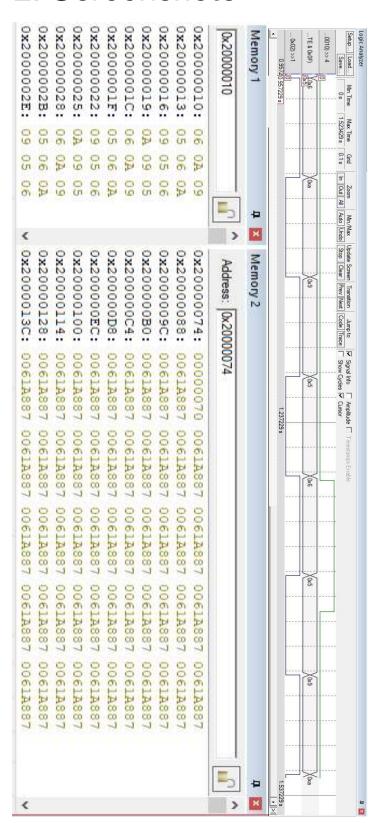
# Lab 4 Deliverables

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## 2. Screenshots



#### 3. Source Code

```
22 SysTick Init
23 ; **-UUU-**Implement this function****
       LDR RO, =NVIC_ST_CTRL_R
24
       MOV R1, #0
25
26
       STR R1, [R0] ; disable Systick during setup
27
       LDR RO, =NVIC ST RELOAD R
28
      LDR R1, =0x00FFFFFF
29
       STR R1, [R0] ; max reload value
30
31
32
       LDR RO, =NVIC ST CURRENT R
33
      MOV R1, #0
34
       STR R1, [R0] ; any write to current clears
35
      LDR RO, =NVIC_ST_CTRL_R
36
      MOV R1, #0x05
37
38
       STR R1, [R0]
39
      BX LR
40
                                       ; return
41
42
43
       ALIGN
                                       ; make sure the end of this section is aligned
       END
44
                                       ; end of file
```

```
77 loop
78 LDR R1,=GPIO_PORTF_DATA_R
79 LDR R4,[R1]
80 EOR R4,R4,#0x02
81 STR R4,[R1];toggle LED
82
```

```
Switch Init
   ; activate clock for Port A
     LDR R1, =SYSCTL RCGCGPIO R
     LDR RO, [R1]
     ORR RO, RO, #0x21 ; Clock for A and F
     STR RO, [R1]
     NOP
                        ; allow time to finish activating
     NOP
   ; set direction register
     LDR R1, =GPIO_PORTA_DIR_R
     LDR RO, [R1]
     BIC RO, RO, #0x10
                        ; Input on PA4
     STR RO, [R1]
    ; 5) enable digital port
     LDR R1, =GPIO PORTA DEN R
     LDR RO, [R1]
     ORR RO, RO, #0x10 ; enable PA4
     STR RO, [R1]
     LDR R1, =GPIO PORTF DIR R
     LDR RO, [R1]
     ORR RO, RO, #0x02
     STR RO, [R1]
     LDR R1, =GPIO PORTF_DEN_R
     LDR R0, [R1]
     ORR RO, RO, #0x02
     STR RO, [R1]
     BX LR
```

```
185 Debug Init
186
     PUSH (RO-R4, LR)
187
        LDR RO,=DataBuffer
188
             R1, #0xFF
189
         MOV
        MOV
190
             R2,#100
191 100 CMP
             R2,#0
192
        BEQ done
193
        STR
             R1, [R0]
194
        ADD RO, #1
        SUB R2,#1
196
        В
              loo ; fill databuffer with 0xFF
197
198 done LDR RO,=TimeBuffer
199 LDR R1, = 0xFFFFFFFF
        MOV R2, #100
200
             R2,#0
201 10
       CMP
        BEQ
202
              fin
             R1, [R0]
203
         STR
204
        ADD R0,#4
205
         SUB R2,#1
        В
206
             lo ; fill timebuffer with 0xFFFFFFFF
207
208 fin LDR RO, = DataPt
       LDR R1,=DataBuffer
209
210
        STR R1, [R0] ; set the datapt
211
        LDR RO,=TimePt
        LDR R1,=TimeBuffer
212
213
        STR R1, [R0] ; set the timept
214
        LDR RO, =minTime
        LDR R1, [R0]
215
```

```
STR R1, [R0] ; makes minTime a very large positive number
217
218
219
         BL SysTick Init
220
         POP {RO-R4, PC}
221
         BX LR
226 Debug Capture
227
            PUSH {RO-R10, LR}
228
            LDR R7, = DataPt
229
            LDR R4, [R7] ; R4 is contents of DataPt
230
            LDR R8, =TimePt
231
            LDR R5, [R8] ; R5 is contents of TimePt
232
            LDR R9, =prevtime
233
            LDR R10, [R9]
234
235
            ; begin check to see if databuffer is full
            LDR R6, = DataBuffer
236
237
            ADD R6, R6, #100
238
            CMP R4, R6
            BEQ full ; check if databuffer full
239
240
241
            LDR R6, =GPIO PORTA DATA R
242
            LDRB RO, [R6]
243
            AND RO, #0x10 ; get only bit 4 of port a data
244
245
            LDR R6, =GPIO PORTE DATA R
246
            LDRB R1, [R6]
            AND R1, #0x0F ; only bits 0-3 of port e
247
            ORR RO, RO, R1 ; combine them
248
249
            STRB R0, [R4] ; store to datapointer address
250
            ADD R4, #1 ; incr datapointer
251
            STR R4, [R7] ; store datapointer new value
252
253
            LDR R6, =NVIC ST CURRENT R
254
            LDR R2, [R6] ; R2 has systick current value
255
```

216

256

LDR R3, =0x00FFFFFF

ORR R1, #0x0FFFFFFF

```
SUB R1,R10,R2 ; find elapse time
258
            AND R1, R1, R3
259
260
            LDR R3,=maxTime
            LDR R11, [R3]
                                ;R11 HAS MAXIMUM TIME DIFF
262
            CMP R1,R11
263
            BLE min
                             ; IF CURRENT VALUE <= MAX; SKIP STORING IT
            STR R1, [R3]
265 min LDR R3,=minTime
           DUE SKID ;IF CURRENT VALUE>=MIN; SKIP STORING IT

MOV R11, #0xFF

CMP R1, R11

BLE skip
                             ;R11 HAS MINIMUM TIME DIFF
266
267
268
269
270
271
                             THIS CMP CHECKS TO SEE IF THE DIFF IS LESS THAN THE FIRST FAULTY VALUE-SKIPS IF THIS IS THE CASE;
272
            STR R1, [R3]
273
274 skip STR R1,[R5] ;store elapse to timebuffer
275 skip STR R1, [R5] ;store elapse to timebuffer
276 skip STR R1, [R5] ;store elapse to timebuffer
          ADD R5,R5, #4 ;advance timepointer to next
STR R5,[R8] ;store back timepointer
276
277
278
            STR R2, [R9] ; current time to previous time
279 full POP {R0-R10, PC}
280 BX LR
```

### 4. Running Estimates

The capture function has 44 lines, requiring around 88 instruction cycles, requiring approx. 1100ns. The program has approx. 3.2e6 lines between captures, approx. 6.4e6 instruction cycles and requiring approx. 80ms to execute. Therefore, the overhead with an 80MHz clock is about 0.001375%, which is negligible.

#### 5. Results

See above screenshots for memory data.