

APC\_524

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# Contents

|          |  |          |
|----------|--|----------|
| <b>1</b> | <b>Hierarchical Index</b>                  | <b>1</b> |
| 1.1      | Class Hierarchy . . . . .                  | 1        |
| <b>2</b> | <b>Class Index</b>                         | <b>3</b> |
| 2.1      | Class List . . . . .                       | 3        |
| <b>3</b> | <b>Class Documentation</b>                 | <b>5</b> |
| 3.1      | BC_F_External Class Reference . . . . .    | 5        |
| 3.2      | BC_F_Periodic Class Reference . . . . .    | 6        |
| 3.3      | BC_Field Class Reference . . . . .         | 7        |
| 3.3.1    | Detailed Description . . . . .             | 7        |
| 3.4      | BC_P_Periodic Class Reference . . . . .    | 8        |
| 3.5      | BC_P_Reflecting Class Reference . . . . .  | 9        |
| 3.6      | BC_Particle Class Reference . . . . .      | 10       |
| 3.6.1    | Detailed Description . . . . .             | 10       |
| 3.7      | Boris Class Reference . . . . .            | 11       |
| 3.8      | Depositor Class Reference . . . . .        | 11       |
| 3.9      | Domain Class Reference . . . . .           | 12       |
| 3.9.1    | Member Function Documentation . . . . .    | 12       |
| 3.9.1.1  | mallocGhosts() . . . . .                   | 12       |
| 3.10     | Field_BC_Factory Class Reference . . . . . | 13       |
| 3.10.1   | Detailed Description . . . . .             | 13       |
| 3.10.2   | Member Function Documentation . . . . .    | 13       |
| 3.10.2.1 | constructConditions() . . . . .            | 13       |

|           |  |    |
|-----------|--|----|
| 3.11      | Field_part Struct Reference . . . . .            | 14 |
| 3.12      | FieldBC Class Reference . . . . .                | 14 |
| 3.12.1    | Detailed Description . . . . .                   | 14 |
| 3.12.2    | Member Function Documentation . . . . .          | 14 |
| 3.12.2.1  | applyBCs() . . . . .                             | 14 |
| 3.13      | Grid Class Reference . . . . .                   | 15 |
| 3.13.1    | Detailed Description . . . . .                   | 19 |
| 3.13.2    | Constructor & Destructor Documentation . . . . . | 19 |
| 3.13.2.1  | Grid() . . . . .                                 | 19 |
| 3.13.2.2  | ~Grid() . . . . .                                | 19 |
| 3.13.3    | Member Function Documentation . . . . .          | 20 |
| 3.13.3.1  | addJ() . . . . .                                 | 20 |
| 3.13.3.2  | checkInput_() . . . . .                          | 20 |
| 3.13.3.3  | deleteField_() . . . . .                         | 20 |
| 3.13.3.4  | evolveFields() . . . . .                         | 20 |
| 3.13.3.5  | evolveFieldsES() . . . . .                       | 20 |
| 3.13.3.6  | getCellID() . . . . .                            | 21 |
| 3.13.3.7  | getFieldInterpolatorVec() . . . . .              | 21 |
| 3.13.3.8  | getGhostVec() . . . . .                          | 21 |
| 3.13.3.9  | getGhostVecSize() . . . . .                      | 22 |
| 3.13.3.10 | getNumberOfCells() . . . . .                     | 22 |
| 3.13.3.11 | getNumCells3D() . . . . .                        | 22 |
| 3.13.3.12 | getStepSize() . . . . .                          | 22 |
| 3.13.3.13 | InitializeFields() . . . . .                     | 22 |
| 3.13.3.14 | newField_() . . . . .                            | 23 |
| 3.13.3.15 | setFieldAlongEdge() . . . . .                    | 23 |
| 3.13.3.16 | setFieldInPlane_() . . . . .                     | 23 |
| 3.13.3.17 | setFieldPtr_() . . . . .                         | 23 |
| 3.13.3.18 | setFieldSize_() . . . . .                        | 24 |
| 3.13.3.19 | setFieldType_() . . . . .                        | 24 |

|                                       |    |
|---------------------------------------|----|
| 3.13.3.20 setGhostVec()               | 24 |
| 3.13.3.21 sideToIndex_()              | 24 |
| 3.13.3.22 sliceMatToVec_()            | 25 |
| 3.13.3.23 unsliceMatToVec_()          | 25 |
| 3.13.3.24 updatePeriodicGhostCells()  | 25 |
| 3.14 Input Class Reference            | 25 |
| 3.14.1 Detailed Description           | 26 |
| 3.15 Input_Info_t Struct Reference    | 26 |
| 3.15.1 Detailed Description           | 27 |
| 3.15.2 Member Data Documentation      | 27 |
| 3.15.2.1 charge_ratio                 | 27 |
| 3.15.2.2 debug                        | 27 |
| 3.15.2.3 dens_frac                    | 27 |
| 3.15.2.4 np                           | 27 |
| 3.15.2.5 nProc                        | 27 |
| 3.15.2.6 nspecies                     | 27 |
| 3.15.2.7 nt                           | 28 |
| 3.15.2.8 relativity                   | 28 |
| 3.15.2.9 restart                      | 28 |
| 3.15.2.10 temp                        | 28 |
| 3.15.2.11 xyz0                        | 28 |
| 3.16 Interpolator Class Reference     | 28 |
| 3.17 Part_BC_Factory Class Reference  | 29 |
| 3.17.1 Detailed Description           | 29 |
| 3.18 Particle Struct Reference        | 29 |
| 3.19 Particle_Compare Class Reference | 30 |
| 3.20 Particle_Handler Class Reference | 30 |
| 3.20.1 Detailed Description           | 31 |
| 3.21 Poisson_Solver Class Reference   | 31 |
| 3.21.1 Member Function Documentation  | 33 |

|          |   |    |
|----------|---|----|
| 3.21.1.1 | <a href="#">AToB()</a>                                    | 33 |
| 3.21.1.2 | <a href="#">AToBSingleComp_()</a>                         | 33 |
| 3.21.1.3 | <a href="#">InitializeFields()</a>                        | 33 |
| 3.21.1.4 | <a href="#">phiToE()</a>                                  | 33 |
| 3.21.1.5 | <a href="#">phiToESingleComp_()</a>                       | 34 |
| 3.21.1.6 | <a href="#">zeroA()</a>                                   | 34 |
| 3.21.1.7 | <a href="#">zeroPhi()</a>                                 | 34 |
| 3.22     | <a href="#">Pusher Class Reference</a>                    | 34 |
| 3.23     | <a href="#">Random_Number_Generator Class Reference</a>   | 35 |
| 3.23.1   | <a href="#">Detailed Description</a>                      | 35 |
| 3.24     | <a href="#">RegisterFieldBoundary Struct Reference</a>    | 36 |
| 3.24.1   | <a href="#">Detailed Description</a>                      | 36 |
| 3.25     | <a href="#">RegisterParticleBoundary Struct Reference</a> | 36 |
| 3.26     | <a href="#">Relativistic_Boris Class Reference</a>        | 36 |
| 3.26.1   | <a href="#">Detailed Description</a>                      | 37 |
| 3.27     | <a href="#">RNG_State Struct Reference</a>                | 37 |
| 3.27.1   | <a href="#">Detailed Description</a>                      | 37 |

