Introduction to Metropolis Light Transport

An Intuitive Approach

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Overview

- Monte Carlo
 - Variance Reduction
 - Metropolis Sampling
- Path Tracing
- Metropolis Light Transport

Monte Carlo

We want to solve this: $\int_{\Omega} f(x) dx$



$$\int_{\Omega} f(u)du = \frac{1}{N} \sum_{i=1}^{N} \frac{f(X_i)}{p(X_i)}$$

Probability Density Functions

- Traditional Monte Carlo
 - Use Uniform Probability

$$p(x) = \frac{1}{b-a}$$

 Reduce variance by finding a density function that is close to the real function

$$p(x) \propto f(x)$$

Importance Sampling

Extreme example illustrating how importance sampling helps

$$p(x) \propto f(x)$$

$$p(x) = cf(x)$$

Must normalize probability (something cannot happen more than 100% of the time)

$$c = \frac{1}{\int_{\Omega} f(u) du}$$

Importance Sampling

Extreme example continued

$$\frac{1}{N} \sum_{i=1}^{N} \frac{f(X_i)}{p(X_i)} = \frac{f(X_i)}{cf(X_i)} = \frac{1}{c} = \int_{\Omega} f(u) du$$

Picking from a Distribution

Choose random value, Xi, and solve for x.

$$\xi = \int_0^x p(u)du$$

(We call this a Cumulative Distribution Function)

Multi-Dimensional Monte Carlo

Add integrals on top of integrals

$$\int_{\Omega_n} \cdots \int_{\Omega_2} \int_{\Omega_1} f(u_1, u_2, \dots, u_n) du_1 du_2 \dots du_n$$

$$\int_{\Omega} f(\mathbf{u}) d\mathbf{u}$$

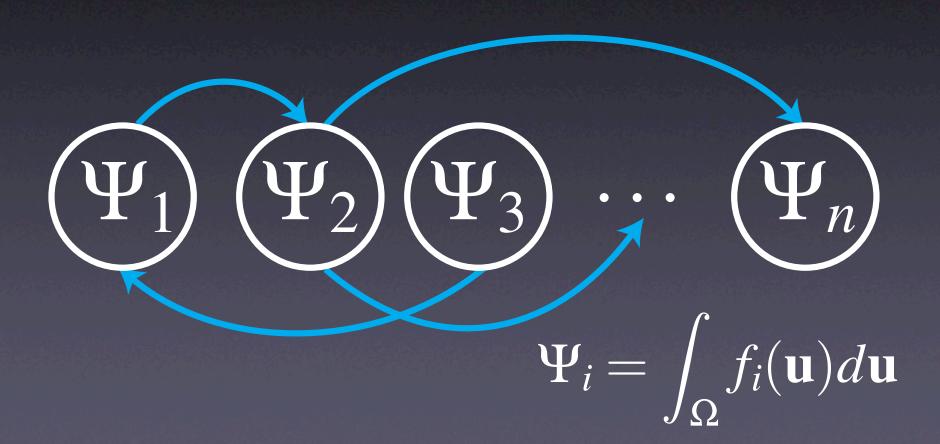
Multi-Dimensional Monte Carlo

 Look at multi-dimensional variables as a vector of variables. Same techniques still applies!

$$\int_{\Omega} f(\mathbf{u}) d\mathbf{u} = \frac{1}{N} \sum_{i} \frac{f(\mathbf{X_i})}{p(\mathbf{X_i})}$$

