism is a strict No. We will pass all codes through the plagiarism checking tool to verify if the code is copied from somewhere. In that case, you get F grade in the course.
- 6. If any two students codes are found exactly same (if they copy from each other), both will get F grade.

1 Functions

1.1 Trid Function

$$f(\mathbf{x}) = \sum_{i=1}^{d} (x_i - 1)^2 - \sum_{i=2}^{d} x_{i-1} x_i$$

1.2 Matyas Function

$$f(\mathbf{x}) = 0.26(x_1^2 + x_2^2) - 0.48x_1 \times x_2$$

2 Algorithms

Implement the following algorithms

2.1 Projected Gradient Method

Refer to lecture 24 slides for pseudocode. Test cases will contain the constraints. There are two types of constraints-

- linear: $\mathbf{lb} \leq \mathbf{x} \leq \mathbf{ub}$ where $\mathbf{lb}, \mathbf{x}, \mathbf{ub} \in \mathbb{R}^n$. In the testcase the constraints will be given in the form of a $2 \times n$ numpy ndarray where \mathbf{lb} and \mathbf{ub} are the first and second vectors respectively.
- $\mathbf{l_2}$: $\|\mathbf{x} \mathbf{c}\| \le r$ where $\mathbf{x}, \mathbf{c} \in \mathbb{R}^n, r \in \mathbb{R}$. In the testcase the constraint will be given in the form of a *tuple* containing its center $(1 \times n \ numpy \ ndarray)$ and radius respectively.

Stopping conditions

- Main algorithm (refer to slide no. 5, lecture 24): Take $\epsilon = 10^{-2}$ or terminate after 1000 iterations.
- Backtracking (refer to slide no. 16, lecture 24): Stop if

$$|f(\mathbf{x_k}) - f(P_c(\mathbf{x_k} - t_k \nabla f(\mathbf{x_k}))) - t_k ||G_{\frac{1}{t_k}}(\mathbf{x_k})||^2| < 10^{-3}$$

2.2 Dual Ascent

For the given problem form the Lagrangian and optimize it using the dual ascent method. You will be provided the function, the derivative, a list of constraints and a list of the derivatives of the constraints. All the constraints are of the form $h_i(x) \leq 0$. You are not allowed to hard code the Lagrangian, you have to form it dynamically. Verify using KKT conditions that the point obtained is a local minima.

Algorithm 1 Dual Ascent

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Initialization: Set \alpha = 10^{-3}, k = 0

while k < 10000 do

\mathbf{x_{k+1}} = \mathbf{x_k} - \alpha \nabla_x \mathcal{L}(\mathbf{x}_k, \lambda_k)

\lambda_{k+1} = \lambda_k + \alpha \nabla_\lambda \mathcal{L}(\mathbf{x}_{k+1}, \lambda_k)

k \leftarrow k+1

\lambda_{k+1,i} \leftarrow max(0, \lambda_{k+1,i}) \forall i

end while

return \mathbf{x_k}
```

3 Submission Instructions

3.1 Allowed Packages

- 1. Python 3.11
- 2. NumPy
- 3. Matplotlib
- 4. PrettyTables

3.2 Boiler Plate

You have been provided with three files

- 1. algos.py: Where you have to implement the algorithms.
- 2. functions.py: Which contains all the functions used for testing.
- 3. main.py: This is the file to be executed to test your code.
- $4. \ test_cases.py$

You are not allowed to create anymore files, nor are you allowed to modify main.py and functions.py. You can make changes to these files for your own test purposes but the final evaluations will use the original files for testing. In algos.py you are allowed to create your own new functions.

3.3 Report

You are required to submit a report (as a pdf) containing the KKT condition derivations from dual ascent.

3.4 Submission Format

Create a folder with your Roll No. as its name containing the four files (algos.py, functions.py, main.py, Report.pdf). Zip it and name it Roll_No.zip Example- 2019111013.zip