# Chapter 1

## Hierarchical Index

### 1.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

|                                    |    |
|------------------------------------|----|
| BC_Field . . . . .                 | 7  |
| BC_F_External . . . . .            | 5  |
| BC_F_Periodic . . . . .            | 6  |
| BC_Particle . . . . .              | 10 |
| BC_P_Periodic . . . . .            | 8  |
| BC_P_Reflecting . . . . .          | 9  |
| Depositor . . . . .                | 11 |
| Domain . . . . .                   | 12 |
| Field_BC_Factory . . . . .         | 13 |
| Field_part . . . . .               | 14 |
| FieldBC . . . . .                  | 14 |
| Grid . . . . .                     | 15 |
| Poisson_Solver . . . . .           | 31 |
| Input . . . . .                    | 25 |
| Input_Info_t . . . . .             | 26 |
| Interpolator . . . . .             | 28 |
| Part_BC_Factory . . . . .          | 29 |
| Particle . . . . .                 | 29 |
| Particle_Compare . . . . .         | 30 |
| Particle_Handler . . . . .         | 30 |
| Pusher . . . . .                   | 34 |
| Boris . . . . .                    | 11 |
| Relativistic_Boris . . . . .       | 36 |
| Relativistic_Boris . . . . .       | 36 |
| Random_Number_Generator . . . . .  | 35 |
| RegisterFieldBoundary . . . . .    | 36 |
| RegisterParticleBoundary . . . . . | 36 |
| RNG_State . . . . .                | 37 |





## Chapter 2

# Class Index

### 2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

|  |    |
|--|----|
| <a href="#">BC_F_External</a>  | 5  |
| <a href="#">BC_F_Periodic</a>  | 6  |
| <a href="#">BC_Field</a>   |    |
| Class which defines a field boundary condition                           | 7  |
| <a href="#">BC_P_Periodic</a>  | 8  |
| <a href="#">BC_P_Reflecting</a>  | 9  |
| <a href="#">BC_Particle</a>  |    |
| Class which defines a particle boundary condition                        | 10 |
| <a href="#">Boris</a>  | 11 |
| <a href="#">Depositor</a>  | 11 |
| <a href="#">Domain</a>   | 12 |
| <a href="#">Field_BC_Factory</a>   |    |
| A singleton class to handle registration of field boundaries/            | 13 |
| <a href="#">Field_part</a>   | 14 |
| <a href="#">FieldBC</a>  |    |
| Class for supplying boundary conditions to field grid                    | 14 |
| <a href="#">Grid</a>   |    |
| Class representing grid on which E and B fields and currents are defined | 15 |
| <a href="#">Input</a>  | 25 |
| <a href="#">Input_Info_t</a>   |    |
| Structure storing info in the input file                                 | 26 |
| <a href="#">Interpolator</a>   | 28 |
| <a href="#">Part_BC_Factory</a>  | 29 |
| <a href="#">Particle</a>   | 29 |
| <a href="#">Particle_Compare</a>   | 30 |
| <a href="#">Particle_Handler</a>   |    |
| Class that handles all particle-relevant operations                      | 30 |
| <a href="#">Poisson_Solver</a>   | 31 |
| <a href="#">Pusher</a>   | 34 |
| <a href="#">Random_Number_Generator</a>                                  |    |
| Class that provides methods to generate random numbers                   | 35 |
| <a href="#">RegisterFieldBoundary</a>                                    |    |
| An object which, when instantiated, registers a field boundary condition | 36 |
| <a href="#">RegisterParticleBoundary</a>                                 | 36 |
| <a href="#">Relativistic_Boris</a>                                       |    |
| Relativistic <a href="#">Boris</a> pusher                                | 36 |
| <a href="#">RNG_State</a>  | 37 |

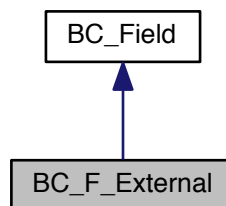


## Chapter 3

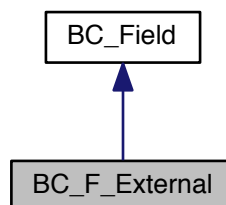
# Class Documentation

### 3.1 BC\_F\_External Class Reference

Inheritance diagram for BC\_F\_External:



Collaboration diagram for BC\_F\_External:



#### Public Member Functions

- **BC\_F\_External** ([Domain](#) \*domain, [Grid](#) \*grids, int side)
- int **completeBC** ()

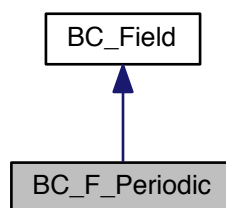
### Additional Inherited Members

The documentation for this class was generated from the following file:

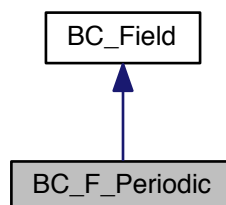
- `src/boundaries/b_fields/bc_f_external.cpp`

## 3.2 BC\_F\_Periodic Class Reference

Inheritance diagram for BC\_F\_Periodic:



Collaboration diagram for BC\_F\_Periodic:



### Public Member Functions

- **BC\_F\_Periodic** ([Domain](#) \*domain, [Grid](#) \*grids, int side)
- int **completeBC** ()

### Additional Inherited Members

The documentation for this class was generated from the following file:

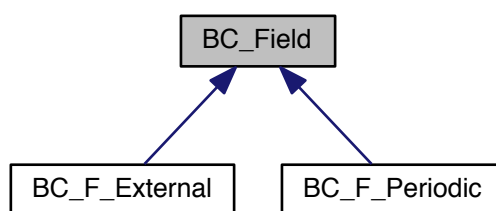
- `src/boundaries/b_fields/bc_f_periodic.cpp`

## 3.3 BC\_Field Class Reference

Class which defines a field boundary condition.

```
#include <fields_boundary.hpp>
```

Inheritance diagram for BC\_Field:



### Public Member Functions

- virtual int **completeBC** (void)=0

### Protected Attributes

- std::string **type\_**
- int **side\_**
- double \* **ghostTmp\_**

#### 3.3.1 Detailed Description

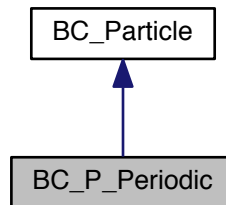
Class which defines a field boundary condition.

The documentation for this class was generated from the following file:

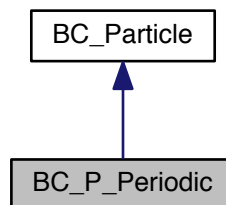
- src/boundaries/fields\_boundary.hpp

### 3.4 BC\_P\_Periodic Class Reference

Inheritance diagram for BC\_P\_Periodic:



Collaboration diagram for BC\_P\_Periodic:



#### Public Member Functions

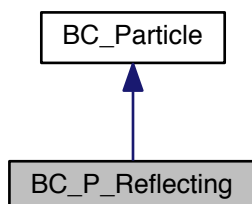
- **BC\_P\_Periodic** ([Domain](#) \*domain, int dim\_Index, short isRight, std::string type)
- void **computeParticleBCs** (std::vector< [Particle](#) > \*pl)
- int **completeBC** (std::vector< [Particle](#) > \*pl)

The documentation for this class was generated from the following file:

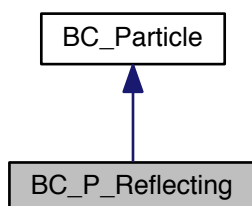
- src/boundaries/b\_particles/bc\_p\_periodic.cpp

## 3.5 BC\_P\_Reflecting Class Reference

Inheritance diagram for BC\_P\_Reflecting:



