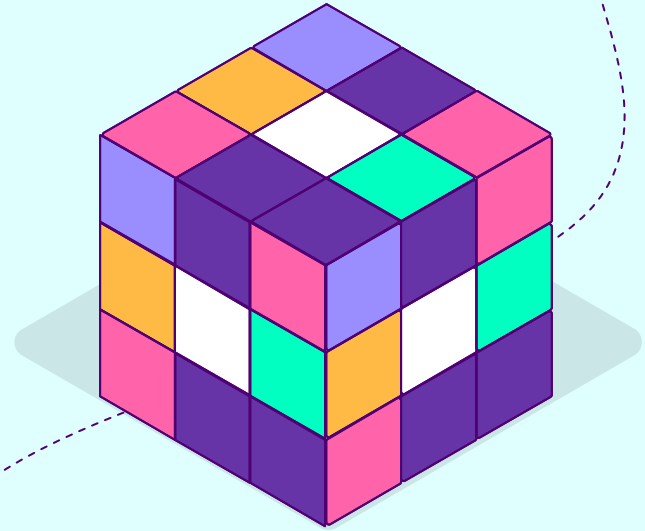
Visual Programming in JupyterLab with Blockly



PyData

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QuantStack
Scientific Computing

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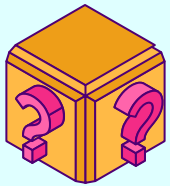
Visual Programming

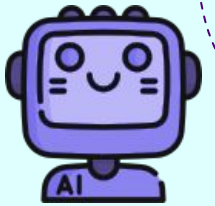
Programming without having to deal with specific syntax



Learn fundamental programming concepts faster

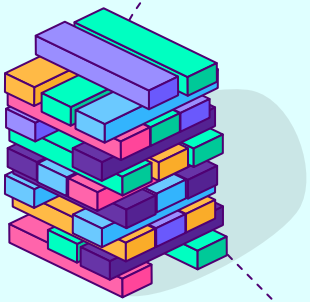
Important part of early computer science education

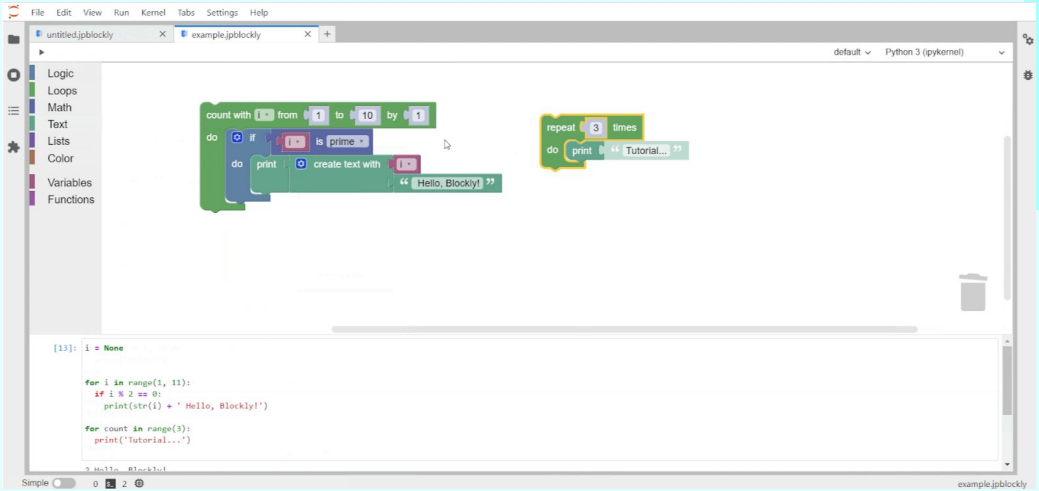
Provide a smoother ramp for learners in the Jupyter ecosystem



