

200010021

September 10, 2022

#LAB 5 : Regression

Regression is generally used for curve fitting task. Here we will demonstrate regression task for the following :

1. Fitting of a Line (One Variable and Two Variables)
2. Fitting of a Plane
3. Fitting of M-dimensional hyperplane
4. Practical Example of Regression task

```
[5]: import numpy as np
import matplotlib.pyplot as plt
```

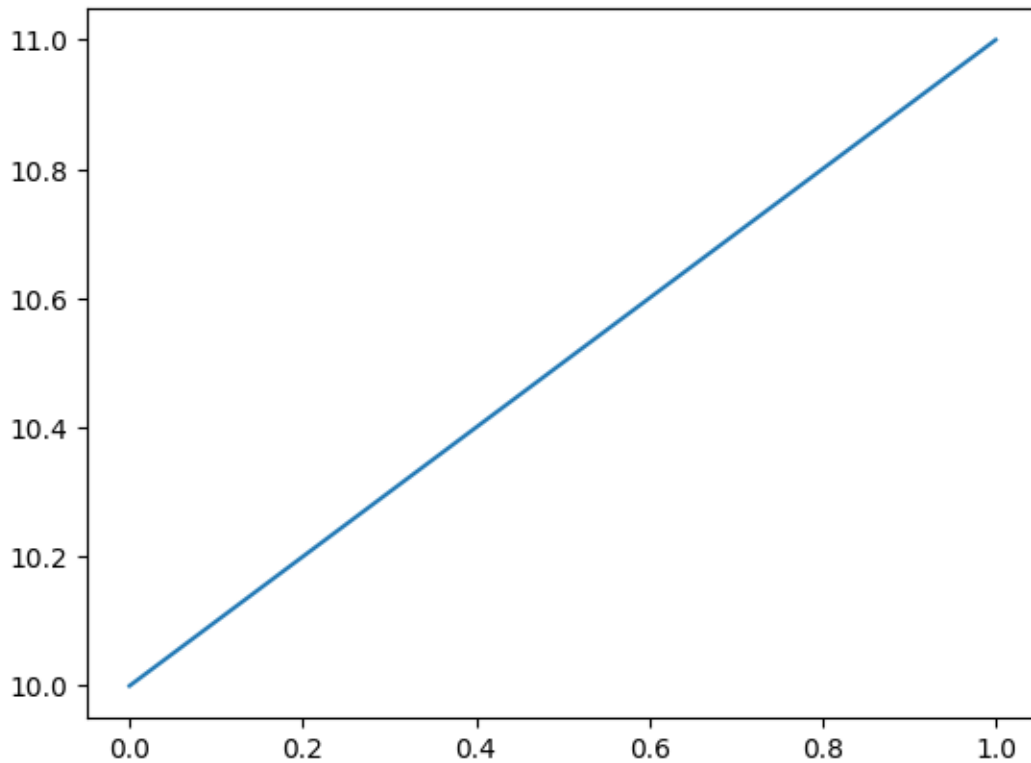
#Fitting of a Line (One Variable)

Generation of line data ($y = w_1x + w_0$)

1. Generate x , 1000 points from 0-1
2. Take $w_0 = 10$ and $w_1 = 1$ and generate y
3. Plot (x,y)

```
[6]: ## Write your code here
X = np.linspace(0,1,1000)
W1 = 1
W0 = 10
Y = W1*X + W0
plt.plot(X,Y)
```

```
[6]: [<matplotlib.lines.Line2D at 0x7f6c02845ac0>]
```



Corruption of data using uniformly sampled random noise

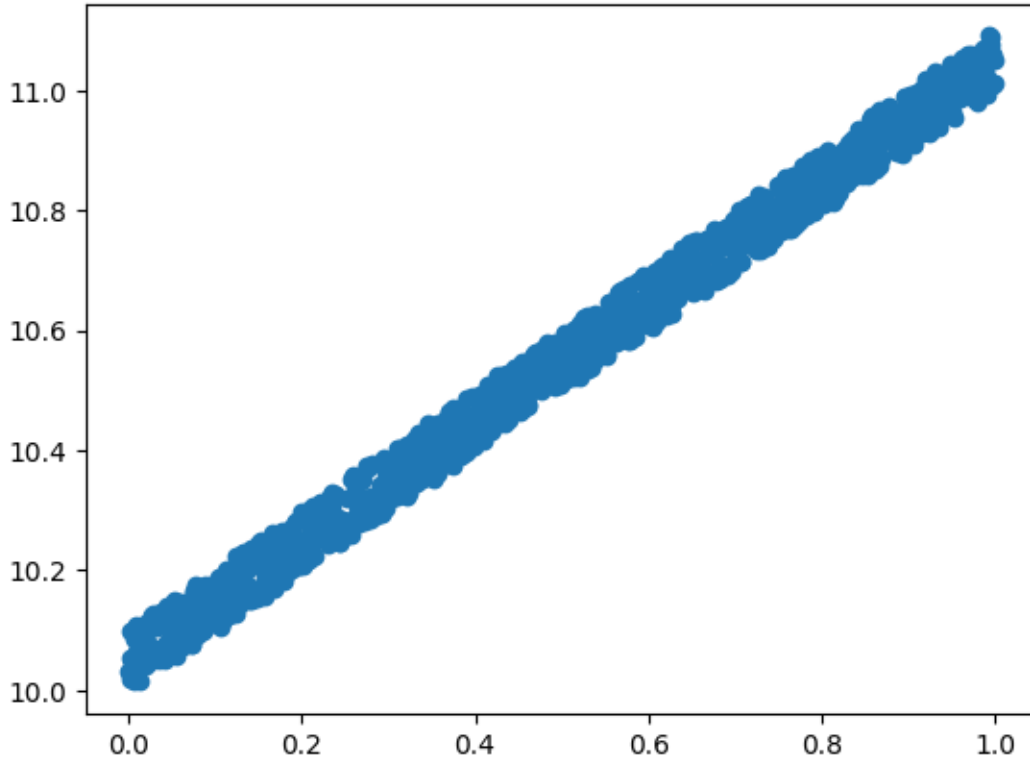
1. Generate random numbers uniformly from (0-1) with same size as y
2. Corrupt y and generate y_{cor} by adding the generated random samples with a weight of 0.1.
3. Plot (x, y_{cor}) (use scatter plot)

```
[7]: ## Write your code here
Random_Noise = np.random.random(Y.shape)

Y_corrupted = Y + 0.1 * Random_Noise

plt.scatter(X, Y_corrupted)
```

```
[7]: <matplotlib.collections.PathCollection at 0x7f6c029f9a00>
```



Heuristically predicting the curve (Generating the Error Curve)

1. Keep $w_0 = 10$ as constant and find w_1
2. Create a search space from -5 to 7 for w_1 , by generating 1000 numbers between that
3. Find y_{pred} using each value of w_1
4. The y_{pred} that provide least norm error with y , will be decided as best y_{pred}

