# Linguaggio L

# Sintassi (BNF)

```
(by value)
C ::= nil | Id = E | C;C | if (E) {C} /else {C}/ | while (E) {C} | D;C | return E
E ::= v | Id | uop E | E bop E | (E) | Id(ae)
D ::= nil | const | Id[:T] = E | var | Id[:T] = E | D;D | function | Id(form) -> T | C; return | E} | form = ae | rec | D
form ::= nil | const ld: T, form | var ld: T, form
ae ::= nil | E, ae
                                                                                             Metavariabili
uop ::= + | - | !
                                                                                             C,C',C'',C_0,C_1,\dots
bop ::= + | - | * | \ | % | == | != | > | >= | < | <= | && | ||
                                                                                             E, E', E'', E_0, E_1, \dots
Id ::= insieme degli identificatori validi
                                                                                             D, D', D'', D_0, D_1, \dots
Val_E ::= \mathbb{Z} \cup \mathbb{R} \cup \{\text{true, false}\} \cup \{s \mid s \in ASCII^*\}
                                                                                             Id, Id', Id_1, x, x', x_1, \dots
T ::= Int | Double | Bool | String
                                                                                             v, v', v'', v_0, v_1, \dots
                           n, n', n_1, \dots
        Int
                          d, d', d_1', \dots

b, b', b_1, \dots \in \{true, false\}
        Double
                                                                                             \tau, \tau', \tau'', \tau_0, \tau_1, \dots
        Bool
        String
                          s, s', s_1, \dots
(by reference)
form ::= nil | const ld: T, form | var ld: T, form | ref ld: T, form
ae ::= nil | E, ae | I, ae
Altri comandi:
 C ::= do {C} while (E) | for (D; E; C) {C} | switch (E) {
                                                                 case v1: C; break
                                                                 case v2: C; break
                                                                 [default: C; break]
                                                           }
```

C simbolo distinto della grammatica, quindi un programma è un comando



# Semantica Statica

comando ben formato  ${\bf C}$ :  $\Delta \vdash_c C$  espressione ben formata  ${\bf E}$ :  $\Delta \vdash_e E : \tau$  dichiarazione ben formata  ${\bf D}$ :  $\Delta \vdash_d D : \Delta'$ 

ambiente statico  $\Delta$ : Id  $\cup$  Val  $\longrightarrow$   $T \cup T$ Loc

# Semantica Statica Espressioni

**Assiomi**:  $(A1) \varnothing \vdash_e i : Int, (A2) \varnothing \vdash_e d : Double, (A3) \varnothing \vdash_e b : Bool, (A4) \varnothing \vdash_e s : String$ 

Regole di inferenza:

$$(R1) \ \frac{(\Delta(Id) = \tau \lor \Delta(Id) = \tau \bot \bigcirc \bigcirc)}{\Delta \vdash_e Id : \tau}, \ \ (R2) \ \frac{\Delta \vdash_e E_1 : \tau_1, uop : \tau_1 \to \tau}{\Delta \vdash_e uop \, E_1 : \tau}, \ \ (R3) \ \frac{\Delta \vdash_e E_1 : \tau_1, \Delta \vdash_e E_2 : \tau_2, bop : \tau_1 \times \tau_2 \to \tau}{\Delta \vdash_e E_1 bop \, E_2 : \tau}$$

$$(R4) \frac{\Delta \vdash_{e} E : \tau}{\Delta \vdash_{e} (E) : \tau}$$

#### Semantica Statica Comandi

Assiomi:  $(A5) \varnothing \vdash_{c} nil$ 

Regole di inferenza:

