Perfect Hashing and Universal Hashing

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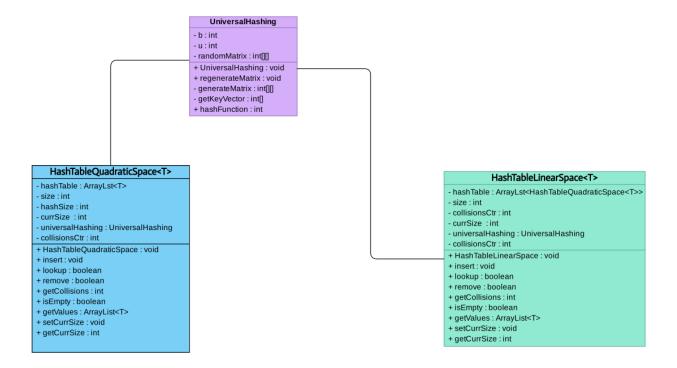
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Contents

UML Diagram	2
Universal Hashing	
Method	
Implementation	
Perfect Hashing	4
O(N²) Space Solution	4
Implementation	4
O(N) Space Solution	5
Space Complexity Analysis	

UML Diagram



Universal Hashing

A probability distribution H over hash functions from U to $\{1, ..., M\}$ is universal if for all x = y in U, we have

$$P r[h(x) = h(y)] \le 1/M \tag{1}$$

Theorem

If H is universal, then for any set $S \subset U$, for any $x \in U$ (that we might want to insert or lookup), for a random h taken from H, the expected number of collisions between x and other elements in S is at most N/M.

Method

- Matrix method is used to construct hash Functions.
- If The table size is M and is power of 2, so an index is b-bits long with M = 2^b
- h(x) = h * x (matrix multiplication with mod 2 addition)
- h will be a random matrix with values ranging from 0 to 1

$$\begin{array}{c|cccc}
h & x & h(x) \\
\hline
1 & 0 & 0 & 0 \\
0 & 1 & 1 & 1 \\
1 & 1 & 1 & 0
\end{array}$$

$$\begin{array}{c|cccc}
1 & 0 & 0 & 0 \\
0 & 1 & 1 & 1 \\
0 & 0 & 0
\end{array}$$

We can show that for x = y, Pr[h(x) = h(y)] = 1/M = 1/2^b

Implementation

- generateMatrix returns 2D int array after generating random entries.
- getKeyVector returns 1D Vector that is a binary representation of x.
- hashFunction returns a key using randomly generated h Matrix.

Perfect Hashing

A **perfect hash function** h for a set S is a hash function that maps distinct elements in S to a set of m integers, with no collisions. In mathematical terms, it is an injective function.

Disadvantages of perfect hash functions are that *S* needs to be known for the construction of the perfect hash function.

"abc" 1 2 2 3 3 4 4 1 5 6 6 6 1 7 7

Perfect Hash Function, H

O(N²) Space Solution

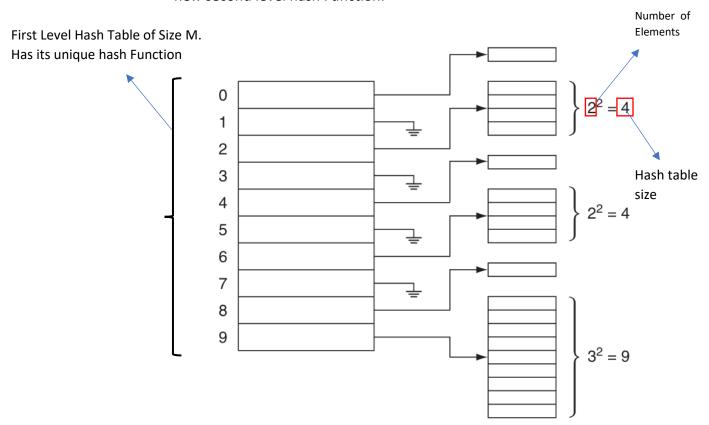
- If there are N elements to be inserted,
 A Hash table of size N² is made.
- Universal Hashing is used to generate a hash function.
- This hash function is used to hash every element.
- If a Collision occurs then we regenerate a Matrix to make a new Hash Function independent from the previous ones and rehash every element into table using the new hash function.
- A N² hash table is made to ensure that the probability that a Collision occurs is ½ and that total amount of Collisions is at most 2.
- Having a Table size of N² is impractical and a new solution is necessary.

Implementation

- Insert function that takes the element as a parameter and checks for an empty bin using a hash function.
- Lookup takes an element as a parameter returns
 Boolean Value True if the given element exists in the hash table, False otherwise.
- Remove takes an element as a parameter returns
 Boolean value Ture if the element exists in the hash
 table and is removed successfully, False otherwise.

O(N) Space Solution

- A cleverer approach to take is to make 2 level hash Table where every entry
 in the hash table is a hash table of Quadratic Space Solution in which its size
 grows as the number of Collisions on this entry grows.
- The First level Hash Table uses a hash function generated using Universal Hashing scheme.
- The First level tries to hash every element into empty bins.
- If a Collision is detected, then a new Hash Table inside the bin is constructed with a unique hash Function then it tries to hash every element hashed using the First level hash function into the bin (where collision occurred) using the new second level hash Function.



- The initial size of each entry is 1, if an entry has N elements in it then its size should be N² (from the O(N²) Solution).
- Each Entry is a Hash Table of Size Squared to number of elements inside it.
- Each Entry Hash Table has a unique hash function that is generated randomly using Universal Hashing Scheme and generated every time a Collision Occurs into this entry.

Implementation

- Insert function that takes the element as a parameter and checks for an empty bin using a hash function.
- Lookup takes an element as a parameter returns
 Boolean Value True if the given element exists in the hash table, False otherwise.
- Remove takes an element as a parameter returns Boolean value Ture if the element exists in the hash table and is removed successfully, False otherwise.

Space Complexity Analysis

N	O(N2) Size	O(N2) Collisions	O(N) Size	O(N) Collisions
10	100	0	23	3
15	225	0	33	5
20	400	0	50	7
25	625	0	60	8
30	900	1	65	10