



$n_1, n_2, n_3, n_4 = g, n_2, n_3, n_4 = g, n_2, n_3, n_4$
 $n_1, g, n_3, n_4 = n_1, g, n_3, n_4$
 $n_1, n_2, g, n_4, n_1, n_2, y_3, n_4$
 $n_1, n_2, n_3, g, n_4, n_1, n_2, n_3, y_4$
 im_1, im_2, im_3, im_4
 $p-f_1, p-f_2, p-f_3, p-f_4$

} Data String

$TL_1, TL_2, TL_3, TL_4 \Rightarrow Data Transfer$

$t_1 := (n_1, n_2, n_3, n_4 \neq \text{NULL})$
 $g_1, n_2, n_3, n_4 = n_1, n_2, n_3, n_4$
 $\text{TLX.SendOverNetwork}(\text{"green"})$
 $p - f - 1 = n_1, n_2, n_3, n_4$
 Same for $t_3, t_5, t_7 + \text{TLX.SendOverNetwork}(\text{"red"})$

$y_1, n_2, n_3, n_4 = y_1, n_2, n_3, n_4$
T11. Send Over Network ("yellow")

$$tg: (n_1, n_2, n_3, y_n \neq NULL)$$

$t_{-f_1} : \text{grad}' (p_{-f_1} \neq \text{NULL}) \text{ \& } i_1(\text{im}1) \neq \text{NULL}$
 $t_2. \text{Dynamic Delay} = "F_{\text{c}} \cdot v_2"$

Same for: $t_{-f_2}, t_{-f_3}, t_{-f_n}$