

## Mecânica Clássica

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EXEMPLO 1 – Uma mola com duas massas iguais  $m$  vinculadas a um aro de raio  $R$

$$T = \frac{m}{2}(R\dot{\theta})^2 + \frac{m}{2}(R\dot{\varphi})^2$$

$$V = -mgR(1 - \cos\theta) - mgR(1 - \cos\varphi) + \frac{k}{2}[2R\sin\left(\frac{\varphi - \theta}{2}\right)]^2$$

$$\mathcal{L} = \frac{m}{2}R^2(\dot{\theta}^2 + \dot{\varphi}^2) + mgR(2 - \cos\theta - \cos\varphi) - 2kR^2\sin^2\left(\frac{\varphi - \theta}{2}\right)$$

$$\frac{\partial \mathcal{L}}{\partial \dot{\theta}} = mR^2\dot{\theta} \quad \frac{d}{dt}\frac{\partial \mathcal{L}}{\partial \dot{\theta}} = mR^2\ddot{\theta}$$

$$\frac{\partial \mathcal{L}}{\partial \theta} = mgR\sin\theta + kR^2\sin(\varphi - \theta)$$

$$mR^2\ddot{\theta} = mgR\sin\theta + kR^2\sin(\varphi - \theta)$$

$$\ddot{\theta} = \frac{g}{R}\sin\theta + \frac{k}{m}\sin(\varphi - \theta)$$

$$\ddot{\varphi} = \frac{g}{R}\sin\varphi + \frac{k}{m}\sin(\varphi - \theta)$$

EXEMPLO 2 – Um pendulo de comprimento  $2l$  com uma massa  $m$  e uma articulação em  $l$

$$V = -mgl(\cos\theta + \cos\varphi)$$

$$T = \frac{ml^2}{2}[\dot{\theta}^2 + \dot{\varphi}^2 + 2\dot{\theta}\dot{\varphi}\cos(\theta - \varphi)]$$

$$\mathcal{L} = \frac{ml^2}{2}[\dot{\theta}^2 + \dot{\varphi}^2 + 2\dot{\theta}\dot{\varphi}\cos(\theta - \varphi)] + mgl(\cos\theta + \cos\varphi)$$

$$\frac{\partial \mathcal{L}}{\partial \dot{\varphi}} = ml^2[\dot{\varphi} + \dot{\theta}\cos(\theta - \varphi)]$$

$$\frac{d}{dt}\frac{\partial \mathcal{L}}{\partial \dot{\varphi}} = ml^2\ddot{\varphi} + ml^2\ddot{\theta}\cos(\theta - \varphi) - ml^2\dot{\theta}\sin(\theta - \varphi)(\dot{\theta} - \dot{\varphi})$$

$$\frac{\partial \mathcal{L}}{\partial \varphi} = 2\dot{\theta}\dot{\varphi}\sin(\theta - \varphi)\frac{ml^2}{2} - mgl\sin\varphi$$