$$error = \frac{1}{m} \sum_{i=1}^M (y_i - y_{pred_i})^2$$

5. Plot error vs search_ w_1
6. First plot the scatter plot (x, y_{cor}) , over that plot $(x, y_{bestpred})$

```
[36]: def heuristic_search(X, Y_corrupted):
    search_space_W1 = np.linspace(-5, 7, 1000)
    search_space_W1 = search_space_W1.reshape(search_space_W1.shape[0], 1)
    X = X.reshape(X.shape[0], 1)
    Y_Pred = search_space_W1 @ X.T + W0

    Y_corrupted_1000_shape = np.tile(Y_corrupted, (X.shape[0], 1))

    error_in_y = np.mean(np.power((Y_corrupted_1000_shape - Y_Pred), 2), axis= 1)

    W1_heuristic = search_space_W1[np.where(error_in_y == np.min(error_in_y))]
```

```

    return W1_heuristic, search_space_W1, error_in_y

W1_heuristic, search_space_W1, error_in_y = heuristic_search(X, Y_corrupted)
minimun_index = np.where(error_in_y == np.min(error_in_y))

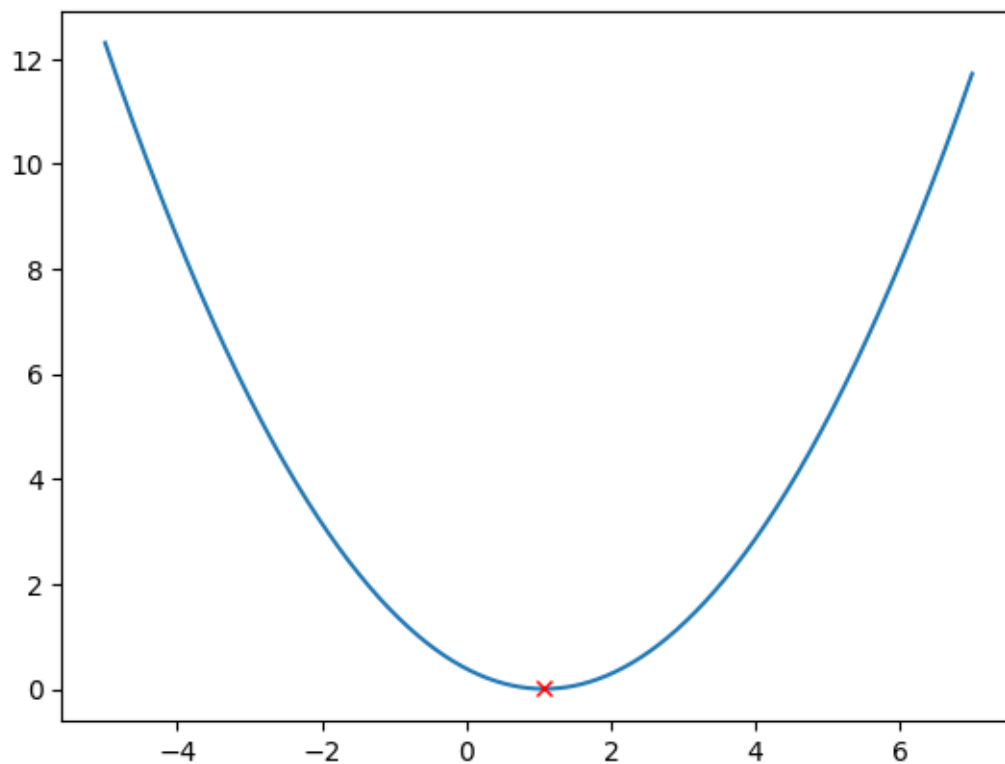
plt.figure()
plt.plot(search_space_W1, error_in_y)
plt.plot(W1_heuristic, error_in_y[minimun_index], 'x' ,color='r' )

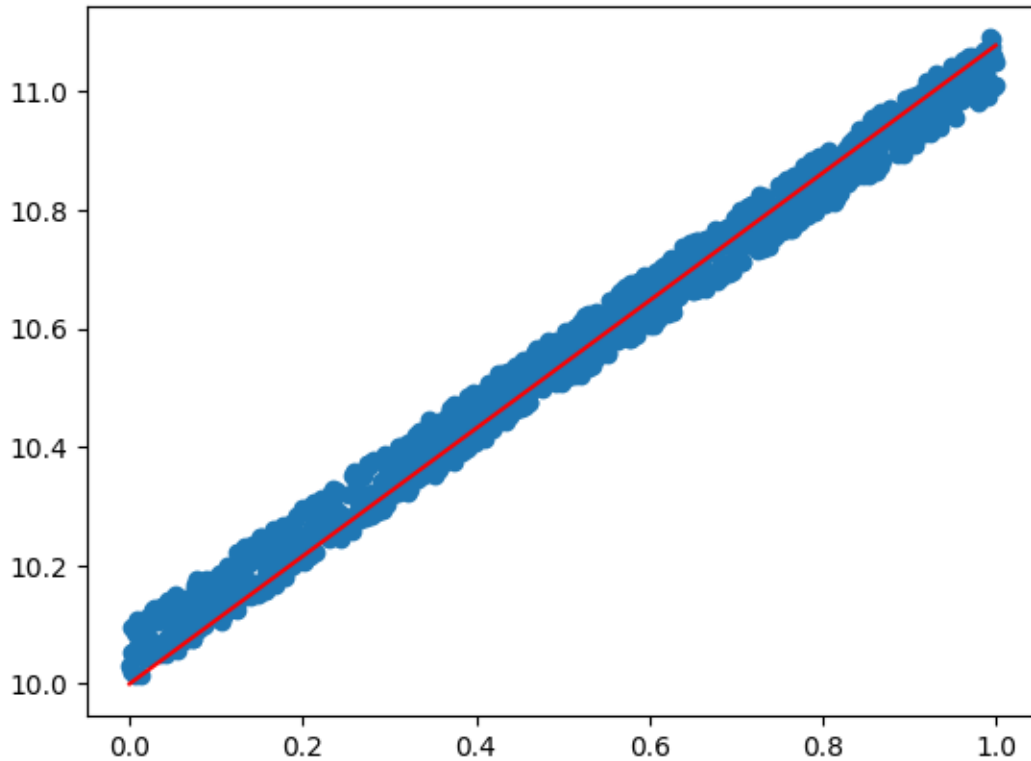
Y_best = W1_heuristic * X + W0
plt.figure()
plt.scatter(X, Y_corrupted)
plt.plot(X, Y_best.T, color='r')

print(f'Optimal W1 using heuristic is {W1_heuristic[0][0]}')

```

Optimal W1 using heuristic is 1.0780780780780779





Using Gradient Descent to predict the curve

1. $Error = \frac{1}{m} \sum_{i=1}^M (y_i - y_{pred_i})^2 = \frac{1}{m} \sum_{i=1}^M (y_i - (w_0 + w_1 x_i))^2$
2. $\nabla Error|_{w_1} = \frac{-2}{M} \sum_{i=1}^M (y_i - y_{pred_i}) \times x_i$
3. $w_1|_{new} = w_1|_{old} - \lambda \nabla Error|_{w_1} = w_1|_{old} + \frac{2\lambda}{M} \sum_{i=1}^M (y_i - y_{pred_i}) \times x_i$

