

GM9236S025

Lo-Cog® DC Servo Gearmotor



Assembly Data	Symbol	Units	Value	
Reference Voltage	Е	V	12	
No-Load Speed	S_{NL}	rpm (rad/s)	71	(7.4)
Continuous Torque (Max.) ¹	T_C	oz-in (N-m)	480	(3.4E+00)
Peak Torque (Stall) ²	T_{PK}	oz-in (N-m)	2585	(1.8E+01)
Weight	W_{M}	oz (g)	23.7	(671)
Motor Data				
Torque Constant	K _T	oz-in/A (N-m/A)	3.25	(2.29E-02)
Back-EMF Constant	K _E	V/krpm (V/rad/s)	2.40	(2.29E-02)
Resistance	R_T	Ω	0.71	
Inductance	L	mH	0.66	
No-Load Current	I _{NL}	Α	0.33	
Peak Current (Stall) ²	l _P	Α	16.9	
Motor Constant	K_{M}	oz-in/√W (N-m/√W)	4.11	(2.90E-02)
Friction Torque	T_F	oz-in (N-m)	0.80	(5.6E-03)
Rotor Inertia	J_{M}	oz-in-s ² (kg-m ²)	1.0E-03	(7.1E-06)
Electrical Time Constant	τ_{E}	ms	1.06	
Mechanical Time Constant	τ_{M}	ms	8.5	
Viscous Damping	D	oz-in/krpm (N-m-s)	0.053	(3.5E-06)
Damping Constant	K_D	oz-in/krpm (N-m-s)	12.5	(8.5E-04)
Maximum Winding Temperature	θ_{MAX}	°F (°C)	311	(155)
Thermal Impedance	R_{TH}	°F/watt (°C/watt)	56.3	(13.5)
Thermal Time Constant	$ au_{TH}$	min	13.5	
Gearbox Data				
Reduction Ratio			65.5	
Efficiency ³			0.80	
Maximum Allowable Torque		oz-in (N-m)	500	(3.53)
Encoder Data				
Channels			3	
Resolution		CPR	500	

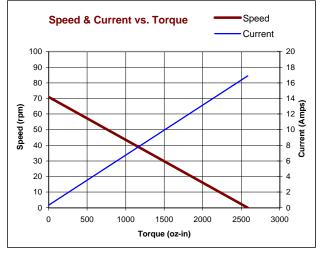
^{1 -} Specified at max. winding temperature at 25°C ambient without heat sink. 2 - Theoretical values supplied for reference only.

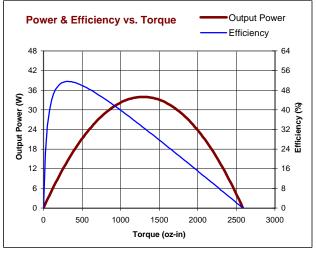
Included Features

2-Pole Stator
Ceramic Magnets
Heavy-Guage Steel Housing
7-Slot Armature
Silicon Steel Laminations
Stainless Steel Shaft
Copper-Graphite Brushes
Diamond Turned Commutator
Motor Ball Bearings
Output Ball Bearing
Wide Face Gears

Customization Options

Alternate Winding
Sleeve or Ball Bearings
Modified Output Shaft
Custom Cable Assembly
Special Brushes
EMI/RFI Suppression
Alternate Gear Material
Special Lubricant
Optional Encoder
Fail-Safe Brake





All values are nominal. Specifications subject to change without notice. Graphs are shown for reference only.

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^{3 -} Effective gearbox efficiency for this unit improved by use of ball bearings