$$(R5) \frac{\Delta(Id) = \tau \bot \circ \circ, \Delta \vdash_{e} E : \tau}{\Delta \vdash_{c} Id = E}, \quad (R6) \frac{\Delta \vdash_{c} C_{1}, \Delta \vdash_{c} C_{2}}{\Delta \vdash_{c} C_{1}; C_{2}}, \quad (R7) \frac{\Delta \vdash_{e} E : \mathsf{Bool}, \Delta \vdash_{c} C_{1}, \Delta \vdash_{c} C_{2}}{\Delta \vdash_{c} \mathsf{if} (E)\{C_{1}\} \mathsf{ else } \{C_{2}\}}$$

$$(R8) \ \frac{\Delta \vdash_{e} E : \mathsf{Bool}, \Delta \vdash_{c} C}{\Delta \vdash_{c} \mathsf{while} \ (E) \ \{C\}}, \ \ (R9) \ \frac{\Delta \vdash_{d} D : \Delta', \Delta[\Delta'] \vdash_{c} C}{\Delta \vdash_{c} D; C}$$

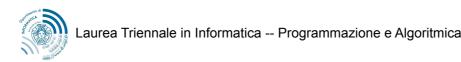
$$\Delta[\Delta'](x) = \begin{cases} \Delta'(x), & \text{se } \Delta'(x) \text{ definito} \\ \Delta(x), & \text{altrimenti} \end{cases}$$

### Semantica Statica Dichiarazioni

**Assiomi**:  $(A6) \varnothing \vdash_d nil : \varnothing$ 

Regole di inferenza:

$$(R10) \ \frac{\Delta \vdash_e E : \tau, T = = \tau}{\Delta \vdash_a \text{const} Id : T = E : [(Id, \tau)]}, \quad (R11) \ \frac{\Delta \vdash_e E : \tau, T = = \tau}{\Delta \vdash_d \text{var} Id : T = E : [(Id, \tau Loc)]}, \quad (R12) \ \frac{\Delta \vdash_d D_1 : \Delta_1, \Delta[\Delta_1] \vdash_d D_2 : \Delta_2}{\Delta \vdash_d D_1; D_2 : \Delta_1[\Delta_2]}$$



### Semantica Statica Funzioni

$$(FS1) \frac{\Delta \vdash_E E : \tau}{\Delta \vdash_C \mathsf{return} E} \begin{cases} \mathscr{T}(\mathit{nil}) = \mathit{nil} \\ \mathscr{T}(\mathsf{const} \; \mathsf{Id} : \tau, \mathsf{form}) = \tau, \mathscr{T}(\mathsf{form}) \\ \mathscr{T}(\mathsf{var} \; \mathsf{Id} : \tau, \mathsf{form}) = \tau, \mathscr{T}(\mathsf{form}) \end{cases}$$

$$(FS2) \frac{\text{form}: \Delta_0, \Delta[\Delta_0] \vdash_C \text{var } res: \tau = E; C; \text{return } res, \Delta[\Delta_0][(res, \tau Loc)] \vdash_E E: \tau}{\Delta \vdash_D \text{function Id(form)} \rightarrow \tau \text{ {var } res: } \tau = E; C; \text{return } res \} : [(\text{Id}, \mathcal{T}(\text{form}) \rightarrow \tau)]$$

$$(FS3) \quad nil:\varnothing, \quad \frac{\mathsf{form}:\Delta_0,\mathsf{Id}\not\in\Delta_0}{\mathsf{const}\;\mathsf{Id}:\tau,\mathsf{form}:\Delta_0[(\mathsf{Id},\tau)]} \quad \frac{\mathsf{form}:\Delta_0,\mathsf{Id}\not\in\Delta_0}{\mathsf{var}\;\mathsf{Id}:\tau,\mathsf{form}:\Delta_0[(\mathsf{Id},\tau loc)]}$$

$$(FS4) \frac{\Delta \vdash_{ae} ae : aet, \Delta(\mathsf{Id}) = aet \to \tau}{\Delta \vdash_{E} \mathsf{Id}(ae) : \tau} \begin{cases} \Delta \vdash_{ae} nil \\ \frac{\Delta \vdash_{E} E:\tau, \Delta \vdash_{ae} ae:aet}{\Delta \vdash_{ae} E, ae:\tau, aet} \end{cases}$$

