# $\nu$ Collective oscillations in 2D

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# 1 Introduction

Collective oscillation of neutrinos is determined by the following equation.

$$i(\partial_t + \boldsymbol{v} \cdot \boldsymbol{\nabla}) \rho(t, \boldsymbol{x}, \boldsymbol{v}) = -\sqrt{2}G_F \int \frac{dv_z' d\phi}{4\pi} (1 - \boldsymbol{v} \cdot \boldsymbol{v}') (\rho(t, \boldsymbol{x}, \boldsymbol{v}') - \bar{\rho}(t, \boldsymbol{x}, \boldsymbol{v}'))$$
(1)

## 1.1 Two flavors

$$\rho = \begin{pmatrix} \rho_{ee} & \rho_{ex} \\ \rho_{ex}^* & \rho_{xx} \end{pmatrix} \tag{2}$$

Another way to represent  $\rho$  is,

$$\rho = \left(\frac{f_{\nu_e} + f_{\nu_x}}{2}\right) I + \left(\frac{f_{\nu_e} - f_{\nu_x}}{2}\right) \times \begin{pmatrix} a & S \\ S^* & -a \end{pmatrix}$$
(3)

# 2 Normal modes

Requiring  $a^2 + |S|^2 = 1$  and  $|S| \ll |a|$ , and taking the ansatz  $S_{\boldsymbol{v}}(t, \boldsymbol{x}) = Q_{\boldsymbol{v}}^{\omega, \boldsymbol{k}} \exp[-i(\omega t - \boldsymbol{k} \cdot \boldsymbol{x})]$  we have,

$$[(\omega - \epsilon_0) - (\mathbf{k} - \mathbf{\epsilon}) \cdot \mathbf{v}] Q_{\mathbf{v}}^{\omega, \mathbf{k}} = -\mu \int \frac{dv_z' d\phi}{2\pi} (1 - \mathbf{v} \cdot \mathbf{v}') G(\mathbf{v}') Q_{\mathbf{v}'}^{\omega, \mathbf{k}}$$
(4)

#### 2.1 ID case

Assume  $\rho$  homogeneous in x and y and also posses azimuthal symmetry. In that case the eq.4 becomes,

$$[(\omega - \epsilon_0) - (k_z - \epsilon_z)v_z]Q_{v_z}^{\omega, k_z} = -\mu \int dv_z' (1 - v_z v_z') G(v_z') Q_{v_z'}^{\omega, k_z}$$
(5)

The eq. 5 can be solved for  $\omega$  as eigen value problem for given  $k_z$ .

#### 2.1.1 Example

Consider  $G(v_z) = g_{\nu_e}(v_z) - \alpha g_{\bar{\nu}_e}$ , where  $g_{\nu_e/\bar{\gamma}nu_e}(v_z) \propto \exp[-\frac{(v_z-1)^2}{2\sigma_{\nu_e,\bar{\nu}_e}}]$ . We choose values of  $\nu_e$  and  $\bar{\nu}_e$  to be 0.6 and 0.5 respectively. The ELN profile( $G(v_z)$ ) for different values of  $\alpha$  and corresponding  $\text{Im}(\omega)$  are given below.

### 2.2 3D Case

Describe the neutrino field evolution in x-z plane. Phase-space distribution of the fields are describe using the velocity component along the z-direction and the azimuthal angle  $\phi$ . In order to justify the treatment of the system only in the x-z plane, we impose the constraint  $\rho(v_z, \phi) = \rho(v_z, -\phi)$ .

