

Dynamic Programming

Matrix Chain-Products



◆ **Dynamic Programming** is a general algorithm design paradigm.

- Rather than give the general structure, let us first give a motivating example:

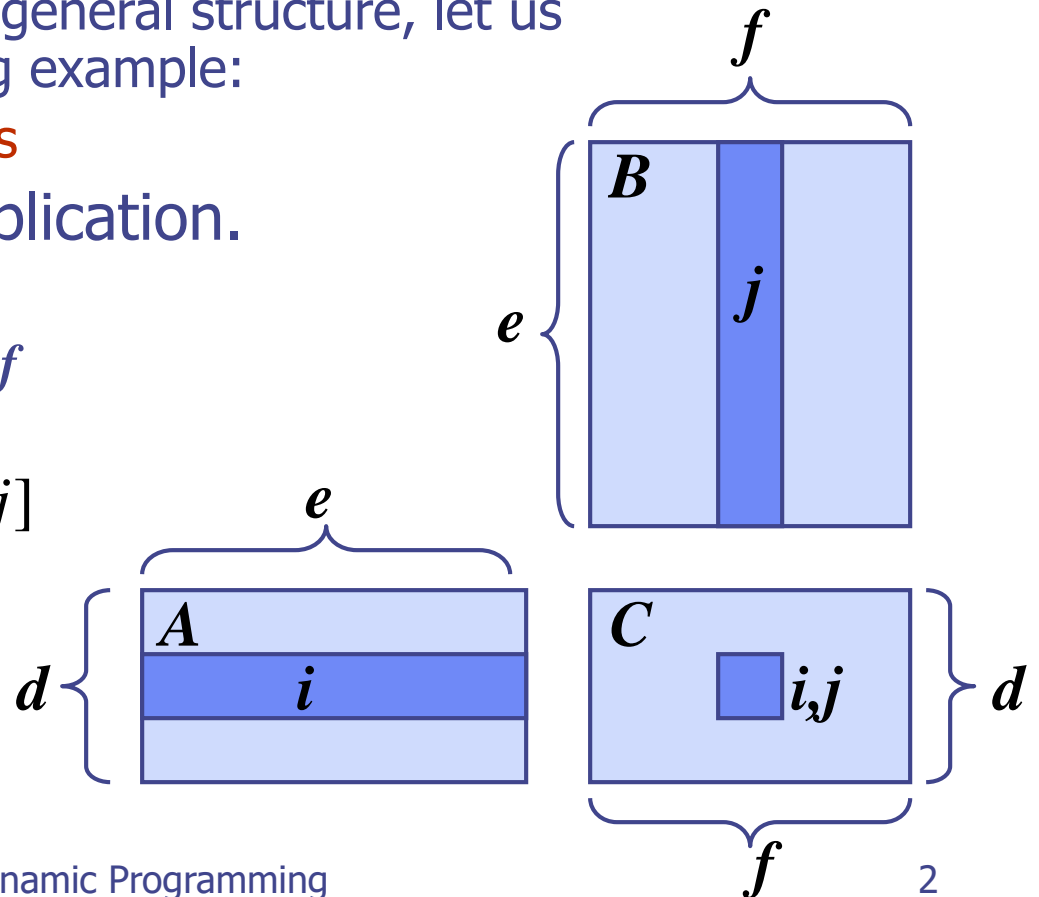
- **Matrix Chain-Products**

◆ **Review: Matrix Multiplication.**

- $C = A * B$
- A is $d \times e$ and B is $e \times f$

$$C[i, j] = \sum_{k=0}^{e-1} A[i, k] * B[k, j]$$

- $O(def)$ time



Matrix Chain-Products



◆ Matrix Chain-Product:

- Compute $A = A_0 * A_1 * \dots * A_{n-1}$
- A_i is $d_i \times d_{i+1}$
- Problem: How to parenthesize?

◆ Example

- B is 3×100
- C is 100×5
- D is 5×5
- $(B * C) * D$ takes $1500 + 75 = 1575$ ops
- $B * (C * D)$ takes $1500 + 2500 = 4000$ ops

An Enumeration Approach



◆ Matrix Chain-Product Alg.:

- Try all possible ways to parenthesize $A=A_0*A_1*\dots*A_{n-1}$
- Calculate number of ops for each one
- Pick the one that is best

◆ Running time:

- The number of paranthesizations is equal to the number of binary trees with n nodes
- This is **exponential**!
- It is called the Catalan number, and it is almost 4^n .
- This is a terrible algorithm!