## Semantica Statica (dichiarazione) Funzioni Ricorsive

#### Creazione ambiente:

$$(FS2') \vdash_D \text{function Id(form)} \rightarrow \tau \text{ {var } res : } \tau = E; C; \text{ return } res \} : [(Id, \mathcal{T}(\text{form}) \rightarrow \tau)]$$

#### Validazione ambiente:

$$(FS2'') \frac{\mathsf{form} : \Delta_0, \Delta[\Delta_0] \vdash_C \mathsf{var} \ res : \tau = E; C; \mathsf{return} \ res, \Delta[\Delta_0][(res, \tau)] \vdash_E E : \tau}{\Delta \vdash_D \mathsf{function} \, \mathsf{Id}(\mathsf{form}) \ \rightarrow \tau \ \{\mathsf{var} \ res : \tau = E; C; \mathsf{return} \ res \}}$$

$$(RS1') \frac{\vdash_D D : \Delta}{\vdash_D rec D : \Delta}$$

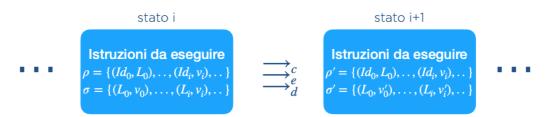
$$(RS1'') \frac{\vdash_D D : \Delta', \Delta[\Delta'_{|I_0}] \vdash_D D}{\Delta \vdash_D rec D}, I_0 = FI(D) \cap BI(D)$$

# Semantica Dinamica

```
esecuzione C: \langle C, \rho, \sigma \rangle \longrightarrow_c \langle C', \rho', \sigma' \rangle, \operatorname{Exec}(C, \rho, \sigma) = \sigma' \iff \langle C, \rho, \sigma \rangle \longrightarrow_c^* \sigma' valutazione E: \langle E, \rho, \sigma \rangle \longrightarrow_e \langle E', \rho, \sigma \rangle, \operatorname{Eval}(E, \rho, \sigma) = v \in \operatorname{Val} \iff \langle E, \rho, \sigma \rangle \longrightarrow_e^* v elaborazione D: \langle D, \rho, \sigma \rangle \longrightarrow_d \langle D', \rho', \sigma' \rangle, \operatorname{Elab}(D, \rho, \sigma) = \langle \rho', \sigma' \rangle \iff \langle D, \rho, \sigma \rangle \longrightarrow_d^* \langle \rho', \sigma' \rangle ambiente (dinamico) \rho: Id \longrightarrow Loc U Val memoria \sigma: Loc \longrightarrow Val
```

 $\longrightarrow_c$  ,  $\longrightarrow_e$  ,  $\longrightarrow_d$  sono le funzioni di interpretazione semantica di C, E e D

#### SISTEMA DI TRANSIZIONI



stato finale

nil  $\rho = \{ (Id_0, L_0), \dots, (Id_i, v_i), \dots \}$   $\sigma = \{ (L_0, v_0), \dots, (L_i, v_i), \dots \}$ 

# Semantica Dinamica Espressioni

$$(Id1) \frac{\rho(Id) = v \lor (\rho(Id) = L \in Loc \land \sigma(L) = v)}{\langle Id, \rho, \sigma \rangle \longrightarrow_{\sigma} v}$$

$$(uop1) \ \frac{\langle E,\rho,\sigma\rangle \longrightarrow_e \langle E',\rho,\sigma\rangle}{\langle uop\,E,\rho,\sigma\rangle \longrightarrow_e \langle uop\,E',\rho,\sigma\rangle} \qquad \qquad (uop2) \ \langle uop\,v,\rho,\sigma\rangle \longrightarrow_e v' = \mathsf{uop}\,v$$

$$(bop1)\frac{\langle E_1,\rho,\sigma\rangle \longrightarrow_e \langle E_1',\rho,\sigma\rangle}{\langle E_1 \,bop \, E_2,\rho,\sigma\rangle \longrightarrow_e \langle E_1' \,bop \, E_2,\rho,\sigma\rangle} \quad (bop2)\frac{\langle E_2,\rho,\sigma\rangle \longrightarrow_e \langle E_2',\rho,\sigma\rangle}{\langle v_1 \,bop \, E_2,\rho,\sigma\rangle \longrightarrow_e \langle v_1 \,bop \, E_2',\rho,\sigma\rangle}$$

