

Figure 1: test1.sara:  $m_0 = 50p_0$ ,  $m_f = 10p_3 + 10q_0 + 10r_0 + 10q_2 + 10r_2q$

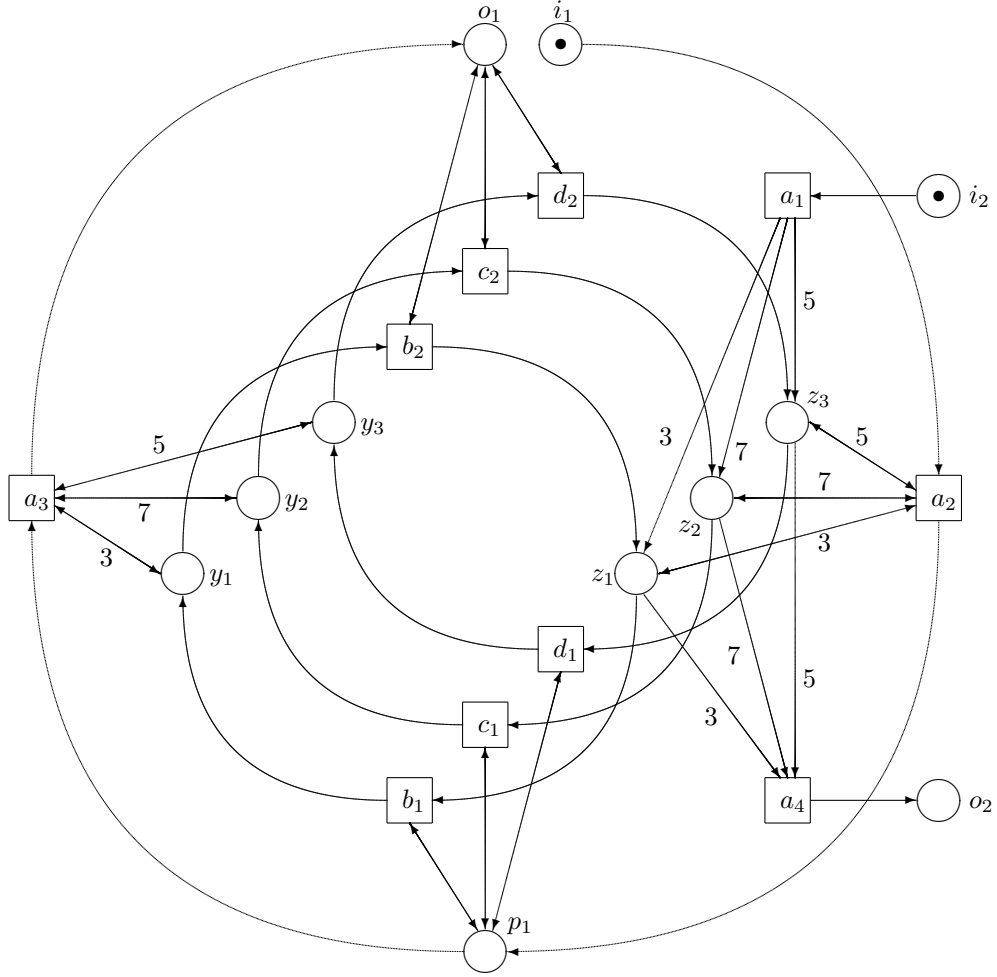


Figure 2: test2.sara:  $m_0 = 1i_1 + 1i_2$ ,  $m_f = 1o_1 + 1o_2$

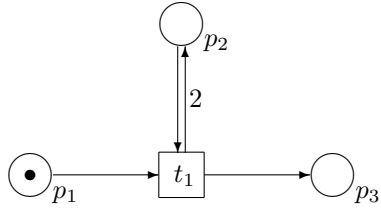


Figure 3: test3.sara:  $m_0 = 1p_1$ ,  $m_f = 1p_2 + 1p_3$ ; test12.sara:  $m_0 = 2p_1$ ,  $m_f = 3p_2 + 1p_3$

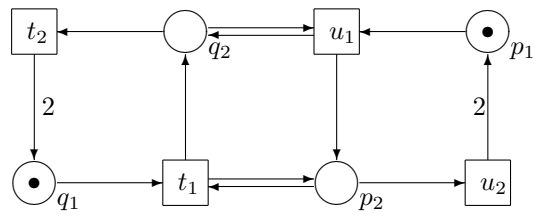


Figure 4: test4.sara:  $m_0 = 1p_1 + 1q_1$ ,  $m_f = 2p_1 + 2q_1$

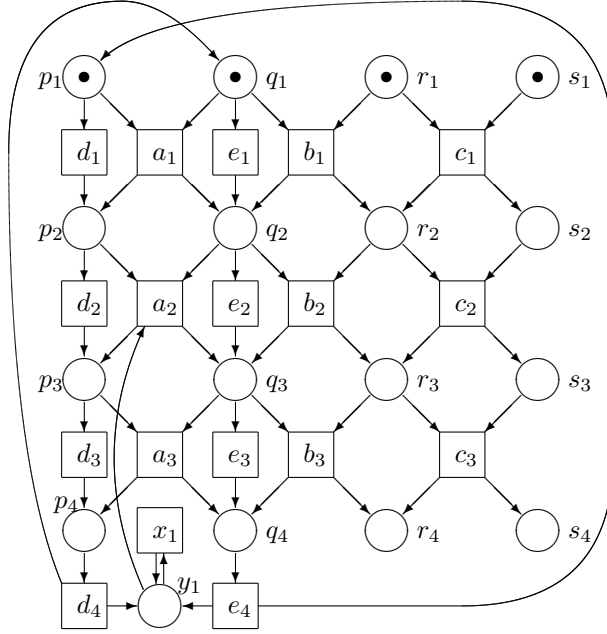


Figure 5: test5.sara:  $m_0 = 1p_1 + 1q_1 + 1r_1 + 1s_1$ ,  $m_f = 1p_4 + 1q_4 + 1r_4 + 1s_4 + 1y_1$

