

# Assignment 3 Devlin Maya

1.2.1 Objective is to show that a function  $f: X \rightarrow Y$  is continuous if and only if for every closed subset  $A$  of  $Y$ , the pre-image  $f^{-1}(A)$  is a closed subset of  $X$ . First assume that  $f$  is a continuous function. Let  $A$  be a closed subset of  $Y$ . Since  $A$  is closed the complement of  $A$  is in  $Y$  so  $Y-A$  is open. We know  $f$  is continuous and also that the pre-image of an open set is open thus  $f^{-1}(Y-A)$  is open in  $X$ .  $f^{-1}(A)$  has complement  $f^{-1}(Y-A)$  in  $X$ . Therefore  $f^{-1}(A)$  has an open complement and  $f^{-1}(A)$  is closed.

Now the other direction. Assume that for every closed set  $A$  in  $Y$  its pre-image  $f^{-1}(A)$  is closed in  $X$ . Take an arbitrary open set  $B$  in  $Y$  then  $Y-B$  is closed in

Y. We know for every closed set A in Y  
 the pre image  $f^{-1}(A)$  is closed in X  
 thus  $f^{-1}(Y-B)$  is closed in X.  $f^{-1}(B)$  in  
 X has complement  $f^{-1}(Y-B)$  and we know  
 the complement B closed thus  $f^{-1}(B)$  is  
 open. Therefore the pre image of every  
 open set Y is open in X & f is  
 continuous.

1.2.4 The objective is to show that for  
 two continuous functions  $f: X \rightarrow Y$  then  $(g: Y \rightarrow Z)$   
 the composition function  $g \circ f$  is  $X \rightarrow Z$  is continuous.

Suppose both  $f: X \rightarrow Y$  &  $g: Y \rightarrow Z$  are  
 continuous. The objective is to show that for any  
 open set U in Z the pre image  $g^{-1}(U)$  is  
 open in X, we know g is continuous the pre image  
 $g^{-1}(U)$  is an open set Y also since f is continuous  
 the pre image of an open set in Y is open

$f^{-1}(g^{-1}(U))$  is open in  $X$ . Thus the pre-image  $f^{-1}(g^{-1}(U))$  is open in  $X$ .  $f^{-1}(g^{-1}(U))$  is the same as  $g \circ f^{-1}(U)$  since the pre-image of  $U$  through composition  $g \circ f$  is the set of all points in  $X$  which when  $U$  is applied there is a mapping of such points in  $U$ . This is the same as the set of points in  $X$  where there is a mapping from  $f$  to  $g^{-1}(U)$  which is  $f^{-1}g^{-1}(U)$ . For every open set  $U$  in  $Z$  the pre-image through composition  $g \circ f$  is open in  $X$ . Therefore this aligns with the definition of continuity so the composition of continuous functions is continuous.

1.2.5 This question will be approached with a counter example in order to prove that  $A$  and  $B$  are closed in the gluing lemma is necessary.

The approach will begin with making  $X = \text{Real numbers}$  and two intervals say  $P$  and  $Q$  that are

not closed in the set of real numbers

$A = (0, 1]$  and  $B = [1, 2)$  also

take  $Z = \mathbb{R}$ . Then both continuous functions are  $f: A \rightarrow Z$   $(g: B \rightarrow Z)$

where  $f(x) = 1$  for  $x$  in  $A$  and  $g(x) = 0$  for  $x$  in  $B$ . We know Both are continuous  $f(x)$  and  $g(x)$ . Then

$D: X \rightarrow Z$  the same in the gluing

lemma thus  $D(x) = f(x)$  for  $x$  in  $A$  and  $D(x) = g(x)$  for  $x$  in  $B$ . Here it is observed that when  $x=1$   $D(x)=1$  for  $x$  in  $A$  and  $D(x)$  also is equal to 0 for  $x$  in  $B$ .

so  $D$  is not continuous at  $x=1$  since the  $\lim D(x)$  when  $x$

approaches 1 is not equal when the limit approaches from either direction.

Thus if  $f$  and  $g$  are continuous and  $f(x) = g(x)$  for  $x$  in  $A \cap B$  then

We know that  $D$  is not continuous since  $A \cup B$  aren't closed. Therefore it must be that  $A \cup B$  are closed in the gluing lemma.