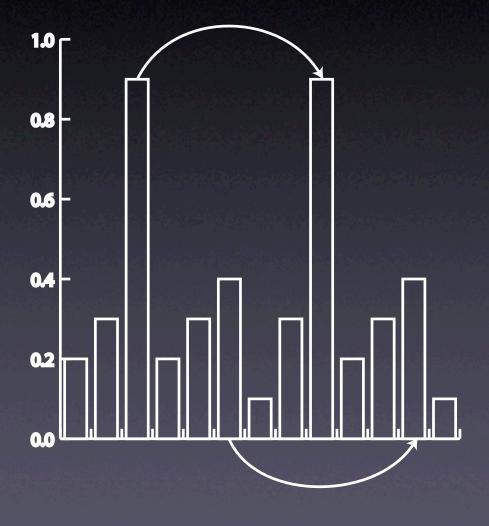
Variance Reduction

- Metropolis Sampling
 - Simple idea ~ Similar integrals should share samples



Metropolis Sampling

- Histogram view
- Move samples around for similar integrals



Metropolis Sampling

- How do we share samples without biasing (un-randomizing) result?
- We create a general balance between samples

General Balance

Maintaining Balance

Transfer Probability

$$T(y \rightarrow x)$$

- Most difficult to choose transfer probability
- As long as general balance is held within the limit, the function is suited for Metropolis
- Want to find function that produces the best result, with the fewest samples.

Metropolis Sampling Algorithm

```
choose starting sample x
for i = 0 to mutations
  y = mutate(x)
  acceptance = y/x T(y > x)/T(x > y)
  if (randomReal(0, I) < acceptance)
     x = y
  deposit sample x
end for
```

Neat Example

choose random starting pos (x,y)T(y > x)/T(x > y) = I

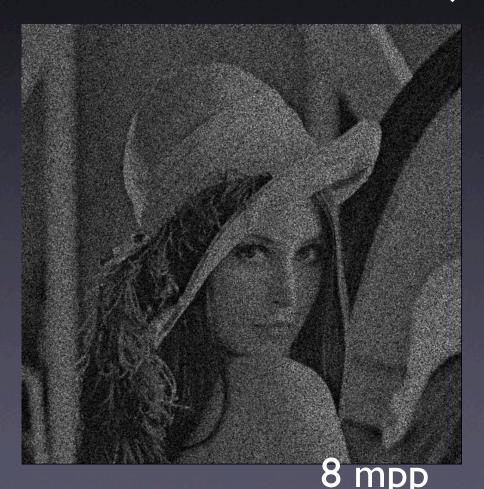
for i = 0 to mutations
 npos = random pos
 acceptance = val[npos]/val[pos]
 if (randomReal(0,1) < acceptance)
 pos = npos</pre>

