The following are the Deliverables for the Deep Learning Based Sensor Fusion for Mixed Reality Systems project

* Extracting Hololens Inertial Data
* Deep learning SF Research
* Sensor Fusion model testing/evaluation
* Accuracy analysis of SF algorithm
* Create the tracking app in Unity
* Develop DNN model creator
* Develop SF algorithm
* Obtain accuracy data through MATLAB testing
* Create graphical/figure representation of SF algorithm results