Great tool for robotics prototyping

JupyterLab-Blockly

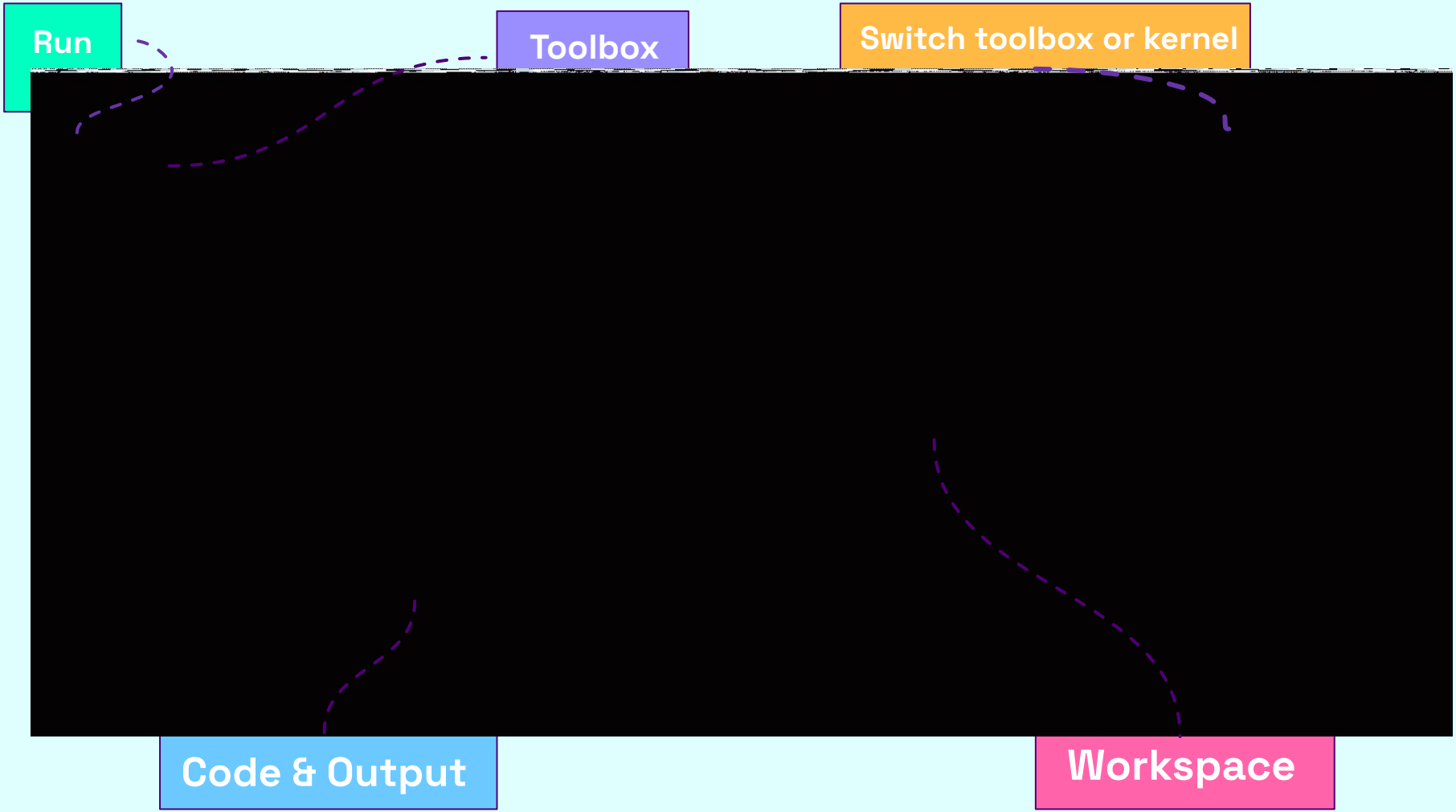




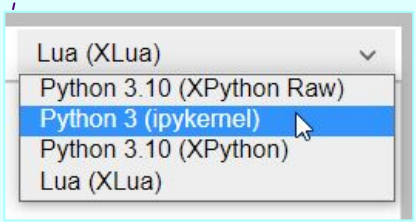
Blockly

An open source library designed by Google to make coding easier and more accessible through block-based visual programming.