Now the eq. 4 assumes the form,

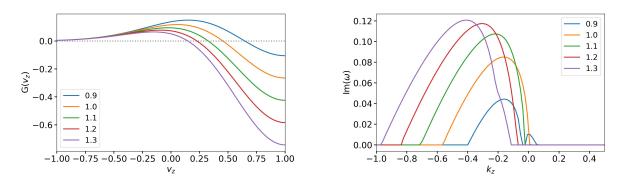


Figure 1: ELN (left) and corresponding  $\text{Im}(\omega)$  (right) for different values of  $\alpha$ 

$$[(\omega - \epsilon_0) - (k_x - \epsilon_x)v_{\perp}c_{\phi} - (k_y - \epsilon_y)v_{\perp}s_{\phi} - (k_z - \epsilon_z)v_z]Q_{v_z}^{\omega, k_x, k_z}$$

$$= -\mu \int \frac{dv_z'd\phi'}{2\pi} (1 - v_{\perp}v_{\perp}'(c_{\phi}c_{\phi'} + s_{\phi}s_{\phi'}) - v_zv_z')G(v_z', \phi')Q_{v_z', \phi'}^{\omega, k_x, k_z}$$
(6)

For simplicity, consider that neutrino beams are constrained to the angular bins such that,

$$v_z \in \{v_z^-, v_z^+\}, \quad \phi \in \{\phi^+, \phi^-\}$$
 (7)

Also, while expanding we only consider  $v_x$  and  $v_z$  (we neglect quantities along  $\hat{y}$ ). Generalization to full  $v_x, v_y$  and  $v_z$  is straight forward.

1.  $v_z = v_z^+, \ \phi = \phi^+$ :

$$\begin{split} &(\omega-\epsilon_0)Q_{c_{\phi}+,v_z^{\pm}}^{\omega,k_z,k_z} - \left[ (k_x-\epsilon_x)v_{\perp}^{+}c_{\phi} + (k_z-\epsilon_z)v_{z}^{+} \right]Q_{c_{\phi}+,v_z^{\pm}}^{\omega,k_z,k_z} = \\ &-\tilde{\mu} \left\{ g_{c_{\phi}+,v_z^{\pm}}Q_{c_{\phi}+,v_z^{\pm}}^{\omega,k_z,k_z} + g_{c_{\phi}-,v_z^{\pm}}Q_{c_{\phi}+,v_z^{\pm}}^{\omega,k_z,k_z} + g_{c_{\phi}-,v_z^{\pm}}Q_{c_{\phi}+,v_z^{\pm}}^{\omega,k_z,k_z} + g_{c_{\phi}-,v_z^{\pm}}Q_{c_{\phi}+,v_z^{\pm}}^{\omega,k_z,k_z} + c_{\phi}-g_{c_{\phi}-,v_z^{\pm}}Q_{c_{\phi}+,v_z^{\pm}}^{\omega,k_z,k_z} + v_{\phi}-g_{c_{\phi}-,v_z^{\pm}}Q_{c_{\phi}+,v_z^{\pm}}^{\omega,k_z,k_z} + v_{\phi}-g_{c_{\phi}-,v_z^{\pm}}Q_{c_{\phi}+,v_z^{\pm}}^{\omega,k_z,k_z} + g_{c_{\phi}-,v_z^{\pm}}Q_{c_{\phi}+,v_z^{\pm}}^{\omega,k_z,k_z} + c_{\phi}-g_{c_{\phi}-,v_z^{\pm}}Q_{c_{\phi}-,v_z^{\pm}}^{\omega,k_z,k_z} + g_{c_{\phi}-,v_z^{\pm}}Q_{c_{\phi}-,v_z^{\pm}}^{\omega,k_z,k_z} + v_{\phi}-g_{c_{\phi}-,v_z^{\pm}}Q_{c_{\phi}-,v_z^{\pm}}^{\omega,k_z,k_z} + g_{c_{\phi}-,v_z^{\pm}}Q_{c_{\phi}-,v_z^{\pm}}^{\omega,k_z,k_z} + g_{c_{\phi}-,v_z^{\pm}}Q_{c_{\phi}-,v_z^{\pm}}^{\omega,$$

