

推导位势积分公式：利用第二类Green公式，取v=1/r

第二类Green公式

设Ω⊂R³是一有界区域，且∂Ω光滑。设u和v都在C²(Ω)∩C¹(Ω̄)中于是因为

$$u\Delta v=\sum_{j=1}^3\frac{\partial}{\partial x_j}\left(u\frac{\partial v}{\partial x_j}\right)-\sum_{j=1}^3\frac{\partial u}{\partial x_j}\frac{\partial v}{\partial x_j},$$
$$v\Delta u=\sum_{j=1}^3\frac{\partial}{\partial x_j}\left(v\frac{\partial u}{\partial x_j}\right)-\sum_{j=1}^3\frac{\partial v}{\partial x_j}\frac{\partial u}{\partial x_j},$$

二者相减有uΔv-vΔu=∑_{j=1}³ $\frac{\partial}{\partial x_j}$ ($u\frac{\partial v}{\partial x_j}$ - $v\frac{\partial u}{\partial x_j}$)。

两边在Ω上积分，利用数学分析中的高斯定理，即得以下重要的格林公式：

$$\iiint_{\Omega}(u\Delta v-v\Delta u)\mathrm{d}x=\iint_{\partial\Omega}\left[u\frac{\partial v}{\partial n}-v\frac{\partial u}{\partial n}\right]\mathrm{d}S,\text{ }n\text{是}\partial\Omega\text{的单位外法向量}。$$

令v= $\frac{1}{r}$ ，代入Green公式，设B_ε(Q)是以Q为圆心，ε为半径小球，Ω_ε=Ω\B_ε，P是动点，|PQ|=r

则v= $\frac{1}{r}\in C^2(\Omega_\epsilon)\cap C^1(\overline{\Omega}_\epsilon)$,在Ω_ε上使用Green公式，u仍为一般的C²(Ω_ε)∩C¹(Ω̄_ε)

$$\text{则}\iiint_{\Omega_\epsilon}\left[u\Delta\left(\frac{1}{r}\right)-\frac{1}{r}\Delta u\right]\mathrm{d}x=\iint_{\partial\Omega_\epsilon}\left[u\frac{\partial}{\partial n}\left(\frac{1}{r}\right)-\frac{1}{r}\frac{\partial u}{\partial n}\right]\mathrm{d}S$$

把这个空心小球的两部分拆开： $\iiint_{\Omega_\epsilon}\left[u\Delta\left(\frac{1}{r}\right)-\frac{1}{r}\Delta u\right]\mathrm{d}x=\iint_{\partial\Omega}\left[u\frac{\partial}{\partial n}\left(\frac{1}{r}\right)-\frac{1}{r}\frac{\partial u}{\partial n}\right]\mathrm{d}S-\iint_{\partial B_\epsilon(Q)}\left[u\frac{\partial}{\partial r}\left(\frac{1}{r}\right)-\frac{1}{r}\frac{\partial u}{\partial r}\right]\mathrm{d}S\quad(*)$

其中因为 $\frac{1}{r}$ 是基本解的主项，即Δc₃($\frac{1}{r}$)=δ,则在Ω_ε中有Δ($\frac{1}{r}$)=0⇒ $\iint_{\Omega_\epsilon}u\Delta\left(\frac{1}{r}\right)\mathrm{d}x=0$ ，则等式(*)左端=- $\iint_{\Omega_\epsilon}\frac{1}{r}\Delta u\mathrm{d}x$

下考虑 $\iint_{\partial B_\epsilon(Q)}\left[u\frac{\partial}{\partial r}\left(\frac{1}{r}\right)-\frac{1}{r}\frac{\partial u}{\partial r}\right]\mathrm{d}S:r=\epsilon$,则为 $-\frac{1}{\epsilon^2}\iint_{\partial B_\epsilon(Q)}u\mathrm{d}S-\frac{1}{\epsilon}\iint_{\partial B_\epsilon(Q)}\frac{\partial u}{\partial r}\mathrm{d}S$