A Greedy Approach



- ◆ **Idea #1:** repeatedly select the product that uses (up) the most operations.
- ◆ **Counter-example:**
 - A is 10×5
 - B is 5×10
 - C is 10×5
 - D is 5×10
 - Greedy idea #1 gives $(A*B)*(C*D)$, which takes $500+1000+500 = 2000$ ops
 - **But** $A*((B*C)*D)$ takes $500+250+250 = 1000$ ops

Another Greedy Approach



◆ **Idea #2:** repeatedly select the product that uses the fewest operations.

◆ **Counter-example:**

- A is 101×11
- B is 11×9
- C is 9×100
- D is 100×99
- Greedy idea #2 gives $A*((B*C)*D)$, which takes $109989 + 9900 + 108900 = 228789$ ops
- $(A*B)*(C*D)$ takes $9999 + 89991 + 89100 = 189090$ ops

◆ The greedy approach is not giving us the optimal value.

A “Recursive” Approach



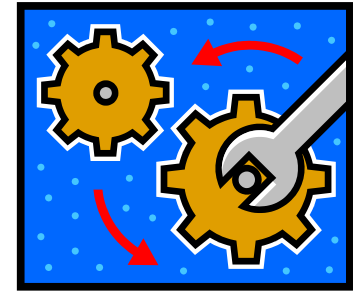
◆ Define **subproblems**:

- Find the best parenthesization of $A_i * A_{i+1} * \dots * A_j$.
- Let $N_{i,j}$ denote the number of operations done by this subproblem.
- The optimal solution for the whole problem is $N_{0,n-1}$.

◆ **Subproblem optimality**: The optimal solution can be defined in terms of optimal subproblems

- There has to be a final multiplication (root of the expression tree) for the optimal solution.
- Say, the final multiply is at index i : $(A_0 * \dots * A_i) * (A_{i+1} * \dots * A_{n-1})$.
- Then the optimal solution $N_{0,n-1}$ is the sum of two optimal subproblems, $N_{0,i}$ and $N_{i+1,n-1}$ plus the time for the last multiply.
- If the global optimum did not have these optimal subproblems, we could define an even better “optimal” solution.

A Characterizing Equation



- ◆ The global optimal has to be defined in terms of optimal subproblems, depending on where the final multiply is at.
- ◆ Let us consider all possible places for that final multiply:
 - Recall that A_i is a $d_i \times d_{i+1}$ dimensional matrix.
 - So, a characterizing equation for $N_{i,j}$ is the following:

$$N_{i,j} = \min_{i \leq k < j} \{ N_{i,k} + N_{k+1,j} + d_i d_{k+1} d_{j+1} \}$$

- ◆ Note that subproblems are not independent--the **subproblems overlap**.

A Dynamic Programming Algorithm



- ◆ Since **subproblems overlap**, we don't use recursion.
- ◆ Instead, we construct optimal subproblems "**bottom-up**."
- ◆ $N_{i,i}$'s are easy, so start with them
- ◆ Then do length 2,3,... subproblems, and so on.
- ◆ Running time: $O(n^3)$

Algorithm *matrixChain*(S):

