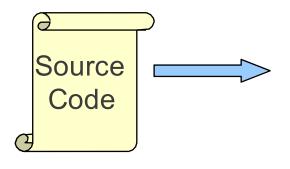
Optimization

Where We Are



Lexical Analysis

Syntax Analysis

Semantic Analysis

IR Generation

IR Optimization

Code Generation

Optimization



Machine Code

Optimization

- Code produced by standard algorithms can often be made to run faster, take less space or both
- These improvements are achieved through transformations called optimization
- Compilers that apply these transformations are called optimizing compilers
- It is especially important to optimize frequently executed parts of a program



Criteria for Transformations

- A transformation must preserve the meaning of a program
 - -Can not change the output produced for any input
 - -Can not introduce an error
- Transformations should, on average, speed up programs
- Transformations should be worth the effort

Beyond Optimizing Compilers

- Really improvements can be made at various phases
- Source code:
 - Algorithmic transformations can produce spectacular improvements
 - -Profiling can be helpful to focus a programmer's attention on important code
- Intermediate code:
 - -Compiler can improve loops, procedure calls, and address calculations
 - -Typically only optimizing compilers include this phase
- Target code:
 - -Compilers can use registers efficiently
 - Peephole transformation can be applied

Peephole Optimizations

- A simple technique for locally improving target code (can also be applied to intermediate code)
- The peephole is a small, moving window on the target program
- Each improvement replaces the instructions of the peephole with a shorter or faster sequence
- Each improvement may create opportunities for additional improvements
- Repeated passes may be necessary

Redundant-Instruction Elimination

Redundant loads and stores:

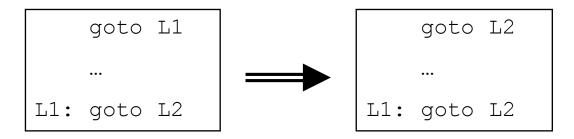
```
(1) MOV R0, a
(2) MOV a, R0
```

Unreachable code:

```
#define debug 0
if (debug) {
   /* print debugging information */
}
```

Flow-of-Control Optimizations

- Jumps to jumps, jumps to conditional jumps, and conditional jumps to jumps are not necessary
- Jumps to jumps example:
 - –The following replacement is valid:



- —If there are no other jumps to $\mathbb{L}1$ and $\mathbb{L}1$ is preceded by an unconditional jump, the statement at $\mathbb{L}1$ can be eliminated
- Jumps to conditional jumps and conditional jumps to jumps lead to similar transformations

Other Peephole Optimizations

- A few algebraic identities that occur frequently (such as x = x + 0 or x = x + 1) can be eliminated
- Reduction in strength replaces expensive operations with cheaper ones
 - –Calculating x * x is likely much cheaper than x^2 using an exponentiation routine
 - -It may be cheaper to implement x * 5 as x * 4 + x
- Some machines may have hardware instructions to implement certain specific operations efficiently
 - -For example, auto-increment may be cheaper than a straight-forward x := x + 1
 - Auto-increment and auto-decrement are also useful when pushing into or popping off of a stack

Optimizing Intermediate Code

- This phase is generally only included in optimizing compilers
- Offers the following advantages:
 - -Operations needed to implement high-level constructs are made explicit (i.e. address calculations)
 - -Intermediate code is independent of target machine; code generator can be replaced for different machine
- We are assuming intermediate code uses threeaddress instructions

Local vs. Global Transformations

- Local transformations involve statements within a single basic block
- All other transformations are called global transformations
- Local transformations are generally performed first
- Many types of transformations can be performed either locally or globally

Common Subexpressions

- E is a common subexpression if:
 - -E was previously computed
 - –Variables in E have not changed since previous computation
- Can avoid recomputing E if previously computed value is still available
- Dags are useful to detect common subexpressions

Copy Propagation

- Assignments of the form £ := g are called copy statements (or copies)
- The idea behind copy propagation is to use g for f whenever possible after such a statement
- For example, applied to block B5 of the previous flow graph, we obtain:

```
x := t3
a[t2] := t5
a[t4] := t3
qoto B2
```