[43]: *## Write your code here*

```
def make_gradient_step(X, Y, W1, lr ):
    W1_new = W1 - lr * np.average((W1*X+W0 - Y) * X)
    return W1_new

def error(W1, Y):
    return np.mean(np.power(W1*X+W0 - Y, 2))

plt.figure()
plt.plot(search_space_W1,error_in_y)

W1_grad = 6
W0 = 10
lr = 0.1
```

```

precision = 1e-10

for i in range(1000):
    W1_prev = W1_grad
    W1_grad = make_gradient_step(X, Y_corrupted, W1_grad, lr)

    plt.
    ↪plot([W1_prev,W1_grad],[error(W1_prev,Y_corrupted),error(W1_grad,Y_corrupted)],color='r')

    if np.abs(error(W1_grad,Y_corrupted) - error(W1_prev,Y_corrupted)) <_
    ↪precision:
        break

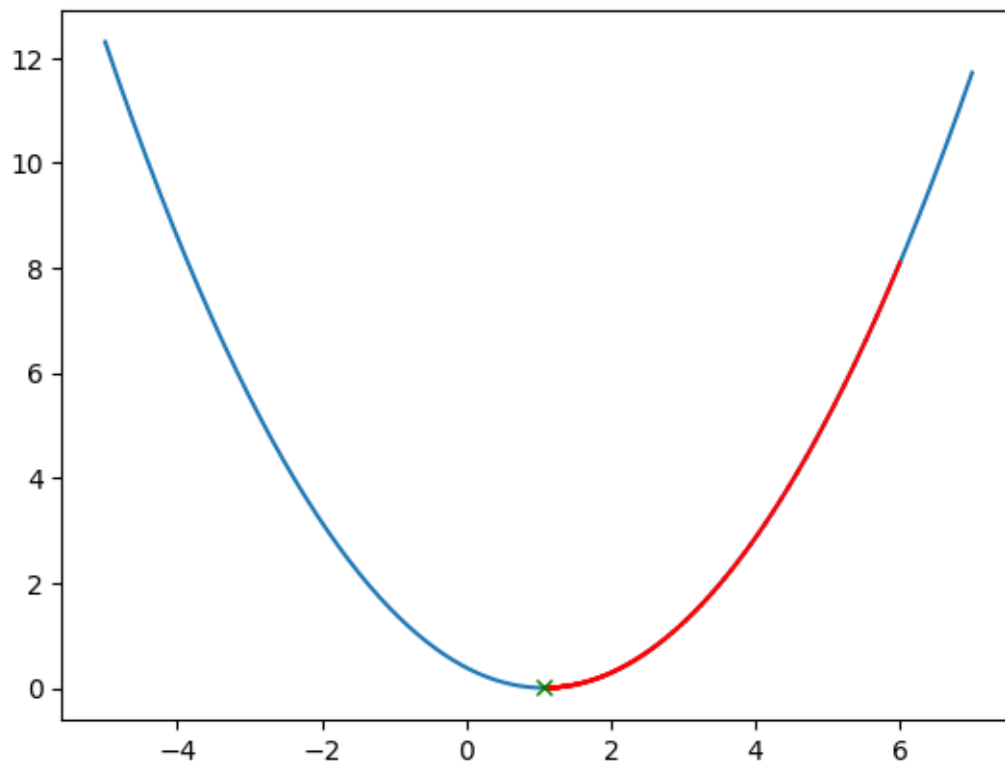
print(W1_grad)
plt.plot(W1_grad,error(W1_grad,Y_corrupted),'x',color='g')

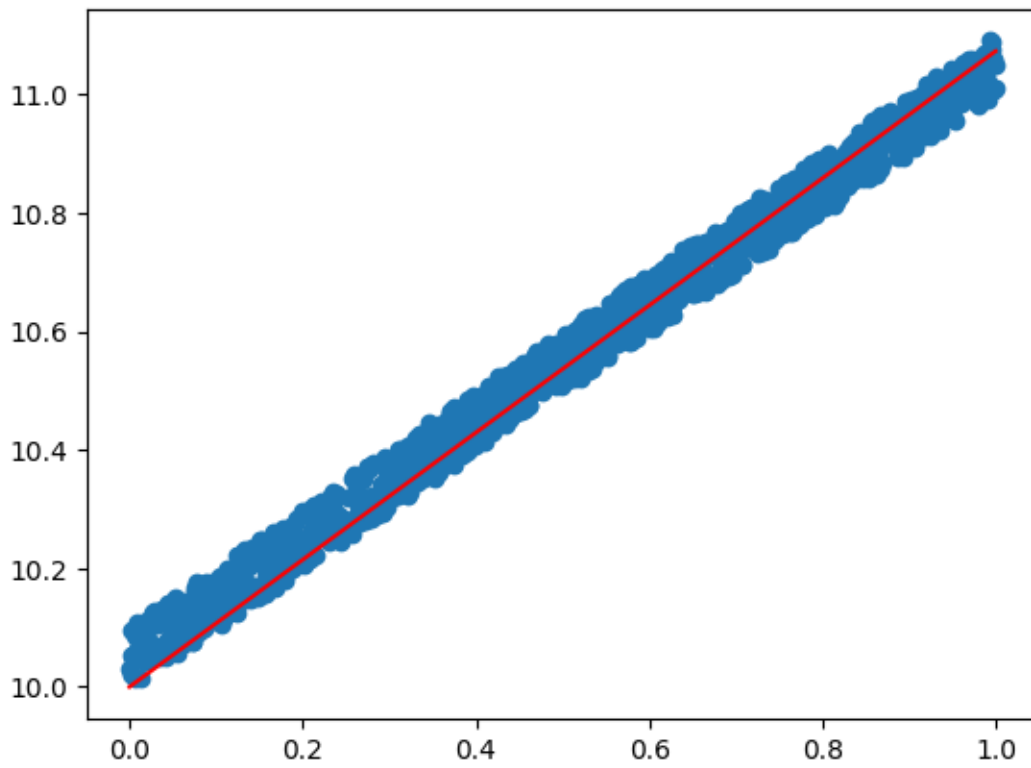
Y_best_grad = W1_grad*X+W0
plt.figure()
plt.scatter(X, Y_corrupted)
plt.plot(X, Y_best_grad, color='r')

```

1.0736174242257677

[43]: [<matplotlib.lines.Line2D at 0x7f6bfc573e50>]





#Fitting of a Line (Two Variables)

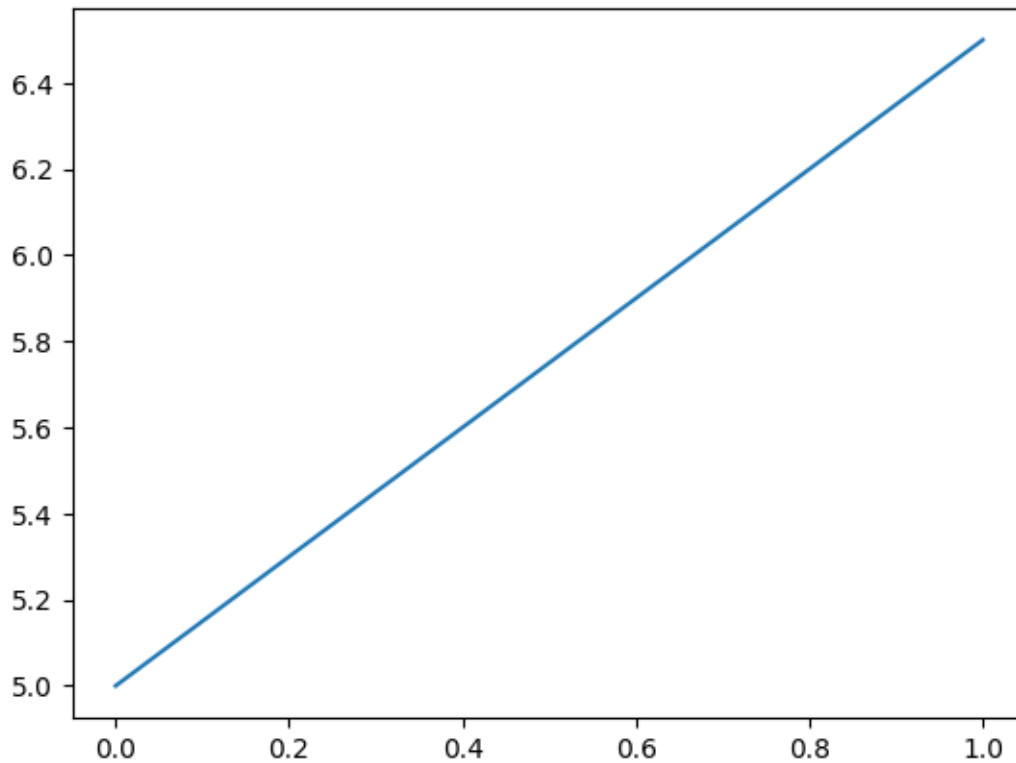
Generation of Line Data ($y = w_1x + w_0$)

1. Generate x , 1000 points from 0-1
2. Take $w_0 = 5$ and $w_1 = 1.5$ and generate y
3. Plot (x,y)

```
[44]: ## Write your code here
import numpy as np
import matplotlib.pyplot as plt

X = np.linspace(0,1,1000)
W0 = 5
W1 = 1.5
Y = W1*X + W0
plt.plot(X,Y)
```

```
[44]: [<matplotlib.lines.Line2D at 0x7f6bfc475ac0>]
```

