



# Design Of A Novel Low Cost Consequent Pole Permanent Magnet Synchronous Machine

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# Introduction

## PERMANENT MAGNET SYNCHRONOUS MACHINE

- Permanent Magnet Synchronous Machine(PMSM) is widely used for various industrial applications, Electric Vehicles and House hold appliances.
- PMSM is advantageous due to their high efficiency ,high torque and power density.
- The cost of PMSM directly depend on amount of Permanent Magnet(PM) used.

# Objectives

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- To Design a low-cost PMSM with identical torque features to conventional PMSM.
- To study and analyse different possible topologies of PMSM..

- Reluctance torque can help motors to reduce amount of PM used.
- Surface PMSM have high torque density, But their reluctance torque produced is low.
- In conventional machines  $i_d=0$  control is used for utilizing the reluctance torque.

- Axially sandwiched PMSM will make full use of magnetic and reluctance torque for total torque production.
- Consequent Pole PMSM (CP-PMSM) is with dovetailed consequent-pole rotor will reduce PM and provide lower harmonic distortion .
- Tangential PMs are embedded into the proposed rotors of the CPM machines to form the novel hybrid-pole PM (HPM) machines.

# Current Advancements

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- By using N-S iron sequences and flux barriers the output torque and efficiency can be improved

# Working Principle

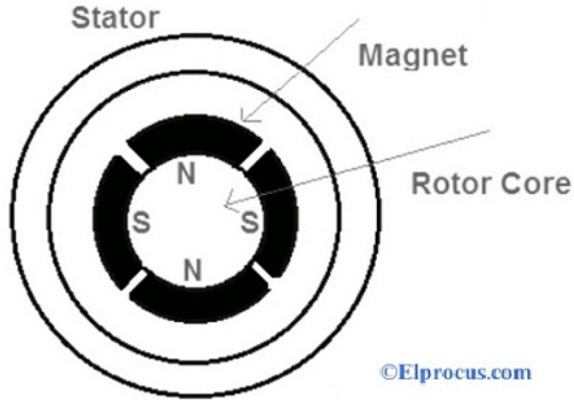
## Conventional PMSM

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- Similar to Synchronous Motor.
- Permanent Magnet is the Rotor.
- Stator winding is energised by 3 phase supply.

# Working Principle

## Surface Mounted PMSM



**Figure:** Top view of Surface Mounted Conventional PMSM



# Working Principle

## Interior PMSM

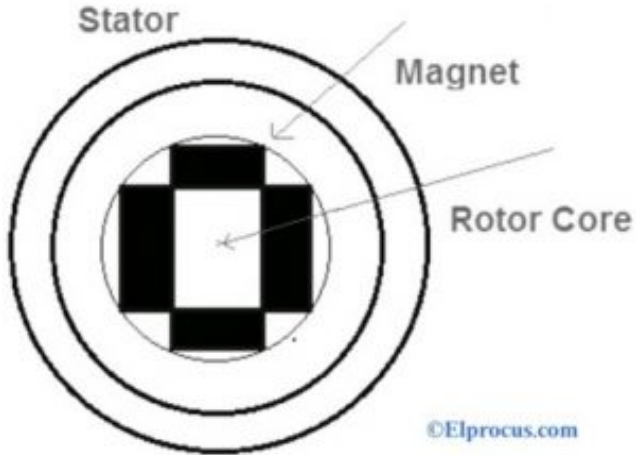


Figure: Top view of Interior Mounted Conventional

# FEASIBLE PRINCIPLE OF DIFFERENT TOPOLOGIES

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The following assumptions are made for analysis

- Permeance of Iron core is infinite.
- Flux leakage and end effect is neglected
- Recoil Permeability of PM is same as that of air gap