 $+ \left. \tilde{\mu}(v_{\perp}^{-}c_{\phi^{+}}) \left\{ v_{\perp}^{+} \left( c_{\phi^{+}} g_{c_{\phi^{+}},v_{z}^{+}} + Q_{c_{\phi^{-}},v_{z}^{+}}^{\omega,k_{x},k_{z}} + c_{\phi^{-}} g_{c_{\phi^{-}},v_{z}^{+}} Q_{c_{\phi^{-}},v_{z}^{+}}^{\omega,k_{x},k_{z}} \right) + v_{\perp}^{-} \left( c_{\phi^{+}} g_{c_{\phi^{+}},v_{z}^{-}} Q_{c_{\phi^{+}},v_{z}^{-}}^{\omega,k_{x},k_{z}} + c_{\phi^{-}} g_{c_{\phi^{-}},v_{z}^{-}} Q_{c_{\phi^{-}},v_{z}^{-}}^{\omega,k_{x},k_{z}} \right) \right\}$ 

 $\left. + \tilde{\mu}v_z^- \left\{ v_z^+ \left( g_{c_{\phi^+},v_z^+} Q_{c_{\phi^+},v_z^+}^{\omega,k_x,k_z} + g_{c_{\phi^-},v_z^+} Q_{c_{\phi^-},v_z^+}^{\omega,k_x,k_z} \right) + v_z^- \left( g_{c_{\phi^+},v_z^-} Q_{c_{\phi^+},v_z^-}^{\omega,k_x,k_z} + g_{c_{\phi^-},v_z^-} Q_{c_{\phi^-},v_z^-}^{\omega,k_x,k_z} \right) \right\}$ 

 $-\left.\tilde{\mu}\left\{g_{c_{,+},v_{z}^{+}}Q_{c_{,+},v_{z}^{+}}^{\omega,k_{x},k_{z}}+g_{c_{,-},v_{z}^{+}}Q_{c_{,-},v_{z}^{+}}^{\omega,k_{x},k_{z}}+g_{c_{,+},v_{z}^{-}}Q_{c_{,+},v_{z}^{-}}^{\omega,k_{x},k_{z}}+g_{c_{,-},v_{z}^{-}}Q_{c_{,-},v_{z}^{-}}^{\omega,k_{x},k_{z}}\right\}$ 

4.  $v_z = v_z^-, \, \phi = \phi^-$ :

$$\begin{split} & \left(\omega-\epsilon_{0}\right)Q_{c_{\phi^{-}},v_{z}^{-}}^{\omega,k_{x},k_{z}}-\left[\left(k_{x}-\epsilon_{x}\right)v_{\perp}^{-}c_{\phi^{-}}+\left(k_{z}-\epsilon_{z}\right)v_{z}^{-}\right]Q_{c_{\phi^{-}},v_{z}^{-}}^{\omega,k_{x},k_{z}}=\\ & -\tilde{\mu}\left\{g_{c_{\phi^{+}},v_{z}^{+}}Q_{c_{\phi^{+}},v_{z}^{+}}^{\omega,k_{x},k_{z}}+g_{c_{\phi^{-}},v_{z}^{+}}Q_{c_{\phi^{-}},v_{z}^{-}}^{\omega,k_{x},k_{z}}+g_{c_{\phi^{+}},v_{z}^{-}}Q_{c_{\phi^{+}},v_{z}^{-}}^{\omega,k_{x},k_{z}}+g_{c_{\phi^{-}},v_{z}^{-}}Q_{c_{\phi^{-}},v_{z}^{-}}^{\omega,k_{x},k_{z}}\right\}\\ & +\tilde{\mu}(v_{\perp}^{-}c_{\phi^{-}})\left\{v_{\perp}^{+}\left(c_{\phi^{+}}g_{c_{\phi^{+}},v_{z}^{+}}Q_{c_{\phi^{+}},v_{z}^{+}}^{\omega,k_{x},k_{z}}+c_{\phi^{-}}g_{c_{\phi^{-}},v_{z}^{+}}Q_{c_{\phi^{-}},v_{z}^{+}}^{\omega,k_{x},k_{z}}\right)+v_{\perp}^{-}\left(c_{\phi^{+}}g_{c_{\phi^{+}},v_{z}^{-}}Q_{c_{\phi^{+}},v_{z}^{-}}^{\omega,k_{x},k_{z}}+c_{\phi^{-}}g_{c_{\phi^{-}},v_{z}^{-}}Q_{c_{\phi^{-}},v_{z}^{-}}^{\omega,k_{x},k_{z}}\right)\right\}\\ & +\tilde{\mu}v_{z}^{-}\left\{v_{z}^{+}\left(g_{c_{\phi^{+}},v_{z}^{+}}Q_{c_{\phi^{+}},v_{z}^{+}}^{\omega,k_{x},k_{z}}+g_{c_{\phi^{-}},v_{z}^{+}}Q_{c_{\phi^{-}},v_{z}^{+}}^{\omega,k_{x},k_{z}}\right)+v_{z}^{-}\left(g_{c_{\phi^{+}},v_{z}^{-}}Q_{c_{\phi^{+}},v_{z}^{-}}^{\omega,k_{x},k_{z}}+g_{c_{\phi^{-}},v_{z}^{-}}Q_{c_{\phi^{-}},v_{z}^{-}}^{\omega,k_{x},k_{z}}\right)\right\} \end{split}$$