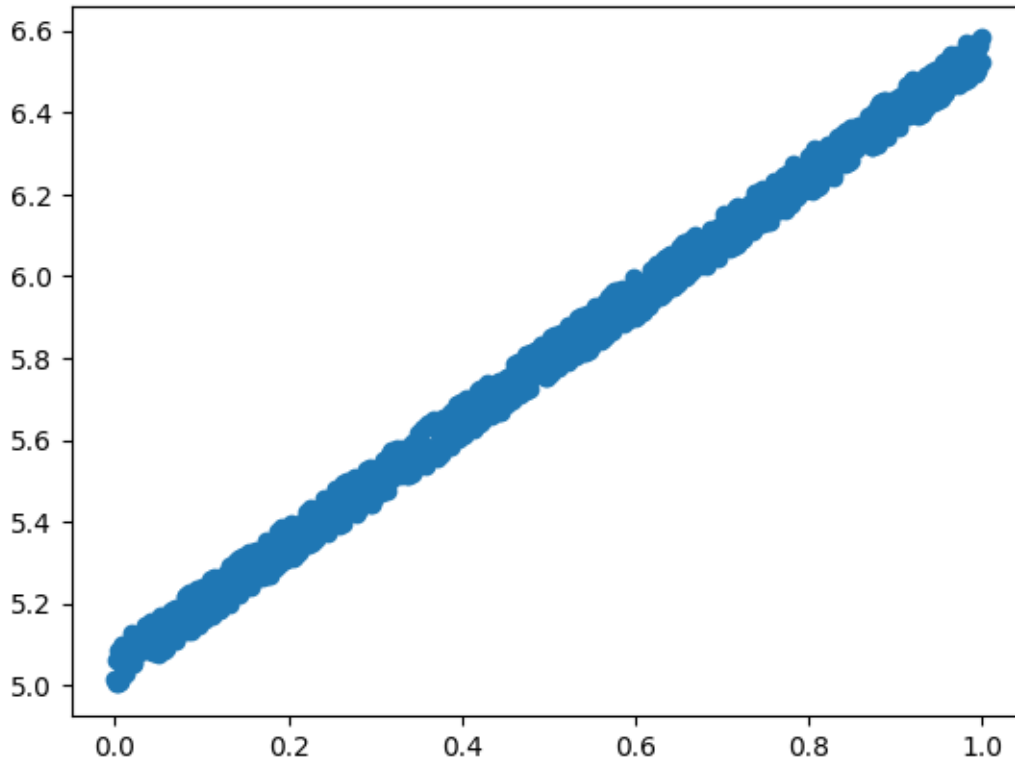


Corrupt the data using uniformly sampled random noise

1. Generate random numbers uniformly from (0-1) with same size as y
2. Corrupt y and generate y_{cor} by adding the generated random samples with a weight of 0.1
3. Plot (x, y_{cor}) (use scatter plot)

```
[45]: ## Write your code here  
Random_Noise = np.random.random(Y.shape)  
  
Y_corrupted = Y + 0.1 * Random_Noise  
  
plt.scatter(X, Y_corrupted)
```

```
[45]: <matplotlib.collections.PathCollection at 0x7f6bfc3cadf0>
```

Plot the Error Surface

1. we have all the data points available in y_{cor} , now we have to fit a line with it. (i.e from y_{cor} we have to predict the true value of w_1 and w_0)
2. Take w_1 and w_0 from -10 to 10, to get the error surface

```
[54]: search_space_W1=np.linspace(-10,10,100)
search_space_W0=np.linspace(-10,10,100)

Search_space_W1,Search_space_W0 = np.meshgrid(search_space_W1,search_space_W0)

def error(w1,w0,x,y):
    err=np.zeros(w1.shape)
    for x_i,y_i in zip(x,y):
        err1=np.power((np.tile(y_i,w1.shape)-(w1*x_i+w0)),2)
        err=err+err1
    return err/x.shape[0]

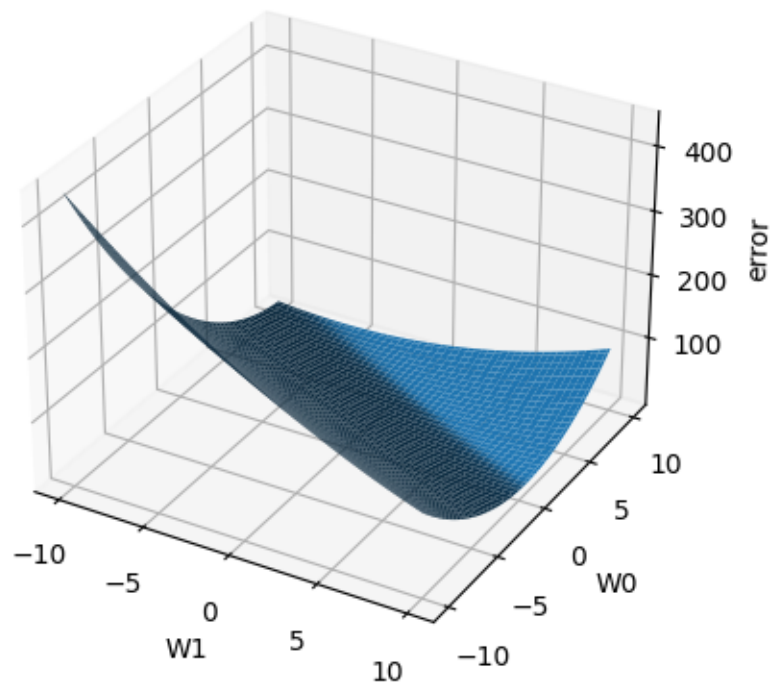
error_with_W1_W0 = error(Search_space_W1,Search_space_W0,X,Y_corrupted)

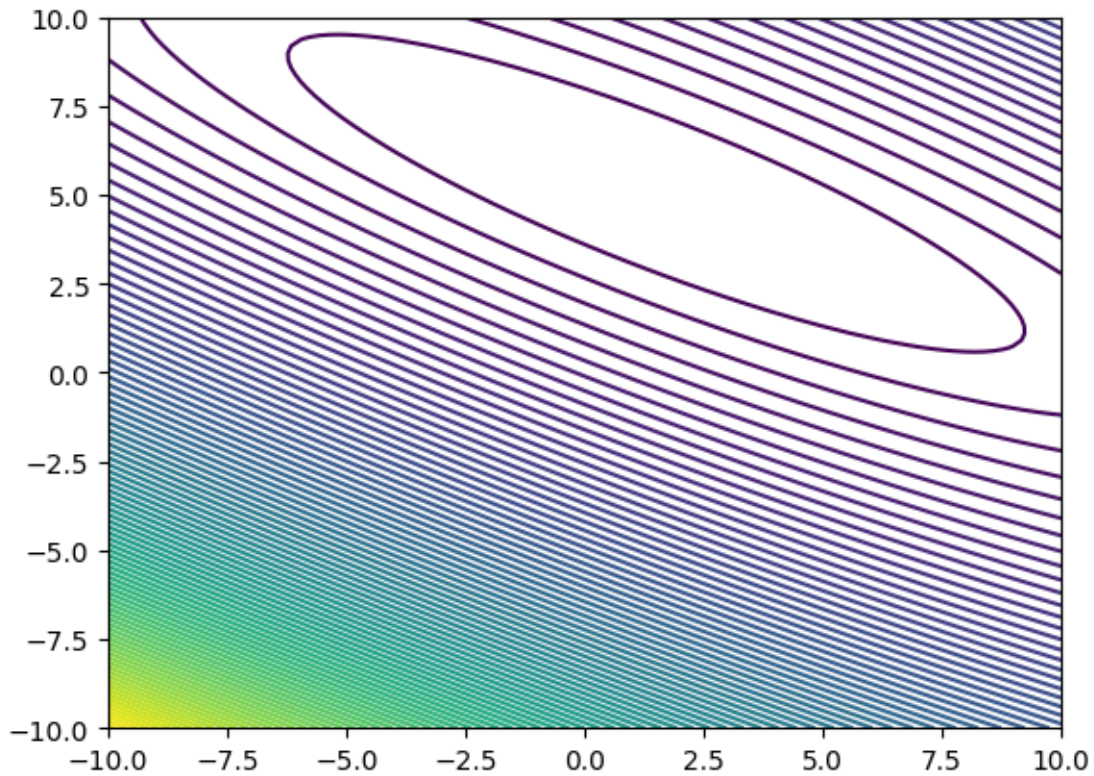
plt.figure()
ax = plt.axes(projection='3d')
ax.plot_surface(Search_space_W1, Search_space_W0, error_with_W1_W0)
```

```
ax.set_xlabel('W1')
ax.set_ylabel('W0')
ax.set_zlabel('error');

plt.figure()
plt.contour(Search_space_W1, Search_space_W0, error_with_W1_W0,100)
```

