

Wind Turbine Mechanics

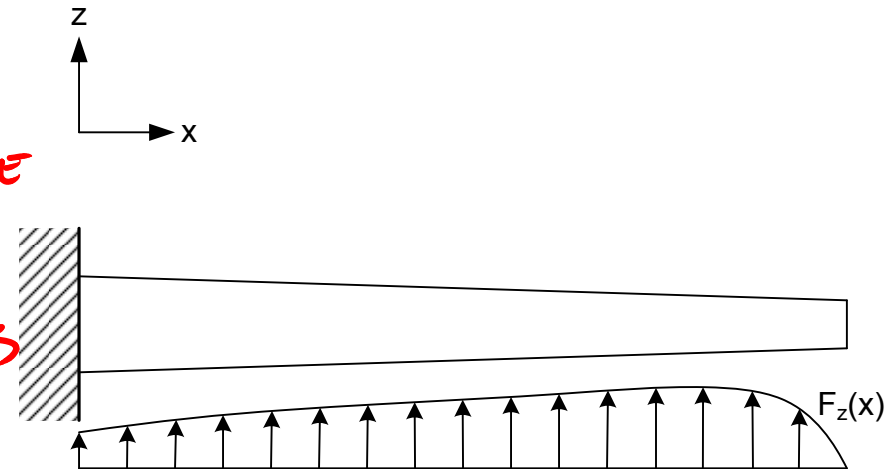
C. Static and Dynamic Modeling of Wind Turbines

WE'VE DISCUSSED FORCES & MOMENTS ACTING ON WIND TURBINES

T, M_y, T_x, M_β

WE'VE DISCUSSED WHERE THEY COME FROM

GRAVITY
INERTIA
AERODYNAMIC } FORCES



WANT TO CONSIDER RESPONSE OF
WIND TURBINE TO THESE LOADS

STATICALLY
DYNAMICALLY

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CONSIDER STATIC MODELING FIRST → BLADE IS IN EQUILIBRIUM

RECALL THAT TURBINE WILL RESPOND STATICALLY TO

→ STEADY LOADS

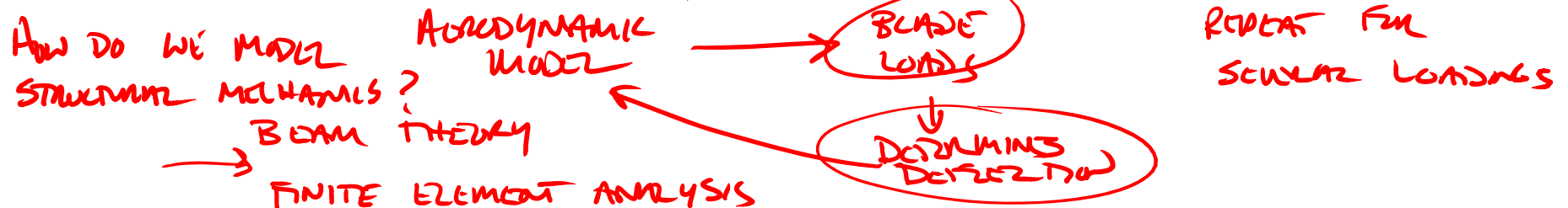
→ "LOW FREQUENCY" UNSTEADY LOADS

OUR INTEREST HERE IS IN

BLADE FORCES & MOMENTS

BLADE DISPLACEMENT (ANGULAR DEFLECTION & DEFLECTION)

EVEN FOR STATIC LOADS, AERODYNAMICS & STRUCTURAL MECHANICS
ARE TIGHTLY COUPLED



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NOW CONSIDER DYNAMIC MODELING