由【积分中值定理】得， $\iint_{\partial B_\epsilon(Q)}u\mathrm{d}S=u(Q^*)4\pi\epsilon^2$ ， $\iint_{\partial B_\epsilon(Q)}\frac{\partial u}{\partial r}\mathrm{d}S=\frac{\partial u}{\partial r}(Q)4\pi\epsilon^2$,其中Q*,Q̄∈∂B_ε(Q)

$$\text{则}\lim_{\epsilon\rightarrow 0}\iint_{\partial B_\epsilon(Q)}\left[u\frac{\partial}{\partial r}\left(\frac{1}{r}\right)-\frac{1}{r}\frac{\partial u}{\partial r}\right]\mathrm{d}S=-4\pi u(Q),\text{此时原方程化为}-\iiint_{\Omega}\frac{1}{r}\Delta u\mathrm{d}x=\iint_{\partial\Omega}\left[u\frac{\partial}{\partial n}\left(\frac{1}{r}\right)-\frac{1}{r}\frac{\partial u}{\partial n}\right]\mathrm{d}S+4\pi u(Q)$$

整理得到位势积分公式： $u(Q)=\frac{1}{4\pi}\left[\iint_{\partial\Omega}\frac{1}{r}\frac{\partial u}{\partial n}\mathrm{d}S-\iint_{\partial\Omega}u\frac{\partial}{\partial n}\left(\frac{1}{r}\right)\mathrm{d}S-\iint_{\Omega}\frac{1}{r}\Delta u\mathrm{d}x\right]$

$$n>3\text{时的位势积分公式:}u(Q)=\frac{1}{(n-2)!S^{n-1}}\left[\int_{\partial\Omega}r^{2-n}\frac{\partial u}{\partial n}\mathrm{d}S_P-\int_{\partial\Omega}u\frac{\partial}{\partial n}(r^{2-n})\mathrm{d}S_P-\int_{\Omega}r^{2-n}\Delta u\mathrm{d}x_P\right]$$

证明调和函数的可去奇点定理：在以λ为球心R为半径的小球上研究问题，构造补充定义后的函数u。用W衡量两个函数的差距，手段是再构造一个V比较V和W，先让Q→λ，极值原理证明|W|≤V在小圆环上成立，再让ε→0，证明在去心圆盘上成立

当n=2时，若u(Q)在A点附近调和，且u(Q)=o(1)lnr(A,Q)，则可补充定义，s.t.Δu=0，x∈B_δ(A)

证明：取小球B_R(A)⊂Ω作为研究的对象。B_δ(A)⊂B_R(A)

设u₁满足 $\begin{cases}\Delta u_1=0\\u_1|_{\partial B_\delta}=u|_{\partial B_\delta}\end{cases}$ ，下证明u₁和u在除了A点地方都离得很近

【手段：构造辅助函数】令W=u₁-u⇒ $\begin{cases}\Delta W=0,B_R\setminus B_\delta\\W|_{\partial B_\delta}=0\end{cases}$ ，

令V_ε=ε(ln $\frac{1}{r(A,Q)}$ -ln $\frac{1}{R}$)，则V_ε满足 $\begin{cases}\Delta V_\epsilon=0\\V_\epsilon|_{\partial B_R}=0\end{cases}$ ，进而通过比较V_ε和W来说明u₁和u离得很近

由条件， $\lim_{Q\rightarrow A}\frac{u_1(Q)}{\ln r(A,Q)}=0$,则有 $\lim_{Q\rightarrow A}\frac{u_1(Q)}{\ln r(A,Q)}=0(Q\rightarrow A\text{时}\ln r(A,Q)\rightarrow\infty,\text{而}u_1(Q)\text{的大小能被边界所控制住})$

