Problem Set 4

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1 Theory Component

- [Q1]. Consider a layer in CNN that takes in a single channel input of 64×64 , and has 96 filters. In each of the following cases, compute the number of parameters that are learned in this layer. We assume that bias is present for each weight.
 - 1. A convolution layer with filters of same size as the input.
 - 2. A convolution layer with 8×8 filters with stride of 4
 - 3. A convolution layer with 1×1 filter and a stride of 1

Solution

1. one convolution filter:

no of parameters = size of filter
$$\times$$
 number of channels + 1
= $64 \times 64 \times 1 + 1$
= 4097

full convolution layer:

no of parameters =
$$4097 \times 96$$

= 393312

number of parameters for one convolution filter:

no of parameters =
$$8 \times 8 \times 1 + 1$$

= 65

full convolution layer:

no of parameters =
$$65 \times 96$$

= 6240

2. one convolution filter:

no of parameters =
$$1 \times 1 \times 1 + 1$$

= 2

full convolution layer:

no of parameters =
$$2 \times 96$$

= 192

[Q2].

Suppose you would have a neuron which has an RBF kernel as activation function (remember the evil wolf? Drop your linear style of thoughts. Circumferential thoughts can be nice too.)

$$y = \exp(-(x_1^2 + x_2^2)) + b$$

with parameter b. What would be the shapes realized by the set of points $\{(x_1, x_2) : y((x_1, x_2)) = 0\}$ as a function of b? Explain in at most 2 sentences and/or a little math.

Suppose now we add weights:

$$y = \exp(-(w_1x_1^2 + w_2x_2^2)) + b$$

What shapes could you realize now? Explain in at most 5 sentences and/or a little math. You can make references to publicly available in the internet materials to explain.

Solution For
$$y = \exp(-(x_1^2 + x_2^2)) + b$$
, when $(x_1, x_2) : y((x_1, x_2)) = 0$

$$0 = \exp(-(x_1^2 + x_2^2)) + b$$

$$-b = \exp(-(x_1^2 + x_2^2))$$

$$-\ln(-b) = x_1^2 + x_2^2$$

The shape of the function is a circle with centre, $x_1 = 0$, $x_2 = 0$ and radius, $\sqrt{-\ln(-b)}$.

$$\sqrt{-\ln(-b)} \ge 0$$
$$-\ln(-b) \ge 0$$
$$\ln(-b) \le 0$$

$$-b \le \exp(0) -b \ge 0$$

$$b \ge -1 \quad b \le 0$$
where $-1 \ge b \ge 0$
For $y = \exp(-(w_1 x_1^2 + w_2 x_2^2)) + b$, when $(x_1, x_2) : y((x_1, x_2)) = 0$

$$0 = \exp(-(w_1 x_1^2 + w_2 x_2^2)) + b$$

$$-b = \exp(-(w_1 x_1^2 + w_2 x_2^2))$$

$$-b = \exp(-(w_1 x_1^2 + w_2 x_2^2))$$

$$-\ln(-b) = w_1 x_1^2 + w_2 x_2^2$$

$$\frac{-\ln(-b)}{w_1 w_2} = \frac{x_1^2}{w_2} + \frac{x_2^2}{w_1}$$

The shape of the function is a ellipse with centre, $x_1=0,\ x_2=0,$ x_1 -axis radius, $\sqrt{\frac{-\ln(-b)}{w_1}}$ and x_2 -axis radius, $\sqrt{\frac{-\ln(-b)}{w_2}}$. where $-1 \geq b \geq 0$

[Q3].

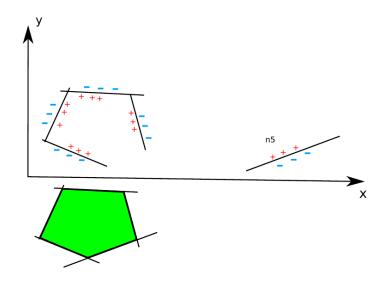


Figure 1: shapes

Suppose you have five linear neurons neurons n_1, \ldots, n_5 , realizing above decision boundaries as shown in Figure 1. That is: for every decision boundary we have outputs are = 0.5 in the zones marked with red plusses, and = 0.2 in the zones marked with the blue minuses. As you know, each neuron is realized by:

$$n_i = 0.3H(w_1^{(i)}x_1 + w_2^{(i)}x_2 + b^{(i)}) + 0.2, H(z) \in \{0, 1\}$$

where H is the threshold activation function.

You want to predict positive values in a shape marked in green in Figure 1. You want to achieve this prediction by combining these neurons using a threshold neuron H:

$$y = H(\sum_{i} v_i^* n_i + b^*)$$

- 1. what do you have to do with the weights of n_5 so that you can move the decision boundary of n_5 so that you can realize the shape in green shown above (in the sense of having positive values inside and negative values outside.)? Give a qualitative description. Note: Give a qualitative description in 3 sentences at most. Note that there is an x- and an y-axis, which helps you to express vectors qualitatively.
- 2. after moving the decision boundary of n_5 appropriately, the green shape looks a bit like an logical AND-combination of the +-zones for every neuron. How to choose the weights v_i^* and the bias b^* in

$$y = H(\sum_{i} v_i^* n_i + b^*)$$

so that you can realize the green shape (in the sense of having positive values inside and negative values outside that shape)?

Note: n_i gives out values either 0.5 or 0.2.

I hope that exercise explains you more what neural networks with 2 layers can achieve as shapes. With 3 layers you can realize an OR-combination of green shapes as above.

