# NAOYA MURAMATSU

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#### **EDUCATION**

# University of Cape Town

April 2021 – Present

PhD student in Electrical Engineering

· PhD Proposal title: "On the Neuromechanics of the Cheetah"

· Adviser: Amir Patel

#### University of Tsukuba

April 2018 – March 2021

MSc in Information Science

· Dissertation title: "SNN Meets ANN: Combining Spiking Neural Network (SNN) and Artificial Neural Network (ANN) for Image Classification"

Adviser: Tetsuji SatohSubadviser: Hai-Tao Yu

#### University of Tsukuba

April 2016 - March 2018

BSc in Library and Information Science

· Dissertation title: "Deep Learning in Reciprocal Lattice Space"

· Adviser: Yoichi Ochiai

# National Institute of Technology, Nagano College

April 2015 – March 2016

Foundation Degree

・Dissertation title: "Indoor location acquisition using a power-saving wireless network"(省電力無線ネットワークを用いた屋内位置情報取得)

· Adviser: Takashi Miyazaki

#### INDUSTRIAL EXPERIENCE

 $JUNGLE^{x}$ 

June 2022 – Present

Fellow

· Technical consultant and developing the 3D motion capture system for high-speed objects.

#### Good Answers, Inc.

February 2021 – Present

Fellow

· Technical consultant and developing the motor control algorithm for electric scooters.

#### Landscape Co.,Ltd.

January 2020 – Present

Outside CTO

· Developing various systems with machine learning techniques, such as optical character recognition and image recognition.

# Information-technology Promotion Agency, Japan. Exploratory Software Project (MI-TOU) June 2018 – March 2019

Creator

- · Developed the robot control system, walking even with broken legs using hierarchy Q-learning.
- $\cdot$  2,304,000 JPY / nine months.

#### Pixie Dust Technologies, Inc.

August 2017 – April 2019

Software Engineer

· Acquired a new big project and worked on the development of management systems and web applications.

#### **Fixstars Corporation**

August 2016 – December 2016

Software Engineer Intern

· Worked on the development of a semantic segmentation system for self-driving cars with poor computational resource.

#### **Fixstars Corporation**

August 2014 – September 2014

Software Engineer Intern

· Worked on software optimisation for the microcomputer of cars.

#### **PUBLICATIONS**

#### **JOURNALS**

· Naoya Muramatsu\*, Hai-Tao Yu, Tetsuji Satoh, "Combining Spiking Neural Networks with Artificial Neural Networks for Enhanced Image Classification," *IEICE Transactions on Information and Systems*, 2022. (under review)

#### REFEREED CONFERENCES

- · Naoya Muramatsu\*, Zico da Silva\*, Daniel Joska, Fred Nicolls, Amir Patel, "Improving 3D Markerless Pose Estimation of Animals in the Wild using Low-Cost Cameras," in Proc. IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2022) (\* co-first authors). (under review)
- · Amaan Vally, Daniel Joska, **Naoya Muramatsu**, Paul Amayo, Amir Patel, "3D Markerless Motion Capture of Animals in the Wild using Autonomous Tracking Cameras," in Proc. IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2022). (under review)
- · Daniel Joska, Liam Clark, **Naoya Muramatsu**, Ricky Jericevich, Fred Nicolls, Alexander Mathis, Mackenzie Mathis, Amir Patel, "AcinoSet: A 3D Pose Estimation Dataset and Baseline Models for Cheetahs in the Wild," in Proc. IEEE International Conference on Robotics and Automation (ICRA 2021).
- · Chun Wei Ooi, **Naoya Muramatsu**, Yoichi Ochiai, "Eholo glass: Electroholography glass. A lensless approach to holographic augmented reality near-eye display," in Technical Briefs of 11th ACM SIGGRAPH Asia (SA 2018).
- Natsumi Kato\*, Hiroyuki Osone\*, Daitetsu Sato, **Naoya Muramatsu**, Yoichi Ochiai, "DeepWear: a Case Study of Collaborative Design between Human and Artificial Intelligence," in Proc. 12th ACM Twelfth International Conference on Tangible, Embedded, and Embodied Interaction (TEI 2018). (\* co-first authors)
- · Natsumi Kato, Hiroyuki Osone, Daitetsu Sato, **Naoya Muramatsu**, Yoichi Ochiai, "Crowd Sourcing Clothes Design Directed by Adversarial Neural Networks," in Adjunct Proc. 31st Neural Information Processing Systems (NIPS 2017 Workshop).
- Naoya Muramatsu, Chun Wei Ooi, Yuta Itoh, Yoichi Ochiai, "DeepHolo: Recognizing 3D Objects using a Binary-weighted Computer-Generated Hologram," in Technical Briefs of 10th ACM SIGGRAPH Asia (SA 2017).
- · Mose Sakashita, Yuta Sato, Ayaka Ebisu, Keisuke Kawahara, Satoshi Hashizume, **Naoya Muramatsu**, Yoichi Ochiai, "Haptic Marionette: Wrist Control Technology Combined with Electrical Muscle Stimulation and Hanger Reflex," in in Adjunct Proc. 10th ACM SIGGRAPH Asia (SA 2017 Posters).