# FEASIBLE PRINCIPLE OF DIFFERENT TOPOLOGIES

## Conventional PMSM Structure

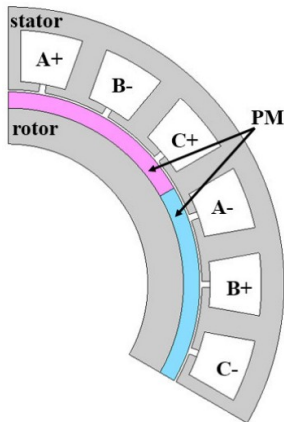


Figure: Structure of  
Conventional PMSM

# FEASIBLE PRINCIPLE OF DIFFERENT TOPOLOGIES

## Conventional PMSM Magnetic Circuit

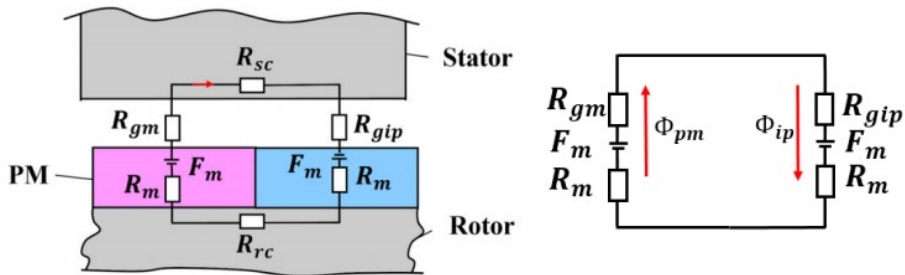


Figure: Conventional PMSM Magnetic Circuit

# FEASIBLE PRINCIPLE OF DIFFERENT TOPOLOGIES

## Conventional PMSM Magnetic Circuit

$$AirGapFlux = \frac{2F_m}{2R_m + R_{gm} + R_{gip} + R_{sc} + R_{rc}}$$

Which can be reduced to,

$$\frac{2F_m}{2R_m + R_{gm} + R_{gip}}$$

The resultant torque is

$$Torque = \frac{3p * [A_{pm} * i_q]}{2}$$

# FEASIBLE PRINCIPLE OF DIFFERENT TOPOLOGIES

## CP PMSM Structure

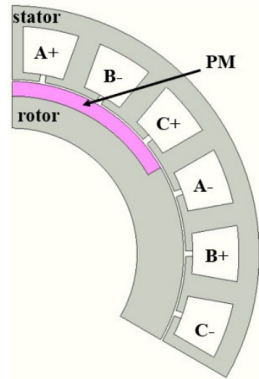


Figure: Structure of CP PMSM

# FEASIBLE PRINCIPLE OF DIFFERENT TOPOLOGIES

## Conventional PMSM Magnetic Circuit

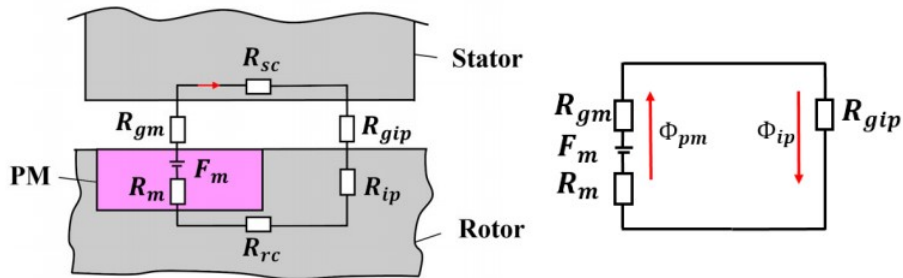


Figure: Conventional PMSM Magnetic Circuit

# FEASIBLE PRINCIPLE OF DIFFERENT TOPOLOGIES

## CP PMSM Magnetic Circuit

$$AirGapFlux = \frac{F_m}{R_m + R_{gm} + R_{gip} + R_{sc} + R_{rc}}$$

Which can be reduced to,

$$\frac{F_m}{R_m + R_{gm} + R_{gip}}$$

The resultant torque is

$$Torque = \frac{3p}{2} [A_{pm} * i_q + (L_d - L_q) * i_d * i_q]$$



# FEASIBLE PRINCIPLE OF DIFFERENT TOPOLOGIES

## ICP PMSM Structure

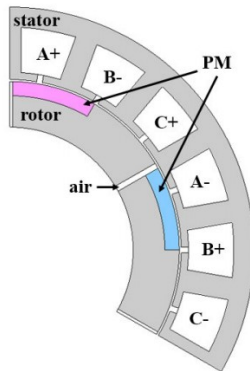


Figure: Structure of proposed ICP PMSM

# FEASIBLE PRINCIPLE OF DIFFERENT TOPOLOGIES

## ICP PMSM Magnetic Circuit

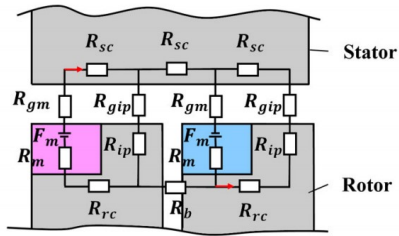


Figure: Magnetic circuit.