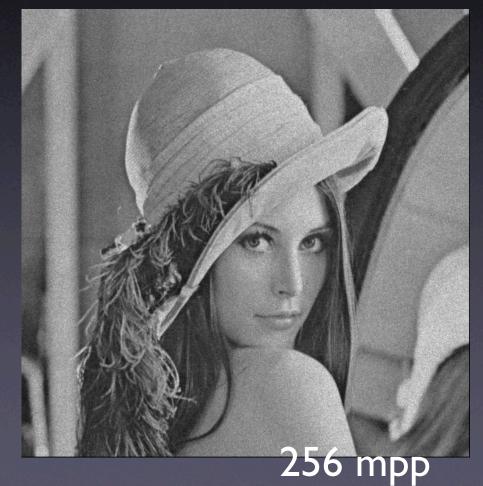
add I at posend for

Neat Example



- Equal probability of transfer
- For mutation we just choose another pixel

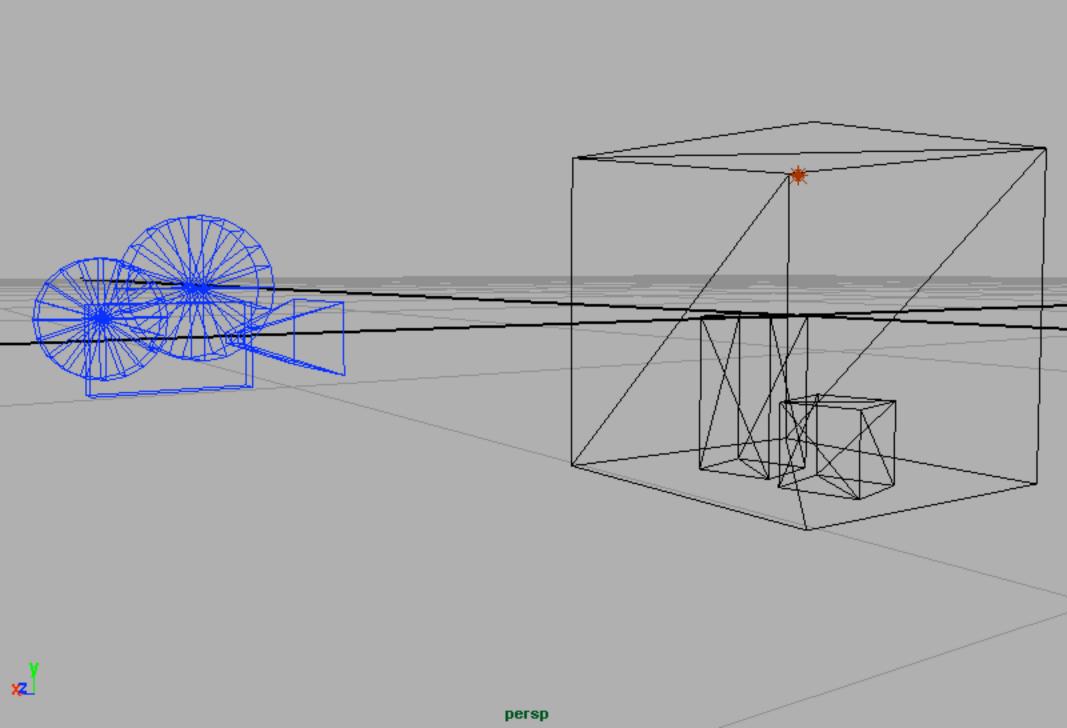




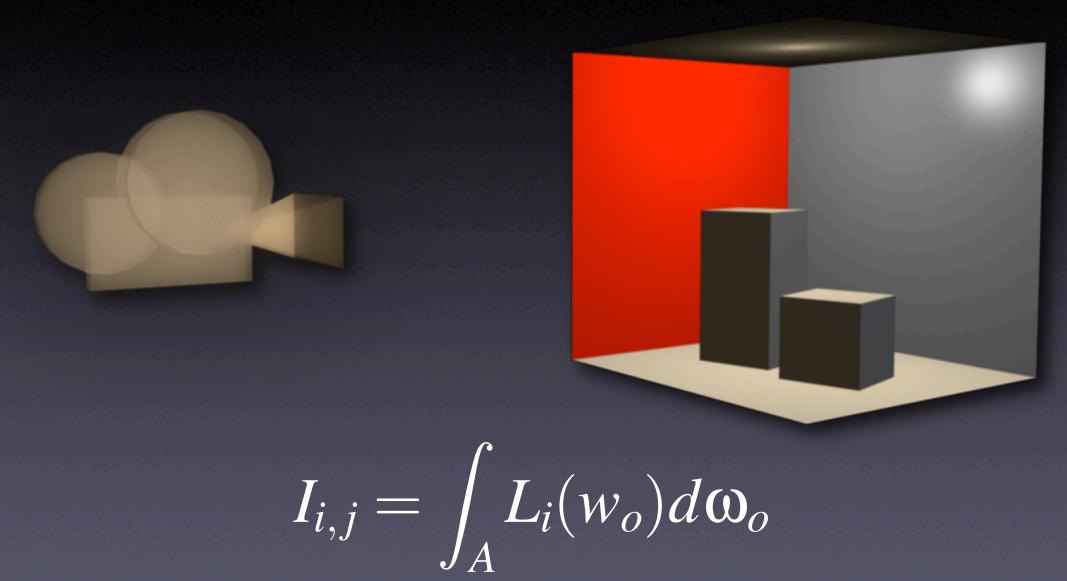
Neat Example

- We see that the more samples we transfer between the integrands (pixels) the closer we come to the real solution
- Shows MS is unbiased, as in the limit, it will properly distribute the samples across the integrands

