

# Hidden Markov Model

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Oct. 2018

## 1 Basic Concepts & Examples

### 1.1 Basic Concepts

*Definition 1.1* Assume  $X = \{X_n; n \geq 1\}$  is a Markov chain over finite state space  $\Phi = \{1, 2, \dots, K\}$ , if states of  $X$  are unobservable,  $Y = \{Y_n; n \geq 1\}$  is an observable random variable series over finite set  $V = \{v_1, v_2, \dots, v_L\}$  that is correlated with  $X$ , then  $(X, Y) = \{(X_n, Y_n); n \geq 1\}$  is a *Hidden Markov Chain*.

Denote  $\pi = \{\pi_1, \pi_2, \dots, \pi_k\}$  is the initial distribution of  $X$ ,  $A = [a_{ij}]$  is the transition matrix of  $X$

$$a_{ij} = P\{X_{n+1} = j | X_n = i\}, i, j \in \Phi \quad (1)$$

is the one-step transition probability of  $X$ . Denote

$$b_{ij} = P\{Y_n = v_j | X_n = i\}, i \in \Phi, v_j \in V \quad (2)$$

represents the probability that  $Y$  equals to  $v_j$  given  $X$  is at state  $i$  at time  $n$ . If  $X$  is homogeneous, then  $Y$  is also irrelevant with time  $n$ . Denote  $B = [b_{ij}]$  as the observation probability matrix. Due to the unobservability of  $X$ ,  $\pi, A, B$  can not be directly measured. Generally, we call parameter set  $\lambda = \{\pi, A, B\}$  the math model of Hidden Markov chain  $(X, Y)$ , as well as *Hidden Markov Model* (HMM).

*Property 1.1* Assume  $N$  is the length of time on observation, denote  $\mathbf{X} = \{X_1, X_2, \dots, X_N\}$ ,  $\mathbf{Y} = \{Y_1, Y_2, \dots, Y_N\}$  as the sample series of Markov chain  $X$  and observation series  $Y$  in the time period  $1 \sim N$  respectively, then the joint distribution of  $\mathbf{X}$  and  $\mathbf{Y}$  satisfy the following *Hidden Markov Condition*.

$$P\{\mathbf{X} = x, \mathbf{Y} = y\} = \pi_{i_1} b_{i_1 j_1} \dots b_{i_{N-1} j_{N-1}} b_{i_N j_N} \quad (3)$$

where  $x = \{i_1, \dots, i_N\}$ ,  $y = \{v_{j_1}, \dots, v_{j_N}\}$ .

### 1.2 Examples

*Coin flipping problem* Stochastically choose a coin from two coins indexed 1 and 2, and then toss it, observe the result and repeat this process. Denote  $X_n$  as the coin chosen in  $n^{th}$  time, then  $X = \{X_n; n \geq 1\}$  is a Markov chain over state space  $\Phi = \{1, 2\}$ . Denote  $Y_n$  as the result of  $n^{th}$  experiment, then  $Y = \{Y_n; n \geq 1\}$

is observation series that takes values from  $V = \{H, T\}$ , where  $H$  means the front side and  $T$  means the back side. State transition matrix and observation probability matrix are

$$A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}, B = \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix}, \quad (4)$$

where summation of each row equals to 1. For initial distribution  $\pi = \{\pi_1, \pi_2\}$ , we have  $\pi_1 + \pi_2 = 1$ . Then  $\lambda = \{\pi, A, B\}$  is the corresponding HMM of Hidden Markov chain  $(X, Y)$ , which contains 5 unknown parameters.

## 2 Basic Problems & Solutions

### 2.1 Basic Problems

*Problem 1* For a specific observation sample series  $\mathbf{Y} = \{Y_1, \dots, Y_n\}$ , known it is generated by one of the given HMMs, determine which model that generates the sample series is called *Pattern Recognition* problem, as well as *classification* problem.