Now, if we define a vector  $Q^{\omega,k_x,k_z} = \left(Q^{\omega,k_x,k_z}_{\phi^-,v_z^-},Q^{\omega,k_x,k_z}_{\phi^+,v_z^-},Q^{\omega,k_x,k_z}_{\phi^-,v_z^+},Q^{\omega,k_x,k_z}_{\phi^+,v_z^+}\right)^T$  for each pair of  $(k_x,k_z)$  the above set equations can be written as following form.

$$\omega Q^{\omega, k_x, k_z} = \left[ \epsilon_0 A_0 + (k_x - \epsilon_x) A_x + (k_z - \epsilon_z) A_z \right] Q^{\omega, k_x, k_z} - \tilde{\mu} \left[ I_0 - I_x - I_x \right] Q^{\omega, k_x, k_z}$$
(8)

where,  $\tilde{\mu} = \mu \left( \frac{\Delta v_z \Delta \phi}{2\pi} \right)$  and

$$A_0 = I_{N \times N}, \quad \text{where, } N = n_{v_z} \times n_{\phi},$$
 (9a)

$$A_x = \operatorname{diag}\left(\begin{bmatrix} v_{\perp}^- \\ v_{\perp}^+ \end{bmatrix} \otimes \begin{bmatrix} \cos(\phi^-) \\ \cos(\phi^+) \end{bmatrix}\right) \tag{9b}$$

$$A_z = \operatorname{diag}\left(\begin{bmatrix} v_z^- \\ v_z^+ \end{bmatrix} \otimes \begin{bmatrix} 1 \\ 1 \end{bmatrix}\right) \tag{9c}$$

$$I_{0} = \begin{bmatrix} 1\\1\\1\\1 \end{bmatrix} \otimes \left[ G(v_{z}^{-}, \phi^{-}), \ G(v_{z}^{-}, \phi^{+}), \ G(v_{z}^{+}, \phi^{-}), \ G(v_{z}^{+}, \phi^{+}) \right]$$
(9d)

$$I_{x} = \begin{bmatrix} v_{\perp}^{-}\cos(\phi^{-}) \\ v_{\perp}^{-}\cos(\phi^{+}) \\ v_{\perp}^{+}\cos(\phi^{-}) \\ v_{\perp}^{+}\cos(\phi^{+}) \end{bmatrix} \otimes \begin{bmatrix} v_{z}^{-}\cos(\phi^{-})G(v_{z}^{-},\phi^{-}), \ v_{z}^{-}\cos(\phi^{+})G(v_{z}^{-},\phi^{+}), \ v_{z}^{+}\cos(\phi^{-})G(v_{z}^{+},\phi^{-}), \ v_{z}^{+}\cos(\phi^{+})G(v_{z}^{+},\phi^{+}) \end{bmatrix}$$

$$(9e)$$

$$I_{z} = \begin{bmatrix} v_{z}^{-} \\ v_{z}^{-} \\ v_{z}^{+} \\ v_{z}^{+} \\ v_{z}^{+} \end{bmatrix} \otimes \left[ v_{z}^{-} G(v_{z}^{-}, \phi^{-}), \ v_{z}^{-} G(v_{z}^{-}, \phi^{+}), \ v_{z}^{+} G(v_{z}^{+}, \phi^{-}), \ v_{z}^{+} G(v_{z}^{+}, \phi^{+}) \right]$$
(9f)