Collaboration diagram for BC\_P\_Reflecting:



### Public Member Functions

- **BC\_P\_Reflecting** ([Domain](#) \*domain, int dim\_Index, short isRight, std::string type)
- void **computeParticleBCs** (std::vector< [Particle](#) > \*pl)
- int **completeBC** (std::vector< [Particle](#) > \*pl)

The documentation for this class was generated from the following file:

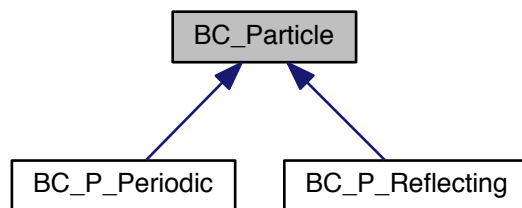
- src/boundaries/b\_particles/bc\_p\_reflecting.cpp

## 3.6 BC\_Particle Class Reference

Class which defines a particle boundary condition.

```
#include <particles_boundary.hpp>
```

Inheritance diagram for BC\_Particle:



### Public Member Functions

- int **computeParticleBCs** (std::vector< [Particle](#) > \*pl)

#### 3.6.1 Detailed Description

Class which defines a particle boundary condition.

Boundary conditions have two stages.

1st stage: Cycling through particle list and determining which particles need to have boundary conditions applied, then applies them.

2nd stage: Perform any more auxilliary computations, including MPI calls, creating new ghost particles, shuffling particles ETC...

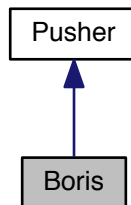
The documentation for this class was generated from the following files:

- src/boundaries/particles\_boundary.hpp
- src/boundaries/particles\_boundary.cpp

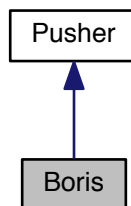


## 3.7 Boris Class Reference

Inheritance diagram for Boris:



Collaboration diagram for Boris:



### Public Member Functions

- int **Step** ([Particle](#) \*part, [Field\\_part](#) \*field, double dt)

The documentation for this class was generated from the following files:

- src/pusher/boris.hpp
- src/pusher/boris.cpp

## 3.8 Depositor Class Reference

### Public Member Functions

- void **deposit\_particle\_J** ([Particle](#) \*part, double \*lcell, double \*cellverts, double \*JObj)
- void **deposit\_particle\_Rho** ([Particle](#) \*part, double \*lcell, double \*cellverts, double \*RhoObj)

The documentation for this class was generated from the following files:

- src/particles/deposit.hpp
- src/particles/deposit.cpp

## 3.9 Domain Class Reference

### Public Member Functions

- **Domain** ([Input\\_Info\\_t](#) \*input\_info)
- int **getnGhosts** (void)
- int \* **getnxyz** (void)
- int \* **getn2xyz** (void)
- double \* **getxyz0** (void)
- double \* **getLxyz** (void)
- double **getmindx** (void)  
*Find minimum grid size.*
- void **mallocGhosts** (int xgsize, int ygsize, int zgsize)  
*Allocate ghost buffers for MPI.*
- void **freeGhosts** (void)
- void **PassFields** ([Grid](#) \*grids, [Input\\_Info\\_t](#) \*input\_info, int sendID)  
*Pass fields across boundaries, or execute physical boundary conditions.*
- double **GetMaxValueAcrossDomains** (double send\_val)  
*Find maximum of values across MPI domains.*
- int \* **getnProctxyz** (void)
- int \* **getmyijk** (void)
- int \* **getNeighbours** ()
- int **getxl** (void)
- int **getyl** (void)
- int **getzl** (void)
- int **getxr** (void)
- int **getyr** (void)
- int **getzr** (void)
- int **ijkToRank** (int i, int j, int k)  
*return rank for assigned i,j,k*
- void **RankToijk** (int rank, int \*myijk)  
*assign value to allocated myijk[3]*

### 3.9.1 Member Function Documentation

#### 3.9.1.1 mallocGhosts()

```
void Domain::mallocGhosts (
    int xgsize,
    int ygsize,
    int zgsize )
```

Allocate ghost buffers for MPI.

xgsize : size of ghost buffer in x direction ygsize : size of ghost buffer in y direction zgsize : size of ghost buffer in z direction

The documentation for this class was generated from the following files:

- src/domain/domain.hpp
- src/domain/domain.cpp
- src/domain/ghosts.cpp
- src/domain/pass\_fields.cpp

## 3.10 Field\_BC\_Factory Class Reference

A singleton class to handle registration of field boundaries/.

```
#include <field_bc_factory.hpp>
```

### Public Types

- typedef [BC\\_Field](#) \*(\* **Factory**) ([Domain](#) \*domain, [Grid](#) \*grids, int side)

### Public Member Functions

- void [constructConditions](#) ([Domain](#) \*domain, [Grid](#) \*grids, const char(\*bound)[NCHAR])
- void **declare** (const std::string &type, Factory factory)
- Factory **lookup** (const std::string &type)
- std::vector< const std::string \* > **types** () const

### Static Public Member Functions

- static [Field\\_BC\\_Factory](#) & **getInstance** ()

#### 3.10.1 Detailed Description

A singleton class to handle registration of field boundaries/.

#### 3.10.2 Member Function Documentation

##### 3.10.2.1 [constructConditions\(\)](#)

```
void Field_BC_Factory::constructConditions (
    Domain * domain,
    Grid * grids,
    const char(*) bound[NCHAR] )
```

Construct the boundary condition array (must be freed!) Takes in an array of size 6.

The documentation for this class was generated from the following files:

- src/boundaries/field\_bc\_factory.hpp
- src/boundaries/field\_bc\_factory.cpp

### 3.11 Field\_part Struct Reference

#### Public Attributes

- double **e1**
- double **e2**
- double **e3**
- double **b1**
- double **b2**
- double **b3**

The documentation for this struct was generated from the following file:

- src/particles/particle.hpp

### 3.12 FieldBC Class Reference

Class for supplying boundary conditions to field grid.

```
#include <fieldBC.hpp>
```

#### Public Member Functions

- **FieldBC** (std::string &fieldStr, int dim, bool edge, double amp, double omega, double phase)
- void [applyBCs](#) (double t, [Grid](#) &grid)  
*Apply boundary condition to grid.*

#### 3.12.1 Detailed Description

Class for supplying boundary conditions to field grid.

Boundary conditions are of form:

$\text{amp} * \cos(\omega * t + \text{phase})$

along plane perpendicular to dimension dim (0 = x, 1 = y, 2 = z) on edge ( false = left, true = right)

fieldStr one of Ex, Ey, Ez, Bx, By, Bz

#### 3.12.2 Member Function Documentation

##### 3.12.2.1 applyBCs()

```
void FieldBC::applyBCs (
    double t,
    Grid & grid )
```

Apply boundary condition to grid.

Uses setFieldAlongEdge method in grid to add field to grid.