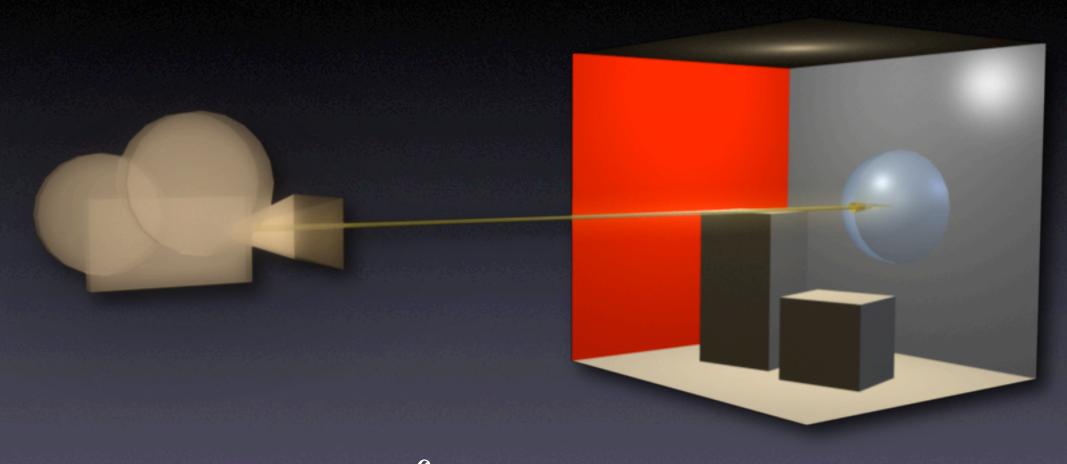
Path Tracing



Pixel

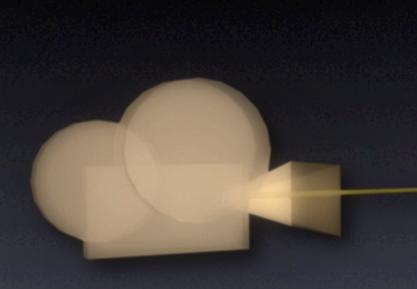


Primary Ray



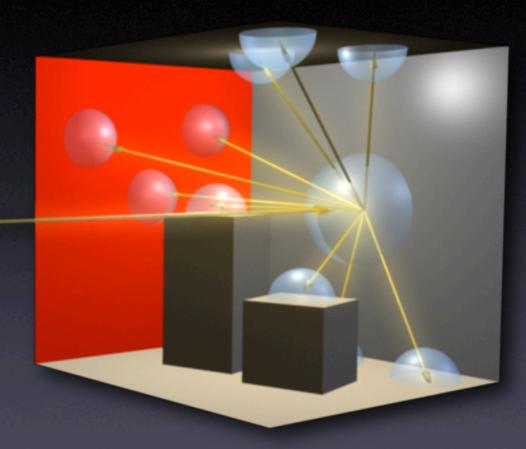
$$L_i(\omega_o) = L_e + \int_{\Omega} L_i(\omega_i) f(\omega_i, \omega_o) \cos \theta_i d\omega_i$$

Secondary Ray



Recursive definition consolidated to function of finite dimension, g

of finite dimension, g
$$I_{i,j} = \int_A \int_{\Omega_1} \int_{\Omega_2} \dots \int_{\Omega_n} g(\omega_o, \omega_{i_1}, \omega_{i_2}, \dots, \omega_{i_n}) d\omega_{i_n} \dots d\omega_{i_2} d\omega_{i_1} d\omega_o$$



