

Wind Turbine Control

B. Control Basics

5. Wind Turbine Control

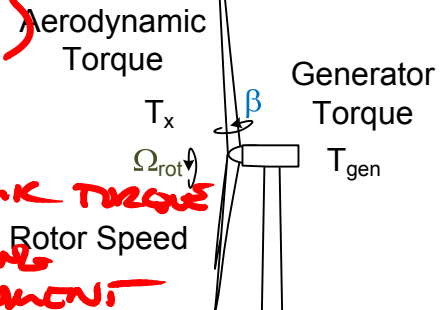
*A WIND TURBINE → MULTIPLE INPUTS
→ MULTIPLE OUTPUTS*

*INPUTS - BLADE PITCH ANGLE
- GENERATOR TORQUE
- YAW ANGLE*

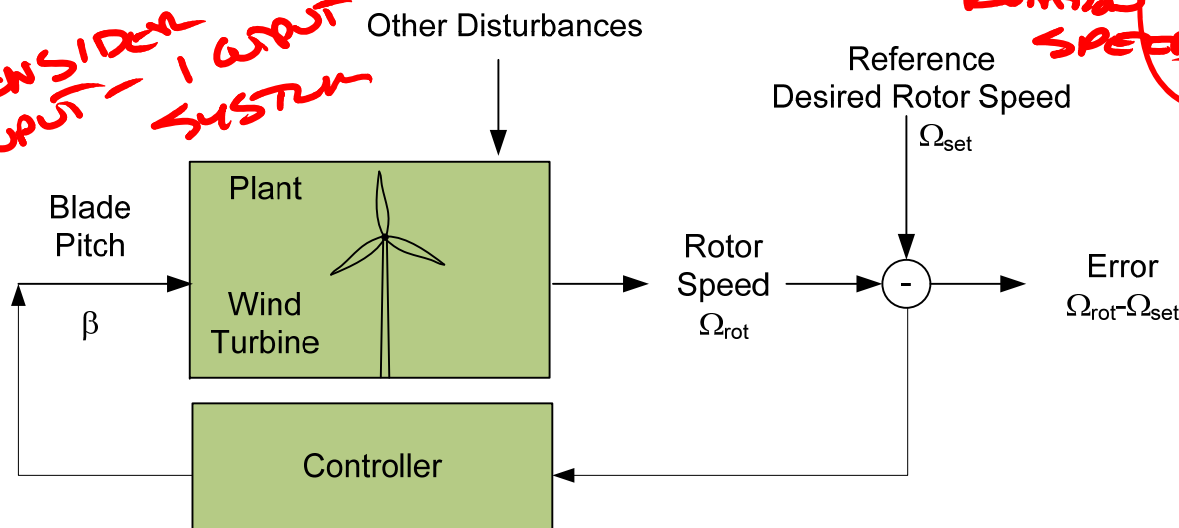
OUTPUTS -

*- AERODYNAMIC TORQUE