The documentation for this class was generated from the following files:

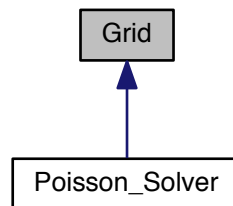
- src/grid/fieldBC.hpp
- src/grid/fieldBC.cpp

### 3.13 Grid Class Reference

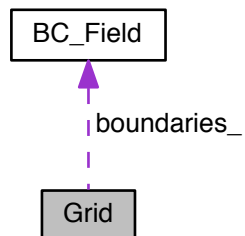
Class representing grid on which E and B fields and currents are defined.

```
#include <grid.hpp>
```

Inheritance diagram for Grid:



Collaboration diagram for Grid:



#### Public Member Functions

- `Grid` (int \*nxyz, int nGhosts, double \*xyz0, double \*Lxyz)  
*Grid constructor.*
- virtual `~Grid` ()  
*Grid destructor.*
- int `evolveFields` (double dt)  
*Evolve Electric and Magnetic fields in time.*
- int `evolveFieldsES` (double dt)  
*Evolve Electric Fields Electrostatically.*
- virtual void `InitializeFields` (void)  
*Initialize E and B fields.*
- void `zeroJ` ()

- sets all components of J to be identically zero*
  - void **zeroRho** ()
- sets rho to be identically zero*
  - void **zeroE** ()
- sets all components of E to be identically zero*
  - void **zeroB** ()
- sets all components of B and B\_tm1 to be identically zero*
  - int **addJ** (int cellID, double \*Jvec)
- Add currents from particle to grid.*
  - int **addRho** (int cellID, double \*Rhovec)
- Add charge from particle to grid.*
  - int **getFieldInterpolatorVec** (int cellID, double \*InterpolatorVec)
- Return vector for field interpolation.*
  - int **getCellID** (double x, double y, double z)
- Get cell ID based on particle position.*
  - int **getCellVertex** (int cellID, double \*xyz)
- Returns vertex corresponding to cell ID.*
  - int **getNumberOfCells** ()
- Get total number of cells in grid.*
  - int **getNumCells3D** (double \*nvec)
- Get # of cells in each dimension of grid.*
  - double **getStepSize** (int dimension)
- Get step size along dimension in grid.*
  - int **setFieldAlongEdge** (std::string &fieldStr, int dim, bool edge, double fieldVal)
- Set field along a certain edge.*
  - int **getGhostVecSize** ()
- returns size of ghost cell data to send*
  - void **getGhostVec** (const int side, double \*ghostVec, int sendID)
- bundles the data in the ghost cells to send*
  - void **setGhostVec** (const int side, double \*ghostVec, int sendID)
- unbundles the data in the ghost cells to send*
  - void **updatePeriodicGhostCells** ()
- updates J,E,B ghost cells in y/z directions with periodic boundary conditions*
  - void **setBoundaryVec** (const int side, const double \*ghostVec)
- void **executeBC** (void)
- Execute field boundary conditions.*
  - void **setBoundaries** (BC\_Field \*\*bc)

## Public Attributes

- double \* **sliceTmp**
- double \* **ghostTmp**

## Protected Member Functions

- double \*\*\* [newField\\_](#) (int ifield)  
*allocates memory for a single field*
- void [deleteField\\_](#) (double \*\*\*fieldPt, int ifield)  
*frees memory for a single field*
- int \*\* [setFieldSize\\_](#) ()  
*constructs and returns fieldSize\_ array*
- void [deleteFieldSize\\_](#) ()  
*deletes fieldSize\_ array*
- int \* [setFieldType\\_](#) ()  
*constructs and returns fieldType\_ array*
- void [deleteFieldType\\_](#) ()  
*deletes fieldType\_ array*
- double \*\*\*\* [setFieldPtr\\_](#) ()  
*constructs and returns fieldPtr\_\_ array*
- void [deleteFieldPtr\\_](#) ()  
*deletes fieldPtr\_ array*
- void [zeroField\\_](#) (const int fieldID)  
*sets field corresponding to fieldID to zero*
- int [sideToIndex\\_](#) (const int side, const int fieldID)  
*function to convert +/- 1 left/right side indicator to index in x direction (description out of date)*
- void [checkInput\\_](#) ()  
*checks validity of input parameters for [Grid](#) constructor*
- void [sliceMatToVec\\_](#) (const int fieldID, const int side, const int offset, double \*vec)  
*slices a physical plane in the specified direction (excludes ghosts)*
- void [unsliceMatToVec\\_](#) (const int fieldID, const int side, const int offset, double \*vec)  
*unslices a physical plane in the specified direction (excludes ghosts)*
- int [setFieldInPlane\\_](#) (int dim, int indx, double \*\*\*field, double fieldVal)  
*Internal method to set field along a plane.*
- **FRIEND\_TEST** (oGridInternalTest, EMWave)
- **FRIEND\_TEST** (oGridInternalTest, EMWaveLong)
- **FRIEND\_TEST** (GridPrivateTest, fieldSizeTest)
- **FRIEND\_TEST** (GridPrivateTest, fieldPtrTest)
- **FRIEND\_TEST** (GridPrivateTest, zeroFields)
- **FRIEND\_TEST** (GridPrivateTest, sideToIndexTest)
- **FRIEND\_TEST** (GridPrivateTest, periodicUpdateTest)
- **FRIEND\_TEST** (GridPrivateTest, ghostVecSizeTest)

## Protected Attributes

- [BC\\_Field](#) \*\* **boundaries\_**
- const int **nx\_**
- const int **ny\_**
- const int **nz\_**
- const int **nGhosts\_**
- const int **nxTot\_**
- const int **nyTot\_**
- const int **nzTot\_**
- const double **x0\_**
- const double **y0\_**
- const double **z0\_**

- const double **Lx\_**
- const double **Ly\_**
- const double **Lz\_**
- const int **iBeg\_**
- const int **jBeg\_**
- const int **kBeg\_**
- const double **dx\_**
- const double **dy\_**
- const double **dz\_**
- const double **idx\_**
- const double **idy\_**
- const double **idz\_**
- const int **maxPointsInPlane\_**
- const int **nFieldsToSend\_**
- const int **ghostVecSize\_**
- const int **nFieldsTotal\_**
- const int **ExID\_**
- const int **EyID\_**
- const int **EzID\_**
- const int **BxID\_**
- const int **ByID\_**
- const int **BzID\_**
- const int **JxID\_**
- const int **JyID\_**
- const int **JzID\_**
- const int **Bx\_tm1ID\_**
- const int **By\_tm1ID\_**
- const int **Bz\_tm1ID\_**
- const int **rhold\_**
- const int **nTypes\_**
- const int **edgeXID\_**
- const int **edgeYID\_**
- const int **edgeZID\_**
- const int **faceXID\_**
- const int **faceYID\_**
- const int **faceZID\_**
- const int **vertID\_**
- double \*\*\* **Ex\_**
- double \*\*\* **Ey\_**
- double \*\*\* **Ez\_**
- double \*\*\* **Bx\_**
- double \*\*\* **By\_**
- double \*\*\* **Bz\_**
- double \*\*\* **Bx\_tm1\_**
- double \*\*\* **By\_tm1\_**
- double \*\*\* **Bz\_tm1\_**
- double \*\*\* **Jx\_**
- double \*\*\* **Jy\_**
- double \*\*\* **Jz\_**
- double \*\*\* **rho\_**
- int \* **fieldType\_**
- int \*\* **fieldSize\_**
- double \*\*\*\* **fieldPtr\_**
- double \* **fieldsContiguous\_**



## Friends

- class **oGridInternalTest**
- class **GridPrivateTest**

### 3.13.1 Detailed Description

Class representing grid on which E and B fields and currents are defined.

[Grid](#) has ghost cells on each face. The ghost cell updating in y and z arises from periodic boundary conditions. x-direction ghost cells allow communication between MPI domains.

Following Yee (1966), electric fields and currents reside on edges, and magnetic fields on faces. Fields are updated using a set of finite-difference equations approximating Ampere's and Faraday's Laws.