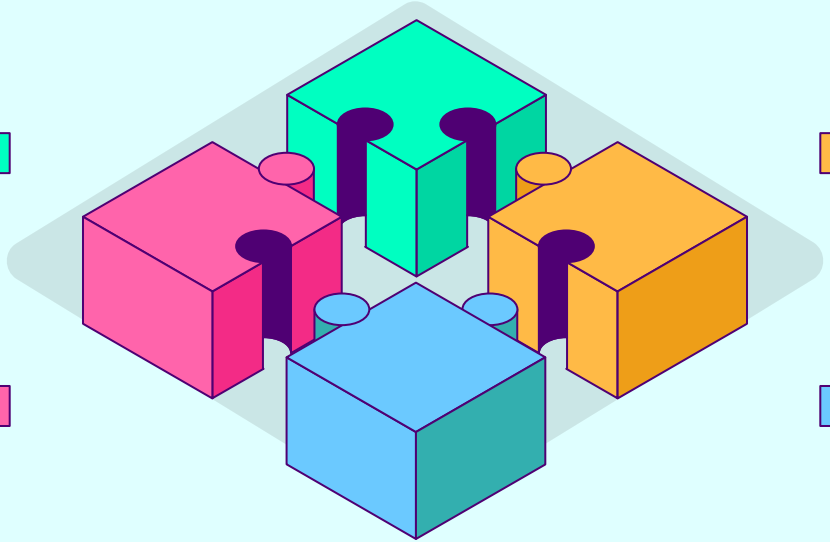
A JupyterLab extension that uses **interlocking graphical blocks** to represent coding concepts, while giving the user full creative freedom, it removes all language specific syntax requirements.


Run
Toolbox
Switch toolbox or kernel
Code & Output
Workspace

Smooth Jupyter Integration



Use **Jupyter kernels** to execute the generated code

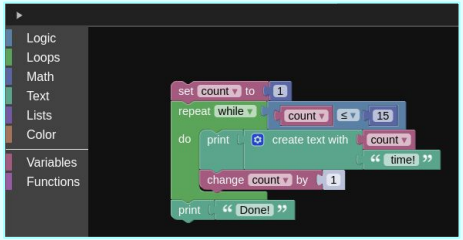


```
[1]: for i = 1, 10, 1 do
       print(i .. ' Hello, Blockly!')
     end

1 Hello, Blockly!
2 Hello, Blockly!
3 Hello, Blockly!
4 Hello, Blockly!
5 Hello, Blockly!
6 Hello, Blockly!
```

Reuse the JupyterLab **code cell** component to display the generated code

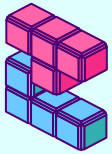
Modify its colors based on your individual **theme** (dark, light or personalized)



Support **translations and localization** (blocks and workspace)


```
mamba install -c conda-forge jupyterlab-blockly
```

jupyterlab-blockly.readthedocs.io



STEP BY STEP how to build on top of JupyterLab-Blockly

```
cookiecutter https://github.com/jupyterlab/extension-cookiecutter-ts
```

Create JL extension from template

01

02

Import JupyterLab-Blockly

```
jlpm add jupyterlab-blockly
```

```
import { IBlocklyRegistry } from 'jupyterlab-blockly';
```

Register new blocks, toolboxes, generators

03

04

Include patches

```
// patches/@jupyterlab+codeeditor+3.4.3.patch

diff --git a/node_modules/@jupyterlab/codeeditor/lib/editor.d
index ffe8d1f..d63b2f8 100644
--- a/node_modules/@jupyterlab/codeeditor/lib/editor.d.ts
+++ b/node_modules/@jupyterlab/codeeditor/lib/editor.d.ts
@@ -44,7 +44,7 @@ export declare namespace CodeEditor {
     /**
      * An interface describing editor state coordinates.
      */
-    interface ICoordinate extends JSONObject, ClientRect {
+    interface ICoordinate extends JSONObject {
     }
     /**
      * A range.
```

Additional configurations

```
// setup.py : 57

setup_args = dict(
  ...
  install_requires=['jupyterlab-blockly>=0.1.1,<0.2']
  ...
)
```