则 $\lim_{Q\rightarrow A}\frac{|W|}{\ln r(A,Q)}=\lim_{Q\rightarrow A}\frac{|u_1-u|}{\ln r(A,Q)}=0$,而显然∀ε>0, $\lim_{Q\rightarrow A}\frac{|W|}{V_\epsilon}=0$ ，则∃δ₀,s.t.|W|≤V_ε,∀x∈∂B_R
⇒ $\begin{cases}\Delta(W-V_\epsilon)=0,B_R\setminus B_{\delta_0},\text{在去掉小圆盘上调和}\\(W-V_\epsilon)|_{\partial B_R}=0,\text{在大圆盘边界上是0}\\(W-V_\epsilon)|_{\partial B_{\delta_0}}\leq 0\text{或}\geq 0,\text{在小圆盘边界上保号}\end{cases}$ 由于极值原理⇒W-V_ε在B_R\B_{δ₀}上保号，令δ₀→0⁺仍成立

则|W|≤V_ε在B_R\{A}上成立，再让ε→0，则|W|=|u₁-u|=0,B_R\{A},即可在u(A)处补充定义使之成为u₁

以n=3为例，对t>0， $\frac{\partial}{\partial t}E(t)-a^2\Delta E(x,t)=\delta(x,t)$

对x做Fourier变换，ode方程求出F(ξ)，再做逆变换，凑成Gauss积分

等式两边对x做Fourier变换： $F_{x\rightarrow\xi}\left(\frac{\partial}{\partial t}E(x,t)-a^2\Delta E(x,t)\right)(\xi,t)=(F_{x\rightarrow\xi}\delta(x,t))(\xi,t)$

⇒ $\frac{\partial}{\partial t}\hat{E}(\xi,t)+a^2|\xi|^2\hat{E}(\xi,t)=\delta(t)$ 即为 $\hat{E}(\xi,t)$ 的一阶线性非齐次ode方程，解得为 $\hat{E}(\xi,t)=H(t)e^{-a^2|\xi|^2t}$ ，

令v(t)=e^{a²|ξ²Ê(ξ,t)}Ê(ξ,t),这样方程化为v'(t)=δ̂(t),v(t)=H(t)+C,因为做Fourier变换要求E(x,t)∈S'(Rⁿ⁺¹),

则也要求Ê(x,t)∈S'(Rⁿ⁺¹),所以要求t→-∞时Ê(ξ,t)=(H(t)+C)e^{a²|ξ²Ê(ξ,t)}的任意解导数都趋于0,则C=0

则E(x,t)=F⁻¹ $\left[H(t)e^{-a^2|\xi|^2t}\right]=(2\pi)^{-3}\int_{\mathbb{R}^3}e^{i\xi x}H(t)e^{-a^2|\xi|^2t}\mathrm{d}\xi$

$$\xrightarrow{\text{凑成Gauss积分}}\frac{H(t)(2\pi)^{-3}\int_{\mathbb{R}^3}\exp\left[i\cdot\frac{x}{a\sqrt{2t}}(a\sqrt{2t}\xi)\right]\cdot\exp\left(-\frac{1}{2}|a\sqrt{2t}\xi|^2\right)\mathrm{d}\xi}{F_{x\rightarrow\xi}\left(e^{-\frac{|\xi|^2}{2}}\right)=(2\pi)^{\frac{n}{2}}e^{\frac{|\xi|^2}{2}}\rightarrow F^{-1}\left(e^{-\frac{|\xi|^2}{2}}\right)=(2\pi)^{-\frac{n}{2}}e^{-\frac{|\xi|^2}{2}}}\frac{H(t)(a\sqrt{2t})^{-n}}{(2\pi)^{-\frac{n}{2}}e^{-\frac{1}{2}|\frac{x}{a\sqrt{2t}}|^2}}=H(t)(4\pi a^2t)^{-\frac{n}{2}}e^{-\frac{|x|^2}{4a^2t}},t>0$$

