

# 1 Convolution from Scratch

In this exercise, you will explore the fundamentals of convolution, a vital operation in various fields such as signal processing, image processing, and deep learning. Convolution is a mathematical operation that combines two functions to produce a third, representing how one function modifies the other. To gain a deeper understanding of convolution, you will perform a manual convolution operation.

## 1.1 Subtask 1: Importing Essential Packages

### Preparing for Manual Convolution 🚀

#### 1. Set Up Your Coding Environment

Before delving into manual convolution, ensure you have a suitable coding environment ready. If you already have one, excellent! If not, now is the time to set it up.

#### 2. Identify Required Packages

Our journey requires a couple of trusty packages. Specifically, we need NumPy and SciPy. NumPy excels in numerical operations and array manipulations, while SciPy empowers you with advanced scientific computing capabilities. So, equip yourself with these powerful tools.

#### 3. Import Packages

With your treasures located, let's summon them into your coding realm with the following incantations:

```
1 import numpy as np # NumPy for arrays and math
2 from scipy import signal # SciPy for scientific
   computing
```

**Pro Tip:** If you're feeling creative, give your packages cool nicknames (like "np" for NumPy) to make your code even more magical and easy to type.

**3... 2... 1... Abracadabra!** You now have the mystical powers of NumPy and SciPy at your fingertips. You're all set to conquer the world of manual convolution!

## 1.2 Subtask 2: Loading and Preparing Data

### Data Preparation for Manual Convolution

#### 1. Load Data

Let's begin by loading our starship data, the image, from the enigmatic `sample.npy` file using NumPy's magic:

```
1 img = np.load("sample.npy")
```

#### 2. Data Transformation

Prepare the image by rounding down its values with the `np.floor()` command and save it back to `img`:

```
1 img = np.floor(img / 2)
```

#### 3. Load the Filter

But wait, we also need a top-secret filter to navigate through the cosmos! Load it from the `"filter.npy"` file with NumPy:

```
1 fltr = np.load("filter.npy")
```

#### 4. Data Verification

Before our journey commences, inspect the first few elements of `img` and `fltr` by printing them:

```

1 print("Image data:")
2 print(img[:5])} #Print the first 5 elements of img
3
4 print("Filter data:")
5 print(fltr[:5]) #Print the first 5 elements of fltr

```

## 5. Ready to Roll

With our data loaded, transformed, and the filter in hand, we're all set to kick off the thrilling manual convolution process. Get ready to explore the universe of convolution in Subtask 3!

Exciting times await in the universe of manual convolution.

## 1.3 Subtask 3: Implementing Manual Convolution

### Navigating the Galaxy of Image Processing

#### 1. The Manual Convolution Function

It's time to implement a custom convolution function named `Myconv2d`. Let's break it down step by step:

```

1 def Myconv2d(a, b):

```

This function takes two inputs, `a` and `b`, representing your data and filter.

#### 2. Convert to NumPy Arrays

To prepare your data and filter for the convolution process, convert `a` and `b` into NumPy arrays:

```

1 a = np.array(a) #Convert data to a NumPy array
2 b = np.array(b) #Convert filter to a NumPy array

```

#### 3. Determine Data and Filter Shapes

Understand the dimensions of your data and filter by determining their shapes:

```

1 a_shape = np.shape(a) #Get the shape of data
2 b_shape = np.shape(b) #Get the shape of the
   filter

```

#### 4. Calculate Result Dimensions

Calculate the dimensions of the result, "res" based on the differences in dimensions:

```

1 res_shape1 = np.abs(a_shape[0] - b_shape[0]) + 1
   #Calculate the first dimension of the result
2 res_shape2 = np.abs(a_shape[1] - b_shape[1]) + 1
   #Calculate the second dimension of the result

```

#### 5. Create an Empty Result Matrix

Prepare a matrix, "res" to store the convolution results:

```

1 res = np.zeros([res_shape1, res_shape2]) #Create
   a matrix to store convolution results

```

#### 6. Perform Manual Convolution

Traverse through the data to calculate the convolution result:

```

1 for i in range(res_shape1):
2     for j in range(res_shape2):
3         res[i, j] = np.sum(
4             np.multiply(
5                 np.flip(b), a[i:i + b_shape[0], j
6                     :j + b_shape[1]]
7             )

```

## 7. Return the Resulting Matrix

Your manual convolution function is complete. Now, return the resulting matrix, "res":

```
1 return res # Return the convolution result
```

You've successfully created your manual convolution function! Get ready to apply it to your data and explore the fascinating world of convolution in action!

May the convolution be with you!

## 1.4 Subtask 4: Checking the Result of Your Implementation

### Comparing Manual Convolution to Python Library Implementation

#### 1. Calculate the Manual Convolution Result

Your custom convolution function Myconv2d is ready. Put it to the test:

```
1 Result_Imp = Myconv2d(img, fltr) # Calculate the
convolution result using your implementation
```

#### 2. Calculate the Python Library Convolution Result

Don't forget Python's library magic! Use the signal.convolve2d function from SciPy to calculate the convolution result:

```
1 Result_Python = signal.convolve2d(img, fltr, mode="
valid") # Calculate the convolution result using
the Python library
```

#### 3. Compare the Results

It's time for a grand comparison. Calculate the error value by comparing the results from your implementation and the Python library:

```
1 checkup = np.sum(np.abs(Result_Imp - Result_Python))
# Calculate the error value by comparing the two
results
```

#### 4. Display the Error Value

Display the error value to gauge how closely your implementation matches the Python library:

```
1 print("The Error Value is:", checkup) # Display the
error value to assess the closeness of your
results to the Python library
```

#### 5. The Verdict

Results checked! If the error value is close to zero, your manual convolution implementation is performing admirably. The smaller the error, the closer your results align with the Python library's results.

You're now ready to evaluate your manual convolution implementation. May the results be in your favor! 