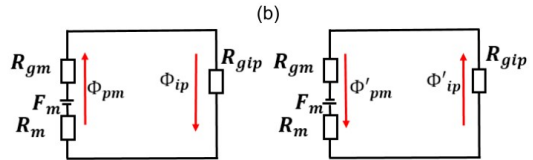


Figure: Equivalent magnetic circuit

# FEASIBLE PRINCIPLE OF DIFFERENT TOPOLOGIES

## ICP PMSM Magnetic Circuit

$$AirGapFlux = \frac{F_m}{R_m + R_{gm} + R_{gip}}$$

The resultant torque is

$$Torque = \frac{3p}{2} [A_{pm} * i_s * \cos(\delta) + 0.5 * (L_d - L_q) * i_s^2 * \cos(2\delta)]$$

# FEASIBLE PRINCIPLE OF DIFFERENT TOPOLOGIES

## ICP PMSM Torque

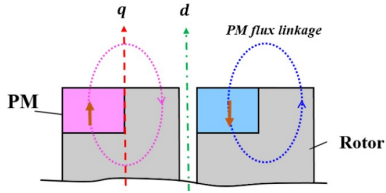


Figure: PM Torque

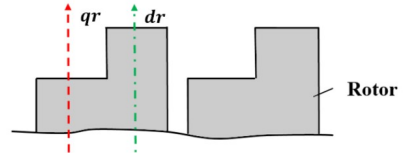


Figure: Reluctance Torque

# FEASIBLE PRINCIPLE OF DIFFERENT TOPOLOGIES

## ISCP PMSM Structure

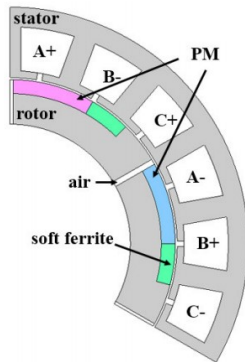


Figure: Structure of proposed ISCP PMSM

# OPTIMIZATION DESIGN OF ROTORS

## CP PMSM Rotor

- The PM arc ratio is

$$\alpha p = \frac{\Theta_{pm} * p}{2\pi}$$

- By Optimizing PM arc ratio we obtain the maximum Torque at

$$\alpha p = 0.68$$

- And minimum Torque at

$$\alpha p = 0.5$$

- CP PMSM cannot reach the torque and torque ripple similar to Conventional PMSM.

# OPTIMIZATION DESIGN OF ROTORS

## CP PMSM Rotor

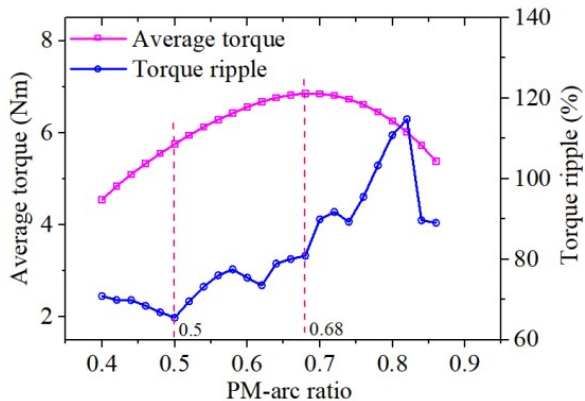


Figure: Average torque and torque ripple with variable  $\alpha p$

# OPTIMIZATION DESIGN OF ROTORS

## ICP PMSM Rotor

- PM-arc ratio and air barrier width are complex for maximum torque.
- By using GA method optimal design results are obtained.
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$$b = 1.423mm$$