[54]: <matplotlib.contour.QuadContourSet at 0x7f6bfc6f1b20>





Gradient Descent to find optimal Values

```
[69]: ## Write your code here
def make_gradient_step(X, Y, W1, W0, lr ):
    W0_new = W0 - lr * np.average((W1*X+W0 - Y))
    W1_new = W1 - lr * np.average((W1*X+W0 - Y) * X)
    return W0_new, W1_new

def error(w1,w0,x,y):
    return np.mean(np.power(y-(w1*x + w0),2))

plt.figure()
plt.contour(Search_space_W1, Search_space_W0, error_with_W1_W0,100)

W1_grad = 6
W0_grad = 6
lr = 1.5

precision = 1e-10

for i in range(1000):
    W0_prev = W0_grad
```

```

W1_prev = W1_grad

W0_grad, W1_grad = make_gradient_step(X, Y_corrupted, W1_grad, W0_grad,lr)

plt.plot([W1_prev,W1_grad],[W0_prev, W0_grad],color='r')

    if np.abs(error(W1_grad,W0_grad, X, Y_corrupted) - error(W1_prev,W0_prev,X, Y_corrupted)) < precision:
        break

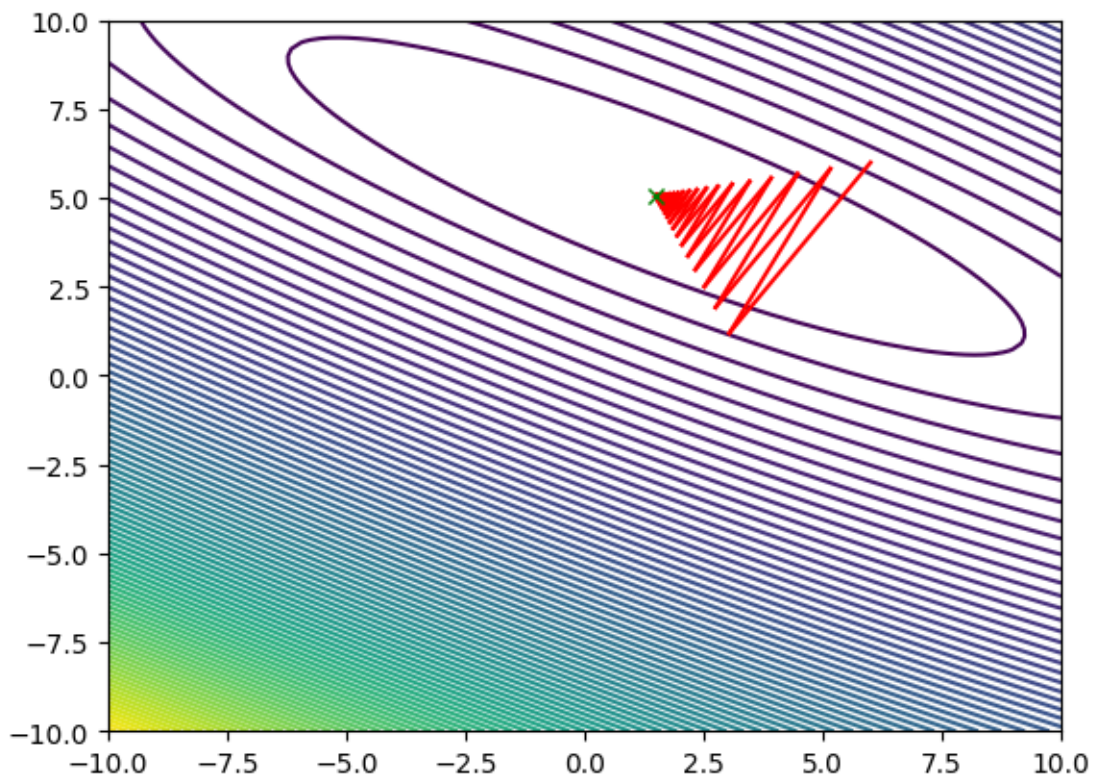
print(W0_grad,W1_grad)
plt.plot(W1_grad,W0_grad,'x',color='g')

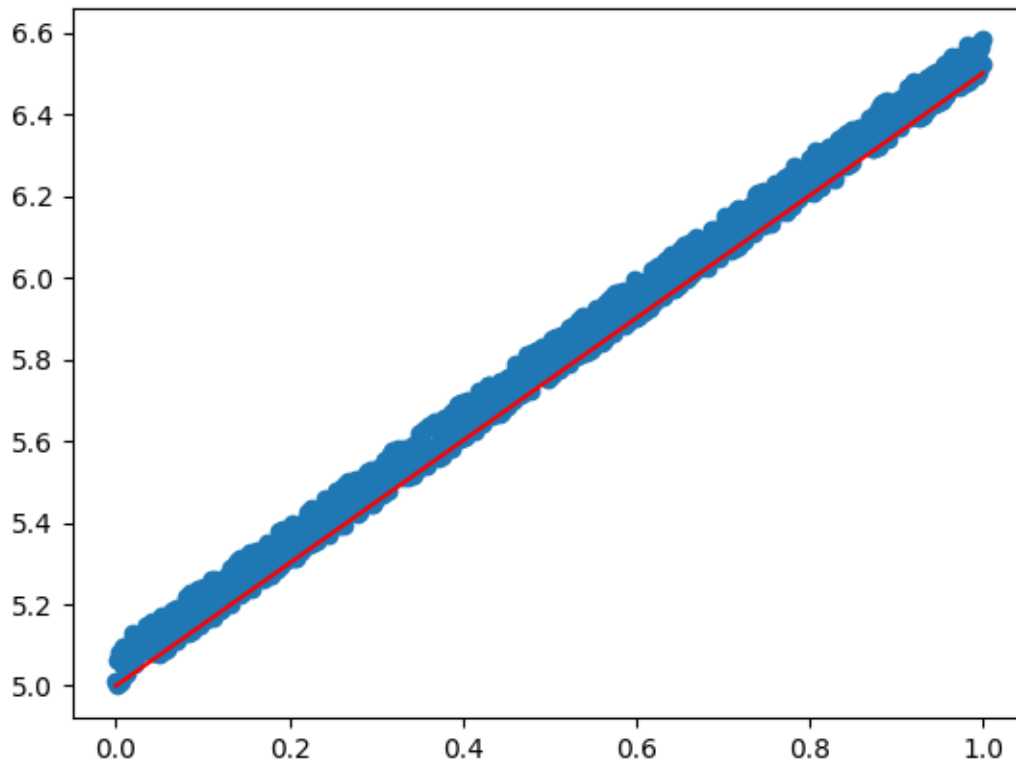
Y_best_grad = W1_grad*X+W0
plt.figure()
plt.scatter(X, Y_corrupted)
plt.plot(X, Y_best_grad, color='r')

```

5.048242710621524 1.5007734450119137

[69]: [<matplotlib.lines.Line2D at 0x7f6bf8e41910>]