 Copy propagation often turns the copy statement into "dead code"

Dead-Code Elimination

- Dead code includes code that can never be reached and code that computes a value that never gets used
- Consider: if (debug) print ...
 - -It can sometimes be deduced at compile time that the value of an expression is constant
 - Then the constant can be used in place of the expression (constant folding)
 - -Let's assume a previous statement assigns debug := false
 and value never changes
 - -Then the print statement becomes unreachable and can be eliminated
- Consider the example from the previous slide
 - –The value of x computed by the copy statement never gets used after the copy propagation
 - -The copy statement is now dead code and can be eliminated

Loop Optimizations (1)

- The running time of a program may be improved if we do both of the following:
 - -Decrease the number of statements in an inner loop
 - -Increase the number of statements in the outer loop
- Code motion moves code outside of a loop
 - –For example, consider:

```
while (i \leq limit-2) ...
```

-The result of code motion would be:

```
t = limit - 2
while (i <= t) ...
```

Loop Optimizations (2)

- Induction variables: variables that remain in "lock-step"
 - -For example, in block B3 of previous flow graph, j and t4 are induction variables
 - Induction-variable elimination can sometimes eliminate all but one of a set of induction variables
- Reduction in strength replaces a more expensive operation with a less expensive one
 - -For example, in block B3, t4 decreases by four with every iteration
 - If initialized correctly, can replace multiplication with subtraction
 - Often application of reduction in strength leads to inductionvariable elimination
- Methods exist to recognize induction variables and apply appropriate transformations automatically

Example

```
P:=0
for I:=1 to 20 do
P:=P+A[I]*B[I]
```

```
(1)P:=0
                            B1
(2)1:=1
                            B2
    T1:=4*I
(4) T2:=addr(A)-4
(5) T3:=T2[T1]
(6) T4:=4*I
(7) T5:=addr(B)-4
(8) T6:=T5[T4]
   T7:=T3*T6
(10) P:=P+T7
(11) | 1 = 1 + 1
(12) if I \le 20 goto(3)
```

Local Common Subexpressions

```
P:=0
for I:=1 to 20 do
P:=P+A[I]*B[I]
```

```
(1)P:=0
                             B1
    T1:=4*I
                             B2
   T2:=addr(A)-4
   T3:=T2[T1]
    T4:=T1
   T5:=addr(B)-4
(8) T6:=T5[T4]
    T7:=T3*T6
(10) P := P + T7
(11) | 1 = 1 + 1
(12) if I \le 20 goto(3)
```

Code motion moves code outside of a loop

```
B1
(1) P:=0
(4) T2:=addr(A)-4
(7) T5:=addr(B)-4
                        B2
    T1:=4*I
    T3:=T2[T1]
    T4:=T1
    T6:=T5[T4]
    T7:=T3*T6
(10) P:=P+T7
(11) | 1 = 1 + 1
(12) if I \le 20 goto(3)
```

Using Cheaper operations

```
B1
    P:=0
   T2:=addr(A)-4
   T5:=addr(B)-4
   T1:=4*I
                         B2
(5)
    T3:=T2[T1]
    T4:=T1
    T6:=T5[T4]
    T7:=T3*T6
(10) P := P + T7
(11) | 1 = 1 + 1
    T1:=T1+4
(12) if I \le 20 goto(5)
```

Copy Propagation

```
B1
                                                        B1
   P:=0
                                       P:=0
   T2:=addr(A)-4
                                       T2:=addr(A)-4
   T5:=addr(B)-4
                                       T5:=addr(B)-4
    T1:=4*I
                                       T1:=4
                        B2
                                       T3:=T2[T1]
                                                           B2
    T3:=T2[T1]
                                        T4:=T1
    T4:=T1
                                       T6:=T5[T1]
    T6:=T5[T4]
                                       T7:=T3*T6
    T7:=T3*T6
                                   (10) P := P + T7
(10) P := P + T7
                                   (11) | 1 = 1 + 1
(11) | 1 = 1 + 1
                                   (3') T1:=T1+4
(12) if I \le 20 \text{ goto}(5)
                                   (12) if T1<=80 goto(3)
```