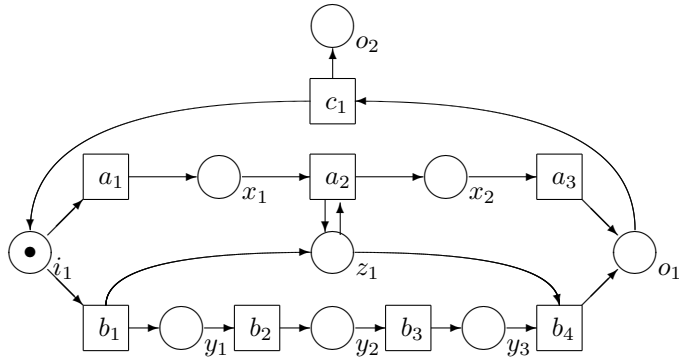


Figure 6: test6.sara:  $m_0 = i_1$ ,  $m_f = o_1 + 5o_2$

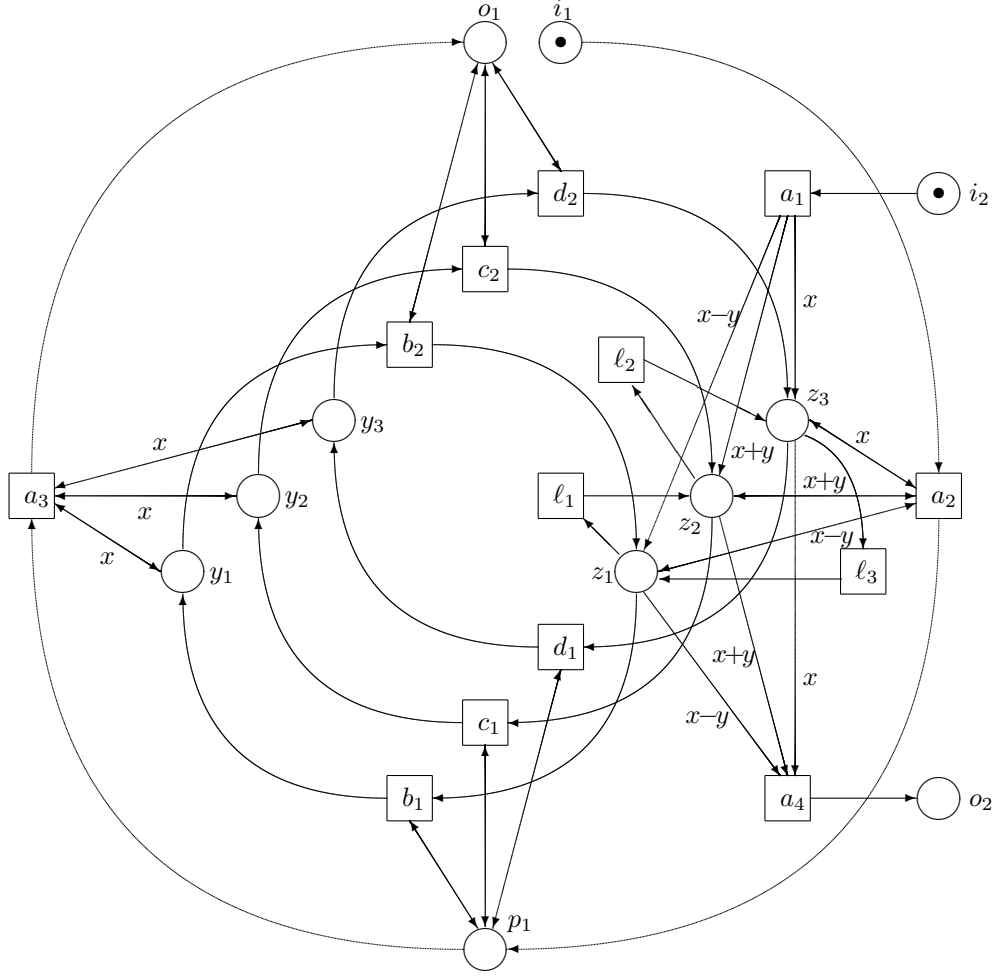


Figure 7: test series 7/8 and test9.sara:  $m_0 = 1i_1 + 1i_2$ ,  $m_f = 1o_1 + 1o_2$ ; multiarcs belong to  $a$ -transitions. For test7-n.sara:  $x = 5n$ ,  $y = 2$ ; for test8-n.sara:  $x = 5n$ ,  $y = 2n$ ; for test9.sara:  $x = 4$ ,  $y = 2$  except for the loop  $a_3$ - $y_2$  that has weight 5. For test10.sara:  $m_0 = 1i_1 + 1i_2$ ,  $m_f = 2o_1 + 1o_2$ ,  $x = 100$ ,  $y = 20$ .

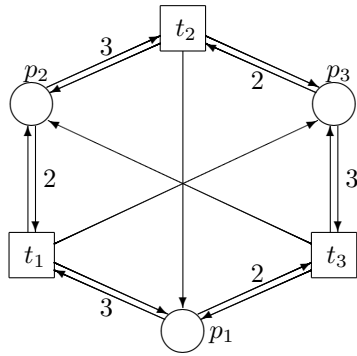


Figure 8: test11.sara:  $m_0 = 5p_1 + 5p_2 + 5p_3$ ,  $m_f = 4p_1 + 4p_2 + 4p_3$ . In test11a: reachability, in test11b: reachability of this or a lower marking, in test11c: coverability