- · Naoya Muramatsu, Ooi Chun Wei, Takashi Miyazaki, "Development of High Performance Filter for Indoor Positioning System," in Proc. 5th IIAE International Conference on Intelligent Systems and Image Processing 2017 (ICISIP 2017).
- · Naoya Muramatsu, Kazuki Ohshima, Ryota Kawamura, Ooi Chun Wei, Yuta Sato, Yoichi Ochiai, "Sonoliards: Rendering Audible Sound Spots by Reflecting the Ultrasound Beams," in Adjunct Proc. 30th ACM User Interface Software and Technology (UIST 2017 Adjunct).

#### NON-REFEREED CONFERENCES

- · Naoya Muramatsu, Hai-Tao Yu, "Combining Spiking Neural Network and Artificial Neural Network for Enhanced Image Classification," in Proc. 13th Data Engineering and Information Management (DEIM 2021).
- · Naoya Muramatsu, Tetsuji Satoh, Takayasu Fushimi, "Product Attribute Extraction Method Based on Transition Pattern of Review Point of View," in Proc. 9th Data Engineering and Information Management (DEIM 2017). (Student Presentation Award)

#### PROFESSIONAL EXPERIENCE

#### PAPER REVIEWER

- · IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2022.
- · ACM Augmented Human International Conference (AH), 2018.

#### **CERTIFICATES**

- · Kinematics: Describing the Motions of Spacecraft (Coursera), University of Colorado Boulder, 2022.
- · Motion Planning for Self-Driving Cars (Coursera), University of Toronto, 2021.
- · Robotics: Mobility (Coursera), University of Pennsylvania, 2021.
- · Julia Scientific Programming (Coursera), University of Cape Town, 2021.
- · State Estimation and Localization for Self-Driving Cars (Coursera), University of Toronto, 2021.
- · Visual Perception for Self-Driving Cars (Coursera), University of Toronto, 2021.

#### **FELLOWSHIPS**

2022 Incoming International Student Scholarship at University of Cape Town (35,000 ZAR) Electrical Engineering P/G Scholarship at University of Cape Town (20,000 ZAR)

### **AWARDS**

2019	Super Creator at MITOU Projects
	(This award were given 16 creators from 27 people adopted from 300+ applications)
2018	MITOU Projects (2,304,000 JPY)
2018	President's Award for Students at University of Tsukuba
2017	Student Presentation Award at DEIM 2017
2015	Third Prize at RoboCupJunior Soccer 2015 (Hokushinetsu Block)

#### TECHNICAL STRENGTHS

Programming Languages	Python(most fluent), MATLAB, Julia, C, C++, Verilog,
	Shell Script, SQL
Machine Learning Libraries	Tensorflow, Keras, PyTorch, Scikit-learn, Chainer
Software	Git, Docker, PyBullet, Pyomo, IPOPT, Processing
$\mathbf{OS}$	MacOS, Ubuntu, Windows, TrueNAS, CentOS
Hardware	mbed, Arduino, Raspberry Pi, Hexapod

# LINKS

Portfolio GitHub Linkedin https://denden047.github.io/index\_en.html https://github.com/DenDen047 https://www.linkedin.com/in/naoya-muramatsu-a01182184/