A set of getters are available to allow particles to interpolate electric fields based on their position.

### 3.13.2 Constructor & Destructor Documentation

#### 3.13.2.1 Grid()

```
Grid::Grid (
    int * nxyz,
    int nGhosts,
    double * xyz0,
    double * Lxyz )
```

[Grid](#) constructor.

[Input](#) arguments:

nxyz: integer array [nx,ny,nz] where nx is the total number of cells (physical + ghost) in the x direction in the simulation, and the same for ny,nz.

nGhosts: integer number of ghost cells on each side of the domain. This should always be at least 1. Currently the code does not support nGhosts>1, though it may in the future (to take advantage of higher order finite difference and interpolation methods, for instance).

xyz0: integer array [x0,y0,z0] where x0 is the initial x position, and the same for y0,z0

Lxyz0: double array [Lx,Ly,Lz] where Lx is the physical length of each cell in the x direction, and the same for Ly,Lz

#### 3.13.2.2 ~Grid()

```
Grid::~~Grid ( ) [virtual]
```

[Grid](#) destructor.

calls deleteField\_ on each of the double\*\*\* fields

### 3.13.3 Member Function Documentation

#### 3.13.3.1 addJ()

```
int Grid::addJ (
    int cellID,
    double * Jvec )
```

Add currents from particle to grid.

Currents added to cell with ID cellID via input vector of form:

[Jx((0,0,0) -> (1,0,0)), Jx((0,1,0) -> (1,1,0)), Jx((0,1,1) -> (1,1,1)), Jx((0,0,1) -> (1,0,1)),...  
 Jy((0,0,0) -> (0,1,0)), Jy((0,0,1) -> (0,1,1)), Jy((1,0,1) -> (1,1,1)), Jy((1,0,0) -> (1,1,0)),...  
 Jz((0,0,0) -> (0,0,1)), Jz((1,0,0) -> (1,0,1)), Jz((1,1,0) -> (1,1,1)), Jz((0,1,0) -> (0,1,1))]

#### 3.13.3.2 checkInput\_()

```
void Grid::checkInput_ ( ) [protected]
```

checks validity of input parameters for [Grid](#) constructor

asserts necessary conditions on each input (mainly positivity of many parameters). Terminates program if inputs are incorrect.

#### 3.13.3.3 deleteField\_()

```
void Grid::deleteField_ (
    double *** fieldPt,
    int fieldID ) [protected]
```

frees memory for a single field

Uses fieldsContiguous\_ to determine contiguous or noncontiguous deletion method

#### 3.13.3.4 evolveFields()

```
int Grid::evolveFields (
    double dt )
```

Evolve Electric and Magnetic fields in time.

Uses Yee algorithm to advance E and B fields. Assumes Gaussian-style Maxwell equation, with  $c = 1$ .

#### 3.13.3.5 evolveFieldsES()

```
int Grid::evolveFieldsES (
    double dt )
```

Evolve Electric Fields Electrostatically.

Ignores "light wave" contribution (curl terms), effectively only solves poisson equation.

3.13.3.6 `getCellID()`

```
int Grid::getCellID (
    double x,
    double y,
    double z )
```

Get cell ID based on particle position.

Cell ID is uniquely given by  $(ny\_nz\_)*ix + nz\_iy + iz$ .

If particle is in a ghost cell or off the grid entirely, returns

-1 if off (-z), -2 if off (+z)

-3 if off (-y), -4 if off (+y)

-5 if off (-x), -6 if off (+x)

3.13.3.7 `getFieldInterpolatorVec()`

```
int Grid::getFieldInterpolatorVec (
    int cellID,
    double * InterpolatorVec )
```

Return vector for field interpolation.

Based on cellID, return relevant edge E and face B fields and cell origin, in format:

[x, y, z, ...

Ex( ix, iy, iz ), Ex( ix, iy+1, iz ), Ex( ix, iy+1, iz+1 ), Ex( ix, iy, iz+1 ), ...

Ey( ix, iy, iz ), Ey( ix, iy, iz+1 ), Ey( ix+1, iy, iz+1 ), Ey( ix+1, iy, iz ), ...

Ez( ix, iy, iz ), Ez( ix+1, iy, iz ), Ez( ix+1, iy+1, iz ), Ez( ix, iy+1, iz ), ...

Bx( ix, iy, iz ), Bx( ix+1, iy, iz ), ...

By( ix, iy, iz ), By( ix, iy+1, iz ), ...

Bz( ix, iy, iz ), Bz( ix, iy, iz+1 ), ...]

where ix, iy, and iz are the row indices for each of the three dimensions (calculated from the cellID)

3.13.3.8 `getGhostVec()`

```
void Grid::getGhostVec (
    const int side,
    double * ghostVec,
    int sendID )
```

bundles the data in the ghost cells to send

side = +/- 1 for left/right x direction, +/- 2 for y, +/- 3 for z

ghostVec is the vector to store the data in, which must be of length ghostVecSize\_ (can be determined with [getGhostVecSize\(\)](#))

sendID = -1 to get JEB fields, or sendID = an individual field ID (e.g. ExID\_) to get just that field (used for Poisson updating for example)

Stores the data of the E,B,J fields along the specified boundary plane into a 1D array to be sent with a single MPI call. If sendID = -1 (as used in each time step update), stores in order: Ex,Ey,Ez,Bx,By,Bz,Jx,Jy,Jz.

ghostVec can (and should) be unpacked with setGhostVec function

### 3.13.3.9 getGhostVecSize()

```
int Grid::getGhostVecSize ( )
```

returns size of ghost cell data to send

This size is stored in the protected int ghostVecSize\_

It is of length equal to the maximum number of total points in any plane, so that it will be large enough to send the maximum amount of data in a single plane of any of the fields.

### 3.13.3.10 getNumberOfCells()

```
int Grid::getNumberOfCells ( )
```

Get total number of cells in grid.

Includes ghost cells.

### 3.13.3.11 getNumCells3D()

```
int Grid::getNumCells3D (
    double * nvec )
```

Get # of cells in each dimension of grid.

Includes ghost cells.

### 3.13.3.12 getStepSize()

```
double Grid::getStepSize (
    int dimension )
```

Get step size along dimension in grid.

Returns step size along dimension according to; dimension = 0: x dimension = 1: y dimension = 2: z Returns -1 if invalid dimension.

### 3.13.3.13 InitializeFields()

```
void Grid::InitializeFields (
    void ) [virtual]
```

Initialize E and B fields.

Use restart file to set values of initial E,B,J fields

Reimplemented in [Poisson\\_Solver](#).

**3.13.3.14 newField\_()**

```
double *** Grid::newField_ (
    int fieldID ) [protected]
```

allocates memory for a single field

Returns double\*\*\* of size [nx\_+1][ny\_+1][nz\_+1].

First attempts to allocate contiguously. If that fails, issues a warning and attempts to allocate with several calls to new.

**3.13.3.15 setFieldAlongEdge()**

```
int Grid::setFieldAlongEdge (
    std::string & fieldStr,
    int dim,
    bool edge,
    double fieldVal )
```

Set field along a certain edge.

Inputs:

fieldStr: string of format "Ex", "Bz", etc

dim: dimension along which to apply boundary condition

edge: side along which to apply boundary condition

**3.13.3.16 setFieldInPlane\_()**

```
int Grid::setFieldInPlane_ (
    int dim,
    int indx,
    double *** field,
    double fieldVal ) [protected]
```

Internal method to set field along a plane.