WE ARE INTERESTED IN SAME QUANTITIES

{ FORCES & MOMENTS
DEFLECTIONS

BUT UNDER UNSTEADY LOADING

YIELDS THE EFFECTS OF DYNAMIC LOADING AS WELL
AS COUPLING BETWEEN THE UNSTEADY LOADS & UNSTEADY
RESPONSE

→ FULLED VIBRATIONS → TURBINE RESPONSE

HOW DO WE MODEL THE DYNAMICS

- SIMPLE HINGE/BLADE MODEL
- MDOF MODELS BASED ON STRUCTURAL MODES
- FULLY COUPLED AERO/FEM

COMPLETE MODEL OF TURBINE WILL INCLUDE ALL COMPONENTS

→ SHAFTS, GEARBOX, GENERATOR, TOWER

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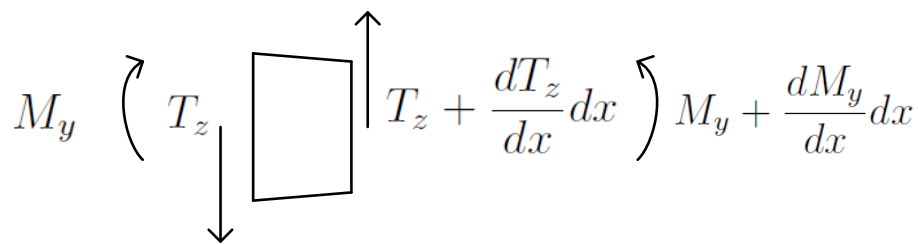
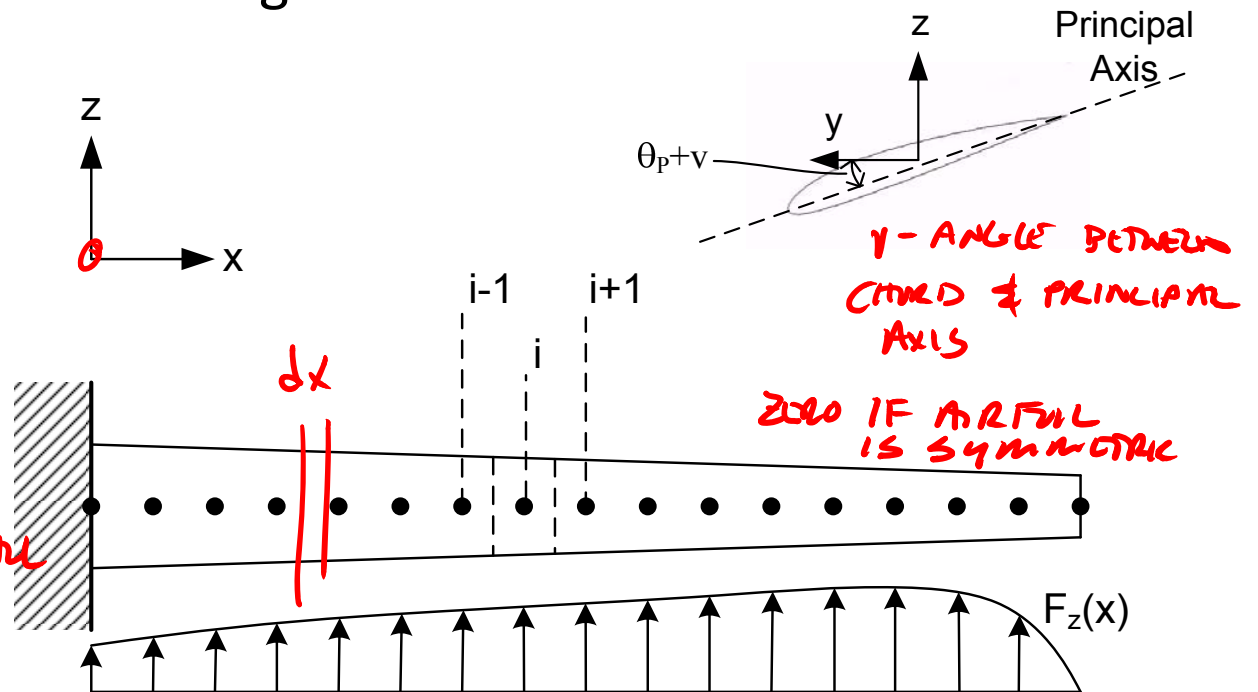
C. Static and Dynamic Modeling of Wind Turbines

