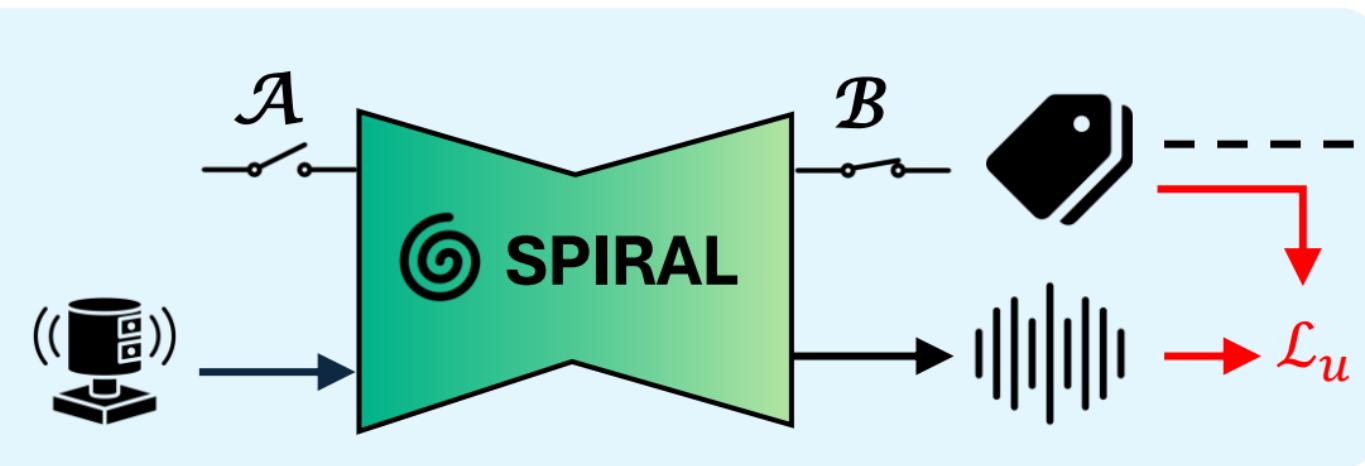
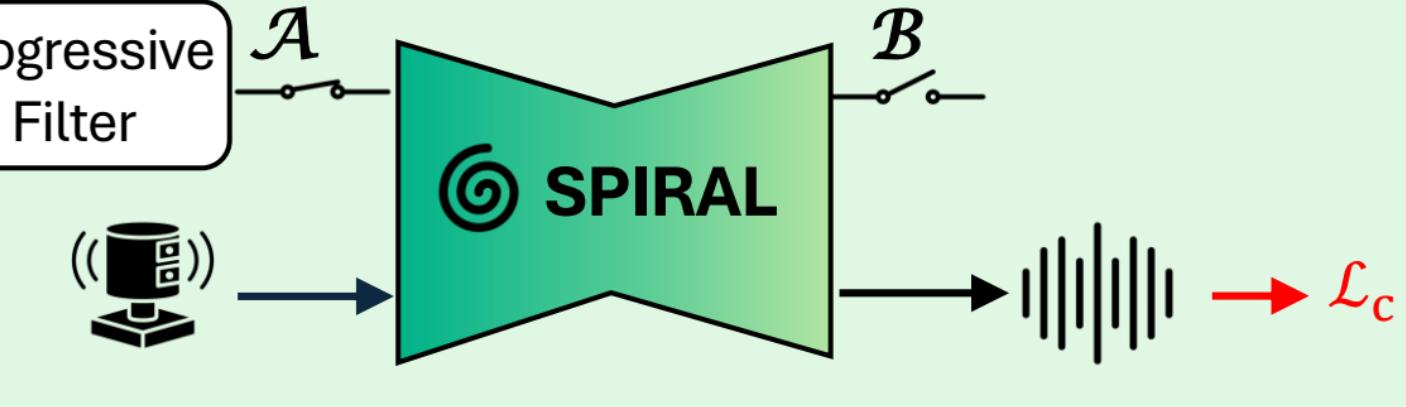


(a) Unconditional Step

- Noisy LiDAR scene x_t
- Predicted noise $\hat{\epsilon}_t$
- Predicted seg. label \hat{y}_t
- Training & Inference
- Training only
- Inference only



(b) Conditional Step



Open-Looped Mode

Unconditional Step

Closed-Looped Mode

Unconditional Step

Conditional Step

(c) Open-/Closed-Loop Mode Switch