|  |  |  |
| --- | --- | --- |
|  | |  |
| **Programming Languages:** | C++, Embedded C, Python, MatLab, Java | |
| **Robotics Tools:** | Robotic Operating System, Gazebo, V-REP, OpenCV, Keras, PyTorch | |
| **Other Tools:** | Unix ecosystem, Windows kernel development, CUDA/openACC | |
| **Languages**: | English (native), Russian (native), Spanish (proficient) | |

EDUCATION

**Carnegie Mellon University**  *2019 – 2021 (expected)*

* Master of Science in Robotics
* Advisor: Prof. Kris Kitani

**University of Minnesota**  *2015 – 2019*

* Bachelor of Science (Honors) in Computer Engineering, Summa Cum Laude with Distinction

### Thesis: *Indoor Micro-UAV Navigation with Minimal Sensing (*Prof. Volkan Isler & Prof. Derya Aksaray)

### IEEE-Eta Kappa Nu – Omicron Student Chapter – Vice President 2018-2019

# WORK EXPERIENCE

**Nextdroid Robotics, Software Engineering Intern** *Summer 2018*

* Achieved sensorless high-precision motor speed control for subsea robotic platform
* Co-developed high-accuracy image processing pipeline on military hardware
* Designed data storage architecture using Ruby/AWS for secure client data processing

**National Instruments, Software Engineering Intern**  *Summer 2017*

* Implemented network interfaces for measurement device drivers
* Developed encryption schemes for device firmware/driver communication

**Robotic Sensor Network Laboratory, Research Assistant** *2015-2019*

* Research in autonomous robotic rendezvous problems
* Development of GPS-denied micro-UAV platform for agricultural monitoring

**Department of Civil Engineering, Computer Science Research Assistant** *2015-2016*

* Massively parallelized state-of-art wave algorithms & designed MN Dept. of Transport user interfaces

**Laketrails Base Camp, Guide** *2014-2015*

* Led teenagers on five day canoe trips in Northern Minnesota

PROJECTS

**Gesture Based Micro-UAV Control**  *Fall 2017*

* High precision gesture tracking to control micro-UAV flight & control language for flight plans

**Micro-UAV Agricultural Monitoring Platform** *2017-2019*

* Fully autonomous system for data collection in restricted environments
* Lightweight (<50g) package for quick and easy deployment

**Contour Plot Software/Wrappers**  *Spring 2016*

* Java software rapidly reads/processes/displays data from ground penetrating radar

**iRobot Create Autonomous Navigation** *Fall 2015*

* C++ implementation of autonomous navigation algorithm with minimal sensing