1. Beam Theory

APPROACH IS SAME AS
THAT IN BASIC MECHANICS
COURSE

CONSIDER THE BLADE AS
A CANTILEVERED BEAM

CONSIDER FORCES ON A SMALL
ELEMENT FROM THE BEAM



$$\frac{dT_z}{dx} = -F_z(x)$$

T_z DECREASES
WITH x

$$\frac{dM_y}{dx} = T_z$$

F_z COMES FROM
 F_N & F_T
FORCES / ELEMENT

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Similarly

$$\frac{dT_y}{dx} = -F_y(x)$$

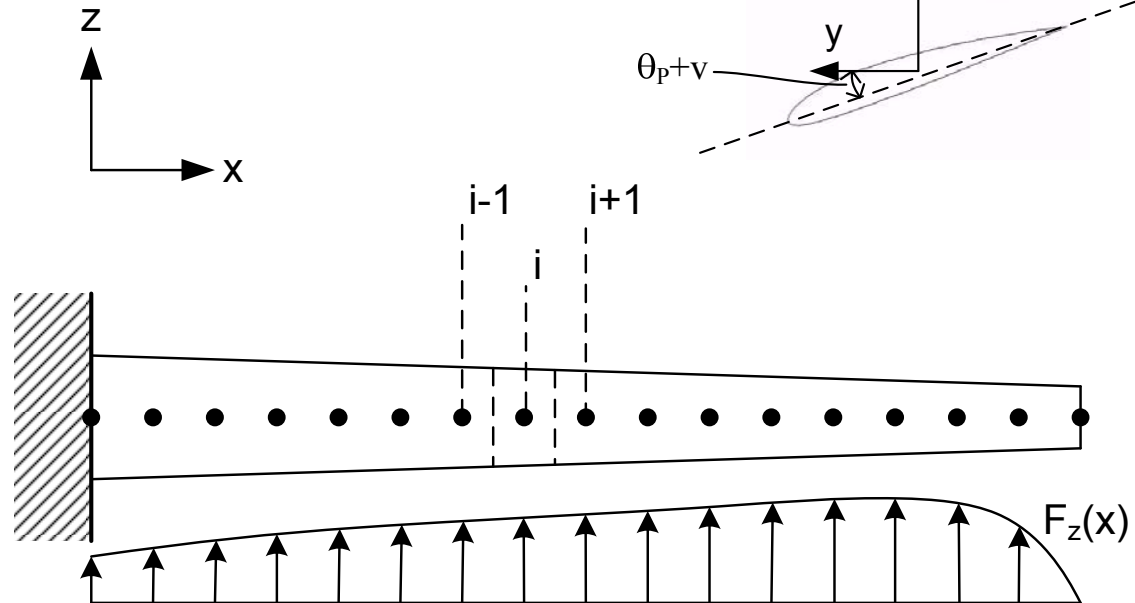
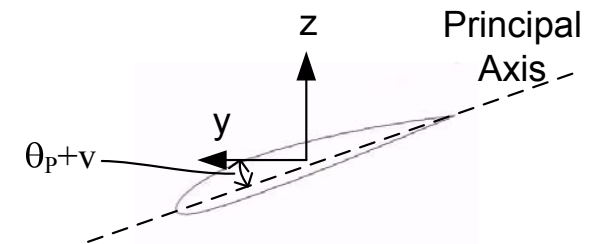
$$\frac{dM_z}{dx} = -T_y$$

From moments we get
BENDING (CURVATURE)