1.2.12 Here it is observed that the inverse of the wrapping function is not continuous since if you start at the  $0$  point and approach the point  $1$  from either side there is an evident discontinuity. Since the inverse doesn't map back to a single point it cannot be continuous.

1.2.23 First we will begin by letting

$f: X \rightarrow Y$  be a homeomorphism and  
 $x$  a limit point of subset  $A$  of  $X$ .

It is known that  $x$  is a limit point  
of  $A \cap X$  thus  $f(x)$  is a limit point  
of  $f(A)$  in  $Y$ . This is because a  
homeomorphism preserves limit points.

The objective is to show that every  
open set  $U$  of  $Y$  with  $f(x) \in U$  will  
intersect  $f(A) - \{f(x)\}$  provides a non  
empty set as a result. The pre image  
of  $U$  under  $f$  is an open set in  $X$   
containing  $x$  since  $f$  is a homeomorphism.

$x$  is a limit point of  $A$  so  $A - \{x\}$   
now with the image of such intersection  
under  $f$  is  $f(A) - \{f(x)\}$ , we know

the result is non empty since there exists a bijection thus  $f(x) \in$  limit point of  $f(A)$ .

1.2.2<sup>y</sup> we will begin by letting  $f: X \rightarrow Y$  be a homeomorphism  $x \in$  a limit point of subset  $A$  of  $X$ . If  $x$  is a limit point of  $A$  in  $X$  then  $f(x)$  is a limit point of  $f(A)$  in  $Y$  since a homeomorphism preserves the properties of limit points. Begin with any limit point  $y$  of  $f(A)$  in  $Y$ , we know  $f$  is continuous and its inverse is as well. Then the pre image of  $y$  under  $f$  which is in  $X$  is also a limit point of  $A$ .

If  $B$  observed that the pre image is in  $A$  since it is closed if has all its limit points. It is therefore closed in  $Y$  since  $y = f(f^{-1}(y))$  is in  $f(A)$  and  $f(A)$  has all its limit points.

## Extra prob. 1. Constructing a homeomorphism

between  $(0,1)$  and  $(a,b)$ . First consider

$$f : (0,1) \rightarrow (a,b) \text{ where } f(x) = a + (b-a)x.$$

If  $B$  observed that  $f(x)$  is bijective and also continuous by linearity thus the inverse is continuous  $f^{-1} : (a,b) \rightarrow (0,1)$  by  $f^{-1}(x) = (x-a) \frac{1}{(b-a)}$

Therefore  $f$  is a homeomorphism between  $(0,1)$  and  $(a,b)$

Extra

The stereographic

2.

projection map  $h: S - \{ \text{north pole} \} \rightarrow \mathbb{R}^2$   
from the unit sphere  $S$  in  $\mathbb{R}^3$

To the plane  $\mathbb{R}^2$  is produced

by  $h(x, y, z) = \frac{x}{1-z}, \frac{y}{1-z}$  for all

$(x, y, z)$  in  $S$  with  $z \neq 1$ . Now

the inverse stereographic projection

map  $h^{-1}: \mathbb{R}^2 \rightarrow S - \{ \text{north pole} \}$  is given by

$$h^{-1}(u, v) = 2u \quad 2v \quad \sqrt{u^2 + v^2 + 1}$$

$$\left( u^2 + v^2 + 1 \right)^{-1} \frac{u^2 + v^2 + 1}{u^2 + v^2 + 1}$$

For all  $(u, v) \in \mathbb{R}^2$ , it is observed that the north pole of the sphere  $S$  is at the point  $(0, 0, 1)$ . The stereographic projection and its inverse are continuous thus there is a homeomorphism between the sphere  $S - \{\text{north pole}\}$  and the plane  $\mathbb{R}^2$ .

	<b>Section 1.2:</b> 1, 4, 5, 12, 23, 24. <b>Extra problems:</b> (1) Construct a homomorphism between open intervals $(0, 1)$ and $(a, b)$ . (2) Let $S$ be the unit sphere in three-dimensional Euclidean space $\mathbb{R}^3$ with coordinates $(x, y, z)$ . Identify the plane $\mathbb{R}^2$ as those points in space with $z=0$ . Write down the formula of the stereo projection map $h: S - \{\text{north pole}\} \rightarrow \mathbb{R}^2$ . What is the formula for its inverse map?
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<b>Assignment 4</b>	