User stories:

1. As a user
   I want to select objects to be moved automatically
   So that I can automate loading and unloading systems.

2. As a DoBot
   I want to receive target coordinates
   So that I can grab and move objects onto my conveyor belt.

3. As a camera
   I want to detect and identify different shapes, colors and positions
   So that other entities can use this information for their needs.

4. As a GUI
   I want to show information in a clear way and receive information
   So that a user can read and give information to and from the system.