TRANSFER MOMENTS TO PRINCIPAL AXIS

$$M_1 = M_y \cos(\theta_p + \psi) - M_z \sin(\theta_p + \psi)$$

$$M_2 = M_y \sin(\theta_p + \psi) + M_z \cos(\theta_p + \psi)$$



CURVATURES K_1 & K_2

$$K_1 = \frac{M_1}{EI_1} \quad K_2 = \frac{M_2}{EI_2}$$

E - MODULUS OF ELASTICITY
 I_1, I_2 - MOMENT AREA OF INERTIA

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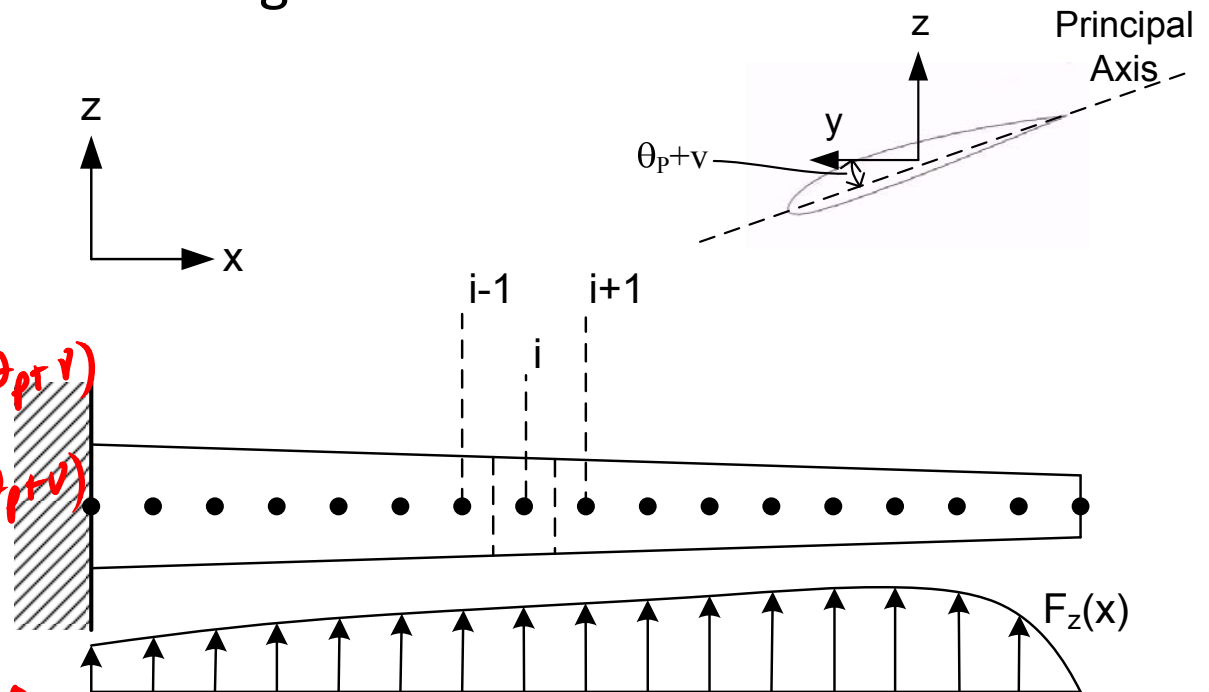
ROTATE CURVATURES BACK TO
X-Z, y