05

06

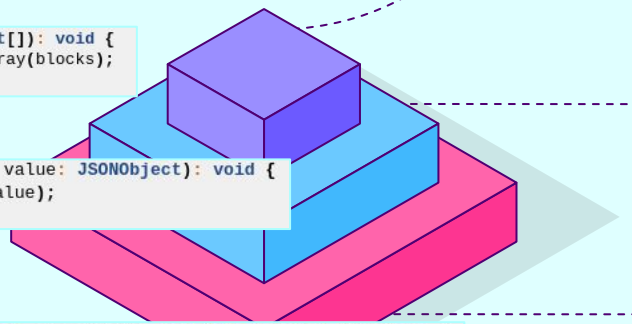
Extra! Use conda to package the extension for easier installation

Importing the IBlocklyRegistry

The class that the JupyterLab-Blockly extension exposes to other plugins, it allows other plugins to register new Toolboxes, Blocks and Generators that users can use in the Blockly editor.

```
registerBlocks(blocks: JSONObject[]): void {
  Blockly.defineBlocksWithJsonArray(blocks);
}
```

```
registerToolbox(name: string, value: JSONObject): void {
  this._toolboxes.set(name, value);
}
```



```
registerGenerator(name: string, generator: Blockly.Generator): void {
  this._generators.set(name, generator);
}
```

01

Register Blocks

Using their JSON definition and generator code in all supported programming languages

02

Register Toolboxes

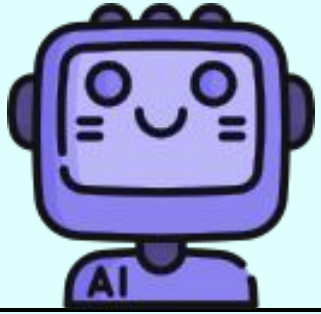
Once registered, the toolbox will appear automatically in your Blockly editor