#Fitting of a Plane

Generation of plane data

1. Generate x_1 and x_2 from range -1 to 1, (30 samples)
2. Equation of plane $y = w_0 + w_1x_1 + w_2x_2$
3. Here we will fix w_0 and will learn w_1 and w_2

```
[70]: X1=np.linspace(-1,1,30)
      X2=np.linspace(-1,1,30)
```

```
W0=0
```

```
W1=-2
```

```
W2=-2
```

```
y= W0+W1*X1+W2*X2
```

```
X1,X2=np.meshgrid(X1,X2)
```

```
Y=W0+W1*X1+W2*X2
```

```

plt.figure()
ax = plt.axes(projection='3d')
ax.plot_surface(X1, X2, Y)
ax.set_xlabel('x1')
ax.set_ylabel('x2')
ax.set_zlabel('y');

Random_Noise=np.random.uniform(0,1,Y.shape)
Y_corrupted =Y+0.1*Random_Noise

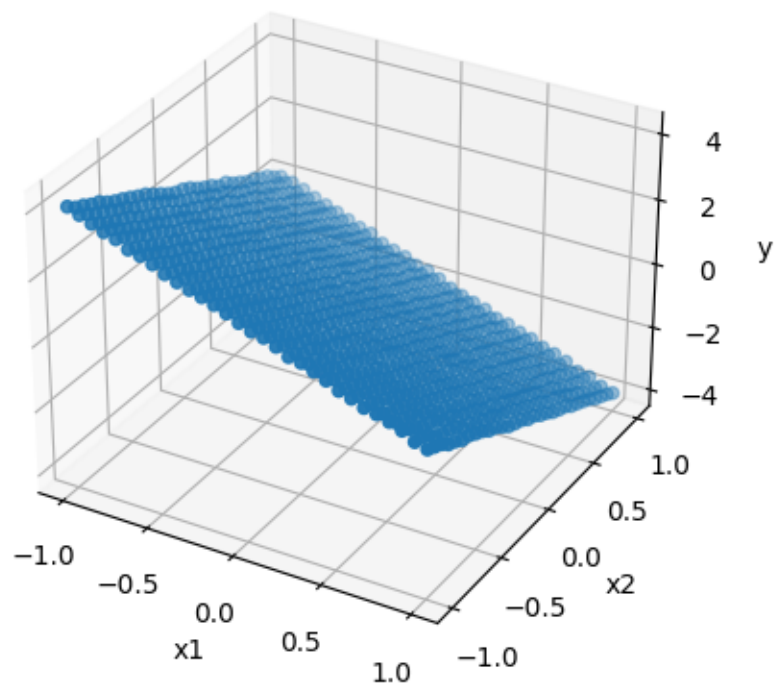
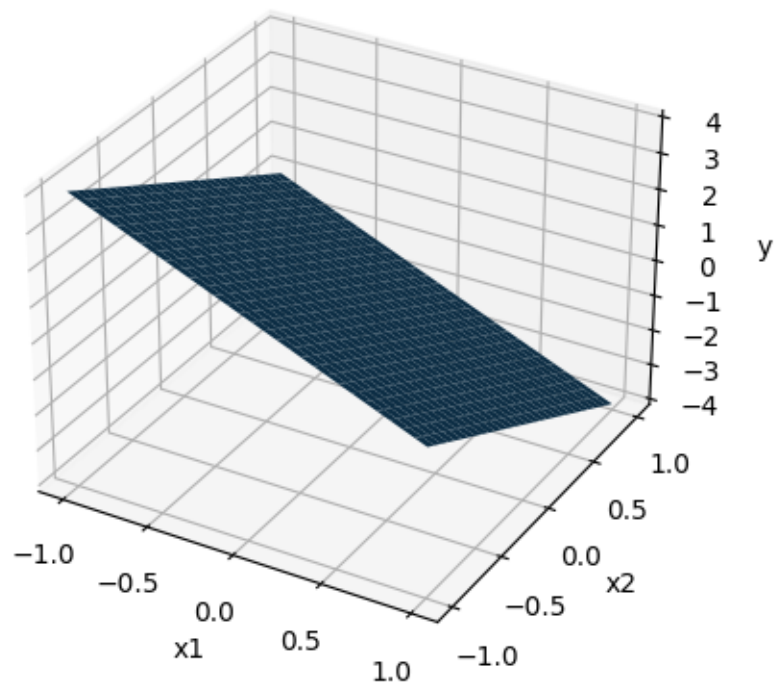
plt.figure()
ax = plt.axes(projection='3d')
ax.scatter3D(X1, X2, Y_corrupted, '.')
ax.set_xlabel('x1')
ax.set_ylabel('x2')
ax.set_zlabel('y');

x1=X1.flatten()
x2=X2.flatten()
y_cor=Y_corrupted.flatten()

print(x1.shape)

```

(900,)



Generate the Error Surface

1. Vary w_1 and w_2 and generate the error surface and find their optimal value
2. Also plot the Contour

```
[73]: search_space_w2=np.linspace(-10,10,100)
search_space_w1=np.linspace(-10,10,100)

Search_space_W2,Search_space_W1=np.meshgrid(search_space_w2,search_space_w1)

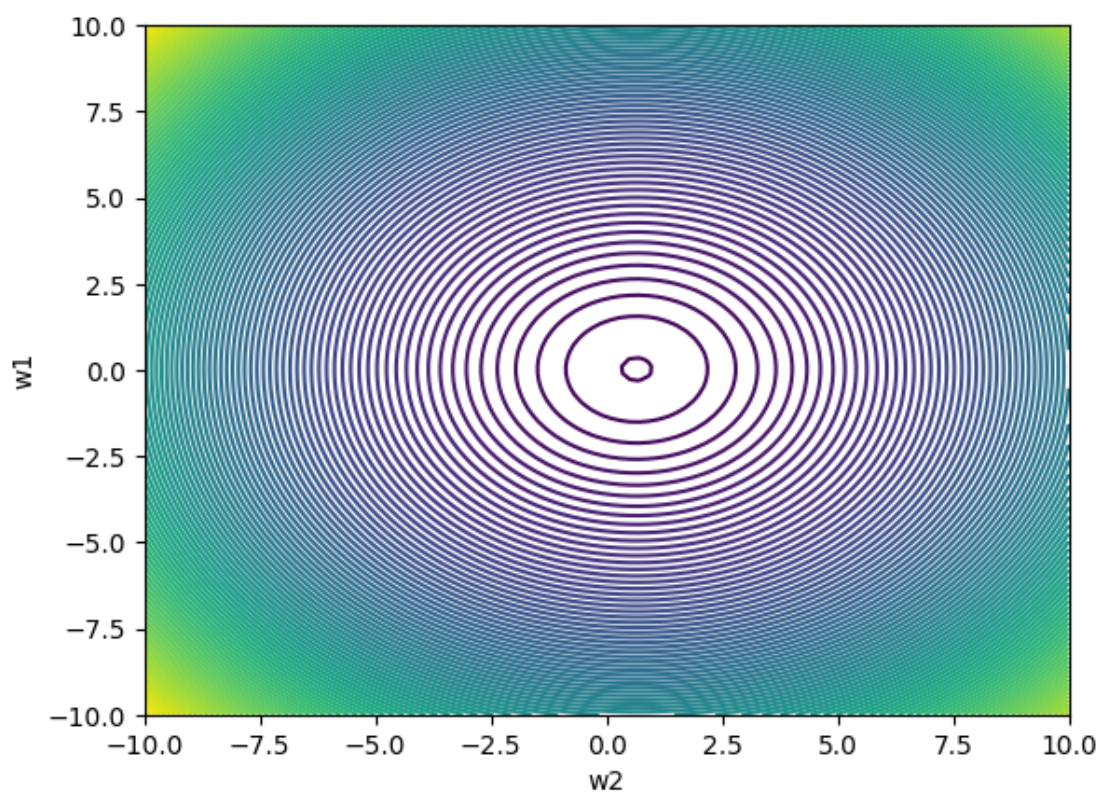
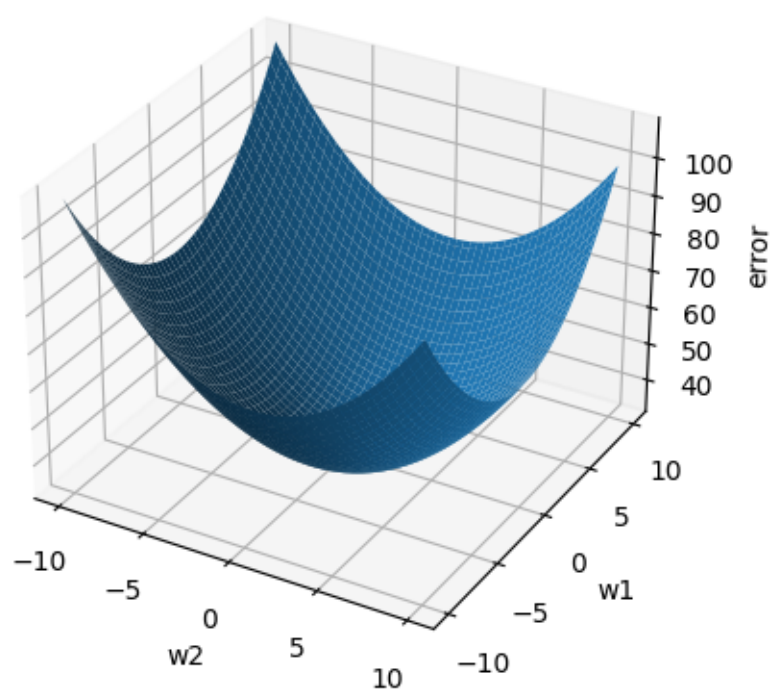
def error(w2,w1,w0,x1,x2,y):
    err=np.zeros(w1.shape)
    for x1_i,x2_i,y_i in zip(x1,x2,y):
        err1=np.power((np.tile(y_i,w1.shape)-(w0+w1*x1_i+w2*x2_i)),2)
        err=err+err1
    return err/x1.shape[0]

err=error(Search_space_W2,Search_space_W1, W0,x1,x2,Y_corrupted)

plt.figure()
ax = plt.axes(projection='3d')
ax.plot_surface(Search_space_W2,Search_space_W1,err)
ax.set_xlabel('w2')
ax.set_ylabel('w1')
ax.set_zlabel('error');

plt.figure()
plt.contour(Search_space_W2, Search_space_W1, err,100)
plt.xlabel('w2')
plt.ylabel('w1')
```

```
[73]: Text(0, 0.5, 'w1')
```