(bop3) 
$$\langle v_1bop\ v_2, \rho, \sigma \rangle \longrightarrow_e v = v_1 \text{ bop } v_2$$
 bop è sintassi bop è semantica

#### Semantica Dinamica Comandi

$$(id2) \frac{\langle E, \rho, \sigma \rangle \longrightarrow_e^* v}{\langle Id = E, \rho, \sigma \rangle \longrightarrow_c \langle Id = v, \rho, \sigma \rangle}$$
 
$$(id3) \langle Id = v, \rho, \sigma \rangle \longrightarrow_c \sigma[\rho(Id) = v]$$

$$(seq1) \frac{\langle C_1, \rho, \sigma \rangle \longrightarrow_c \langle C_1', \rho, \sigma' \rangle}{\langle C_1; C_2, \rho, \sigma \rangle \longrightarrow_c \langle C_1'; C_2, \rho, \sigma' \rangle} \qquad (seq2) \frac{\langle C_1, \rho, \sigma \rangle \longrightarrow_c \sigma'}{\langle C_1; C_2, \rho, \sigma \rangle \longrightarrow_c \langle C_2, \rho, \sigma' \rangle}$$

$$(if1) \frac{\langle E, \rho, \sigma \rangle \longrightarrow_e^* true}{\langle \mathbf{if}(E) \{ C_1 \} \, \mathbf{else} \, \{ C_2 \}, \rho, \sigma \rangle \longrightarrow_c \langle C_1, \rho, \sigma \rangle} \qquad (if2) \frac{\langle E, \rho, \sigma \rangle \longrightarrow_e^* false}{\langle \mathbf{if}(E) \{ C_1 \} \, \mathbf{else} \, \{ C_2 \}, \rho, \sigma \rangle \longrightarrow_c \langle C_2, \rho, \sigma \rangle}$$

$$(rep1) \frac{\langle E, \rho, \sigma \rangle \longrightarrow_e^* true}{\langle \mathsf{while}(E) \{C\}, \rho, \sigma \rangle \longrightarrow_e \langle C; \mathsf{while}(E) \{C\}, \rho, \sigma \rangle} \qquad (rep2) \frac{\langle E, \rho, \sigma \rangle \longrightarrow_e^* false}{\langle \mathsf{while}(E) \{C\}, \rho, \sigma \rangle \longrightarrow_e \sigma}$$

$$(b1) \frac{\langle D, \rho, \sigma \rangle \longrightarrow_d^* \langle \rho', \sigma' \rangle}{\langle D; C, \rho, \sigma \rangle \longrightarrow_c \langle C, \rho[\rho'], \sigma[\sigma'] \rangle}$$

#### Semantica Dinamica Dichiarazioni

$$(const1) \frac{\langle E, \rho, \sigma \rangle \longrightarrow_e^* v}{\langle const Id : T = E, \rho, \sigma \rangle \longrightarrow_d \langle [(Id, v)], \sigma \rangle}$$

$$(var1) \frac{\langle E, \rho, \sigma \rangle \longrightarrow_{e}^{*} v}{\langle var \ Id : T = E, \rho, \sigma \rangle \longrightarrow_{d} \langle [(Id, new \ L)], [(L, v)] \rangle}$$

