

Chapter 4. Determinants.

° Some important properties of determinant.

1. A^{-1} exist when $\det A \neq 0$.

2. $\det A$ equals the volume of a box in \mathbb{R}^n space.

ex) Jacobian.

$$J = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial z} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial z} \\ \frac{\partial z}{\partial r} & \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial z} \end{vmatrix} = r, \quad \begin{cases} x = r \cos \theta \\ y = r \sin \theta \\ z = z \end{cases} \quad \text{Cylindrical coord.}$$

$$dx dy dz = r dr d\theta dz.$$

3. $\det A = \pm$ (product of the pivots)

4. Cramer's rule for $Ax = b$.

$$x_1 = \frac{\det A_1}{\det A}$$

$$A_1 = \begin{bmatrix} b & a_2 & a_3 & \cdots & a_n \end{bmatrix}$$

4.2 Properties of Determinant.

→ demonstrated by 2×2 matrix $\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = ad - bc.$

⊙ Basic Properties.

1. $\det I = 1.$

2. The determinant changes sign when two rows are exchanged.

3. The determinant depends linearly on the first row.

$$\text{ex) } \begin{vmatrix} a+a' & b+b' \\ c & d \end{vmatrix} = \begin{vmatrix} a & b \\ c & d \end{vmatrix} + \begin{vmatrix} a' & b' \\ c & d \end{vmatrix}$$

$$\begin{vmatrix} ta & tb \\ c & d \end{vmatrix} = t \begin{vmatrix} a & b \\ c & d \end{vmatrix}$$

$$\cdot \det(A+B) \neq \det(A) + \det(B)$$

$$\cdot \det(tA) \neq t \det(A)$$

$$\hookrightarrow t^n \det(A).$$

⊙ Additional Properties by 1~3.

4. If two rows are equal, then $\det(A) = 0.$ → by prop. 2

5. Subtracting a multiple of one row from another row leaves the same determinant.

row operation $\begin{vmatrix} a - lc & b - ld \\ c & d \end{vmatrix} = \begin{vmatrix} a & b \\ c & d \end{vmatrix} + \begin{vmatrix} -lc & -ld \\ c & d \end{vmatrix}$

6. If A has a row of zeros, then $\det(A) = 0$.

7. If A is triangular, $\det(A) = \text{product of diagonal entries}$
 $= a_{11} a_{22} \cdots a_{nn}$.

pf) Gauss elimination can remove all the off-diagonal elements without changing the determinant (by rule 5).

$$\det(D) = a_{11} \cdots a_{nn} \text{ for diagonal matrix}$$

8. (If A is singular, $\det(A) = 0$.
 A is non-singular (invertible), $\det(A) \neq 0 \rightarrow \pm \text{product of pivots}$.

9. $\det(AB) = \det(A) \cdot \det(B)$.

$$\det(A^{-1}) = \frac{1}{\det(A)}$$

$$\det(A) = \frac{\det(AB)}{\det(B)} = \det(A) \cdot \frac{\det(B)}{\det(B)}$$

by property 1-3. (1) $B=I$
 (2) row exchange of A .

10. $\det(A^T) = \det(A)$.

(3).

$$PA = LDU \rightarrow \det(PA) = \det(P) \det(A) \rightarrow \det(L) \det(D) \det(U)$$

$$\det(PA)^T = \det(A^T) \det(P^T)$$

$\det \Rightarrow L, D, U \rightarrow \text{diagonal product}$.

$$= \det(U^T) \det(D^T) \det(L^T)$$