Converting Paths to Monte Carlo

$$I_{i,j} = \int_A \int_{\Omega_1} \int_{\Omega_2} \dots \int_{\Omega_n} g(\mathbf{\omega}_o, \mathbf{\omega}_{i_1}, \mathbf{\omega}_{i_2}, \dots, \mathbf{\omega}_{i_n}) d\mathbf{\omega}_{i_n} \dots d\mathbf{\omega}_{i_2} d\mathbf{\omega}_{i_1} d\mathbf{\omega}_o$$

$$I_{i,j} = \int g(\mathbf{u}) d\mathbf{u}$$

$$I_{i,j} pprox rac{1}{N} \sum_{i=1}^{N} rac{g(\mathbf{X}_i)}{p(\mathbf{X}_i)}$$

Path Tracing

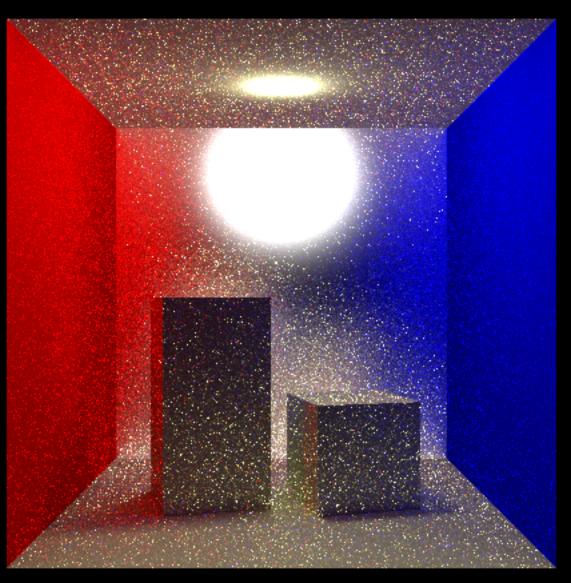
- PDFs are chosen based upon:
 - Material Properties
 - Choice of Light
- Russian Roulette
 - Path length (how many integrals are we going to solve)

Path Tracing

$$X_f = \frac{f_0(\boldsymbol{\omega}_{i_0}, \boldsymbol{\omega}_{o_0}) \cos \boldsymbol{\theta}_{i_0}}{p_0(\boldsymbol{\omega}_{i_0}, \boldsymbol{\omega}_{o_0})} \cdot \frac{f_1(\boldsymbol{\omega}_{i_1}, \boldsymbol{\omega}_{o_1}) \cos \boldsymbol{\theta}_{i_1}}{p_1(\boldsymbol{\omega}_{i_1}, \boldsymbol{\omega}_{o_1})} \cdot \dots \cdot \frac{f_n(\boldsymbol{\omega}_{i_n}, \boldsymbol{\omega}_{o_n}) \cos \boldsymbol{\theta}_{i_n}}{\pi d^2} \cdot \frac{V(x_n, x_{light}) L_e A}{p_{light} p_{len}(n)}$$

- Initially, solve for cosine weighted BRDF divide by probability of sample
- When connecting light, the probability of any direction is uniform, but varies depending upon the distance the path must travel
- Divide by the probability of the light and probability of the length of the path

Results



500 samples per pixel

Improvements to Path Tracing

- Path per wavelength of light
 - Birefringence
- Bi-directional Path Tracing
 - Start generating a path from both the eye and the light
 - Connect them in the middle
 - Further reduces variance

Metropolis Light Transport

- Surprisingly similar to Metropolis Sampling
- Now, the samples are paths
- Hard Part
 - Determining Transfer Probability
 - Changes in Path Density
 - Mutation Strategy

Mutation and Transfer

- Several mutation strategies
 - Lens Perturbation*
 - Caustic Perturbation
 - Random Path Mutation
- Many rules for how a mutation changes the path density