- BLADE BENDING
- ROTOR MOMENT
SPEED*

Can increase complexity



CONSIDER 1 INPUT - 1 OUTPUT SYSTEM

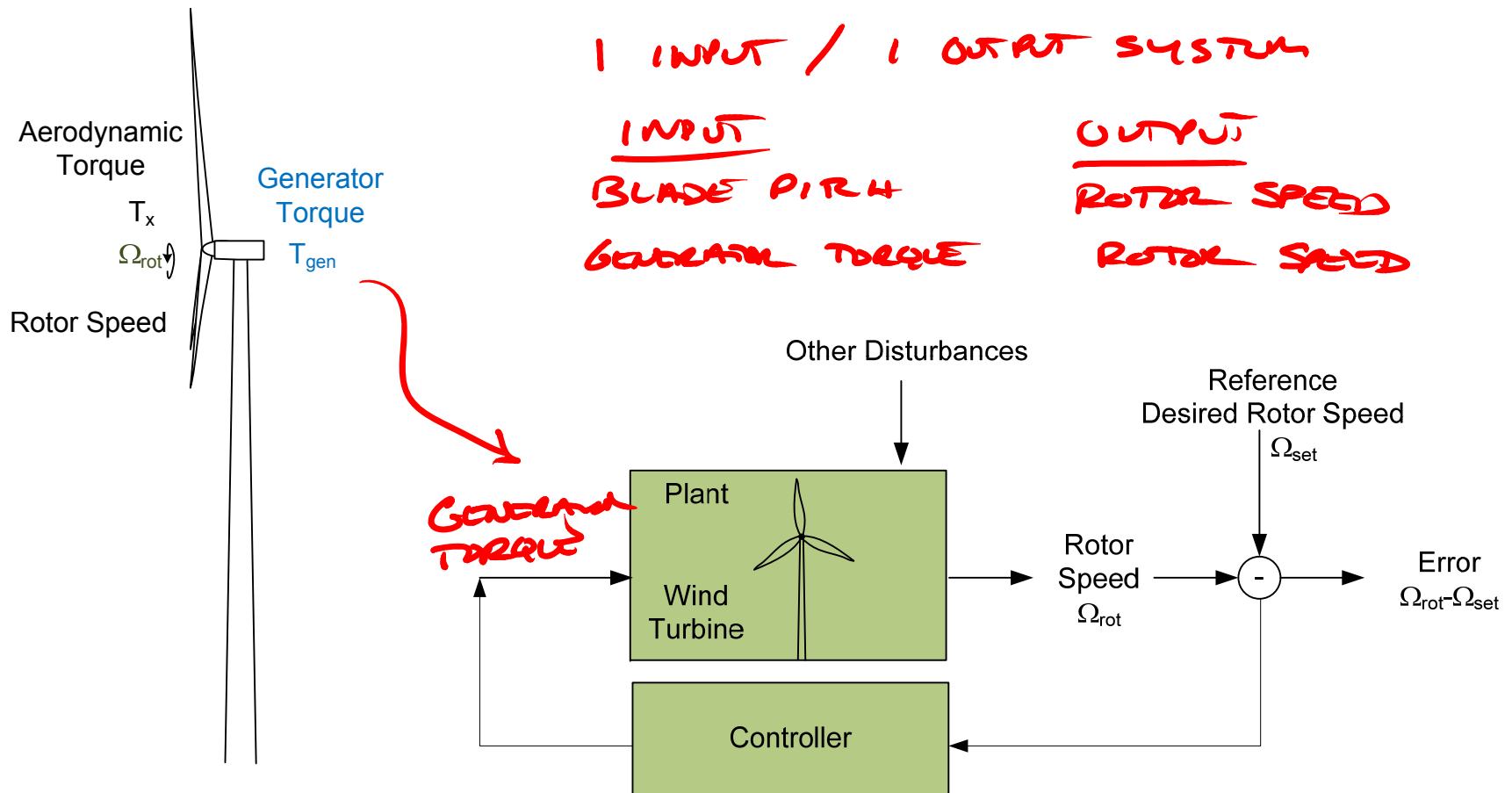


SOME OF THE CONTROLS ARE ONLY USED FOR SUPERLUGARY CONTROL

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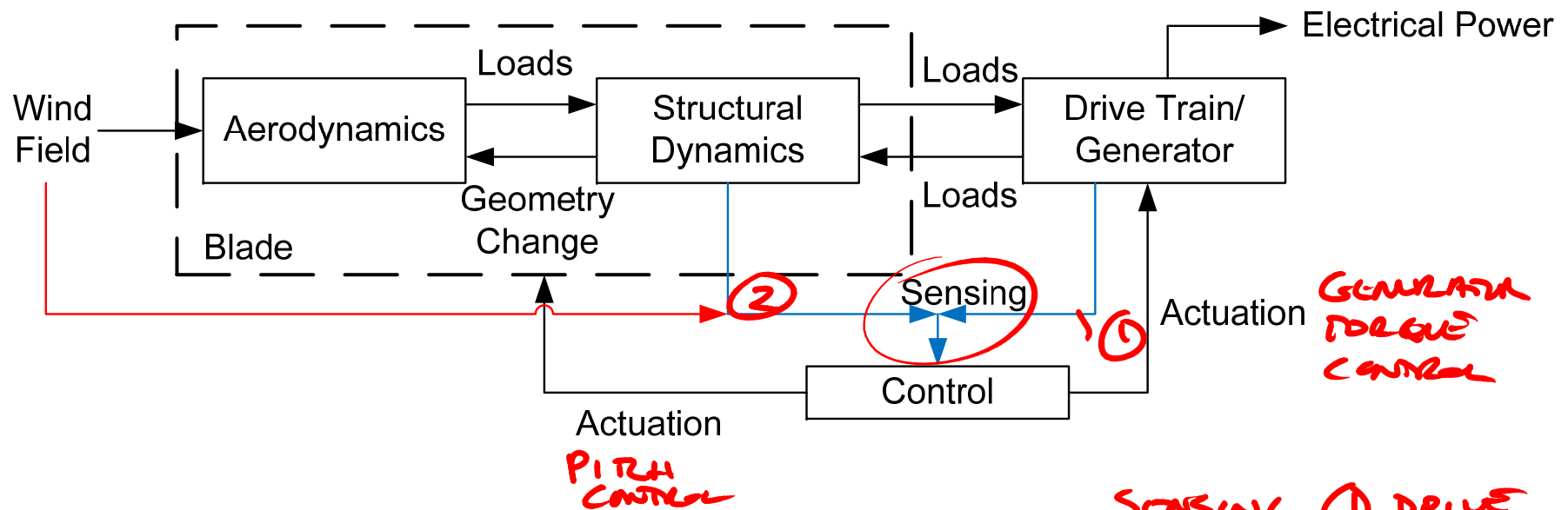