热传导方程的基本解 $K(x,t)=(4\pi t)^{-\frac{n}{2}}H(t)e^{-\frac{|x|^2}{4t}}$

$$(P_1)\begin{cases}\frac{\partial}{\partial t}-a^2\Delta u=f(x,t),&t>0\\u|_{t=0}=\varphi(x)\end{cases},(P_2)\begin{cases}\frac{\partial}{\partial t}-a^2\Delta u=f(x,t),&t>0\\u|_{t=0}=0\end{cases}$$

(P₁) $\begin{cases}\frac{\partial}{\partial t}-a^2\Delta u=0,&t>0\\u|_{t=0}=\varphi(x)\end{cases}$ ，若u₁为P₁的解,u₂为P₂的解,则u₁+u₂=u为(P)的解(线性所以才能叠加)

Step 1: 求解 (P₁)

和基本解的求法基本一致，只是把H(δ)换成了harg(ξ),再利用先卷积再变化=先变化再相乘的性质

step 1:证明当u(x,t)满足(P₁)时,u(x,t)=E(x,t)* $\varphi(x)$

(P₁) $\begin{cases}\frac{\partial}{\partial t}-a^2\Delta u=0,&t>0\\u|_{t=0}=\varphi(x)\end{cases}$ 关于x做Fourier变换⇒ $\begin{cases}\frac{\partial}{\partial t}\hat{u}(t,\xi)+a^2|\xi|^2\hat{u}(t,\xi)=0,&t>0\\\hat{u}|_{t=0}=\hat{\varphi}(\xi)\end{cases}$

⇒ $\hat{u}(t,\xi)=\hat{\varphi}(\xi)e^{-a^2|\xi|^2t}$,u(t,x)=F⁻¹_{ξ→x}($\hat{\varphi}(\xi)e^{-a^2|\xi|^2t}$)【和基本解的做法一致】

由于 $\widehat{f_1*f_2}=\widehat{f_1}\cdot\widehat{f_2}$,令 $\begin{cases}f_1(t,x)=F^{-1}\left(e^{-a^2|\xi|^2t}\right)=(4\pi a^2t)^{-\frac{n}{2}}e^{-\frac{|x|^2}{4a^2t}}\\f_2(x)=\varphi(x)\end{cases}$ ，⇒ $\widehat{f_1}\cdot\widehat{f_2}=u(t,x)=\widehat{f_1*f_2}=(4\pi a^2t)^{-\frac{n}{2}}e^{-\frac{|x|^2}{4a^2t}}*\varphi(x)$

就是基本解去掉H(t),方法一样的,凑成Gauss积分=(4a²t)^{- $\frac{n}{2}$} ∫ $\varphi(y)e^{-\frac{x-y|^2}{4a^2t}}$ dy,t>0=E(x,t)* $\varphi(x)$ 【直接就能看出来】

要验证<δ(x),f(x)>=δ(δf(0)),即等价于说明δ(x)的"时间"和"空间"是可以分离的

接下来要验证：u(x,t)=E(x,t)* $\psi(x)$ 满足(P₁)：

$$\textcircled{1}\left(\frac{\partial}{\partial t}-a^2\Delta\right)(E(x,t)*\psi(x))=\left[\left(\frac{\partial}{\partial t}-a^2\Delta\right)E(x,t)\right]*\psi(x)=\delta(x,t)*\psi(x)=\langle\delta(y,t),\psi(x-y)\rangle_y\stackrel{?}{=} \delta(t)\psi(x)=0$$

claim：⟨δ̂(t,x),f(x)⟩=δ̂(t)f(0)

证明：将δ̂(x,t)磨光，取磨光核Φ_ε(x,t)，令δ_ε(t,x)=δ̂(t,x)*Φ_ε(t,x)∈C₀[∞](Rⁿ⁺¹),∀ψ(t)∈C₀[∞](R),有

$$\langle\delta_\epsilon(t,x),f(x)\rangle=\int\psi(t)\mathrm{d}t\int\delta_\epsilon(t,x)f(x)\mathrm{d}x=\iint\delta_\epsilon(t,x)f(x)\psi(t)\mathrm{d}x\mathrm{d}t=\langle\delta_\epsilon(t,x),f(x)\psi(t)\rangle$$