Solution

- 1. The decision boundary of n_5 is a linear function with gradients that is a function of the ratio of w_1 and w_2 , and bias that is a function of the ratio of b and w_2 . In order to shift the decision boundary, we need to decrease the value of b.
- 2. Let H(x) = 1[z > 0]

where
$$1[x] = \begin{cases} 1 & \text{If } x \text{ is True} \\ 0 & \text{If } x \text{ is False} \end{cases}$$

Consider when within the green region y = 1 and $n_i = 0.5 \ \forall i \in [1, n]$

$$1 = H(\sum_{i} 0.5v_{i}^{*} + b^{*})$$

$$1 = 1[(\sum_{i} 0.5v_{i}^{*} + b^{*}) > 0]$$

$$\sum_{i} 0.5v_{i}^{*} + b^{*} > 0$$

$$b^{*} > -\sum_{i} 0.5v_{i}^{*}$$

Consider when outside the green region y = 0, $n_j = 0.2$ and $n_i = 0.5 \ \forall i \in ([1, n] \setminus j)$

$$0 = H(\sum_{i} 0.5v_{i}^{*} + 0.2v_{j}^{*} + b^{*})$$

$$0 = 1[(\sum_{i} 0.5v_{i}^{*} + 0.2v_{j}^{*} + b^{*}) > 0]$$

$$\sum_{i} 0.5v_{i}^{*} + 0.2v_{j}^{*} + b^{*} \le 0$$

$$\sum_{i} 0.5v_{i}^{*} + 0.2v_{j}^{*} + b^{*} \le 0$$

$$b^{*} \le -\sum_{i} 0.5v_{i}^{*} - 0.2v_{j}^{*}$$

$$-\sum_{i} 0.5v_{i}^{*} - 0.5v_{j}^{*} < b^{*} \le -\sum_{i} 0.5v_{i}^{*} - 0.2v_{j}^{*}$$

We can get the bounded green region as long as we satisfy the above inequality for all values of $v_k \ \forall k \in [1, n]$ with all combinations $\forall j \in [1, n]$ with $i \in ([1, n] \setminus j)$.

2 Coding Component

```
from PIL import Image
from torch import Tensor, tensor
from torch.utils.data import Dataset, DataLoader
from torchvision.models import resnet18
from torchvision.transforms import *
from getimagenetclasses import parsesynsetwords, parseclasslabel
import sys
class cropSet(Dataset):
    def __init__(self, path, xmlDir, size):
        self.path = path
        self.xmlDir = xmlDir
        self.size = size
        self.transform = None
    def __len__(self):
        return self.size
    def __getitem__(self, idx):
        path = self.path.format(idx + 1)
        im = Image.open(path).convert("RGB")
        idx, name = parseclasslabel(self.xmlDir.format(idx + 1), syn2idx)
        if self.transform:
            im = self.transform(im)
        return im, idx
def center (img):
    C, W, H = img. size()
    \operatorname{crop} = \operatorname{img.new\_empty}((3, 224, 224))
    x = img. narrow (1, (W - 224) // 2, 224)
    crop = x.narrow(2, (H - 224) // 2, 224)
    return crop
class centerSet(cropSet):
```

```
def __init__(self, *arg):
        super().__init__(*arg)
         self.transform = \setminus
             Compose (
                 Resize (224),
                 ToTensor(),
                 Normalize (mean = [0.485, 0.456, 0.406],
                            std = [0.229, 0.224, 0.225]),
                 center,
             ])
def five (img):
    C, W, H = img.size()
    crop5 = img.new_empty((5, 3, 224, 224))
    x = img.narrow(1, 0, 224)
    x = x.narrow(2, 0, 224)
    crop 5 [0] = x
    x = img.narrow(1, W - 224, 224)
    x = x.narrow(2, 0, 224)
    crop 5 [1] = x
    x = img.narrow(1, W - 224, 224)
    x = x.narrow(2, H - 224, 224)
    crop5[2] = x
    x = img.narrow(1, 0, 224)
    x = x.narrow(2, H - 224, 224)
    crop5[3] = x
    x = img. narrow (1, (W - 224) // 2, 224)
    x = x.narrow(2, (H - 224) // 2, 224)
    crop 5 [4] = x
    return crop5
class fiveSet(cropSet):
    \mathbf{def} __init__(self, *arg):
        super().__init__(*arg)
         self.transform = \setminus
             Compose (
                 Resize (280),
                 ToTensor(),
                 Normalize (mean = [0.485, 0.456, 0.406],
                            std = [0.229, 0.224, 0.225]),
```

```
five,
            ])
def test (model, dataloader):
    total = 0
    correct = 0
    for n, sample_batched in enumerate(dataloader):
        data, descs = sample_batched
        X = data.view(-1, 3, 224, 224)
        out = model.forward(X)
        out = out.view(batch_size, -1, 1000)
        out = out.mean(1)
        val, pred = out.max(1)
        cmp = pred.eq(descs)
        total += cmp. size(0)
        correct += cmp.sum()
    return int(correct), total
def main(dataDir, xmlDir, synDir, n=250, batch_size=10, is_shuffle=False):
    idx2syn, syn2idx, syn2desc = parsesynsetwords(synDir)
    fivecropset = fiveSet(dataDir, xmlDir, n)
    fivecroploader = DataLoader(
        fivecropset, batch_size=batch_size, shuffle=is_shuffle)
    centercropset = centerSet(dataDir, xmlDir, n)
    centercroploader = DataLoader(
        centercropset, batch_size=batch_size, shuffle=is_shuffle)
    model = resnet18 (pretrained=True)
    model.eval()
    fiveResult = test (model, fivecroploader)
    centerResult = test (model, centercroploader)
    return fiveResult, centerResult
if __name__ = "__main__":
    fiveResult, centerResult = main(sys.argv[1], sys.argv[2], sys.argv[3])
    print("Five_Crop_Accuracy: \_%s" \% fiveResult)
    print("Center_Crop_Accuracy: \[ \] \%s" \% centerResult )
```