The full 3D case is then,

$$\omega Q^{\omega,k_x,k_z} = \left[\epsilon_0 A_0 + (k_x - \epsilon_x) A_x + (k_y - \epsilon_y) A_y + (k_z - \epsilon_z) A_z\right] Q^{\omega,k_x,k_z} - \tilde{\mu} \left[I_0 - I_x - I_x\right] Q^{\omega,k_x,k_z}$$
(10)

$$A_0 = I_{N \times N}, \quad \text{where, } N = n_{v_z} \times n_{\phi},$$
 (11a)

$$A_x = \operatorname{diag}\left(\begin{bmatrix} v_{\perp}^- \\ v_{\perp}^+ \end{bmatrix} \otimes \begin{bmatrix} \cos(\phi^-) \\ \cos(\phi^+) \end{bmatrix}\right) \tag{11b}$$

$$A_y = \operatorname{diag}\left(\begin{bmatrix} v_{\perp}^- \\ v_{\perp}^+ \end{bmatrix} \otimes \begin{bmatrix} \sin(\phi^-) \\ \sin(\phi^+) \end{bmatrix}\right) \tag{11c}$$

$$A_z = \operatorname{diag}\left(\begin{bmatrix} v_z^- \\ v_z^+ \end{bmatrix} \otimes \begin{bmatrix} 1 \\ 1 \end{bmatrix}\right) \tag{11d}$$

$$I_{0} = \begin{bmatrix} 1\\1\\1\\1\\1 \end{bmatrix} \otimes \left[ G(v_{z}^{-}, \phi^{-}), \ G(v_{z}^{-}, \phi^{+}), \ G(v_{z}^{+}, \phi^{-}), \ G(v_{z}^{+}, \phi^{+}) \right]$$
(11e)

$$I_{x} = \begin{bmatrix} v_{\perp}^{-}\cos(\phi^{-}) \\ v_{\perp}^{-}\cos(\phi^{+}) \\ v_{\perp}^{+}\cos(\phi^{-}) \\ v_{\perp}^{+}\cos(\phi^{+}) \end{bmatrix} \otimes \left[ v_{z}^{-}\cos(\phi^{-})G(v_{z}^{-},\phi^{-}), \ v_{z}^{-}\cos(\phi^{+})G(v_{z}^{-},\phi^{+}), \ v_{z}^{+}\cos(\phi^{-})G(v_{z}^{+},\phi^{-}), \ v_{z}^{+}\cos(\phi^{+})G(v_{z}^{+},\phi^{+}) \right]$$

$$(11f)$$

$$I_{y} = \begin{bmatrix} v_{\perp}^{-} \sin(\phi^{-}) \\ v_{\perp}^{-} \sin(\phi^{+}) \\ v_{\perp}^{+} \sin(\phi^{-}) \\ v_{\perp}^{+} \sin(\phi^{+}) \end{bmatrix} \otimes \left[ v_{z}^{-} \sin(\phi^{-}) G(v_{z}^{-}, \phi^{-}), \ v_{z}^{-} \sin(\phi^{+}) G(v_{z}^{-}, \phi^{+}), \ v_{z}^{+} \sin(\phi^{-}) G(v_{z}^{+}, \phi^{-}), \ v_{z}^{+} \sin(\phi^{+}) G(v_{z}^{+}, \phi^{+}) \right]$$

$$(11g)$$

$$I_{z} = \begin{bmatrix} v_{z}^{-} \\ v_{z}^{-} \\ v_{z}^{+} \\ v_{z}^{+} \end{bmatrix} \otimes \left[ v_{z}^{-} G(v_{z}^{-}, \phi^{-}), \ v_{z}^{-} G(v_{z}^{-}, \phi^{+}), \ v_{z}^{+} G(v_{z}^{+}, \phi^{-}), \ v_{z}^{+} G(v_{z}^{+}, \phi^{+}) \right]$$
(11h)