*Problem 2* From a series of observation samples  $\mathbf{Y} = \{Y_1, \dots, Y_n\}$  and known HMM  $\lambda = \{\pi, A, B\}$ , give the best estimate of hidden states is called *State Estimate* problem, as well as *Decoding* problem.

*Problem 3* From a series of observation samples  $\mathbf{Y} = \{Y_1, \dots, Y_n\}$ , give the best estimate of parameter set  $\lambda = \{\pi, A, B\}$ , we call it *Model Learning* problem.

### 2.2 Solutions

*Solution to Problem 1* To solve Problem 1 is mainly to solve  $P\{\mathbf{Y}|\lambda\}$ , for different  $\lambda$ , we can compare with their corresponding  $P\{\mathbf{Y}|\lambda\}$ , and choose the largest one. So how to compute  $P\{\mathbf{Y}|\lambda\}$ ?

$$P\{\mathbf{Y} = y|\lambda\} = \sum_x P\{\mathbf{Y} = y, \mathbf{X} = x|\lambda\} \quad (5)$$

$$= \sum_x \pi_{i_1} b_{i_1 j_1} \dots b_{i_{N-1} j_{N-1}} b_{i_N j_N} \quad (6)$$

In order to make the writing more convenient, we introduce notation  $\alpha_n(i)$  and  $\beta_n(i)$  first.

$$\alpha_n(i) = P\{Y_1 = v_{j_1}, \dots, Y_n = v_{j_n}, X_n = i|\lambda\} \quad (7)$$

$$\beta_n(i) = P\{Y_{n+1} = v_{j_{n+1}}, \dots, Y_N = v_{j_N} | X_n = i, \lambda\} \quad (8)$$

Recurrence relation of  $\alpha_n(i)$ .

$$\alpha_n(i) = \sum_{j=1}^K \alpha_n(j) a_{ji} b_{ij_{n+1}}, n = 1, \dots, N-1 \quad (9)$$

*proof*

$$\alpha_{n+1}(i) = P\{Y_1 = v_{j_1}, Y_n = v_{j_n}, Y_{n+1} = v_{j_{n+1}}, X_{n+1} = i | \lambda\} \quad (10)$$

$$= \sum_{k=1}^K P\{Y_1 = v_{j_1}, \dots, Y_n = v_{j_n}, Y_{n+1} = v_{j_{n+1}}, X_n = k, X_{n+1} = i | \lambda\} \quad (11)$$

$$= \sum_{k=1}^K P_A P_B P_C \quad (12)$$

where

$$P_A = P\{Y_1 = v_{j_1}, \dots, Y_n = v_{j_n}, X_n = k | \lambda\} \quad (13)$$

$$P_B = P\{X_{n+1} = i | Y_1 = v_{j_1}, \dots, Y_n = v_{j_n}, X_n = k, \lambda\} \quad (14)$$

$$P_C = P\{Y_{n+1} = v_{j_{n+1}} | Y_1 = v_{j_1}, \dots, Y_n = v_{j_n}, X_n = k, X_{n+1} = i, \lambda\} \quad (15)$$

Notice that for  $P_A$ , we have

$$P_A = P\{Y_1 = v_{j_1}, \dots, Y_n = v_{j_n}, X_n = k | \lambda\} = \alpha_n(k) \quad (16)$$

$$(17)$$

For  $P_B$ , we have

$$P_B = P\{X_{n+1} = i | Y_1 = v_{j_1}, \dots, Y_n = v_{j_n}, X_n = k, \lambda\} \quad (18)$$

$$= P\{X_{n+1} = i | X_n = k, \lambda\} \quad (19)$$

$$= a_{ki} \quad (20)$$

For  $P_C$ , we have

$$P_C = P\{Y_{n+1} = v_{j_{n+1}} | Y_1 = v_{j_1}, \dots, Y_n = v_{j_n}, X_n = k, X_{n+1} = i, \lambda\} \quad (21)$$