$$(dd1) \frac{\langle D_1, \rho, \sigma \rangle \longrightarrow_d \langle D_1', \rho', \sigma' \rangle}{\langle D_1; D_2, \rho, \sigma \rangle \longrightarrow_d \langle D_1'; D_2, \rho', \sigma' \rangle} \qquad (dd2) \frac{\langle D_2, \rho[\rho_1], \sigma \rangle \longrightarrow_d \langle D_2', \rho[\rho_1]', \sigma' \rangle}{\langle \rho_1; D_2, \rho[\rho_1], \sigma \rangle \longrightarrow_d \langle \rho_1; D_2', \rho[\rho_1]', \sigma' \rangle}$$

$$(dd3) \langle \rho_1; \rho 2, \rho, \sigma \rangle \longrightarrow_d \langle \rho_1[\rho_2], \sigma \rangle$$



le regole (dd2) e (dd3) contengono configurazioni non ammissibili rispetto alla definizione di sistema di transizione

$$(dd2) \langle \rho_1; D_2, \rho, \sigma \rangle, \langle \rho_1; D_2', \rho, \sigma' \rangle \quad (dd3) \langle \rho_1; \rho_2, \rho, \sigma \rangle$$

la parte codice delle configurazioni di stato deve essere generabile dalla grammatiche che definisce D, e questo non vale per le configurazioni sopra

# aggiungo gli ambienti alla sintassi

D ::= nil  $|\cos D[T] = E | var |D[T] = E | D;D|_{Q}$  solo il compilatore può generare gli ambienti della sintassi, non l'utente

Il sistema di transizione delle dichiarazioni è

 $(\{\langle D, \rho, \sigma \rangle \cup \langle \rho', sigma' \rangle\}, \longrightarrow_d, \{\langle \rho', sigma' \rangle\}, \langle dichiarazione da elaborare, ambiente iniziale, memoria iniziale \rangle)$ 

### Semantica Dinamica Funzioni (scoping statico e dinamico)

$$(FD1)\langle \operatorname{tunction} | \operatorname{d}(\operatorname{form}) \to T\{C; \operatorname{return} E\}, \rho, \sigma \rangle \to_{d} \langle (\operatorname{Id}, \lambda \operatorname{form} . \{\rho'; C; \operatorname{return} E\}), \sigma \rangle$$

$$\begin{cases} \rho' = \rho_{|FI(C) - BI(form)} & \operatorname{scoping statico} \\ \rho' = \operatorname{nil} & \operatorname{scoping dinamico} \end{cases}$$

$$(FD2) \frac{\rho(\operatorname{Id}) = \lambda \operatorname{form} . C}{\langle \operatorname{Id}(\operatorname{ae}), \rho, \sigma \rangle \to_{e} \langle \{\operatorname{form} = \operatorname{ae}; C\}, \rho, \sigma \rangle}$$

$$(FD3) \frac{\langle E, \rho, \sigma \rangle \to_{e} \langle E', \rho, \sigma \rangle}{\langle E, \operatorname{ae}, \rho, \sigma \rangle \to_{ae} \langle E', \operatorname{ae}, \rho, \sigma \rangle}$$

$$(FD5) \frac{\langle \operatorname{ae}, \rho, \sigma \rangle \to_{ae} \langle \operatorname{ae}', \rho, \sigma \rangle}{\langle \operatorname{form} = \operatorname{ae}, \rho, \sigma \rangle \to_{ae} \langle \operatorname{ae}', \rho, \sigma \rangle}$$

$$(FD5) \frac{\langle \operatorname{ae}, \rho, \sigma \rangle \to_{ae} \langle \operatorname{ae}', \rho, \sigma \rangle}{\langle \operatorname{form} = \operatorname{ae}, \rho, \sigma \rangle \to_{d} \langle \operatorname{form} = \operatorname{ae}', \rho, \sigma \rangle}$$

$$(FD6) \frac{\operatorname{av} \vdash \operatorname{form} : \rho_0, \sigma_0}{\langle \operatorname{form} = \operatorname{av}, \rho, \sigma \rangle \to_{d} \langle \operatorname{form} = \operatorname{av}, \rho, \sigma \rangle}$$

$$\operatorname{av} \vdash \operatorname{form} : \rho, \sigma$$

$$\operatorname{v} \vdash \operatorname{var} \operatorname{Id} : \tau, \operatorname{form} : \rho[(\operatorname{Id}, l_{(\operatorname{new})})], \sigma[(l_{(\operatorname{new})}, v)]}$$