Dead-Code Elimination

B1 P:=01:=1 T2:=addr(A)-4T5:=addr(B)-4(3) T1:=4T3:=T2[T1] **B2** T4:=T1 T6:=T5[T1] T7:=T3*T6 (10) P:=P+T7 (11) | 1 = 1 + 1

(3') T1:=T1+4

(12) if T1<=80 goto(5)

Quicksort in C

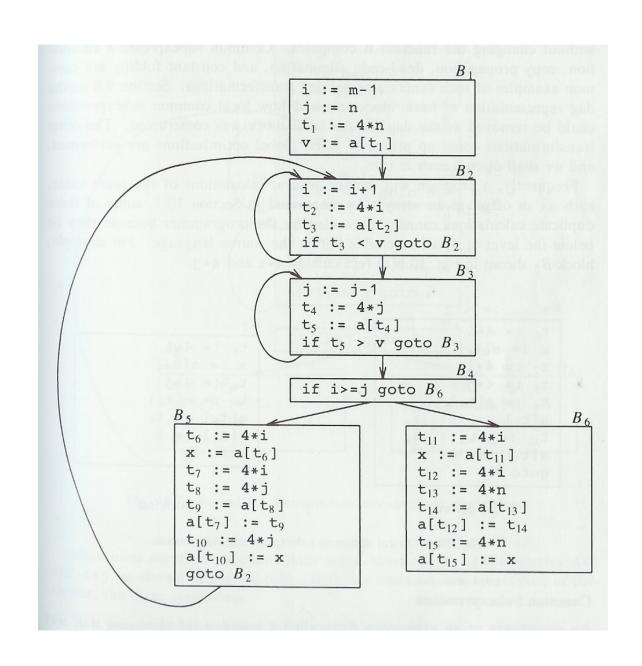
```
void quicksort(int m, int n) {
 int i, j, v, x;
 if (n <= m) return;
 /* Start of partition code */
 i = m-1; j = n; v = a[n];
 while (1) {
   do i = i+1; while (a[i] < v);
   do j = j-1; while (a[j] > v);
    if (i >= j) break;
   x = a[i]; a[i] = a[j]; a[j] = x;
 x = a[i]; a[i] = a[n]; a[n] = x;
 /* End of partition code */
 quicksort(m, j); quicksort(i+1, n);
```

Partition in Three-Address Code

```
(1) i := m-1
 (2) \dot{j} := n
 (3) t1 := 4*n
 (4) v := a[t1]
 (5) i := i+1
 (6) t2 := 4*i
 (7) t3 := a[t2]
 (8) if t3 < v \text{ qoto } (5)
 (9) \ \ \dot{} \ := \dot{} \ -1
(10) t4 := 4*\dot{1}
(11) t5 := a[t4]
(12) if t5 > v goto (9)
(13) if i >= j goto (23)
(14) t6 := 4*i
(15) x := a[t6]
```

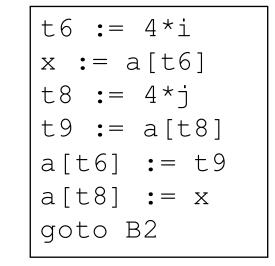
```
(16) t7 := 4*i
(17) t8 := 4*\dot{1}
(18) t9 := a[t8]
(19) a[t7] := t9
(20) t10 := 4*<math>\dot{1}
(21) a[t10] := x
(22) goto (5)
(23) t11 := 4*i
(24) x := a[t11]
(25) t12 := 4*i
(26) t13 := 4*n
(27) t14 := a[t13]
(28) a[t12] := t14
(29) t15 := 4*n
(30) a[t15] := x
```