令ε→0得⟨δ̂(t,x),f(x)⟩,ψ(t)⟩=⟨δ̂(t,x),f(x)ψ(t)⟩=f(0)⟨δ̂(t),ψ(t)⟩=f(0)⟨δ̂(t),ψ(t)⟩=⟨f(0)δ̂(t),ψ(t)⟩⇒⟨δ̂(t,x),f(x)⟩=δ̂(t)f(0)

先证明基本解全空间上的积分是1，再利用该引理将绝对值分成两段，小球内积分自然可任意小，小球外积分要将基本解展开写，换元后易证趋于0

$$\textcircled{2}\text{验证}\lim_{t\rightarrow 0^+}u(t,x)=\lim_{t\rightarrow 0^+}E(t,x)*\varphi(x)=\varphi(x),\text{即证}\lim_{t\rightarrow 0^+}E(t,x)=\delta(x),\text{即证}\forall\varphi(x)\in C_0^\infty(\mathbb{R}^n),\langle E(t,x),\varphi(x)\rangle\stackrel{t\rightarrow 0^+}{\longrightarrow}\varphi(0)$$

claim：∫_{Rⁿ}E(x,t)dx=1,t>0,proof：∫_{Rⁿ}E(x,t)dx=∫_{Rⁿ}(4πt)^{- $\frac{n}{2}$} e^{- $\frac{|x|^2}{4t}$} dx $\stackrel{\text{令}2\sqrt{tx-x}}{=}$ (π)^{- $\frac{n}{2}$} ∫_{Rⁿ}e^{-|x'|²}dz=1

则E(x,t)∈L_{loc}(Rⁿ),∀φ∈C₀[∞](Rⁿ),由连续性可知∀ε>0,∃δ>0,s.t.|x|<δ时,|φ(x)-φ(0)|<ε

$$\text{则}\left|\left\langle E(x,t),\varphi(x)\right\rangle-\varphi(0)\right|=\left|\int_{\mathbb{R}^n}E(x,t)\varphi(x)\mathrm{d}x-\varphi(0)\right|=\left|\int_{\mathbb{R}^n}E(x,t)[\varphi(x)-\varphi(0)]\mathrm{d}x\right|+\left|\int_{\mathbb{R}^n}E(x,t)[\varphi(x)-\varphi(0)]\mathrm{d}x\right|$$

$$\left|\int_{B_\delta(0)}E(x,t)[\varphi(x)-\varphi(0)]\mathrm{d}x\right|\leqslant\varepsilon\left|\int_{B_\delta(0)}E(x,t)\mathrm{d}x\right|\leqslant\varepsilon$$

$$\left|\int_{\mathbb{R}^n\setminus B_\delta(0)}E(x,t)[\varphi(x)-\varphi(0)]\mathrm{d}x\right|\leqslant2\|\varphi\|\infty\int_{\mathbb{R}^n\setminus B_\delta(0)}E(x,t)\mathrm{d}x\stackrel{\text{令}2\sqrt{tx-x}}{=}\left(\pi\right)^{\frac{n}{2}}\|\varphi\|\infty\int_{\mathbb{R}^n\setminus B_{\frac{\delta}{2\sqrt{t}}}(0)}e^{-|x'|^2}\mathrm{d}x\stackrel{t\rightarrow 0^+}{\longrightarrow}0$$

综上,即得∀φ(x)∈C₀[∞](Rⁿ),⟨E(t,x),φ(x)⟩ $\xrightarrow{t\rightarrow 0^+}$ φ(0)

综上,得到了t>0,u₁(x,t)=E(t,x)* $\varphi(x)=H(t)(4\pi a^2t)^{-\frac{n}{2}}\int_{\mathbb{R}^n}\varphi(y)e^{-\frac{|x-y|^2}{4a^2t}}$ dy为(P₁)的解