03

Register Generators

Once registered you can easily switch to it in the Blockly editor

NIRYO
HUMAN - MOTION - ROBOT

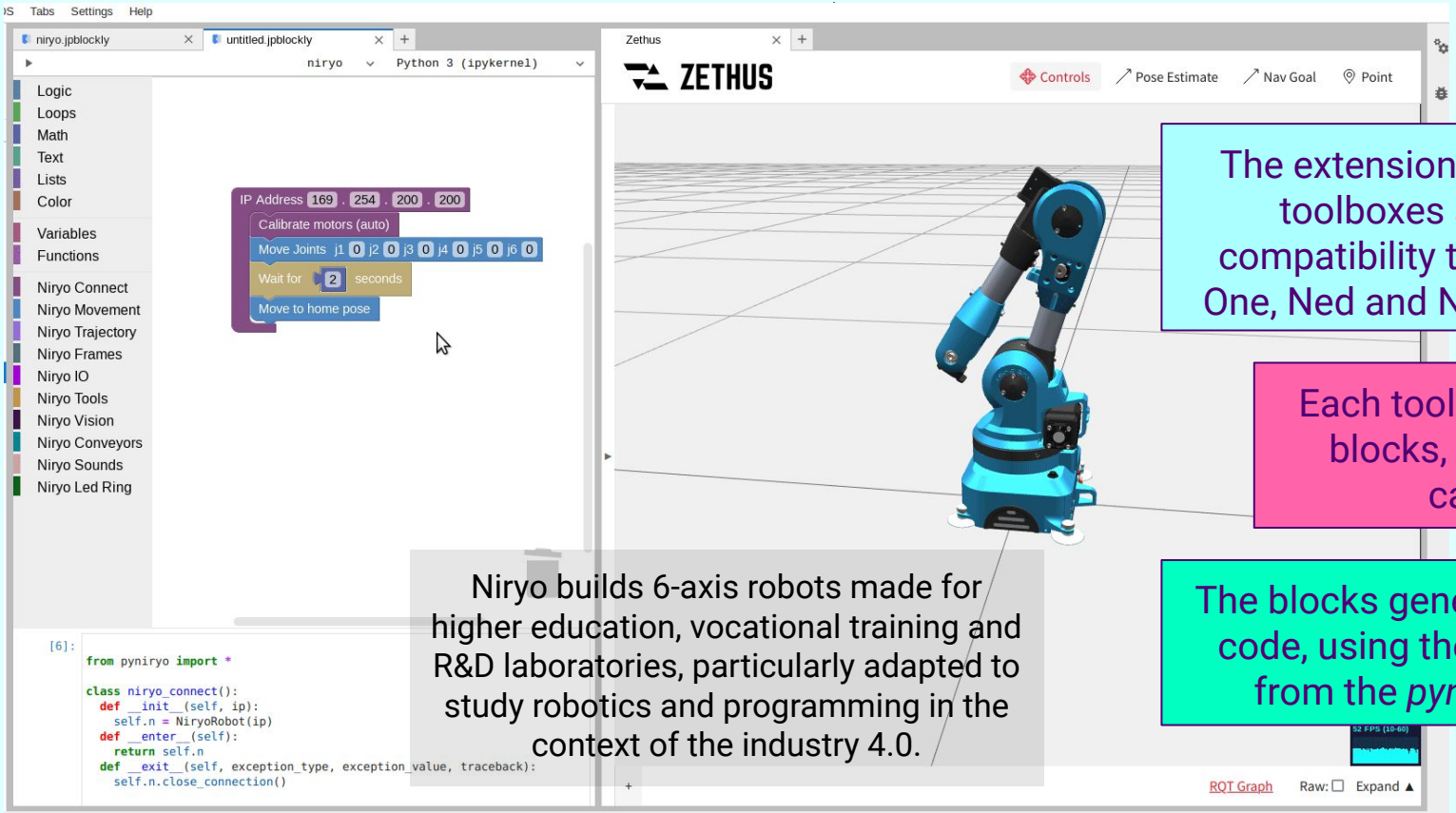


LEGO BOOST BUILD CODE PLAY

Now that you saw how to build on top of JupyterLab-Blockly, let's take a look at the robotics applications we created!

JupyterLab-Niryo-One

NIRYO
HUMAN - MOTION - ROBOT



The extension offers two toolboxes and full compatibility to the Niryo One, Ned and Ned2 robots.

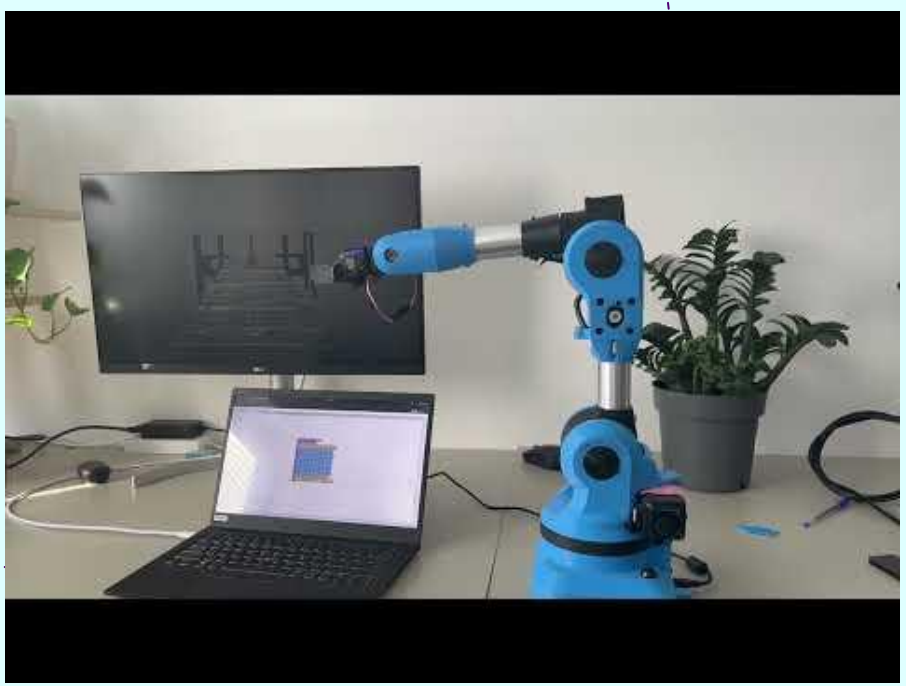
Each toolbox contains 130 blocks, organized in 10 categories.

