

The following are the Deliverables for the Deep Learning Based Sensor Fusion for Mixed Reality Systems project

- Extracting Hololens Inertial Data
- Deep learning SF Research
- Sensor Fusion model testing/evaluation
- Accuracy analysis of SF algorithm
- Create the tracking app in Unity
- Develop DNN model creator
- Develop SF algorithm
- Obtain accuracy data through MATLAB testing
- Create graphical/figure representation of SF algorithm results