Step 2: 利用Duhamel原理求解(P₂)

构造U(x,t,τ)将(P₂)转化为(P₁)的形式

(P₂) $\begin{cases}\frac{\partial}{\partial t}-a^2\Delta u=f(x,t),&t>0\\u|_{t=0}=0\end{cases}$

【齐次化原理(Duhamel原理)】将(P₂)化为齐次方程非零初值问题【即将(P₂)形式的方程转化为(P₁)形式的方程】

构造辅助函数U(x,t,τ)满足 $\begin{cases}\frac{\partial}{\partial t}-a^2\Delta U=0,&t>\tau\\U(x,t,\tau)|_{t=\tau}=f(x,\tau)\end{cases}$ ，令u(x,t)=∫₀^tU(x,t;τ)dr⇒ $\begin{cases}\frac{\partial}{\partial t}-a^2\Delta u=f(x,t),t>0\\u|_{t=0}=0\end{cases}$

具体来说， $\begin{cases}\frac{\partial u}{\partial t}=\frac{\partial U}{\partial t}\int_0^tU(x,t,\tau)\mathrm{d}\tau=U(x,t,t)+\int_0^t\frac{\partial U(x,t,\tau)}{\partial t}\mathrm{d}\tau=f(x,t)+\int_0^ta^2\Delta U(x,t,\tau)\mathrm{d}\tau=f(x,t)+a^2\Delta u(x,t)\\u|_{t=0}=\int_0^0\cdots\mathrm{d}\tau=0\end{cases}$

从而就可由U直接写出U(x,t,τ)的解，把积分写开变成n+1重积分就是u₂的解

利用(P₁)的解,写出 $\begin{cases}\frac{\partial}{\partial t}-a^2\Delta U=0,&t-\tau>0\\U(x,t,\tau)|_{t=\tau=0}=f(x,\tau)\end{cases}$ 的解

$$U(x,t,\tau)=E(x,t-\tau)*f(x,\tau)=\int_{\mathbb{R}^n}(4\pi a^2(t-\tau))^{-\frac{n}{2}}e^{-\frac{|x-y|^2}{4a^2(t-\tau)}}f(y,\tau)\mathrm{d}y=(4\pi a^2(t-\tau))^{-\frac{n}{2}}\int_{\mathbb{R}^n}f(y,\tau)e^{-\frac{|x-y|^2}{4a^2(t-\tau)}}\mathrm{d}y$$

⇒把解出的U(x,t,τ)代入u(x,t)=∫₀^tU(x,t,τ)dτ

$$=\int_0^t(4\pi a^2(t-\tau))^{-\frac{n}{2}}\int_{\mathbb{R}^n}f(y,\tau)\exp\left(-\frac{|x-y|^2}{4a^2(t-\tau)}\right)\mathrm{d}y\mathrm{d}\tau$$
$$=\int_0^t\int_{\mathbb{R}^n}f(y,\tau)\boxed{(4\pi a^2(t-\tau))^{-\frac{n}{2}}\exp\left(-\frac{|x-y|^2}{4a^2(t-\tau)}\right)}\mathrm{d}y\mathrm{d}\tau$$

下面要证E(x,t)*(H(t)f(x,t))=u₂(x,t) Green函数,Heat Kernal

验证u₂(x,t)为(P₂)的解：通过Duhamel原理的推导，已经保证了u₂(x,t)(x,t)必然满足非齐次方程(P₂)的所有要求

于是令u(x,t)=u₁(x,t)+u₂(x,t),为(P) $\begin{cases}\frac{\partial u}{\partial t}-a^2\Delta u=f(x,t),&t>0\\u|_{t=0}=\varphi(x)\end{cases}$ 的解