$$= P\{Y_{n+1} = v_{j_{n+1}} | X_{n+1} = i, \lambda\} \quad (22)$$

$$= b_{ij_{n+1}} \quad (23)$$

Combine the three equations together, we have

$$\alpha_{n+1}(i) = \sum_{k=1}^K P_A P_B P_C \quad (24)$$

$$= \sum_{k=1}^K \alpha_n(k) a_{ki} b_{ij_{n+1}} \quad (25)$$

□

Recurrence relation of  $\beta_n(i)$

$$\beta_n(i) = \sum_{j=1}^K \beta_{n+1}(j) a_{ij} b_{jj_{n+1}}, n = 1, \dots, N-1 \quad (26)$$

*proof*

$$\beta_n(i) = P\{Y_{n+1} = v_{j_{n+1}}, \dots, Y_N = v_{j_N} | X_n = i, \lambda\} \quad (27)$$

$$= \sum_{k=1}^K P\{Y_{n+1} = v_{j_{n+1}}, \dots, Y_N = v_{j_N}, X_{n+1} = k | X_n = i, \lambda\} \quad (28)$$

$$= \sum_{k=1}^K P_X P_Y P_Z \quad (29)$$

where

$$P_X = P\{X_{n+1} = k | X_n = i, \lambda\} \quad (30)$$

$$P_Y = P\{Y_{n+2} = v_{j_{n+1}}, \dots, Y_N = v_{j_N} | X_{n+1} = k, X_n = i, \lambda\} \quad (31)$$

$$P_Z = P\{Y_{n+1} = v_{j_{n+1}} | X_{n+1} = k, X_n = i, Y_{n+2} = v_{j_{n+1}}, \dots, Y_N = v_{j_N}, \lambda\} \quad (32)$$

For  $P_X$ , we have

$$P_X = P\{X_{n+1} = k | X_n = i, \lambda\} = a_{ik} \quad (33)$$

For  $P_Y$ , we have

$$P_Y = P\{Y_{n+2} = v_{j_{n+1}}, \dots, Y_N = v_{j_N} | X_{n+1} = k, X_n = i, \lambda\} \quad (34)$$

$$= P\{Y_{n+2} = v_{j_{n+1}}, \dots, Y_N = v_{j_N} | X_{n+1} = k, \lambda\} \quad (35)$$

$$= \beta_{n+1}(k) \quad (36)$$

For  $P_Z$ , we have

$$P_Z = P\{Y_{n+1} = v_{j_{n+1}} | X_{n+1} = k, X_n = i, Y_{n+2} = v_{j_{n+1}}, \dots, Y_N = v_{j_N}, \lambda\} \quad (37)$$

$$= P\{Y_{n+1} = v_{j_{n+1}} | X_{n+1} = k, \lambda\} \quad (38)$$

$$= b_{kj_{n+1}} \quad (39)$$

Combine the three equations, we have

$$\beta_n(i) = \sum_{k=1}^K P_X P_Y P_Z \quad (40)$$

$$= \sum_{k=1}^K \beta_{n+1}(k) a_{ik} b_{kj_{n+1}} \quad (41)$$

□

From the  $\alpha_n(i), \beta_n(i)$  defined above, we have

$$P\{\mathbf{Y} = y | \lambda\} = \sum_{j=1}^K \alpha_N(j) \quad (42)$$

$$P\{\mathbf{Y} = y | \lambda\} = \sum_{j=1}^K \beta_1(j) \pi_j b_{jj_1} \quad (43)$$

$$(44)$$

If we divide observation series  $\mathbf{Y} = \{Y_1, \dots, Y_N\}$  into  $\{Y_1, \dots, Y_n\}$  and  $\{Y_{n+1}, \dots, Y_N\}$  then we have

$$P\{\mathbf{Y} = y, X_n = i | \lambda\} = \alpha_n(i) \beta_n(i) \quad (45)$$