Partition Flow Graph

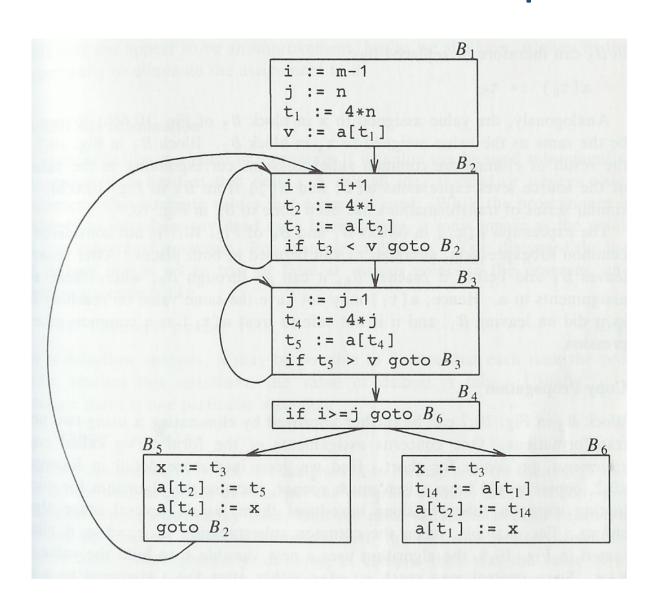


Local Common Subexpressions

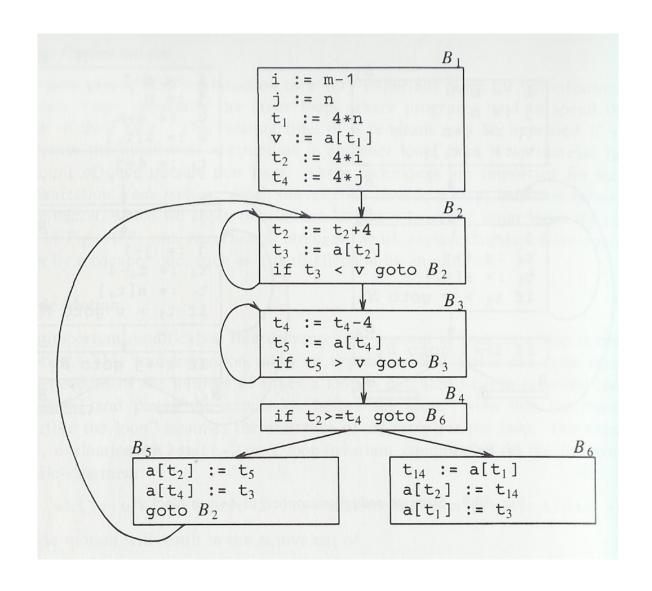
```
t6 := 4*i
x := a[t6]
t7 := 4*i
t8 := 4*j
t9 := a[t8]
a[t7] := t9
t10 := 4*j
a[t10] := x
goto B2
```



Global Common Subexpressions

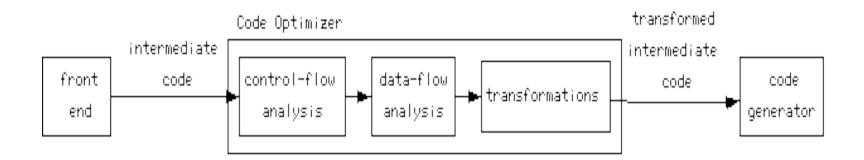


Loop Optimization Example



Implementing a Code Optimizer

- Organization consists of control-flow analysis, then dataflow analysis, and then transformations
- The code generator is applied to the transformed intermediate code
- Details of code optimization are beyond the scope of this course



Reference

- Compilers Principles, Techniques & Tools (Second Edition) Alfred Aho., Monica S. Lam, Ravi Sethi, Jeffrey D. Ullman, Addison-Wesley, 2007
- Coursera Course Compiler, http://www. Coursera.org
- Stanford Course CS143 by Keith Schwarz, http://cs143.stanford.edu