对于线性算子P,基本解为E(x),则u=E*f为Pu=f的∂'解

思路：(P) $\begin{cases}\frac{\partial}{\partial t}-a^2\Delta u=f(x,t),&t>0\\u|_{t=0}=\varphi(x)\end{cases}$ ，令 $\tilde{u}(x,t)=H(t)u(x,t)$,其中u(x,t)为P的解⇒ $\tilde{u}(t,x)\stackrel{t\rightarrow 0}{=}\tilde{u}(x,t)$

$$\left(\frac{\partial}{\partial t}-a^2\Delta\right)\tilde{u}(x,t)=\left(\frac{\partial}{\partial t}-a^2\Delta\right)(H(t)u(x,t))\stackrel{\triangle}{=}F(x,t)\Rightarrow\tilde{u}(x,t)=E(x,t)*F(x,t)\stackrel{t\rightarrow 0}{=}\tilde{u}(x,t)$$

就是一步δ(0)u(x,0)=δ(0)φ(x)的化简

$$\left(\frac{\partial}{\partial t}-a^2\Delta\right)\tilde{u}(x,t)=\left(\frac{\partial}{\partial t}-a^2\Delta\right)(H(t)u(x,t))\stackrel{\triangle}{=}F(x,t)\Rightarrow\tilde{u}(x,t)=E(x,t)*F(x,t)\stackrel{t\rightarrow 0}{=}\tilde{u}(x,t)$$
$$\left(\frac{\partial}{\partial t}-a^2\Delta\right)(H(t)u(x,t))=\delta(t)u(x,t)+H(t)\frac{\partial}{\partial t}u(x,t)-a^2H(t)\Delta u(x,t)=\delta(t)u(x,t)+H(t)f(x,t)$$

下证：δ̂(t)u(x,t)=δ̂(t)φ(x),取∀ψ(t)∈C₀[∞],⟨δ̂(t)u(x,t),ψ(t)⟩=⟨δ̂(t)u(x,t),ψ(t)⟩=⟨δ̂(t),u(x,t)ψ(t)⟩=u(x,0)ψ(0)

$$\parallel\langle\delta(t)\varphi(x),\psi(t)\rangle=\langle\delta(t),\varphi(x)\psi(t)\rangle=\varphi(x)\psi(0)$$

即得δ̂(t)u(x,t)=δ̂(t)φ(x)

则设 $\left(\frac{\partial}{\partial t}-a^2\Delta\right)(H(t)u(x,t))=\delta(t)\varphi(x)+H(t)f(x,t)\stackrel{\triangle}{=}F(x,t)$

由基本解性质，可知 $\tilde{u}(x,t)=E(x,t)*F(x,t)=E(x,t)*(\delta(t)\varphi(x)+H(t)f(x,t))$

两项卷积的第一项化简，依旧是δ磨光，通过卷积的定义转化形式再取极限

①δ̂(t)φ(x)*E(x,t),取Φ_ε(t)为磨光核,令δ_ε(t)=δ̂(t)*Φ_ε(t)∈C₀[∞],⟨δ_ε(t)φ(x),*E(x,t)=∫_{Rⁿ}∫_{Rⁿ}δ_ε(τ)φ(y)E(x-y,t-τ)drdy

由δ_ε(t)∈C₀[∞](R),φ(x)有界连续,E(x,t)在空间方向x为急变的,从而以上积分有意义

⇒上式=∫_{Rⁿ}φ(y)dy∫δ_ε(τ)E(x-y,t-τ)dτ=⟨φ(y),⟨δ_ε(τ),E(x-y,t-τ)⟩⟩

两边取极限⇒(δ̂(t)·φ(x))*E(x,t)=⟨φ(y),E(x-y,t)⟩=E(x,t)* $\varphi(x)=H(t)(4\pi a^2t)^{-\frac{n}{2}}\int_{\mathbb{R}^n}\varphi(y)\exp\left(-\frac{|x-y|^2}{4a^2t}\right)\mathrm{d}y$