$$K_z = -K_1 \sin(\theta_p + v) + K_2 \cos(\theta_p + v)$$

$$K_y = K_1 \cos(\theta_p + v) + K_2 \sin(\theta_p + v)$$

WITH THIS INFORMATION,
THE ANGULAR DEFLECTIONS θ
DEFLECTIONS u

CAN BE CALCULATED



$$\frac{d\theta_y}{dx} = K_y$$

$$\frac{d\theta_z}{dx} = K_z$$

$$\frac{du_z}{dx} = -\theta_y$$

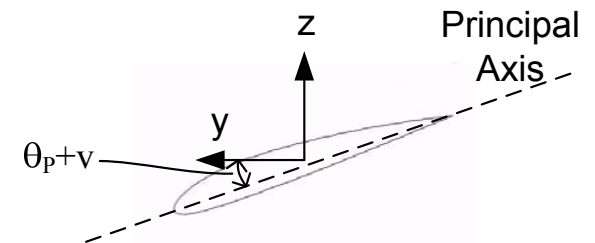
$$\frac{du_y}{dx} = \theta_z$$

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TO SOLVE THESE EQUATIONS, BOUNDARY CONDITIONS ARE REQUIRED

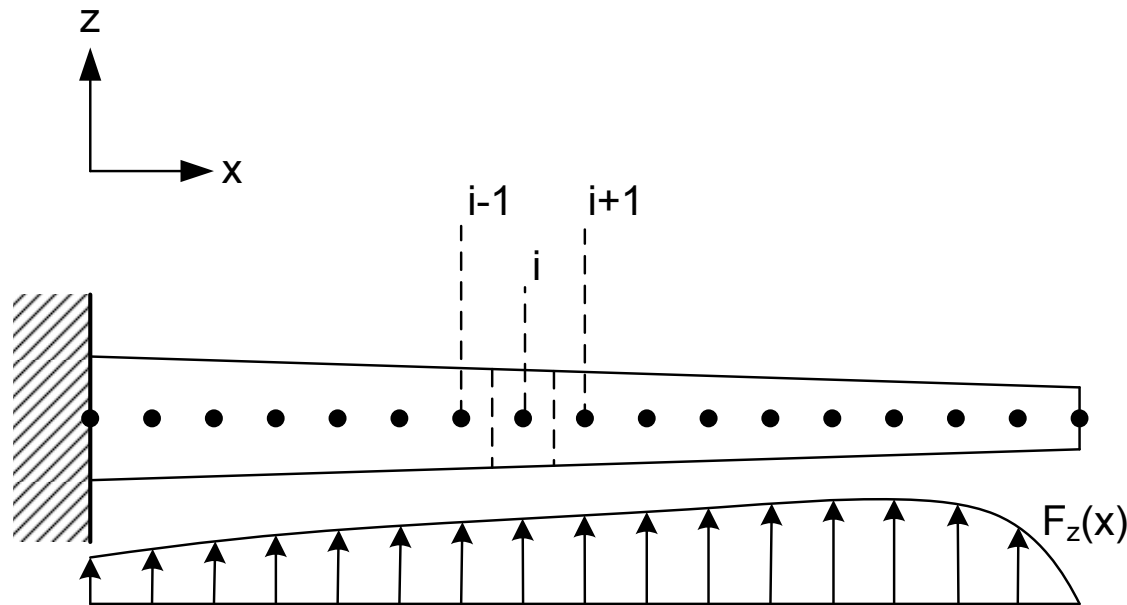


$$\theta_y(x=0) = 0$$

$$\theta_z(x=0) = 0$$

$$u_y(x=0) = 0$$

$$u_z(x=0) = 0$$



$$T_y(x=R) = 0$$

$$T_z(x=R) = 0$$

$$M_y(x=R) = 0$$

$$M_z(x=R) = 0$$

WITH EQUATIONS & BOUNDARY CONDITIONS
→ NOW CAN DETERMINE FORCES, MOMENTS, DEFLECTIONS

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WHY NUMERICAL?