Prediction using Gradient Descent

```
[97]: w2_grad = 6
w1_grad = 6
lr = 0.1
precision = 1e-10

def make_gradient_step(X1, X2, Y, W1, W2, W0, lr ):
    W2_new = W2 - lr * np.average((W2*X2+W1*X1+W0 - Y) * X2)
    W1_new = W1 - lr * np.average((W2*X2+W1*X1+W0 - Y) * X1)
    return W2_new, W1_new

def error(w2,w1,w0,x1,x2,y):
    return np.mean(np.power(y-(w2*x2+w1*x1+w0),2))

plt.figure()
plt.contour(Search_space_W2, Search_space_W1, err,100)

for i in range(10000):
    w2_old = w2_grad
    w1_old = w1_grad
    w2_grad, w1_grad = make_gradient_step(X1,X2,Y, w1_old, w2_old, W0, lr)

    plt.plot([w2_old,w2_grad],[w1_old,w1_grad],color='r')

    if np.abs(error(w2_grad,w1_grad,W0,x1,x2,y_cor) -
    ↪error(w2_old,w1_old,W0,x1,x2,y_cor)) < precision:
        break

print(w2_grad, w1_grad)
plt.plot(w2_grad,w1_grad,'x',color='g')

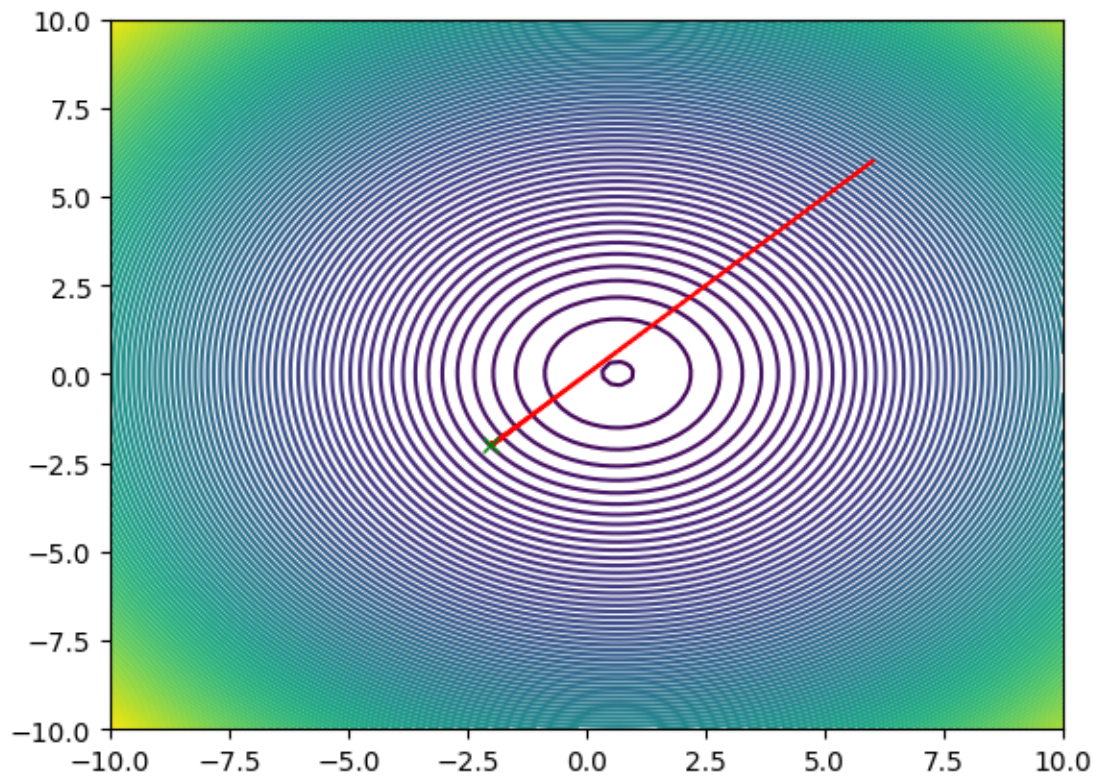
plt.figure()
ax = plt.axes(projection='3d')
ax.scatter3D(x1, x2, y_cor, '.')
ax.set_xlabel('x1')
ax.set_ylabel('x2')
ax.set_zlabel('y');

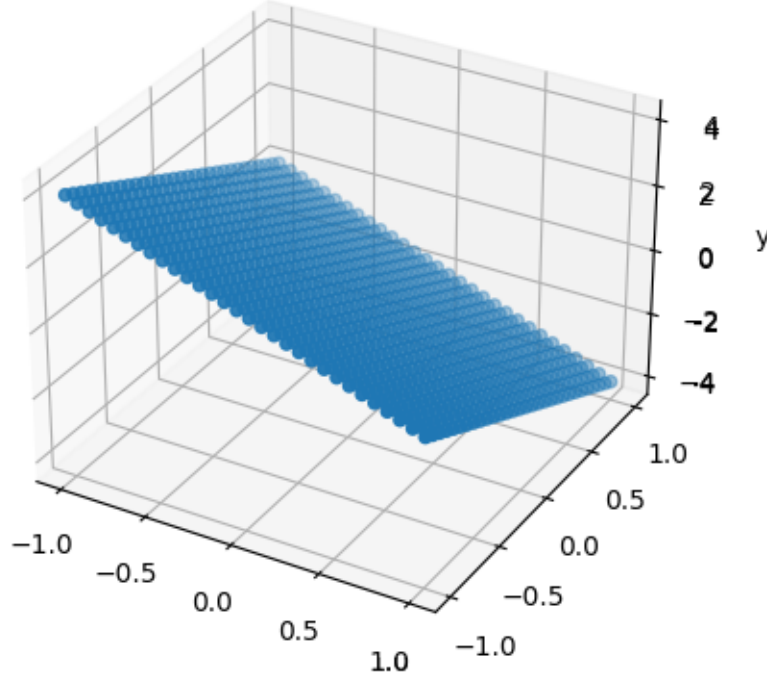
y_bestpred=W0+w1_grad*x1+w2_grad*x2
```

```
ax = plt.axes(projection='3d')
ax.scatter3D(x1, x2, y_bestpred, '.')
```

-1.999964875449235 -1.999964875449235

[97]: <mpl_toolkits.mplot3d.art3d.Path3DCollection at 0x7f6beec93340>





#Fitting of M-dimensional hyperplane (M-dimension, both in matrix inversion and gradient descent)

Here we will vectorize the input and will use matrix method to solve the regression problem.

let we have M- dimensional hyperplane we have to fit using regression, the inputs are $x_1, x_2, x_3, \dots, x_M$. in vector form we can write $[x_1, x_2, \dots, x_M]^T$, and similarly the weights are w_1, w_2, \dots, w_M can be written as a vector $[w_1, w_2, \dots, w_M]^T$, Then the equation of the plane can be written as:

$$y = w_1x_1 + w_2x_2 + \dots + w_Mx_M$$

w_1, w_2, \dots, w_M are the scaling parameters in M different direction, and we also need a offset parameter w_0 , to capture the offset variation while fitting.

The final input vector (generally known as augmented feature vector) is represented as $[1, x_1, x_2, \dots, x_M]^T$ and the weight matrix is $[w_0, w_1, w_2, \dots, w_M]^T$, now the equation of the plane can be written as:

$$y = w_0 + w_1x_1 + w_2x_2 + \dots + w_Mx_M$$

In matrix notation: $y = x^T w$ (for a single data point), but in general we are dealing with N- data points, so in matrix notation

$$Y = X^T W$$

where Y is a $N \times 1$ vector, X is a $M \times N$ matrix and W is a $M \times 1$ vector.

$$Error = \frac{1}{N} ||Y - X^T W||^2$$

it looks like a optimization problem, where we have to find W, which will give minimum error.