The blocks generate Python code, using the functions from the *pyniryo* API.

Niryo builds 6-axis robots made for higher education, vocational training and R&D laboratories, particularly adapted to study robotics and programming in the context of the industry 4.0.

Thank you for Zethus configuration to Isabel Paredes

JupyterLab-Niryo-One



JupyterLab-Lego-Boost

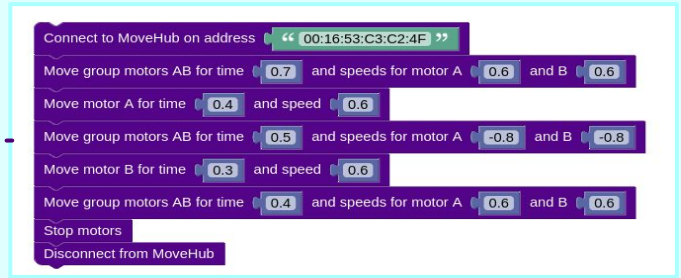
Live Demo!

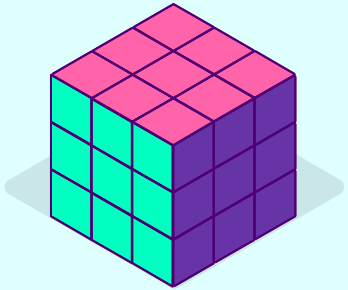
Say hi to Vernie!

- Communicate with the MoveHub (a bluetooth hardware piece)
- Pass commands through Bluetooth Low Energy (BLE) wireless protocol
- Use blocks which generate Python code with the use of the *pylgbst* library

```
from pylgbst.hub import MoveHub
from pylgbst import get_connection_bleak

import time
conn = get_connection_bleak(hub_mac='00:16:53:C3:C2:4F', hub_name=MoveHub.DEFAULT_NAME)
hub = MoveHub(conn)
hub.motor_AB.timed(0.7, 0.6, 0.6)
hub.motor_A.timed(0.4, 0.6)
hub.motor_AB.timed(0.5, (-0.8), (-0.8))
hub.motor_B.timed(0.3, 0.6)
hub.motor_AB.timed(0.4, 0.6, 0.6)
hub.motor_external.stop()
hub.disconnect()
```



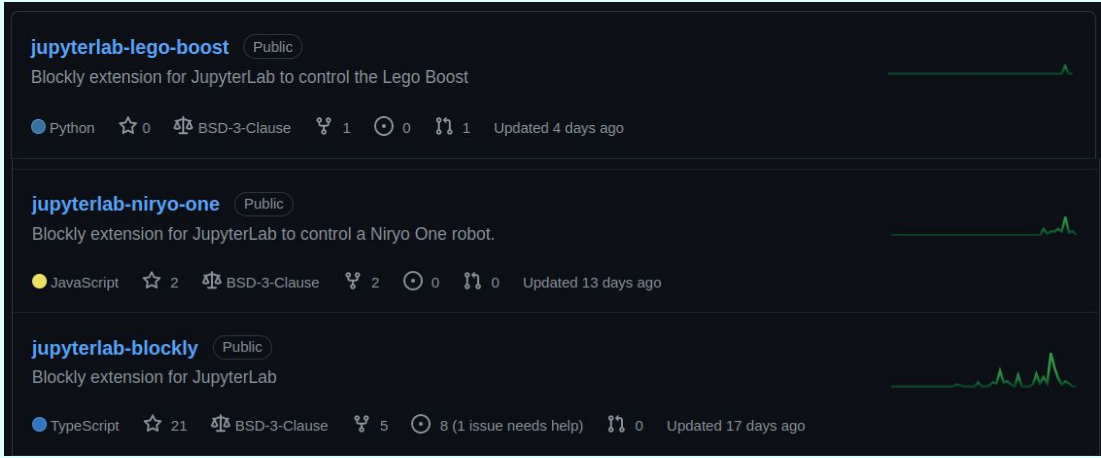


All source code can be found on the **QuantStack Github** page - feel free to give it a try and let us know what you think!

A special thank you to **Carlos Herrero**!

hbcarlos

carlosherrerob



THANK YOU!

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