Lens Perturbation

- Take a path and start it in a new location on the image plane
- With the new location on the image plane, we now have a chain reaction of mutations

Chain Mutation

- Lets walk through the mutation of the following path
- Path X: LDDSE

specular

diffuse

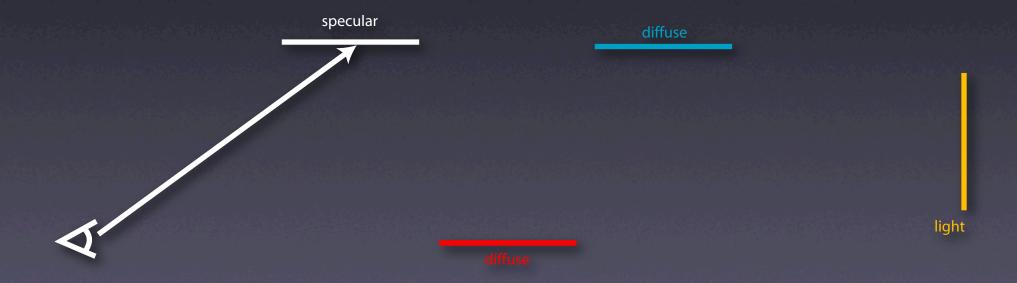
4

light

Lens Perturbation

Equal probability that a new pixel is chosen

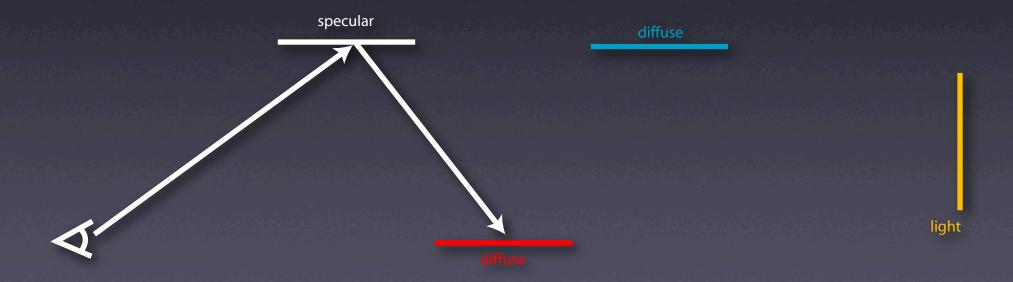
$$\frac{T(y \to x)}{T(x \to y)} = 1$$



Specular > (Specular | Diffuse)