注：δ̂(t)φ(x)*E(x,t)=φ* $\int_{\mathbb{R}^n}E(x,t)$ 与法一中(P₂) $\begin{cases}\frac{\partial}{\partial t}-a^2\Delta u=0,&t>0\\u|_{t=0}=\varphi(x)\end{cases}$ 的结果u₁是一样的

第二项卷积基本没什么可以化简的，只是把H(δ)和H(δ̂)的地方化简了，形式还是复杂的积分

$$\textcircled{2}(H(t)f(x,t))*E(x,t)=\int_{\mathbb{R}^n}\int_{\mathbb{R}}H(\tau)f(y,\tau)\underbrace{H(t-\tau)(4\pi a^2(t-\tau))^{-\frac{n}{2}}\exp\left(-\frac{|x-y|^2}{4a^2(t-\tau)}\right)}_{E(x-y,t-\tau)}\mathrm{d}r\mathrm{d}y$$

只有当τ∈(0,t)时才同时满足H(τ)=1且H(t-τ)=1,所以上式=∫_{Rⁿ}∫₀^tf(y,τ)(4πa²(t-τ))^{- $\frac{n}{2}$} exp(- $\frac{|x-y|^2}{4a^2(t-\tau)}$)drdy

注：(H(t)f(x,t))*E(x,t)与法一中(P₂) $\begin{cases}\frac{\partial}{\partial t}-a^2\Delta u=f(x,t),&t>0\\u|_{t=0}=0\end{cases}$ 的解u₂相同

综上, $\tilde{u}(x,t)=\varphi(x)*E(x,t)(H(t)f(x,t))*E(x,t)+(H(t)f(x,t))*E(x,t)\stackrel{t\rightarrow 0}{=}\tilde{u}(x,t)$ 此时恰为形式解

注：对得到的形式解仍需验证满足方程和初值条件，验证在法一已写过，不再展开

一个解ode初值问题的套路

思路：试求u(x,t)=X(x)T(t)变量分离的形式解,将u(x,t)=X(x)T(t)代入(P₁),试求X(x)和T(t)⇒u(x,t)=X(x)T(t)为形式解，再验证u(x,t)满足方程,初边值条件

⇒u(x,t)为(P₁)的解,又由极值原理的唯一性结论⇒u(x,t)=X(x)T(t)为(P₁)的唯一解

1)代入方程 $X(x)T'(t)-a^2X''(x)T(t)=0$

$$\Rightarrow\frac{X''(x)}{X(x)}=\frac{T'(t)}{a^2T(t)}\stackrel{\triangle}{=}-\mu\Rightarrow X''(x)+\mu X(x)=0$$

(2)满足边界条件： $\begin{cases}u(0,t)=X(0)T(t)=0\\u(l,t)=X(l)T(t)=0\end{cases}\Rightarrow X(0)=X(l)=0$

$$\Rightarrow\text{从而得到形式解应满足ode方程}\begin{cases}X''(x)+\mu X(x)=0\\X(0)=X(l)=0\end{cases}$$

①：μ<0，设μ=-λ²⇒λ=±√-μ
⇒X(x)=C₁e^{√μx}+C₂e^{-√μx}⇒代入边界条件： $\begin{cases}X(0)=C_1+C_2=0\\X(l)=C_1e^{\sqrt{\mu}l}+C_2e^{-\sqrt{\mu}l}=0\end{cases}$

有唯一解需满足系数行列式不为0⇒ $\begin{vmatrix}1&1\\e^{\sqrt{\mu}l}&e^{-\sqrt{\mu}l}\end{vmatrix}\neq 0\Rightarrow C_1=C_2=0\Rightarrow u$ 解为平凡解,舍去

②：μ=0,X(x)=C₁x+C₂⇒边界条件： $\begin{cases}X(0)=C_2=0,\\X(l)=C_1l=0\end{cases}\Rightarrow C_1=0$
⇒C₁=C₂=0⇒解为平凡解：X(x)≡0,舍去

③：μ>0，X(x)=C₁cos(√μ