$$\alpha p = 0.6275$$



# OPTIMIZATION DESIGN OF ROTORS

## ISCP PMSM Rotor

- By using GA method optimal design results are obtained.
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$$b = 1.20mm$$

$$\alpha p = 0.592$$

$$\beta s = 0.770$$

# Performance Analysis and Comparison

## Air-Gap Flux Density

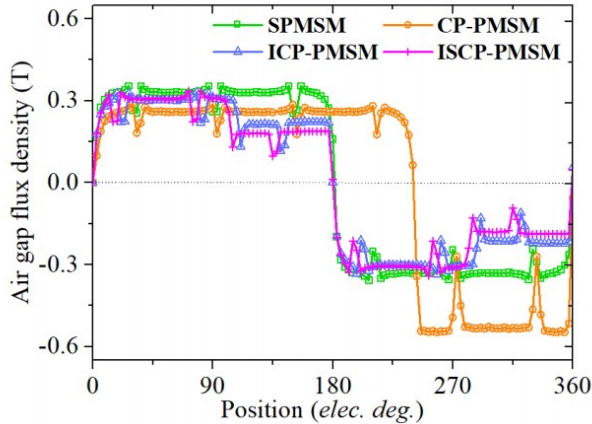


Figure: Air-gap flux density distribution of investigated

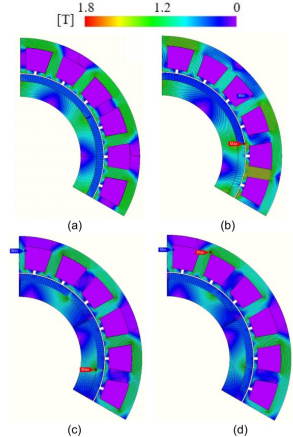


Figure: Magnetic Flux

# Performance Analysis and Comparison

## Back Emf

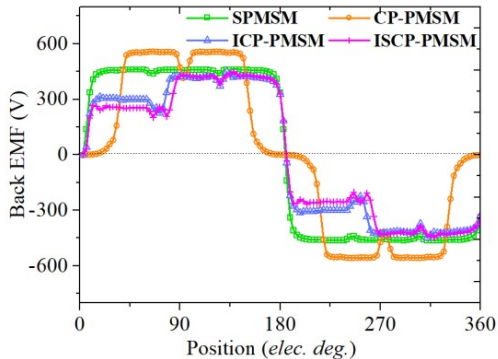


Figure: Air-gap flux density distribution of investigated machines

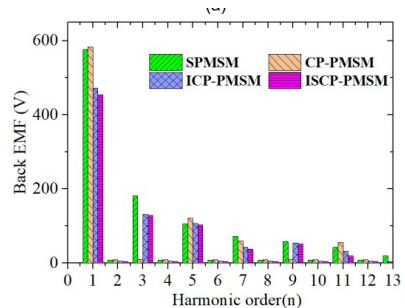


Figure: Magnetic Flux Distribution

# Performance Analysis and Comparison

## Torque Performance

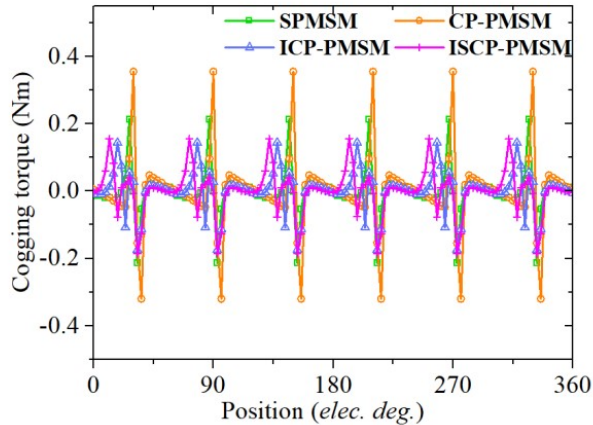


Figure: Variation of cogging torque with rotor positions.

# CONCLUSION

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- Based on conventional PMSM CP-PMSM is presented.
- ICP-PMSM is proposed and optimized using reluctance torque.
- ISCP PMSM is proposed and optimized.
- It is established that ISCP PMSM can completely replace the conventional SPMSM at a lower cost.

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# Thankyou!