## Semantica Dinamica (dichiarazione) Funzioni Ricorsive

Dichiarazione di funzione come se non fosse ricorsiva (effetto: ci sono identificatori liberi nel corpo - in sostanza il nome della funzione):

$$(RD1)\frac{\langle D, \rho - I_0, \sigma \rangle \rightarrow_d \langle D', \rho', \sigma' \rangle}{\langle rec \ D, \rho, \sigma \rangle \rightarrow_d \langle rec \ D', \rho', \sigma' \rangle}, I_0 = FI(D) \cap BI(D)$$

Quando finiamo con la applicazione della RD1, possiamo applicare la RD2:

$$(RD2)\ \langle rec\ \rho_0, \rho, \sigma \rangle \to \langle \{(f, \lambda form\ .\ (rec\ \rho_0) - form; C)\ |\ \rho_0(f) = \lambda form\ .\ C\}, \sigma \rangle$$

# Identificatori Liberi

```
FI_d: D \rightarrow \{\text{occorrenze } Id \text{ liberi}\}
FI_e: E \rightarrow \{\text{occorrenze } Id \text{ liberi}\}
                                                                     FI_c: C \rightarrow \{\text{occorrenze } Id \text{ liberi}\}
FI_{\rho}(\vee) = \emptyset
                                                                     FI_c(\text{nil}) = \emptyset
FI_{\varrho}(\mathrm{Id}) = \{\mathrm{Id}\}
                                                                     FI_c(\text{Id} = \text{E}) = \{\text{Id}\} \cup FI_e(\text{E})
FI_e(uop E) = FI_e(E)
                                                                    FI_c(\text{C1;C2}) = FI_c(\text{C1}) \cup FI_c(\text{C2})
                                                                     FI_c(if (E) {C1} else {C2}) =
FI_e(E1 bop E2) = FI_e(E1) \cup FI_e(E2)
                                                                                    FI_e(E) \cup FI_c(C1) \cup FI_c(C2)
                                                                     FI_c(while (E) {C}) = FI_e(E) \cup FI_c(C)
```

$$\begin{split} &FI_d(\mathsf{nil}) = \varnothing \\ &FI_d(\mathsf{const}\ \mathsf{Id} \colon \mathsf{T} = \mathsf{E}) = FI_e(\mathsf{E}) \\ &FI_d(\mathsf{var}\ \mathsf{Id} \colon \mathsf{T} = \mathsf{E}) = FI_e(\mathsf{E}) \\ &FI_d(\mathsf{D1}; \mathsf{D2}) = FI_d(\mathsf{D1}) \cup (FI_d(\mathsf{D2}) \cdot BI_d(\mathsf{D1})) \end{split}$$

$$BI_c = \overline{FI}_c$$
  
 $BI_e = \overline{FI}_e$   
 $BI_d = \overline{FI}_d$ 

 $FI_c(\mathsf{D};\mathsf{C}) = FI_d(\mathsf{D}) \cup (FI_c(\mathsf{C}) - BI_d(\mathsf{D}))$ 

### Identificatori Liberi Funzioni

```
FI_{c}(\text{return E}) = FI_{c}(E)
FI_{a}(Id(ae)) = \{Id\} \cup FI_{ae}(ae)
FI_{cl}(function Id(form))-> T{C} = FI_{cl}(C) - BI_{form}(form)
FI_{form}(form) = \emptyset
FI_{ae}(E,ae) = FI_{e}(E) \cup FI_{ae}(ae)
```

# Anatomia delle funzioni