→ DISCRETE LOAD

→ PROFILES & PRINCIPAL AXES CHANGE WITH r

$N \sim N$
↓ ↓

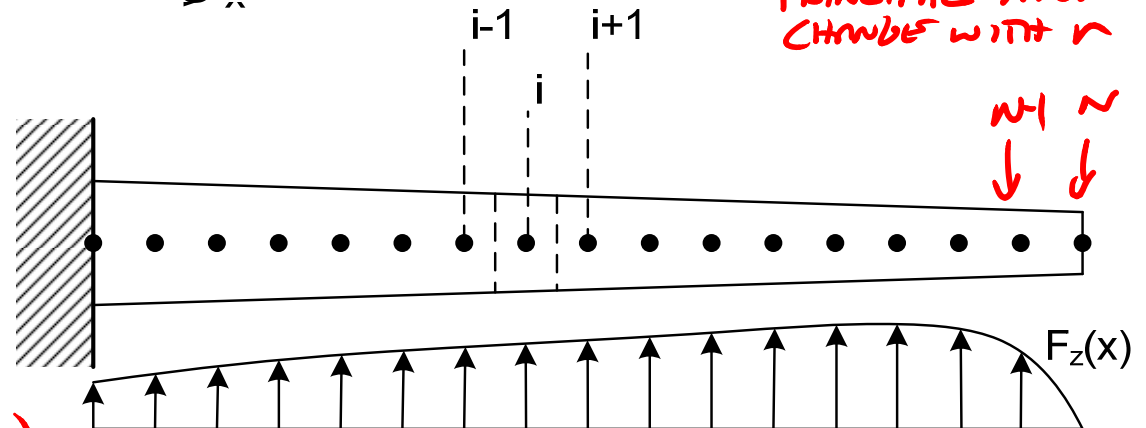
NUMERICALLY SOLVE EQUATIONS

1. DIVIDE BLADE INTO N SECTIONS

2. DETERMINE (OR HAVE PROVIDED) THE LOAD AT EACH POINT
 $F_y(x)$, $F_z(x)$

3. INTEGRATE FORCE & MOMENT EQUATIONS FROM TIP INWARD

→ From $N-1$ INWARD TO $N=1$



$$T_y^{i-1} = T_y^i + \frac{1}{2}(F_y^{i-1} + F_y^i)(x^i - x^{i-1})$$

$$T_z^{i-1} = T_z^i + \frac{1}{2}(F_x^{i-1} + F_x^i)(x^i - x^{i-1})$$

$$M_y^{i-1} = M_y^i - T_z^i(x^i - x^{i-1}) - \left(\frac{1}{6}F_z^{i-1} + \frac{1}{3}F_z^i\right)(x^i - x^{i-1})^2$$

NODE N IS WHERE WE KNOW T , M

$$M_z^{i-1} = M_z^i + T_y^i(x^i - x^{i-1}) + \left(\frac{1}{6}F_y^{i-1} + \frac{1}{3}F_y^i\right)(x^i - x^{i-1})^2$$

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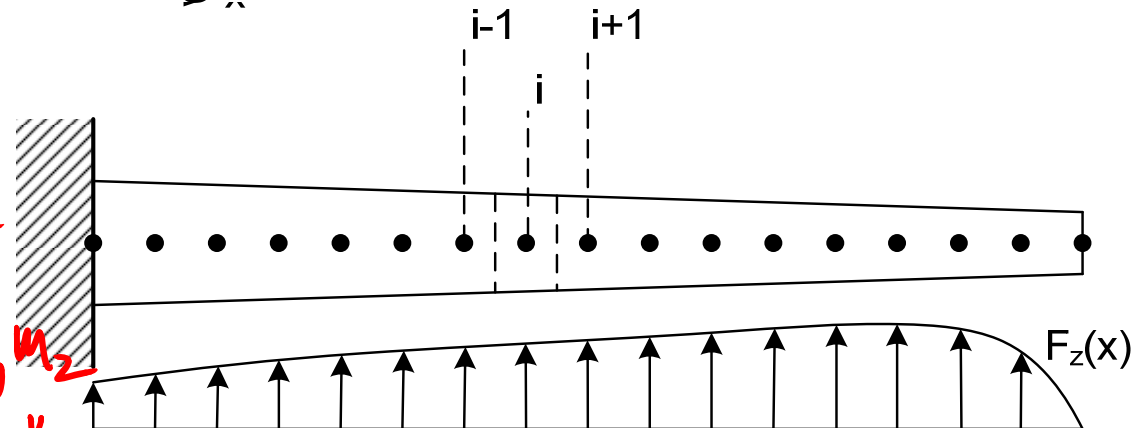
1. Beam Theory

4. DETERMINE CURVATURES

→ AT EACH x_i , TRANSFER
BENDING MOMENTS TO
PRINCIPAL AXES → M_1, M_2

→ DETERMINE CURVATURES κ_1, κ_2

→ TRANSFORM BACK → κ_y, κ_z



$$\theta_y^{i+1} = \theta_y^i + \frac{1}{2}(\kappa_y^{i+1} + \kappa_y^i)(x^{i+1} - x^i)$$

$$\theta_z^{i+1} = \theta_z^i + \frac{1}{2}(\kappa_z^{i+1} + \kappa_z^i)(x^{i+1} - x^i)$$

3. INTEGRATE TO DETERMINE ANGULAR DEFLECTION &

DEFLECTION

$$u_y^{i+1} = u_y^i + \theta_z^i(x^{i+1} - x^i) + \left(\frac{1}{6}\kappa_z^{i+1} + \frac{1}{3}\kappa_z^i\right)(x^{i+1} - x^i)^2$$

START @ ROOT &

INTEGRATE OUTWARD

$$u_z^{i+1} = u_z^i + \theta_y^i(x^{i+1} - x^i) + \left(\frac{1}{6}\kappa_y^{i+1} + \frac{1}{3}\kappa_y^i\right)(x^{i+1} - x^i)^2$$