Input: sequence S of n matrices to be multiplied

Output: number of operations in an optimal paranethization of S

for $i \leftarrow 1$ **to** $n-1$ **do**

$N_{i,i} \leftarrow 0$

for $b \leftarrow 1$ **to** $n-1$ **do**

for $i \leftarrow 0$ **to** $n-b-1$ **do**

$j \leftarrow i+b$

$N_{i,j} \leftarrow +\text{infinity}$

for $k \leftarrow i$ **to** $j-1$ **do**

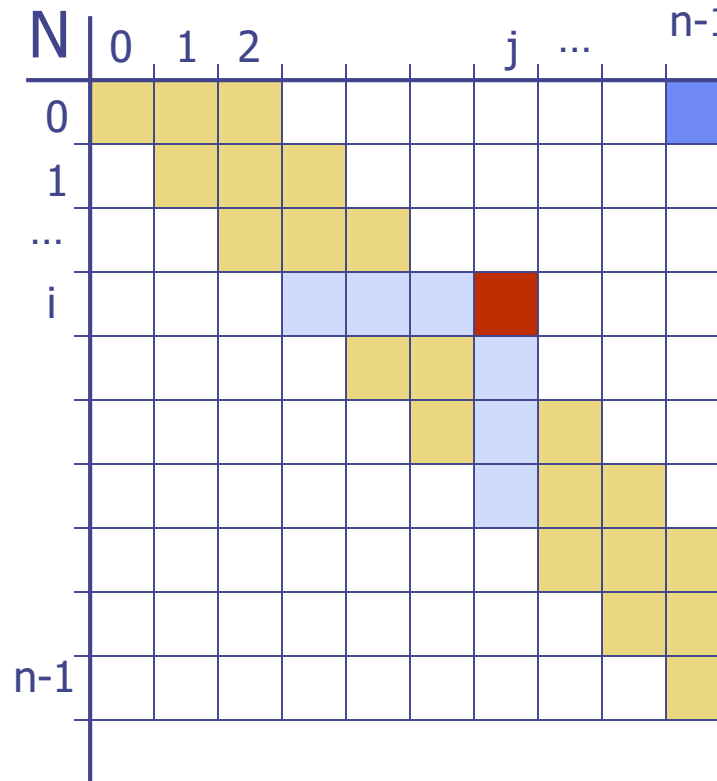
$N_{i,j} \leftarrow \min\{N_{i,j}, N_{i,k} + N_{k+1,j} + d_i d_{k+1} d_{j+1}\}$

A Dynamic Programming Algorithm Visualization



$$N_{i,j} = \min_{i \leq k < j} \{N_{i,k} + N_{k+1,j} + d_i d_{k+1} d_{j+1}\}$$

- ◆ The bottom-up construction fills in the N array by diagonals
- ◆ $N_{i,j}$ gets values from pervious entries in i-th row and j-th column
- ◆ Filling in each entry in the N table takes $O(n)$ time.
- ◆ Total run time: $O(n^3)$
- ◆ Getting actual parenthesization can be done by remembering "k" for each N entry





Matrix Chain algorithm

Algorithm *matrixChain(S)*:

Input: sequence S of n matrices to be multiplied

Output: # of multiplications in optimal parenthesization of S

for $i \leftarrow 0$ to $n-1$ do

$N_{i,i} \leftarrow 0$

for $b \leftarrow 1$ to $n-1$ do // b is # of ops in S

for $i \leftarrow 0$ to $n-b-1$ do

$j \leftarrow i+b$

$N_{i,j} \leftarrow +\text{infinity}$

for $k \leftarrow i$ to $j-1$ do

$\text{sum} = N_{i,k} + N_{k+1,j} + d_i d_{k+1} d_{j+1}$

if ($\text{sum} < N_{i,j}$) then

$N_{i,j} \leftarrow \text{sum}$

$O_{i,j} \leftarrow k$

return $N_{0,n-1}$

◆ **Example: ABCD**

- A is 10×5
- B is 5×10
- C is 10×5
- D is 5×10

N	0	1	2	3
0	0 A	500 ₀ AB	500 ₀ A(BC)	1000 ₂ (A(BC))D
1		0 B	250 ₀ BC	500 ₁ (BC)D
2			0 C	500 ₀ CD
3				0 D



Recovering operations

◆ Example: ABCD

- A is 10×5
- B is 5×10
- C is 10×5
- D is 5×10

N	0	1	2	3
0	0 A	500 ₀ AB	500 ₀ A(BC)	1000 ₂ (A(BC))D
1		0 B	250 ₀ BC	500 ₁ (BC)D
2			0 C	500 ₀ CD
3				0 D

// return expression for multiplying
// matrix chain A_i through A_j

exp(i, j)

if ($i=j$) then
return ' A_i '

// base case, 1 matrix

else

$k = O[i, j]$

// see red values on left

$S1 = \text{exp}(i, k)$

// 2 recursive calls

$S2 = \text{exp}(k+1, j)$

return '(' S1 S2 ')'

Conclusions

- ◆ Dynamic programming is a useful technique for solving certain kind of problems
- ◆ When the solution can be recursively described in terms of partial solutions, we can store these partial solutions and re-use them as necessary
- ◆ Running time
 - Naïve algorithm: $O(4^n)$
 - DP: $O(n^3)$