```
Vec[x_List] := List /@x;
Vec[x__] := Vec[{x}];
V3 =
     Flatten[Table[If[i = j \mid \mid j = k \mid \mid k = i, 0, 1], {i, 1, 3}, {j, 1, 3}, {k, 1, 3}], 1] /
AscendingOp[x_] := Transpose[V3].KroneckerProduct[x, IdentityMatrix[3]].V3;
FusionOp[x_, y_] := Transpose[V3].KroneckerProduct[x, y].V3;
MatrixBasis[i_, j_] := Array[Boole[#1 == i && #2 == j] &, {3, 3}];
HS[x_, y_] := Tr[ConjugateTranspose[x].y]
Transpose[V3].V3 // MatrixForm
 (1 0 0
   0 1 0
 0 0 1
asconbas = AscendingOp[MatrixBasis[First@#, Last@#]] & /@Tuples[{1, 2, 3}, 2];
bas = MatrixBasis[First@#, Last@#] & /@Tuples[{1, 2, 3}, 2];
ascmat = Table[HS[bas[i]], asconbas[j]]], {i, 1, 9}, {j, 1, 9}];
{eigenval, eigenveccoeff} = Eigensystem[ascmat];
eigenvecs = #.bas & /@ eigenveccoeff;
\left\{1, -\frac{1}{2}, -\frac{1}{2}, -\frac{1}{2}, -\frac{1}{2}, -\frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}\right\}
MatrixForm /@ eigenvecs
   \left(\begin{array}{cccc} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{array}\right), \ \left(\begin{array}{cccc} -1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{array}\right), \ \left(\begin{array}{cccc} 0 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{array}\right), \ \left(\begin{array}{ccccc} 0 & 0 & -1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{array}\right),
    \left(\begin{array}{cccc} -\mathbf{1} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{1} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{0} \end{array}\right), \ \left(\begin{array}{cccc} \mathbf{0} & -\mathbf{1} & \mathbf{0} \\ \mathbf{1} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{0} \end{array}\right), \ \left(\begin{array}{cccc} \mathbf{0} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{1} \\ \mathbf{0} & \mathbf{1} & \mathbf{0} \end{array}\right), \ \left(\begin{array}{cccc} \mathbf{0} & \mathbf{0} & \mathbf{1} \\ \mathbf{0} & \mathbf{0} & \mathbf{0} \\ \mathbf{1} & \mathbf{0} & \mathbf{0} \end{array}\right), \ \left(\begin{array}{cccc} \mathbf{0} & \mathbf{1} & \mathbf{0} \\ \mathbf{1} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{0} \end{array}\right) \right\}
eigenvecsbas = Table[HS[bas[i]], eigenvecs[j]]], {i, 1, 9}, {j, 1, 9}];
fusonbas = Table[FusionOp[eigenvecs[i]], eigenvecs[j]]], {i, 1, 9}, {j, 1, 9}];
fusonbasbas = Table[HS[bas[k], fusonbas[i, j]], {i, 1, 9}, {j, 1, 9}, {k, 1, 9}];
fusioncoefficients =
     Table[LinearSolve[eigenvecsbas, fusonbasbas[i, j]], {i, 1, 9}, {j, 1, 9}];
```

fusioncoefficients[8] // MatrixForm

Nmat = Map[Boole@*UnequalTo[0], fusioncoefficients, {3}];

SymmetricMatrixQ@Nmat[#] & /@Range@9

{True, False, True, False, False, False, True, False, False}

FusionOp[eigenvecs[2], eigenvecs[6]] // MatrixForm

$$\begin{pmatrix}
0 & \frac{1}{2} & 0 \\
-\frac{1}{2} & 0 & 0 \\
0 & 0 & 0
\end{pmatrix}$$

checkComm[n_, idx_] :=

And @@ Flatten[Table[n[i, j, k] = n[j, i, k], {i, idx}, {j, idx}, {k, idx}]]; $checkAssoc[n_, idx_] := And @@ Flatten[Table[Sum[n[i, j, k]] n[k, l, m]], \{k, idx\}] = \\$ $Sum[n[j, l, k] n[i, k, m], \{k, idx\}], \{i, idx\}, \{j, idx\}, \{l, idx\}, \{m, idx\}]];$

checkComm[Nmat, {1, 2, 3, 4, 5, 6, 7, 8, 9}]

True

checkAssoc[Nmat, {1, 2, 5}]

False