Inputs:

dimension perpendicular to plane.

For example, if dim=0 (x direction), then this program set field in one yz plane.

indx along dimension perpendicular to plane.

For example, if dim=0 and indx =14, then set field for the 14th yz plane.

field to set along dimension

value to set field

**3.13.3.17 setFieldPtr\_()**

```
double **** Grid::setFieldPtr_ ( ) [protected]
```

constructs and returns fieldPtr\_\_ array

fieldPtr\_ is an nFieldsTotal\_ array storing each field, so that they can be accessed via fieldID

e.g. int fieldID = ExID\_;

double\*\*\* field = fieldPtr\_[fieldID];

### 3.13.3.18 setFieldSize\_()

```
int ** Grid::setFieldSize_ ( ) [protected]
```

constructs and returns fieldSize\_ array

fieldSize\_ is an ntypes by ndim array storing the number of physical + ghost points in each direction. This is necessary because although all field arrays are allocated to be the same size (nx+1,ny+1,nz+1), due to the different locations of each type of field on the grid (3 types of edge locations, 3 types of face locations, vertices) which leads to differences in the number of points needed for nx,ny,nz cells.

rows correspond to fieldType: 0: x edge (Ex/Jx), 1: y edge (Ey/Jy), 2: z edge (Ez/Jz),

3: x face (Bx) , 4: y face (By) , 5: z face (Bz),

6: vertices (rho)

columns correspond to the direction (0,1,2)=(x,y,z)

### 3.13.3.19 setFieldType\_()

```
int * Grid::setFieldType_ ( ) [protected]
```

constructs and returns fieldType\_ array

fieldType\_ is an nFieldsTotal\_ array of ints storing the type of each field (edgeX, faceZ, vertex, etc).

e.g. int typeOfBx = fieldType\_[BxID\_];

### 3.13.3.20 setGhostVec()

```
void Grid::setGhostVec (
    const int side,
    double * ghostVec,
    int sendID )
```

unbundles the data in the ghost cells to send

side = -/+ 1 for left/right x direction, -/+ 2 for y, -/+ 3 for z

ghostVec is the vector to read the data from, which must be of length ghostVecSize\_ (can be determined with [getGhostVecSize\(\)](#) )

sendID = -1 to set JEB fields, or sendID = an individual field ID (e.g. ExID\_) to set just that field (used for Poisson updating for example)

Sets the data of the E,B,J fields along the specified boundary plane from the 1D array ghostVec to be received with a single MPI call. If sendID = -1 (as used in each time step update), fields are read and set in order↔ : Ex,Ey,Ez,Bx,By,Bz,Jx,Jy,Jz.

ghostVec can (and should) be generated with setGhostVec function

### 3.13.3.21 sideToIndex\_()

```
int Grid::sideToIndex_ (
    const int side,
    const int fieldID ) [protected]
```

function to convert -/+ 1 left/right side indicator to index in x direction (description out of date)

For use with ghost cell methods. side=-1 indicates operations on the left side of the domain, side=+1 indicates operations on the right side of the domain. This method converts side into the correct index i to reference ghost cells on that side of the domain. For instance, called by getGhostVec and setGhostVec. Generalizes to any number of ghost cells so long as iBeg\_ and iEnd\_ are initialized correctly. function to convert (-/+)(1,2,3) side indicator into (left/right)(x,y,z) index of boundary physical data point

Helper function for public ghost cell methods which accept side indicator as argument.

Side < 0 will return index of first physical point, side > 0 will return index of last physical point

abs(side) == 1 returns value in x direction, 2 in y, 3 in z

This function is necessary because different field types have a different number of physical grid points in each direction.

fieldID is a private fieldID such as ExID\_

## 3.13.3.22 sliceMatToVec\_()

```
void Grid::sliceMatToVec_ (
    const int fieldID,
    const int side,
    const int offset,
    double * vec ) [protected]
```

slices a physical plane in the specified direction (excludes ghosts)

mat is 3D array whose real (non-ghost) data on one side will be stored in vec as a 1D array. vec must be of size maxPointsInPlane\_. side is an integer +/- 1 to indicate the location on the left/right side in the x direction, +/- 2 in y, +/- 3 in z. offset is an integer offset from the first/last physical index determined by side (e.g. side=-1 and offset=0 gives the yz plane of the 1st physical grid points in x direction, whereas offset=-1 would have returned the adjacent ghost cells and offset = 3 would have returned the 4th physical yz plane from the left). unsliceMatToVec\_ is the inverse function.

## 3.13.3.23 unsliceMatToVec\_()

```
void Grid::unsliceMatToVec_ (
    const int fieldID,
    const int side,
    const int offset,
    double * vec ) [protected]
```

unslices a physical plane in the specified direction (excludes ghosts)

mat is 3D array whose real (non-ghost) data on one side will be replaced by data in the 1D array vec. vec must be of size maxPointsInPlane\_. side is an integer +/- 1 to indicate the location on the left/right side in the x direction, +/- 2 in y, +/- 3 in z. offset is an integer offset from the first/last physical index determined by side (e.g. side=-1 and offset=0 gives the yz plane of the 1st physical grid points in x direction, whereas offset=-1 would have returned the adjacent ghost cells and offset = 3 would have returned the 4th physical yz plane from the left). sliceMatToVec\_ is the inverse function.

## 3.13.3.24 updatePeriodicGhostCells()

```
void Grid::updatePeriodicGhostCells ( )
```

updates J,E,B ghost cells in y/z directions with periodic boundary conditions

Makes 4 calls each to get/setGhostVec for JEB fields all at once

The documentation for this class was generated from the following files:

- src/grid/grid.hpp
- src/grid/grid.cpp
- src/grid/oGrid.cpp
- src/grid/spookyGrid.cpp

## 3.14 Input Class Reference

```
#include <input.hpp>
```

## Public Member Functions

- int **readinfo** (char \*fname)
- int **checkinfo** (void)  
*Check input self-consistency and sufficiency.*
- [Input\\_Info\\_t](#) \* **getinfo** (void)

### 3.14.1 Detailed Description

Class handling input information

The documentation for this class was generated from the following files:

- src/IO/input.hpp
- src/IO/check.cpp
- src/IO/input.cpp
- src/IO/readinfo.cpp

## 3.15 Input\_Info\_t Struct Reference

Structure storing info in the input file.

```
#include <input.hpp>
```

### Public Attributes

- int **nCell** [NDIM]
- int **nProc** [NDIM]
- int **nt**
- int **restart**
- int **debug**
- int **relativity**
- int **nspecies**
- long **np**
- double **t0**  
*number of particles in each domain*
- double **mass\_ratio** [NSPEC]  
*start time of simulation*
- double **charge\_ratio** [NSPEC]
- double **dens\_frac** [NSPEC]
- double **temp** [NSPEC]
- double **xyz0** [NDIM]
- double **Lxyz** [NDIM]
- char **distname** [NCHAR]
- char **parts\_bound** [2 \*NDIM][NCHAR]  
*name of file containing distribution function*
- char **fields\_bound** [2 \*NDIM][NCHAR]  
*particle boundary conditions for 6 sides of box*



### 3.15.1 Detailed Description

Structure storing info in the input file.