1. By computation:

$\nabla Error = 0$ will give us W_{opt} , then W_{opt} can be written as:

$$W_{opt} = (XX^T)^{-1}XY$$

2. By gradient descent:

$$W_{new} = W_{old} + \frac{2\lambda}{N} X(Y - X^T W_{old})$$

1. Create a class named Regression

2. Inside the class, include constructor, and the following functions:

- grad_update: Takes input as previous weight, learning rate, x, y and returns the updated weight.
- error: Takes input as weight, learning rate, x, y and returns the mean squared error.
- mat_inv: This returns the pseudo inverse of train data which is multiplied by labels.
- Regression_grad_des: Here, inside the for loop, write a code to update the weights. Also calculate error after each update of weights and store them in a list. Next, calculate the deviation in error with new_weights and old_weights and break the loop, if it's below a threshold value mentioned the code.

```
[98]: import numpy as np
import matplotlib.pyplot as plt

class regression:

    def __init__(self, name='reg'):
        self.name = name

    def grad_update(self, w_old, lr, y, x):
        w = w_old - (1/x.shape[1]) * lr * (x @ ((x.T @ w_old) - y))
        return w

    def error(self, w, y, x):
        return np.mean(np.power((y - x.T @ w), 2))

    def mat_inv(self, y, x_aug):
        return np.linalg.pinv((x_aug @ x_aug.T)) @ x_aug @ y

    def Regression_grad_des(self, x, y, lr):
```



```

err=[]
w_init=np.random.uniform(-1,1,(x_aug.shape[0],1))
w_old=w_init
w_pred=self.grad_update(w_old,lr,y,x_aug)
for i in range(1000):
    w_old=w_pred
    w_pred=self.grad_update(w_old,lr,y,x_aug)

    err.append(self.error(w_pred,y,x_aug))
    dev=np.abs(self.error(w_pred,y,x_aug)-self.error(w_old,y,x_aug))

    if dev<=1e-4:
        break

return w_pred,err

sim_dim=5
sim_no_data=1000
x=np.random.uniform(-1,1,(sim_dim,sim_no_data))
print(x.shape)

w=np.array([[1],[2],[3],[4],[5],[6]])
print(w.shape)

x_aug=np.concatenate((np.ones((1,x.shape[1])), x),axis=0)
print(x_aug.shape)

y=x_aug.T @ w
print(y.shape)

noise=np.random.uniform(0,1,y.shape)
y=y+0.1*noise

reg=regression()
w_opt=reg.mat_inv(y,x_aug)
print(w_opt)

lr=0.01
w_pred,err=reg.Regression_grad_des(x_aug,y,lr)

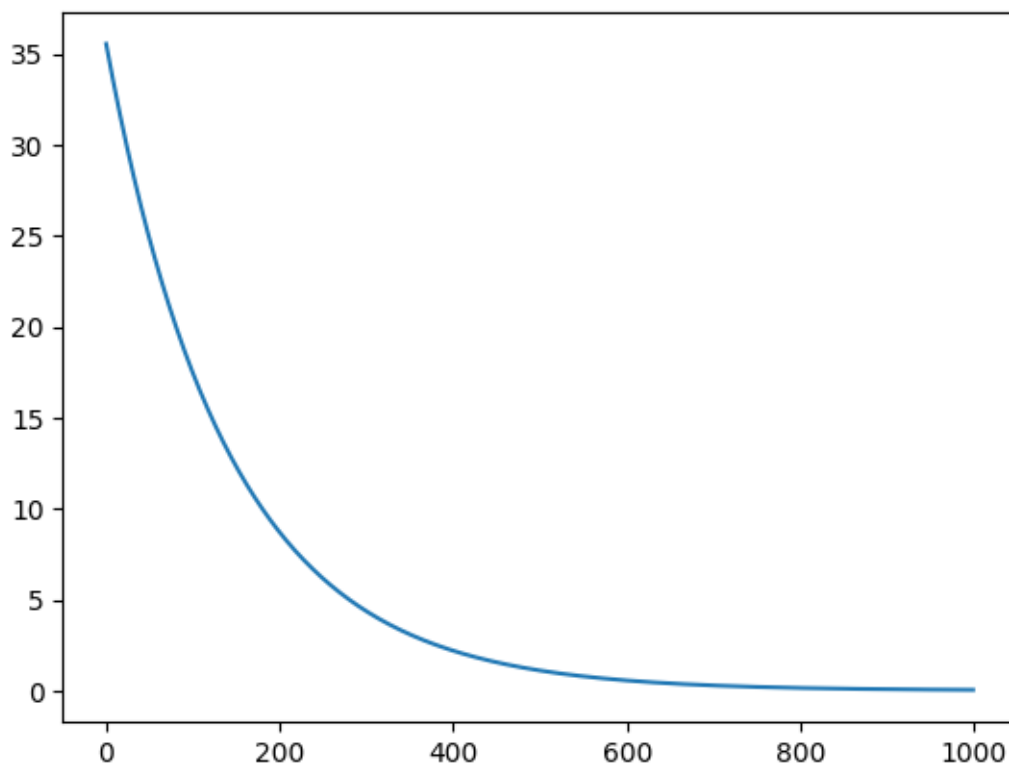
```

```
print(w_pred)
```

```
plt.plot(err)
```

```
(5, 1000)  
(6, 1)  
(6, 1000)  
(1000, 1)  
[[1.05050297]  
 [1.99847755]  
 [3.00224774]  
 [3.9979014 ]  
 [5.00131085]  
 [6.00061041]]  
[[1.05597673]  
 [1.93466829]  
 [2.8884211 ]  
 [3.89944939]  
 [4.78960713]  
 [5.81545119]]
```

```
[98]: [<matplotlib.lines.Line2D at 0x7f6bf9cdc820>]
```



#Practical Example (Salary Prediction)

1. Read data from csv file
2. Do train test split (90% and 10%)
3. Compute optimal weight values and predict the salary using the regression class created above (Use both the methods)
4. Find the mean square error in test.
5. Also find the optimal weight values using regression class from the Sci-kit learn library

```
[112]: import csv
f = open('/home/abhishekj/labs/EE_413_LAB/Lab_5/salary_pred_data.csv')

data_frm_csv = csv.reader(f)

All_rows = []

for row in data_frm_csv:
    All_rows.append(row)

Rows = All_rows[1:]

print(Rows[0])

X = np.zeros((len(Rows), len(Rows[0])))

for i in range(len(X)):
    X[i,:] = Rows[i]

X = X.T

train_data=X[:,0:900]
test_data=X[:,900:]

x_train=train_data[0:5,:]
y_train=train_data[5,:]
y_train=y_train.T
y_train=y_train[:,np.newaxis]

x_test=test_data[0:5,:]
y_test=test_data[5,:]
y_test=y_test.T
y_test=y_test[:,np.newaxis]

x_train=np.concatenate((np.ones((1,x_train.shape[1])), x_train),axis=0)

reg=regression()

w_pred=reg.mat_inv(y_train,x_train)
```



```

error=reg.error(w_pred,y_train,x_train)/((np.max(y_train)-np.mean(y_train))**2)

print(f'Normalized training error= {error}')

XX = np.concatenate((np.ones((1,x_test.shape[1])), x_test),axis=0)

y_pred = XX.T @ w_pred

error=reg.error(w_pred,y_test,XX)/((np.max(y_test)-np.mean(y_test))**2)

print(f'Error is {error}')
print(f'Pred Salary is {y_pred[0:5]}')
print(f'actual salary is {y_test[0:5]}')

```

```

['2', '11', '34', '4', '3', '41368']
Normalized training error= 1.127485750874925e-26
Error is 1.8666508234569391e-26
Pred Salary is [[33184.]
 [52740.]
 [58152.]
 [44292.]
 [50184.]]
actual salary is [[33184.]
 [52740.]
 [58152.]
 [44292.]
 [50184.]]

```

```

[113]: import numpy as np
from sklearn.linear_model import LinearRegression
print(x_train)
print(y_train.shape)

```

```

[[ 1.  1.  1. ...  1.  1.  1.]
 [ 2.  4.  1. ...  2.  2.  3.]
 [11. 14. 13. ...  3.  3.  9.]
 [34. 28. 55. ... 56. 57. 59.]
 [ 4.  1.  3. ...  2.  2.  1.]
 [ 3.  4.  2. ...  2.  6.  3.]]
(900, 1)

```

```

[115]: scikit_regression = LinearRegression()

scikit_regression.fit(x_train.T, y_train)

W = scikit_regression.coef_
print(W)

```

```
y_pred = scikit_regression.predict((np.concatenate((np.ones((1,x_test.  
↪shape[1])), x_test),axis=0)).T)  
  
plt.plot(y_test)  
plt.plot(y_pred, 'r')
```

```
[[0.e+00 2.e+03 1.e+02 2.e+00 3.e+02 5.e+03]]
```

```
[115]: [<matplotlib.lines.Line2D at 0x7f6bf28d46d0>]
```