Travel in the same incoming direction as path x at specular surface

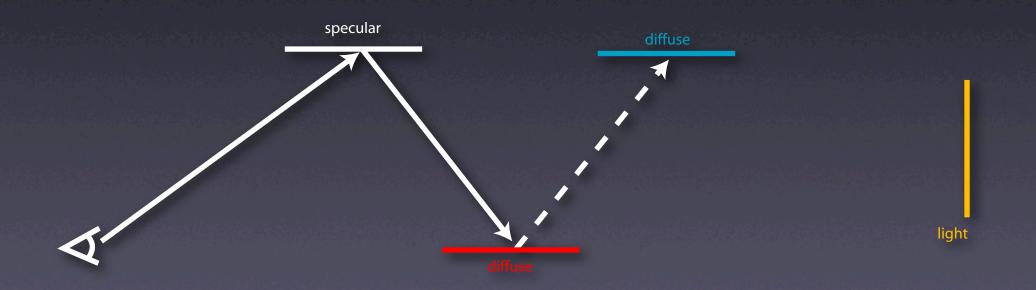
$$\frac{T(y \to x)}{T(x \to y)} = 1$$



Diffuse > Diffuse

If two diffuse connect the paths

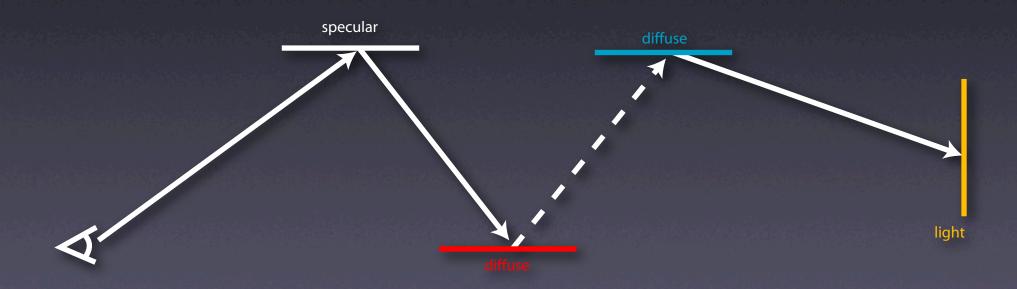
If two diffuse surfaces, just
$$\frac{T(y \to x)}{T(x \to y)} = \frac{\cos \theta_{1_x} \cos \theta_{2_x}}{d_x^2} \frac{d_y^2}{\cos \theta_{1_y} \cos \theta_{2_y}}$$



Remaining Connections

Copy remaining path, possibly perturb if diffuse vertex on path

$$\frac{T(y \to x)}{T(x \to y)} = 1$$



Putting it All Together

```
start with random path x
```

```
for i = 0 to mutations
  y = mutate(x)
  acceptance = y/x T(y > x)/T(x > y)
  if (randomReal(0, I) < acceptance)
    x = y</pre>
```

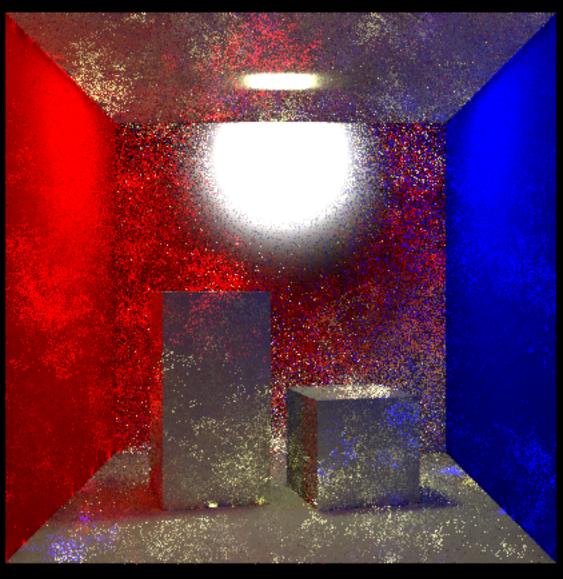
deposit path x at corresponding pixel end for

- we just went over transfer probabilities for paths
- y and x are represented by luminance value of sample when calculating acceptance

Up Scaling

- Undetermined amount of samples per pixel
- Scale up by average number of samples per pixel

Results



200 MC samples 500 mutations

Results

- Difficult to compare in sheer terms of samples
 - Mutations are much faster than MC
 - Path reuse
 - Cache coherence
- Possible specular bug
- Splotchiness?

Problems with MLT

- Start-up Bias
 - If we just mutate one randomly generated path, in the limit, we will eventually get a correct solution if we apply several mutation strategies
 - However, we do not want to be close to the limit, we want to be done with a few samples
 - Thereby, we generate several random paths and mutate them

To Do...

- Transfer probabilities and mutations are the key
 - Several transfer probabilities I did not even describe in this presentation
- Find a better estimation for changes in path density, you could find a better solution
 - Possibly publish another SIGGRAPH paper

Established Improvements

- Importance Sample Mutations
- Energy Redistribution
 - Improved Balance Algorithm
 - Post-process filtering

References

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 Redistribution Path Tracing, SIGGRAPH '05
- Veach, E., Robust Monte Carlo Methods for Light Transport Simulation. Dissertation, Stanford '97