### 3.15.2 Member Data Documentation

#### 3.15.2.1 charge\_ratio

```
double Input_Info_t::charge_ratio[NSPEC]
```

mass of each type of particle in unit of electron mass array of length nspecies eg. in electron-proton plasma mass\_ratio[0]=1; mass\_ratio[1]=1830;

#### 3.15.2.2 debug

```
int Input_Info_t::debug
```

How many previous runs? restart = 0: initial run

#### 3.15.2.3 dens\_frac

```
double Input_Info_t::dens_frac[NSPEC]
```

charge of each type of particle in unit of |e| array of length nspecies eq. in electron-proton plasma chargeratio[0]=-1; chargeratio[1]=1

#### 3.15.2.4 np

```
long Input_Info_t::np
```

How many species of particles eg. nspecies=2 in electron-proton plasma

#### 3.15.2.5 nProc

```
int Input_Info_t::nProc[NDIM]
```

number of cells in each direction

#### 3.15.2.6 nspecies

```
int Input_Info_t::nspecies
```

1: use relativistic pusher 0: use nonrelativistic pusher

### 3.15.2.7 nt

```
int Input_Info_t::nt
```

number of processors to use in each direction

### 3.15.2.8 relativity

```
int Input_Info_t::relativity
```

0: do not print debug statements 1: print minimal debug statements 2: print more debug statements 3: write debug files

### 3.15.2.9 restart

```
int Input_Info_t::restart
```

number of time steps

### 3.15.2.10 temp

```
double Input_Info_t::temp[NSPEC]
```

fractional density, array of length nspecies eg. in quasineutral electron-proton plasma  $\text{frac\_dens}[0]=0.5$ ;  $\text{frac\_dens}[1]=0.5$ ;

### 3.15.2.11 xyz0

```
double Input_Info_t::xyz0[NDIM]
```

Maxwellian temperature in unit of eV if specified array of length nspecies eq. in cold ion and hot electron plasma, possible value  $\text{temp}[0]=100$ ;  $\text{temp}[1]=1.2$ ;

The documentation for this struct was generated from the following file:

- `src/IO/input.hpp`

## 3.16 Interpolator Class Reference

### Public Member Functions

- void **interpolate\_fields** (double \*pos, double \*lcell, double \*cellvars, [Field\\_part](#) \*field)

The documentation for this class was generated from the following files:

- `src/particles/interpolate.hpp`
- `src/particles/interpolate.cpp`

## 3.17 Part\_BC\_Factory Class Reference

```
#include <particle_bc_factory.hpp>
```

### Public Types

- typedef [BC\\_Particle](#) \*(\* **Factory**) ([Domain](#) \*domain, int dim\_Index, short isRight, std::string type)

### Public Member Functions

- [BC\\_Particle](#) \*\* **constructConditions** ([Domain](#) \*domain, const char(\*bound)[NCHAR])
- void **declare** (const std::string &type, Factory factory)
- Factory **lookup** (const std::string &type)
- std::vector< const std::string \* > **types** () const

### Static Public Member Functions

- static [Part\\_BC\\_Factory](#) & **getInstance** ()

#### 3.17.1 Detailed Description

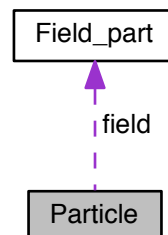
A singleton class to handle registration of particle boundaries

The documentation for this class was generated from the following files:

- src/boundaries/particle\_bc\_factory.hpp
- src/boundaries/particle\_bc\_factory.cpp

## 3.18 Particle Struct Reference

Collaboration diagram for Particle:



## Public Attributes

- double **x** [3]
- double **v** [3]
- double **gamma**
- double **xo** [3]
- double **vo** [3]
- double **dx** [3]
- double **q**
- double **m**
- long **my\_id**
- short **isGhost**
- [Field\\_part](#) field

The documentation for this struct was generated from the following file:

- [src/particles/particle.hpp](#)

## 3.19 Particle\_Compare Class Reference

### Public Member Functions

- **Particle\_Compare** ([Grid](#) \*grid)
- bool **operator()** ([Particle](#) const a, [Particle](#) const b) const

The documentation for this class was generated from the following file:

- [src/particles/particle\\_utils.hpp](#)

## 3.20 Particle\_Handler Class Reference

Class that handles all particle-relevant operations.

```
#include <particle_handler.hpp>
```

### Public Member Functions

- void **Load** ([Input\\_Info\\_t](#) \*input\_info, [Domain](#) \*domain)
- void **Push** (double dt)
- long **nParticles** ()
- void **incrementNParticles** (int inc)
- void **SortParticles** ([Particle\\_Compare](#) comp)
- void **setPusher** ([Pusher](#) \*pusher)
- void **clearGhosts** ()
- void **InterpolateEB** ([Grid](#) \*grid)
- void **depositRhoJ** ([Grid](#) \*grid, bool depositRho)
- std::vector< [Particle](#) > **getParticleVector** ()
- double **computeCFLTimestep** ([Domain](#) \*domain)
- void **setParticleBoundaries** ([BC\\_Particle](#) \*\*bc)
- void **executeParticleBoundaryConditions** ()

### 3.20.1 Detailed Description

Class that handles all particle-relevant operations.

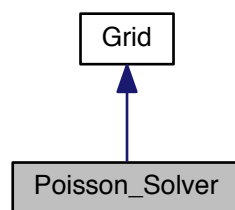
[Particle](#) handler handles all the particle operations. This includes deposition, boundary conditions, particle pushing, and communication between MPI nodes if needed

The documentation for this class was generated from the following files:

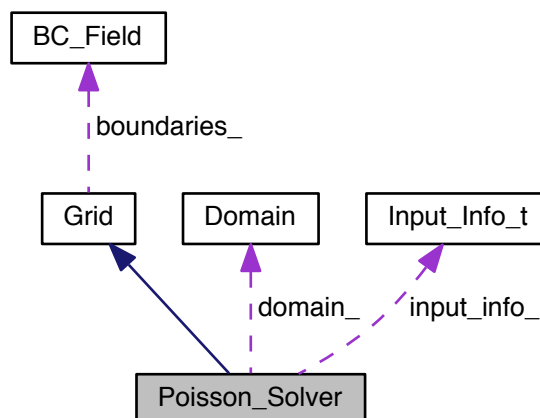
- `src/particles/particle_handler.hpp`
- `src/particles/particle_handler.cpp`

## 3.21 Poisson\_Solver Class Reference

Inheritance diagram for Poisson\_Solver:



Collaboration diagram for Poisson\_Solver:



## Public Member Functions

- **Poisson\_Solver** ([Domain](#) \*domain, [Input\\_Info\\_t](#) \*input\_info)
- void [InitializeFields](#) ()  
*Initialize E and B fields.*
- void [phiToE](#) ()  
*derives E from scalar potential phi:  $E = -\text{grad } \phi$*
- void [AToB](#) ()  
*derives A from vector potential A:  $B = \text{curl } A$*
- void [zeroA](#) ()  
*Set all components of vector potential to zero.*
- void [zeroPhi](#) ()  
*Set all components of scalar potential to zero.*

## Protected Member Functions

- void [run\\_poisson\\_solver\\_](#) (const int fieldID, double \*\*\*u0, double \*\*\*u1, double \*\*\*R, double convergenceTol, double sourceMult)
- void [setPoissonFieldType\\_](#) ()  
*Same as [Grid::setFieldType\\_](#) for phi,A arrays unique to Poisson.*
- void [setPoissonFieldPtr\\_](#) ()  
*Same as [Grid::setFieldPtr\\_](#) for phi,A arrays unique to Poisson.*
- void [phiToESingleComp\\_](#) (const int fieldID, const int dir)  
*Calculates a single component of E from phi.*
- void [AToBSingleComp\\_](#) (const int fieldID, const int dir)  
*calculates a single component of B from A*
- **FRIEND\_TEST** (ConvertPrivateTest, constantPhiTest)