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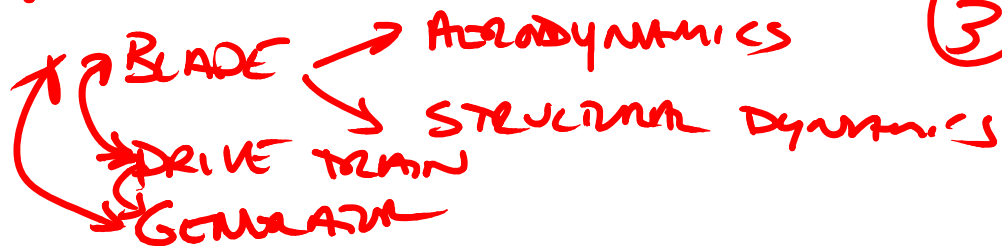
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REAL WIND TURBINE - MUCH MORE COMPLICATED



SYSTEMS INVOLVED



③ INFLOW VELOCITY

SENSING ① DRIVE SHAFT TORQUE / SPEED

② AERODYNAMIC TORQUE
BLADE ROOT BENDING MOMENTS

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CONSIDER A SIMPLE WIND TURBINE

$$X_1 = \frac{1}{3}(M_{\beta,1} + M_{\beta,2} + M_{\beta,3}) \quad \text{BLADE FLAP}$$

$$X_2 = \frac{1}{3}(\dot{M}_{\beta,1} + \dot{M}_{\beta,2} + \dot{M}_{\beta,3}) \quad \text{BLADE FLAP RATE}$$

$$X_3 = \Omega_{rot}$$

$$X_4 = \Omega_{gen}$$

$$X_5 = K(\psi_{rot} - \psi_{gen})$$

$$X_6 = M_{T,F-A}$$

$$X_7 = \dot{M}_{T,F-A}$$

ROTOR ROTATION RATE

GEN ROTATION RATE

TOWER F/A BENDING

TOWER F/A BENDING RATE

Blade Flap
 $M_{\beta,1-3}$

Drive Train
Torsion

$K(\psi_{rot} - \psi_{gen})$

Ω_{rot}

Ω_{gen}

EVEN A
SIMPLE MODEL
CAPTURED

Tower
Fore/Aft
Bend

$M_{T,F-A}$

Wind Turbine Control

C. Typical Control Approaches

1. Constant speed

HISTORICALLY → MOST COMMON DESIGN

GENERATOR DESIGN
GEARBOX DESIGN
ROTOR DESIGN } DETERMINE SPEED

a) Stall regulated

BLADE IS DESIGNED TO CONTROL TORQUE

FIXED PITCH

OPERATE NEAR OPTIMAL λ AT LOW WIND SPEEDS

AS WIND SPEED INCREASES, λ INCREASES

BLADE ROOT STALLS

STALL MOVES AROUND WITH INCREASING WIND SPEED

OPERATION

LIFT & TORQUE LIMITED

DISENGAGE BRAKE

SPIN UP TO OPERATING SPEED (WIND/GENERATOR)

ENGAGE GENERATOR WHEN OPERATING SPEED REACHED

SOME TYPICAL IMPLEMENTATIONS



FAIRLY SIMPLE DESIGN
RIGID BLADES &
STIFF HUB