## Protected Attributes

- [Domain](#) \* **domain\_**
- [Input\\_Info\\_t](#) \* **input\_info\_**
- double \*\*\* **phi1\_**
- double \*\*\* **phi2\_**
- double \*\*\* **Ax1\_**
- double \*\*\* **Ay1\_**
- double \*\*\* **Az1\_**
- double \*\*\* **Ax2\_**
- double \*\*\* **Ay2\_**
- double \*\*\* **Az2\_**
- const int **phi1ID\_**
- const int **phi2ID\_**
- const int **Ax1ID\_**
- const int **Ay1ID\_**
- const int **Az1ID\_**
- const int **Ax2ID\_**
- const int **Ay2ID\_**
- const int **Az2ID\_**

## Friends

- class **ConvertPrivateTest**

## Additional Inherited Members

### 3.21.1 Member Function Documentation

#### 3.21.1.1 AToB()

```
void Poisson_Solver::AToB ( )
```

derives A from vector potential A:  $B = \text{curl } A$

Makes three separate calls to AToBSingleComp to perform calculation

#### 3.21.1.2 AToBSingleComp\_()

```
void Poisson_Solver::AToBSingleComp_ (
    const int fieldID,
    const int dir ) [protected]
```

calculates a single component of B from A

fieldID is the field ID of the component to be solved for (BxID\_, ByID\_, or BzID\_)

dir is the direction corresponding to the component being solved for

#### 3.21.1.3 InitializeFields()

```
void Poisson_Solver::InitializeFields (
    void ) [virtual]
```

Initialize E and B fields.

Use restart file to set values of initial E,B,J fields

Reimplemented from [Grid](#).

#### 3.21.1.4 phiToE()

```
void Poisson_Solver::phiToE ( )
```

derives E from scalar potential phi:  $E = -\text{grad } \phi$

Makes three calls to phiToESingleComp which performs actual computation

### 3.21.1.5 phiToESingleComp\_()

```
void Poisson_Solver::phiToESingleComp_ (
    const int fieldID,
    const int dir ) [protected]
```

Calculates a single component of E from phi.

fieldID is a field's fieldID (ExID\_, EyID\_, or EzID\_)

dir is (0,1,2) for (x,y,z) which must match the component of the fieldID being solved for

### 3.21.1.6 zeroA()

```
void Poisson_Solver::zeroA ( )
```

Set all components of vector potential to zero.

Ax1,Ax2,Ay1,Ay2,Az1,Az2 all zero

### 3.21.1.7 zeroPhi()

```
void Poisson_Solver::zeroPhi ( )
```

Set all components of scalar potential to zero.

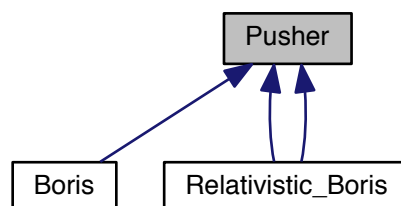
phi1 and phi2 both zero

The documentation for this class was generated from the following files:

- src/poisson/poisson.hpp
- src/poisson/convertFields.cpp
- src/poisson/poisson.cpp

## 3.22 Pusher Class Reference

Inheritance diagram for Pusher:





## Public Member Functions

- virtual int **Step** ([Particle](#) \*part, [Field\\_part](#) \*field, double dt)=0

The documentation for this class was generated from the following file:

- src/pusher/pusher.hpp

## 3.23 Random\_Number\_Generator Class Reference

Class that provides methods to generate random numbers.

```
#include <RNG.hpp>
```

## Public Member Functions

- **Random\_Number\_Generator** (long seed)
- double **getUniform** ()
- long **getInteger** (long min, long max)
- double **getStandardNormal** ()
- double **getGaussian** (double mu, double sigma)
- [RNG\\_State](#) \* **getRNGState** ()
- void **setRNGState** ([RNG\\_State](#) \*state)
- void **setUserPDF** (bool isDiscrete, long size, double \*userVal, double \*userProb)
- void **loadUserPDFFromFile** (const bool isDiscrete, const char \*fname)
- double **getUserNumber** ()

### 3.23.1 Detailed Description

Class that provides methods to generate random numbers.

The Random Number generator class uses the ran2 algorithm from Numerical recipes. The algorithm provides fast random numbers over (0,1) exclusive with a period of over  $10^{15}$ .

This is then used in the implementation for numerous other distributions (standard normal, integer...)

This class can also be loaded with a user defined PDF, either discrete or continuous. User provided PDF does not need to be normalized, but must be positive everywhere.

Discrete PDF is treat as a histogram, while the continuous PDF is treated as piecewise linear and continous. The CDF is calculated (simple partial sum for discrete, triangle rule for continuous) and then used for value sampling. This is done using a binary search.

The documentation for this class was generated from the following files:

- src/utls/RNG.hpp
- src/utls/RNG.cpp

### 3.24 RegisterFieldBoundary Struct Reference

An object which, when instantiated, registers a field boundary condition.

```
#include <field_bc_factory.hpp>
```

#### Public Member Functions

- **RegisterFieldBoundary** (const std::string &type, Field\_BC\_Factory::Factory factory)

#### 3.24.1 Detailed Description

An object which, when instantiated, registers a field boundary condition.

The documentation for this struct was generated from the following file:

- src/boundaries/field\_bc\_factory.hpp

### 3.25 RegisterParticleBoundary Struct Reference

#### Public Member Functions

- **RegisterParticleBoundary** (const std::string &type, Part\_BC\_Factory::Factory factory)

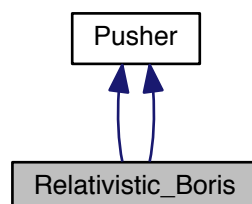
The documentation for this struct was generated from the following file:

- src/boundaries/particle\_bc\_factory.hpp

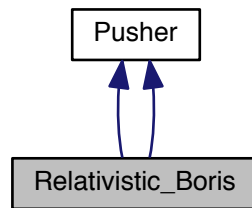
### 3.26 Relativistic\_Boris Class Reference

Relativistic [Boris](#) pusher.

Inheritance diagram for Relativistic\_Boris:



Collaboration diagram for Relativistic\_Boris:



### Public Member Functions

- int **Step** ([Particle](#) \*part, [Field\\_part](#) \*field, double dt)
- int **Step** ([Particle](#) \*part, [Field\\_part](#) \*field, double dt)

#### 3.26.1 Detailed Description

Relativistic [Boris](#) pusher.

Uses the pusher described in "Simulation of beams or plasmas crossing at relativistic velocity"

J.-L. Vay, Phys. Plasmas 15 (5) 2007

The documentation for this class was generated from the following files:

- src/pusher/relativisticBoris.cpp
- src/pusher/relativisticBoris.hpp

## 3.27 RNG\_State Struct Reference

```
#include <RNG.hpp>
```

### Public Attributes

- long int **initialSeed**
- long int **idum**
- long int **idum2**
- long int **iy**
- long int **iv** [RNG\_NTAB]
- double **z0**
- double **z1**
- bool **generate**

#### 3.27.1 Detailed Description

Structure that contains all the information for a random number generator. Can be written/read using fwrite/fread.

The documentation for this struct was generated from the following file:

- src/utils/RNG.hpp

